

# Software Workshop

15 Dec 2025

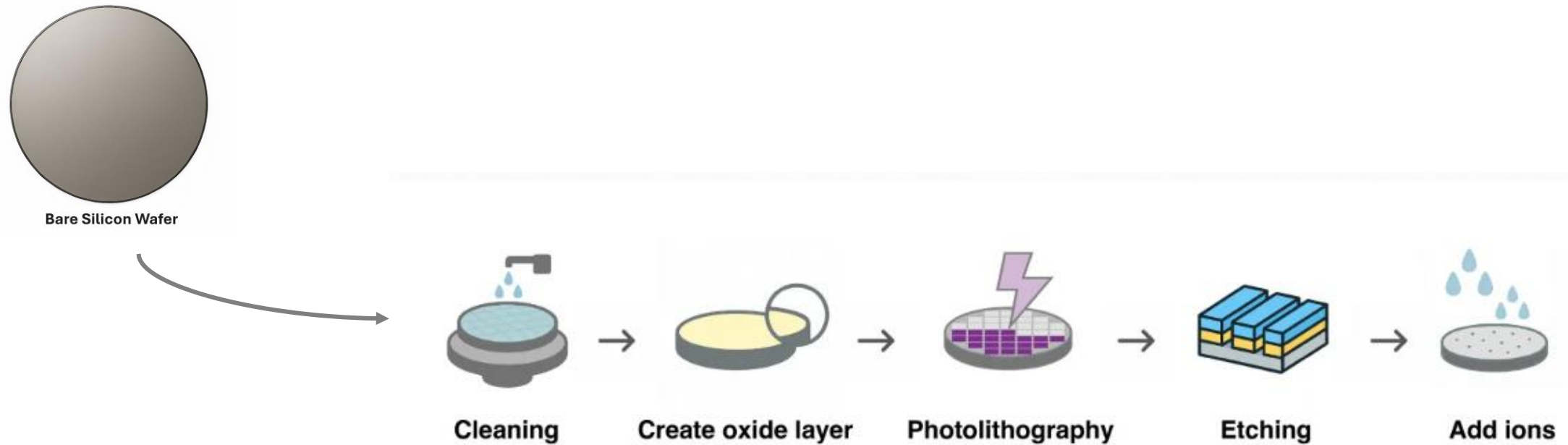
# Agenda for today

Time	Activity
8:00 AM	Problem Statement description (Milestone 1 – 3)
8:30 AM	Students to download input dataset and problem statement PDF
8:45 AM	Students start investigation and solve the problem
9:15 AM	Mentors assigned and will start checking in with you as needed
1:00 PM	Lunch
6:00 – 6:30 PM	Results of Day 1 will be announced.

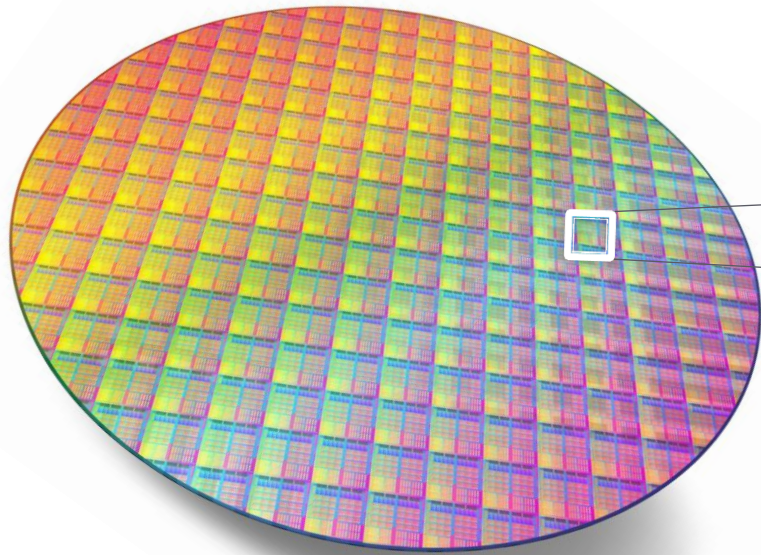
# Terminologies and concepts



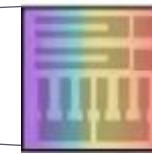
# Chip Manufacturing Process



# Wafer and Die



Wafer



Chip (Die)

