

# Matlab Code

Note:

• Question's and answers to problems are highlighted in Code yellow/green.

Problems highlighted blue.

• Graphs are shown on the last two pages.

```
clear all;
close all;
clc;
format long;
name = 'Kasey Haman';
id = 'A16978114';
%%Problem 1
%Initialize for Euler-----
f = @(t, y) exp(-y).*sin(t+2.*pi.*y);
T = 2; y(1) = 1;
%loop for number of steps and step size
n(1) = 4;
h(1) = T/n;
for l = 1:10
n(l+1) = n(l)*2;
h(l+1) = T/n(l+1);
end
%Solve Euler for each step size
for n = 1:11
i = 0;
y = 1;
for t = 0:h(n):2
i = i + 1;
y(i+1) = y(i) + h(n)*f(t, y(i));
end
Eulertvalues{n} = 0:h(n):2;
Euleryvalues{n} = y(1:end-1);
Eulerysoln(n) = y(end-1);
end
%loop for number of steps for graph.
figure(1), hold on;
for n = 1:11
str(n) = T./h(n);
legend_string{n} = sprintf('Euler with %d steps',str(n));
cs = 'bgrcmkykbrgcm';
plot(Eulertvalues{n},Euleryvalues{n}, cs(n), 'LineWidth',1);
end
legend(legend_string,'Location','Northwest');
xlabel('Time T'); ylabel('yk Approximation');
title('Euler Approximation');
box on; grid on;
set(gca,'FontSize',10)
%Initialize for RK4-----
f = @(t, y) exp(-y).*sin(t+2.*pi.*y);
T = 2; y(1) = 1;
%loop for number of steps and step size
n(1) = 4;
h(1) = T/n;
for l = 1:10
```

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n(l+1) = n(l)*2;
h(l+1) = T/n(l+1);
end
%Solve RK4 for each step size
for n = 1:11
i = 0;
y = 1;
for t = 0:h(n):2
i = i + 1;
k1 = h(n)*f(t, y(i));
k2 = h(n)*f(t+h(n)/2, y(i)+k1/2);
k3 = h(n)*f(t+h(n)/2, y(i)+k2/2);
k4 = h(n)*f(t+h(n), y(i)+k3);
y(i+1) = y(i) + 1/6*(k1+2*(k2+k3)+k4);
end
RK4tvalues{n} = 0:h(n):2;
RK4yvalues{n} = y(1:end-1);
RK4ysoln(n) = y(end-1);
end
%loop for number of steps for graph.
figure(2), hold on;
for n = 1:11
str(n) = T./h(n);
legend_string{n} = sprintf('RK4 with %d steps',str(n));
cs = 'bgrcmkbrgcm';
plot(RK4tvalues{n},RK4yvalues{n}, cs(n), 'LineWidth',1);
end
legend(legend_string,'Location','Northwest');
xlabel('Time T'); ylabel('yk Approximation');
title('RK4 Approximation');
box on; grid on;
set(gca,'FontSize',10)
%Initialize for RK2-----
f = @(t, y) exp(-y).*sin(t+2.*pi.*y);
B1 = 1/2; B2 = 1/2; mew = 1; alpha = 1; T = 2; y(1) = 1;
%loop for number of steps and step size
n(1) = 4;
h(1) = T/n;
for l = 1:10
n(l+1) = n(l)*2;
h(l+1) = T/n(l+1);
end
%Solve RK2 for each step size
for n = 1:11
i = 0;
y = 1;
for t = 0:h(n):2
i = i + 1;
k1 = h(n)*f(t, y(i));

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k2 = h(n)*f(t+mew*h(n), y(i)+alpha*k1);
y(i+1) = y(i) + B1*k1 + B2*k2;
end
RK2tvalues{n} = 0:h(n):2;
RK2yvalues{n} = y(1:end-1);
RK2ysoln(n) = y(end-1);
end
%loop for number of steps for graph.
figure(3), hold on;
for n = 1:11
str(n) = T./h(n);
legend_string{n} = sprintf('RK2 with %d steps',str(n));
cs = 'bgrcmkykbrgcm';
plot(RK2tvalues{n},RK2yvalues{n}, cs(n), 'LineWidth',1);
end
legend(legend_string, 'Location', 'Northwest');
xlabel('Time T'); ylabel('yk Approximation');
title('RK2 Approximation');
box on; grid on;
set(gca, 'FontSize',10)
%Initialize for Custom RK2-----
f = @(t, y) exp(-y).*sin(t+2.*pi.*y);
B1 = 3/4; B2 = 1/4; mew = 2; alpha = 2; T = 2; y(1) = 1;
%loop for number of steps and step size
n(1) = 4;
h(1) = T/n;
for l = 1:10
n(l+1) = n(l)*2;
h(l+1) = T/n(l+1);
end
%Solve RK2 Custom for each step size
for n = 1:11
i = 0;
y = 1;
for t = 0:h(n):2
i = i + 1;
k1 = h(n)*f(t, y(i));
k2 = h(n)*f(t+mew*h(n), y(i)+alpha*k1);
y(i+1) = y(i) + B1*k1 + B2*k2;
end
RK2tvalues{n} = 0:h(n):2;
RK2yvalues{n} = y(1:end-1);
RK2ysoln(n) = y(end-1);
end
%loop for number of steps for graph.
figure(4), hold on;
for n = 1:11
str(n) = T./h(n);
legend_string{n} = sprintf('RK2 with %d steps',str(n));

