

ISAAC KASAHARA

Research Engineer

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[Website](#) | [LinkedIn](#) | [Github](#)

PERSONAL PROFILE

An innovative and self-motivated computer vision engineer. Recently graduated with a Masters in Robotics with a background in computer science. Looking for new and challenging opportunities in computer vision.

PUBLICATIONS

1. Choi*, H., [Kasahara*, I.](#), Engin, S., Graule, M., Chavan-Dafle, N., & Isler, V. (2023).

FineControlNet: Fine-level Text Control for Image Generation with Spatially Aligned Text Control Injection. Under review.

[Website](#) | [Paper](#)

1. [Kasahara, I.](#), Agrawal, S., Engin, S., Chavan-Dafle, N., Song, S., & Isler, V. (2023). RIC:

Rotate-Inpaint-Complete for Generalizable Scene Reconstruction. Under Review. Patent Pending.

[Website](#) | [Paper](#)

1. Agrawal, S., Chavan-Dafle, N., [Kasahara, I.](#), Engin, S., Huh, J. & Isler, V. (2023). Real-time Simultaneous Multi-Object 3D Shape Reconstruction, 6DoF Pose Estimation and Dense Grasp Prediction. **IROS 2023**. Patent Pending.

[Website](#) | [Paper](#)

1. [Kasahara, I.](#), Stent, S., & Park, H. (2022). Look Both Ways: Self-supervising Driver Gaze Estimation and Road Scene Saliency. **ICCV 2022**. Patent Pending.

[Website](#) | [Paper](#)

CAREER HISTORY

RESEARCH ENGINEER

Samsung AI Center NYC, Research Engineer
Research Intern

Apr 2023 - Present
Aug 2022 - Apr 2023

- Worked in Python to develop models and train deep learning models for robotic perception tasks.
- Utilized PyBullet and PyRender to generate synthetic data for training state of the art shape reconstruction models.
- Implemented machine learning models for detecting and locating objects in a real world robotic setting.
- Increased fluency in state of the art visual-language models for text-to-3D algorithms.
- Contributed to novel 6D pose and grasp estimation algorithm for robotics.
- Leveraged the generalization capabilities of large visual-language models for 3D scene reconstruction.
- Developed a method to control details at the instance level for diffusion based text-to-image generation models.

SOFTWARE ENGINEER

Cirrus Aircraft, Engineer I
Intern

Jan 2020 - May 2020
May 2019 - Aug 2019

- Programmed in C++ and Python using Microsoft Visual Studio.
- Developed software requirements for aircraft avionics components.
- Worked on developing algorithms in C++ for experimental sensors on the SF50 Jet using traditional 2D and 3D computer vision techniques.

ACADEMIC HISTORY

UNIVERSITY OF MINNESOTA

Master of Science in Robotics,

Sep 2020 - May 2022

- GPA of 3.9/4.0
- Research Assistant for Professor Hyun Soo Park 2021 - 2022
- Graduate Assistant for the University of Minnesota Robotics Master's program 2020 - 2021

Bachelor of Science in Computer Science,
Emphasis in Robotics and Artificial Intelligence

Sept 2017 - Dec 2019

- Graduated in 2 years with a GPA of 3.6/4.0
- Dean's List Fall 2017 & Spring 2019

SKILLS AND ABILITIES

Languages: Python, MATLAB, C++

Tools: Github, PyTorch, Linux, TensorFlow,

Libraries: NumPy, OpenCV, SciPy, Open3D, PyBullet, PyRender

Skills: Visual-Language Models, 3D Shape Reconstruction, Diffusion Models, Machine Learning, 3D Multiview Geometry, Stereo Depth Estimation, Physics/Calculus, Linear Algebra, Gaze Estimation