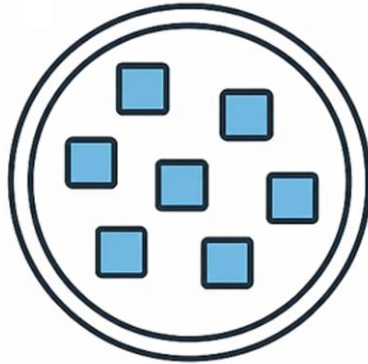


# Advanced Packaging

Dicing of wafers



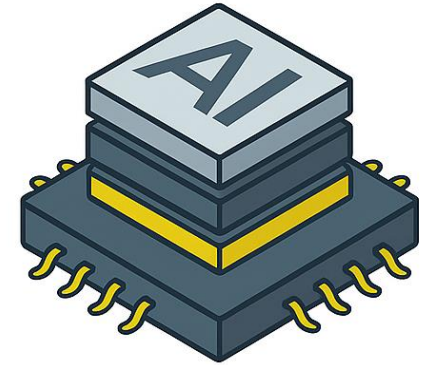
Paste them on  
Film Frame Carrier



Inspect dies



Advanced Packaging  
and Chip stacking

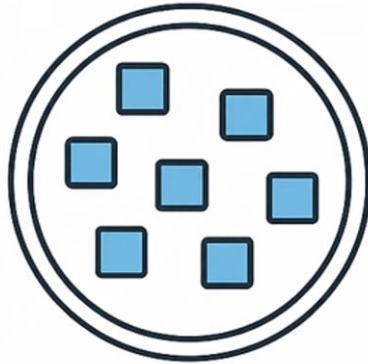