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cs = 'bgrcmkykbrgcm';
plot(RKCTvalues{n},RKCyvalues{n}, cs(n), 'LineWidth',1);
end
legend(legend_string, 'Location', 'Northwest');
xlabel('Time T'); ylabel('yk Approximation');
title('Custom RK2 Approximation');
box on; grid on;
set(gca, 'FontSize',10)
%Solve Runge Kuta 4 for "true" solution-----
f = @(t, y) exp(-y).*sin(t+2.*pi.*y);
T = 2; y(1) = 1; n = 8192; h = T/n;
i = 0;
for t = 0:h:2
i = i + 1;
k1 = h*f(t, y(i));
k2 = h*f(t+h/2, y(i)+k1/2);
k3 = h*f(t+h/2, y(i)+k2/2);
k4 = h*f(t+h, y(i)+k3);
y(i+1) = y(i) + 1/6*(k1+2*(k2+k3)+k4);
end
treuyvalues = y(1:end-1);
treutvalues = 0:h:2;
trueyvalue = treuyvalues(end);
%Initialize for error plot-----
for n = 1:11
ErrorEuler(n) = abs(trueyvalue - Eulerysoln(n));
ErrorRK2(n) = abs(trueyvalue - RK2ysoln(n));
ErrorRKC(n) = abs(trueyvalue - RKCysoIn(n));
ErrorRK4(n) = abs(trueyvalue - RK4ysoln(n));
end
n(1) = 4;
h(1) = T/n;
for l = 1:10
n(l+1) = n(l)*2;
h(l+1) = T/n(l+1);
end
%Plot the log error
figure(5), hold on;
cs = 'krbgmckkrbgm';
plot(log10(n),log10(ErrorEuler), '-k','LineWidth',1);
plot(log10(n),log10(ErrorRK2), 'r','LineWidth',1);
plot(log10(n),log10(ErrorRKC), 'b','LineWidth',1);
plot(log10(n),log10(ErrorRK4), 'c','LineWidth',1);
xlabel('Log10(n)'); ylabel('log10(Error y(T))');
title('Log Error y(T) versus log(n)');
legend('Euler', 'RK2', 'Custom RK2', 'RK4','Location','Southwest');
box on; grid on;
set(gca, 'FontSize',10)
%Q: Comment on the slopes

```

%Ans: We see that RK4 has the highest slope, the RK2 functions (which look nearly identical) have the second highest slope and our euler function has the lowest slope. The slope indicates how fast a function will converge to the correct solution, with a higher slope indicating faster convergence. Thus, RK4 is the fastest among this groupset.

%%Problem 2-----

```
%Plot the log error in y(T) versus log f
%Note: Becuase Rk4 has 4 function evals per step, the amount of function
%evals is n*4. Similarly RK2 has 2 function evals per step (n.*2) and
% Euler's only has one per step (n).
figure(6), hold on;
cs = 'krbgmckrbgm';
plot(log10(n),log10(ErrorEuler), '-k','LineWidth',1);
plot(log10(n.*2),log10(ErrorRK2), 'r','LineWidth',1);
plot(log10(n.*2),log10(ErrorRKC), 'b','LineWidth',1);
plot(log10(n.*4),log10(ErrorRK4), 'c','LineWidth',1);
xlabel('Log10(Function Evals)'); ylabel('log10(Error y(T))');
title('Log Error y(T) versus Function Evaluations');
legend('Euler', 'RK2', 'Custom RK2', 'RK4','Location','Southwest');
box on; grid on;
set(gca,'FontSize',10)

%Q: How do the resulting plots change? Explain why they change the way they
%do.
```

%Ans: Certain plots are translated to the right. This means that there is a higher cost to get the same error. Note that because RK4 has more function evals per step, it has a higher translation than RK2. And because Euler has one function eval per step, it has no translation.

%%Problem 3-----

```
clear all
%loop for number of steps and step size
T = 6;
n(1) = 8;
h(1) = T/n;
for l = 1:6
n(l+1) = n(l)*2;
h(l+1) = T/n(l+1);
end
%Initialize
f = @(z, t, y) exp(-1-sin(z))-sin(t+y).^2.*(1+z.^2).^(1/3);
y(1) = 4;
for n = 1:7
[yk_values{n},t_values{n}] = RK4(f, y, 0, h(n));
end
%Plot solution approximations
figure(7), hold on;
for n = 1:7
str(n) = T./h(n);
legend_string{n} = sprintf('RK4 with %d steps',str(n));
cs = 'bgrcmykbrgcm';
```

