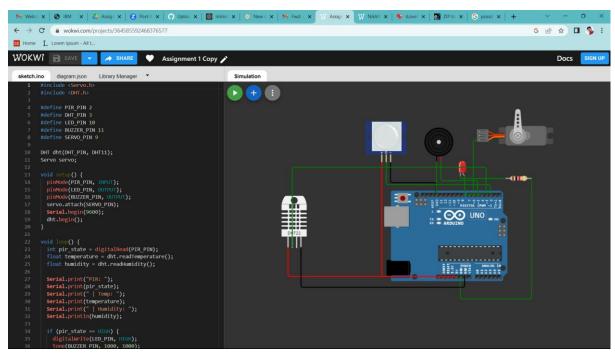
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REG NO.: 732720121021

https://wokwi.com/projects/364586323671899137



```
#include <Servo.h>
#include <DHT.h>
#define PIR PIN 2
#define DHT_PIN 3
#define LED_PIN 10
#define BUZZER PIN 11
#define SERVO_PIN 9
DHT dht(DHT_PIN, DHT11);
Servo servo;
void setup() {
  pinMode(PIR_PIN, INPUT);
 pinMode(LED_PIN, OUTPUT);
  pinMode(BUZZER_PIN, OUTPUT);
  servo.attach(SERVO_PIN);
 Serial.begin(9600);
  dht.begin();
void loop() {
  int pir_state = digitalRead(PIR_PIN);
```

```
float temperature = dht.readTemperature();
float humidity = dht.readHumidity();
Serial.print("PIR: ");
Serial.print(pir_state);
Serial.print(" | Temp: ");
Serial.print(temperature);
Serial.print(" | Humidity: ");
Serial.println(humidity);
if (pir_state == HIGH) {
 digitalWrite(LED_PIN, HIGH);
  tone(BUZZER_PIN, 1000, 1000);
 delay(500);
 digitalWrite(LED_PIN, LOW);
 noTone(BUZZER_PIN);
 servo.write(90);
 delay(5000);
 servo.write(0);
```