# Advanced Packaging

Dicing of wafers



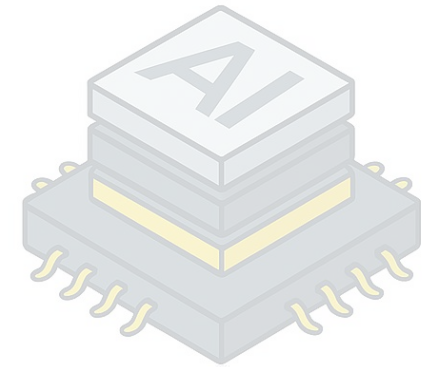
Paste them on  
Film Frame Carrier



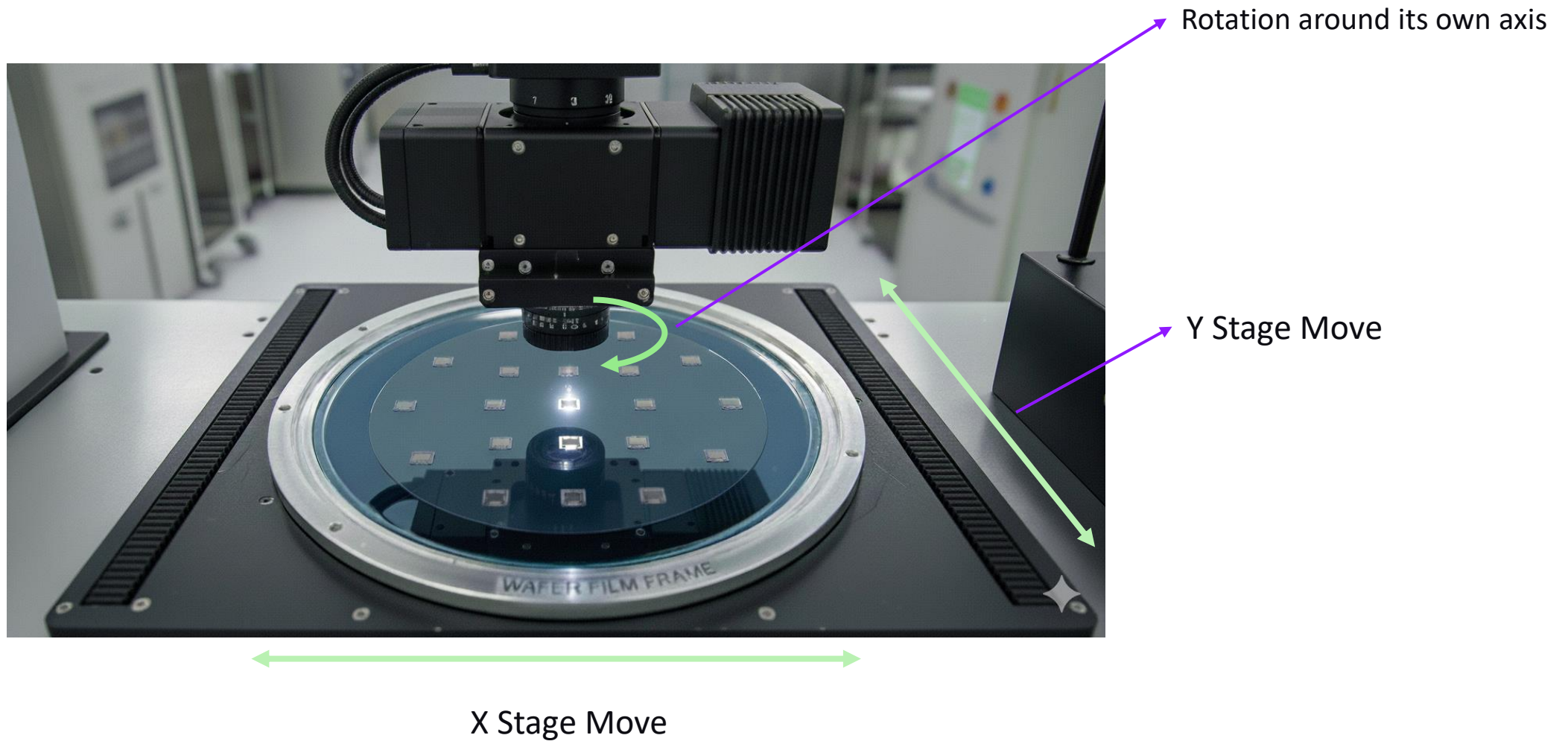
Inspect dies



Advanced Packaging  
and Chip stacking

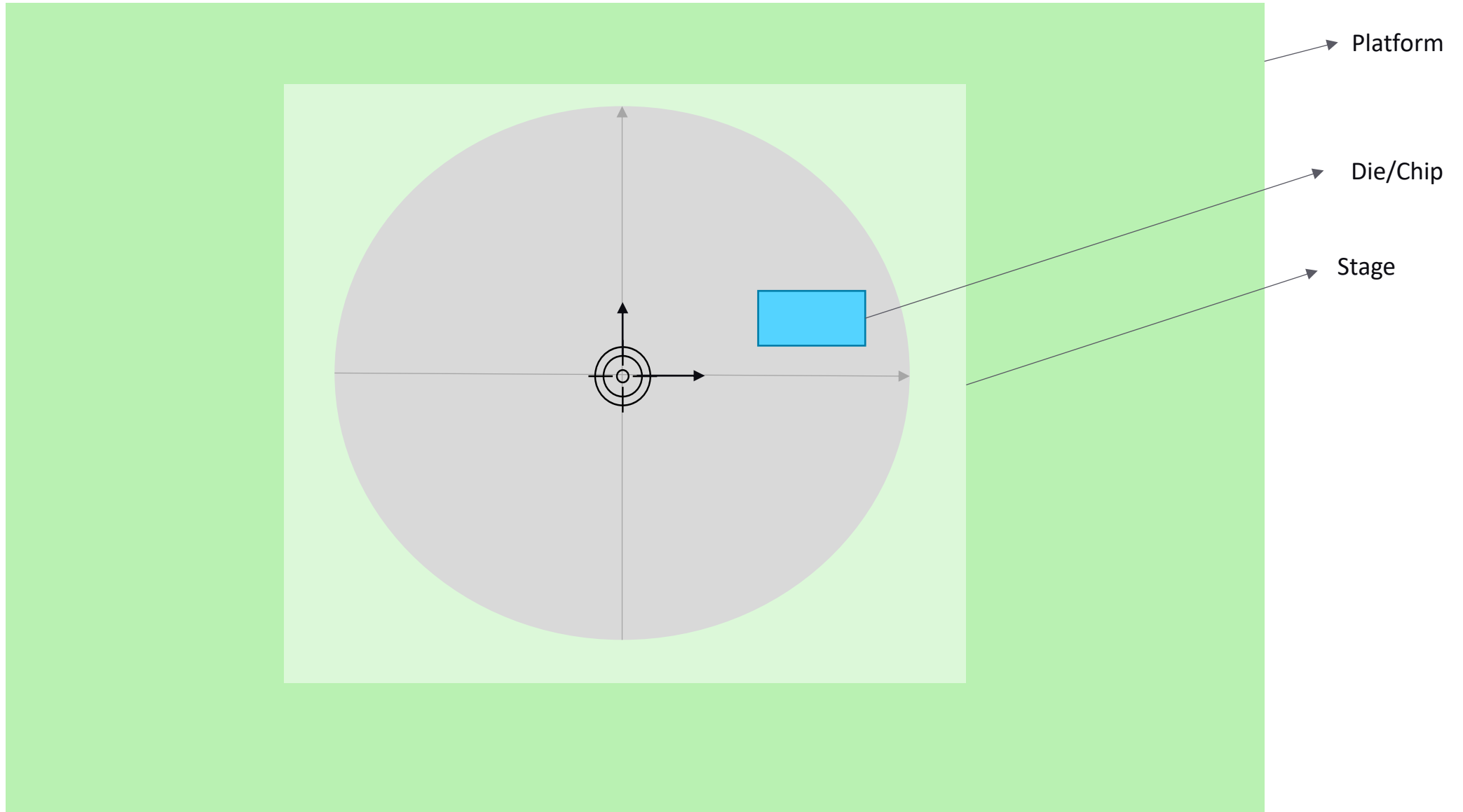
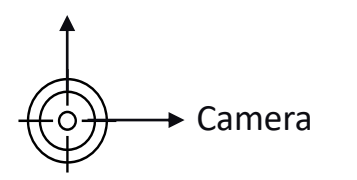


# Inspection on Film Frame Carrier

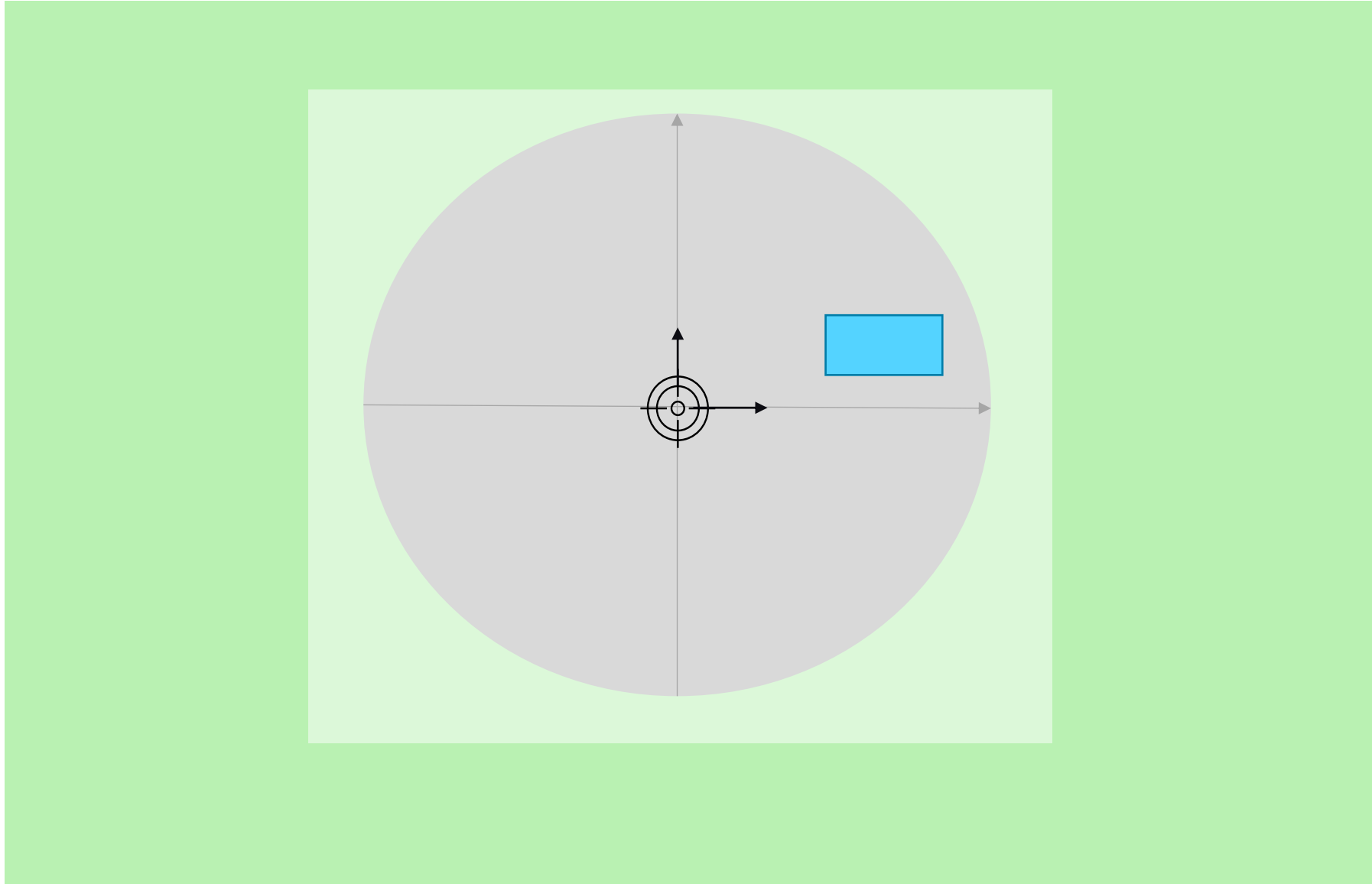




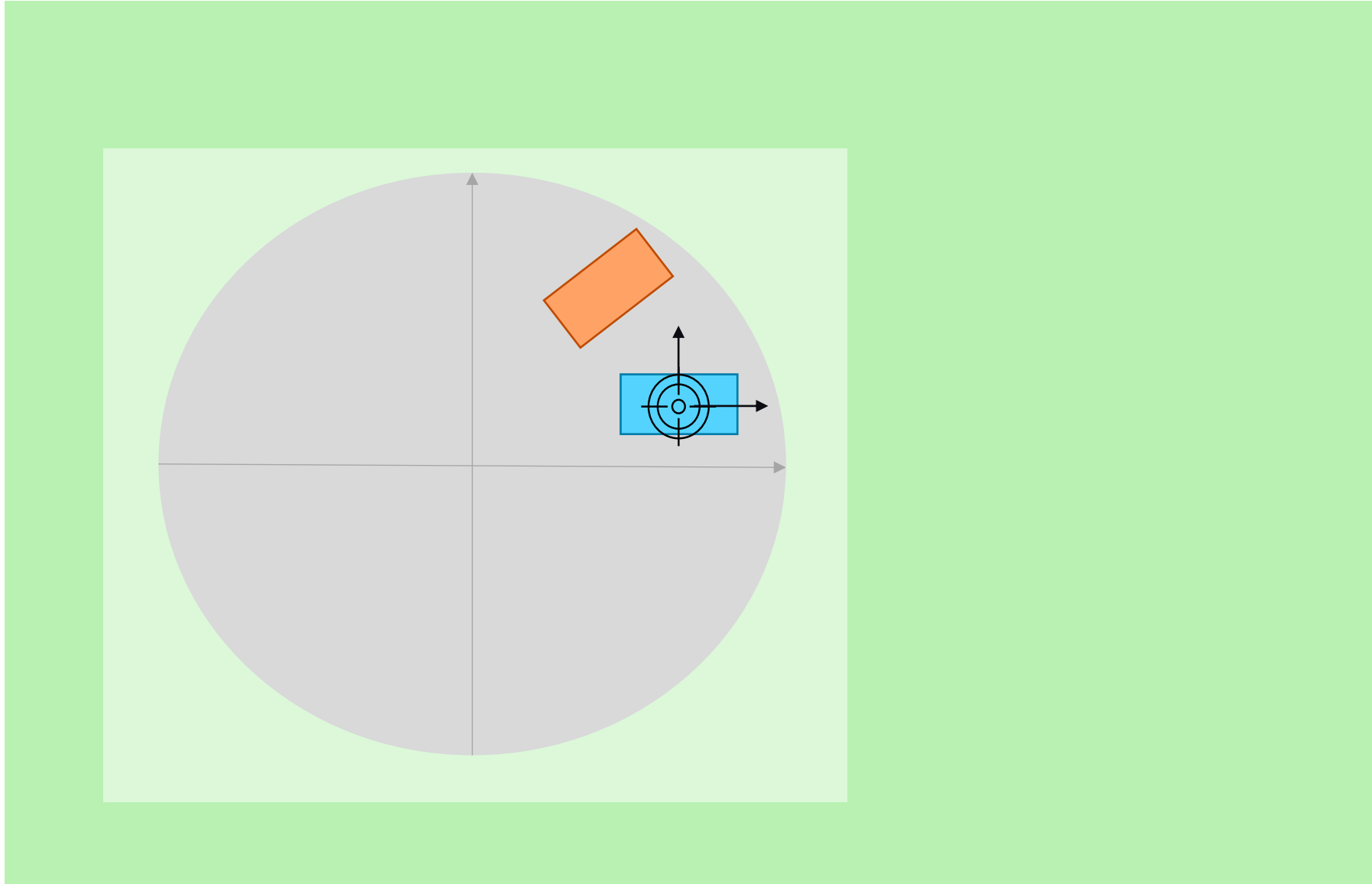
# Stage Movement and Camera Rotation Explained



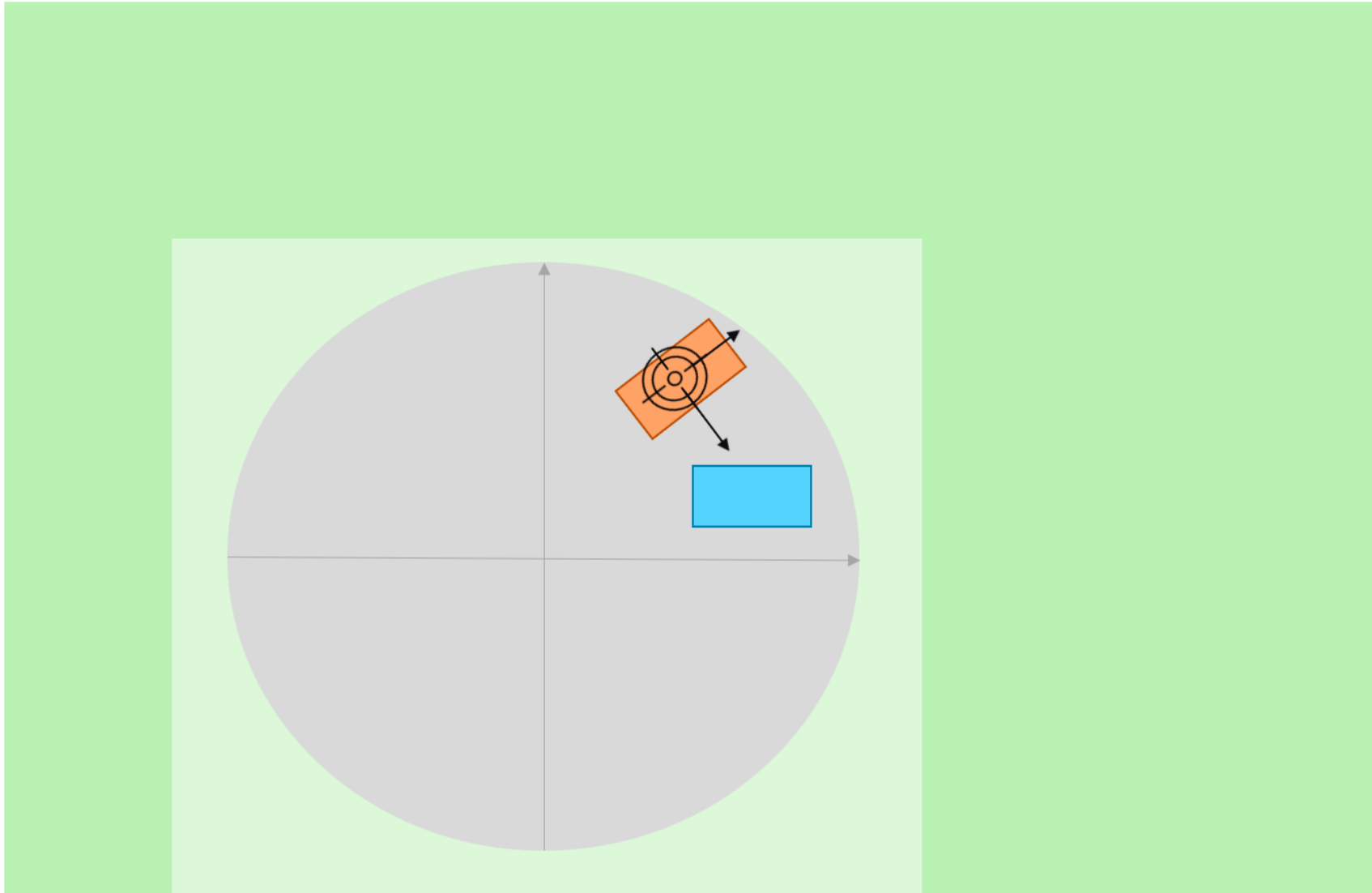
# Stage Movement and Camera Rotation Explained



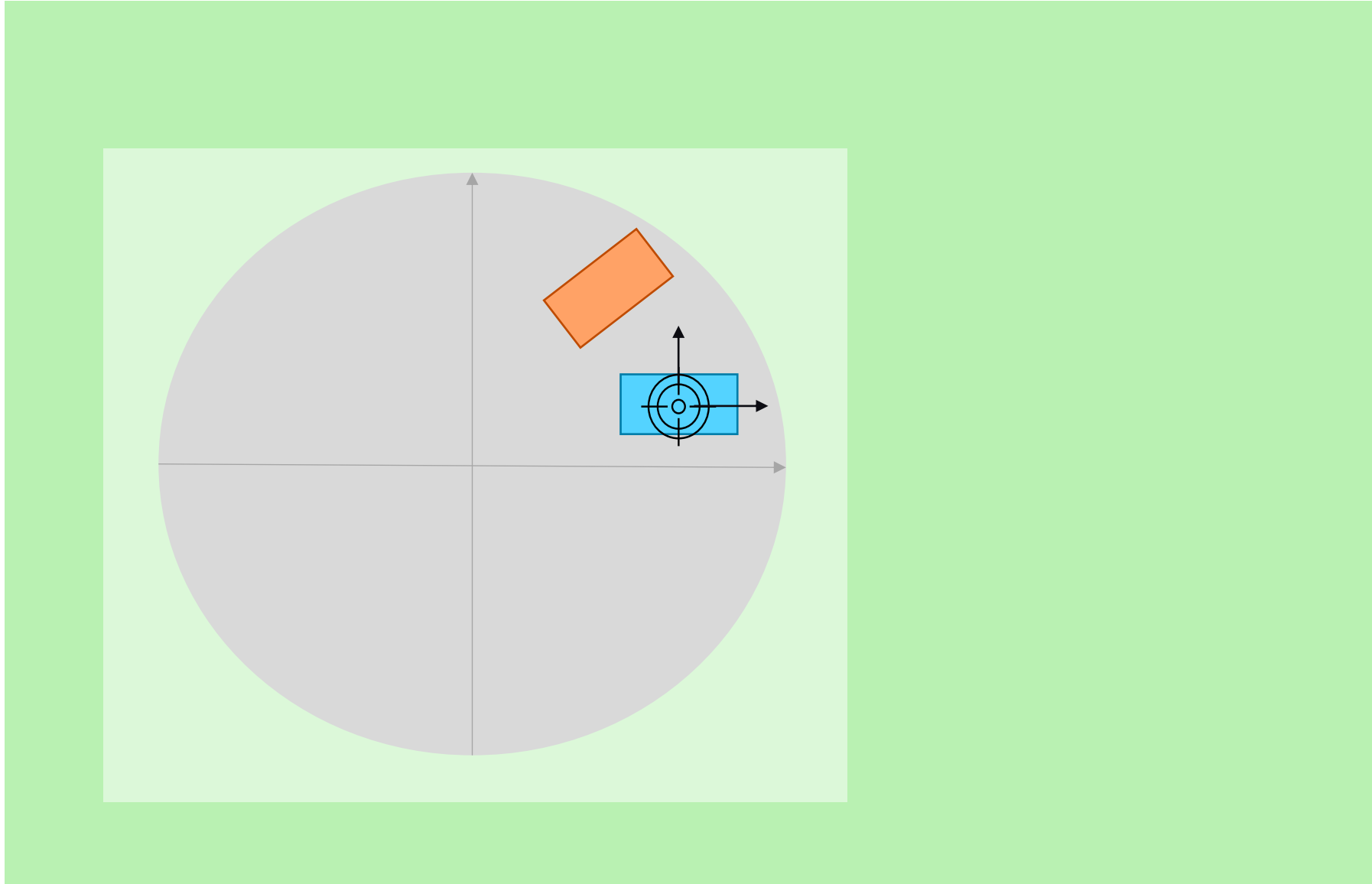
# Stage Movement and Camera Rotation Explained



# Stage Movement and Camera Rotation Explained

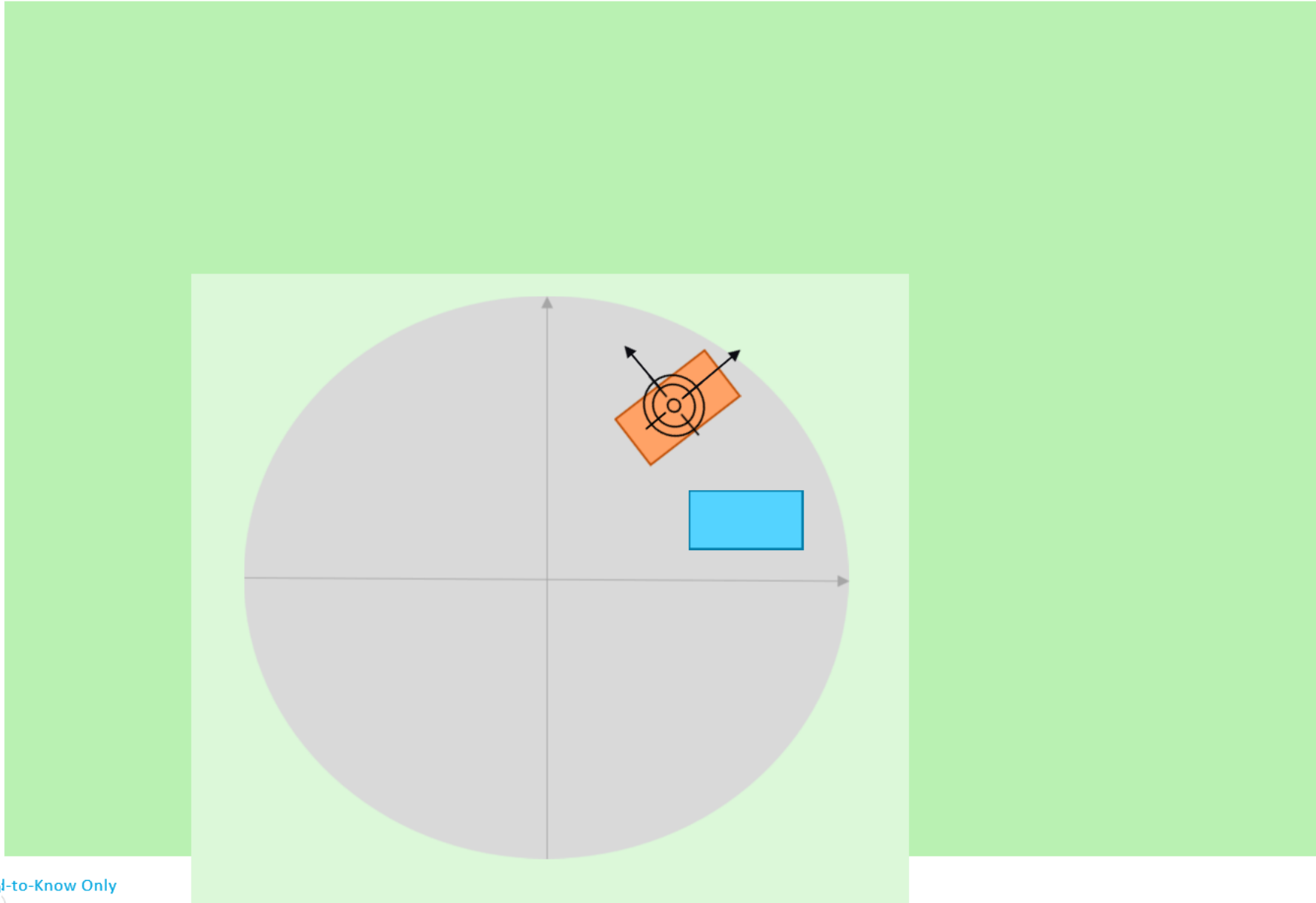


# Stage Movement and Camera Rotation Explained





# Stage Movement and Camera Rotation Explained



# Problem Statement



# Objective

Given a list of dies, find the optimal path and time to inspect all the dies.

# Output

```
{  
  "TotalTime": 3.962,  
  "Path": [  
    [0, 50],  
    [60.0, 0.0],  
    [30.0, 0.0],  
    [0.0, 0.0],  
    [-30.0, 0.0],  
    [-60.0, 0.0]  
  ]  
}
```

Diagram illustrating the output structure and units:

- `"TotalTime": 3.962` is annotated with **In ms**.
- `"Path": [ [0, 50], ... ]` is annotated with **In mm**.

# Milestone 1

## ■ Input

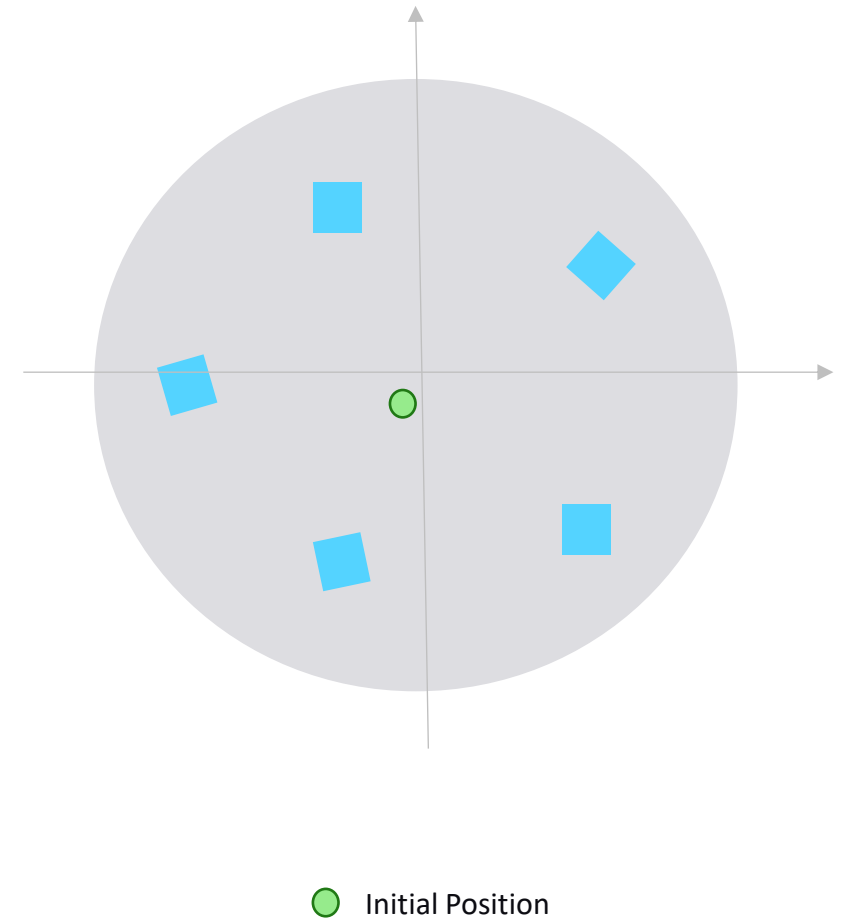
- Die Coordinates (mm)
- Initial position (x, y) of stage (in mm)
- Constant velocity (v) of stage movement (in mm/ms)





# Milestone 2

- Additional Input
  - Constant camera angular velocity (in deg/ms)



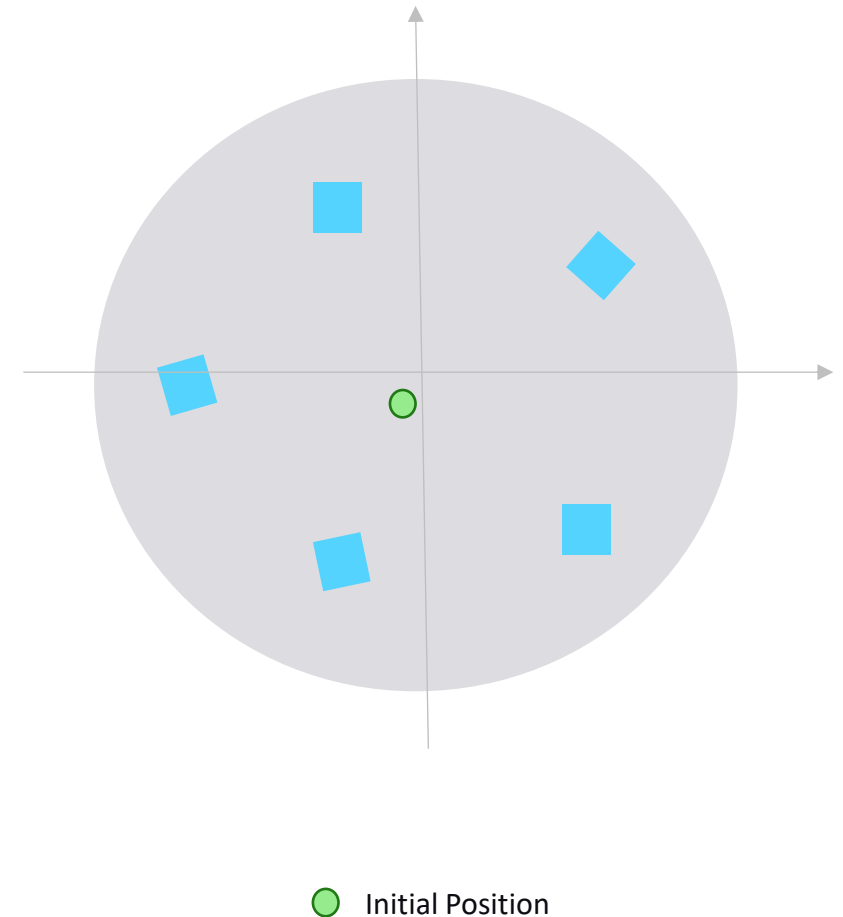
# Milestone 3

## ■ Additional Input

- Maximum stage velocity ( $v_{\max}$ ) in mm/ms
- Maximum stage acceleration ( $a_{\max}$ ) in mm/ms<sup>2</sup>
- Maximum camera angular velocity in deg/ms
- Maximum camera angular acceleration in deg/ms<sup>2</sup>

## ■ Assumption

- Consider the deceleration value to be equal to the given acceleration value (same magnitude, opposite direction).



# Guidelines/Instructions

- Problem Statement and Input testcases will be sent over email.
- Code Check in
  - Check in source code to your github in public repo every hour
  - Share the repo with [klauniversityworkshophiring@gmail.com](mailto:klauniversityworkshophiring@gmail.com)
- Usage of AI is allowed.
- Make sure you create single piece of code to run all milestones.
- Proper Data structures, class design, scalable solution, proper boundary condition check
  - These will be valued.

# Solution Validator

- [klasolutionvalidator2025.azurewebsites.net](https://klasolutionvalidator2025.azurewebsites.net)



## Workshop 2025 - Solution Validator

Student Roll Number

Full Name

College Name

Drag & Drop Files Here  
or click to Select Multiple

**Note:** File names must match the pattern: **TestCase\_<Milestone#>\_<TestCase#>.json** (e.g., TestCase\_1\_2.json)

Submit

# Questions