```

plot(t_values{n},yk_values{n}, cs(n),'LineWidth',1);
end
legend(legend_string,'Location','southwest');
xlabel('Time T'); ylabel('yk Approximation');
title('Problem 3 RK4 Approximation');
box on; grid on;
set(gca,'FontSize',10)
%Q: Explain why you selected the various step sizes. Would it make sense to
%have relation between the number of Runge Kutta steps and the number of
%steps in the fixed point component?
%A: I chose step sizes that varied up to 500 steps in order to see if the
%system would converge quickly with a low step size, using 500 steps as a true
%solution. It makes sense to ensure that the step sizes between fixed point
%and Runge Kutta are similar, as in real life we don't have infinite
%computing power. So we should practice with having equal calculation for
%both fixed point method and Runge Kutta in order to minimize
%error.

```

## Function for problem 3:

```

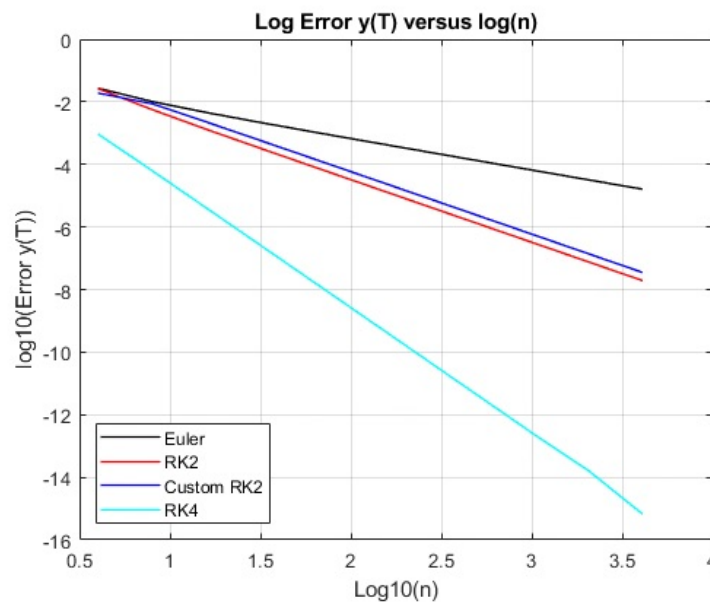
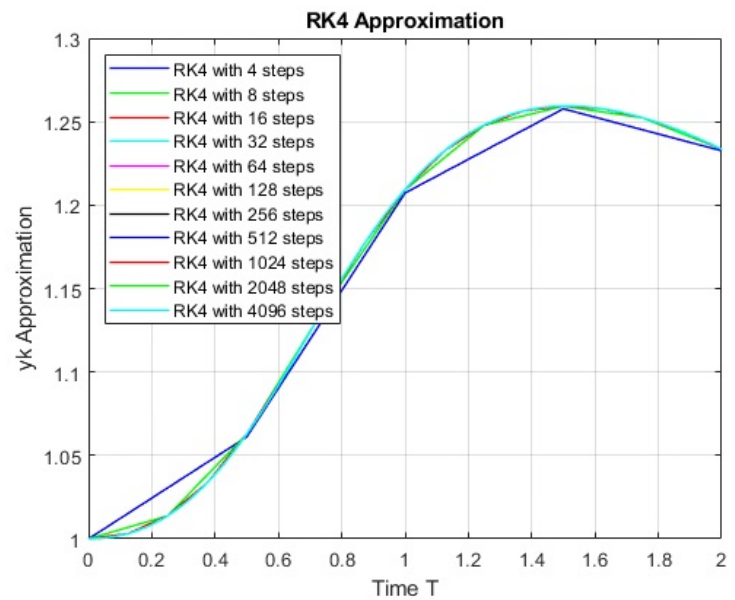
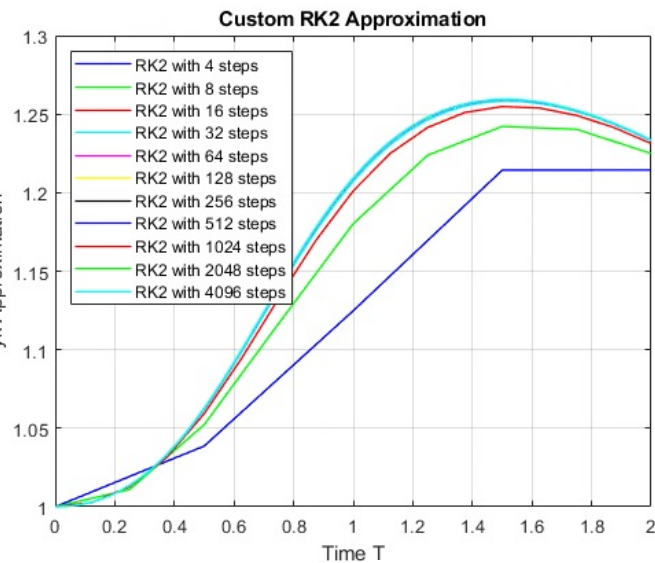
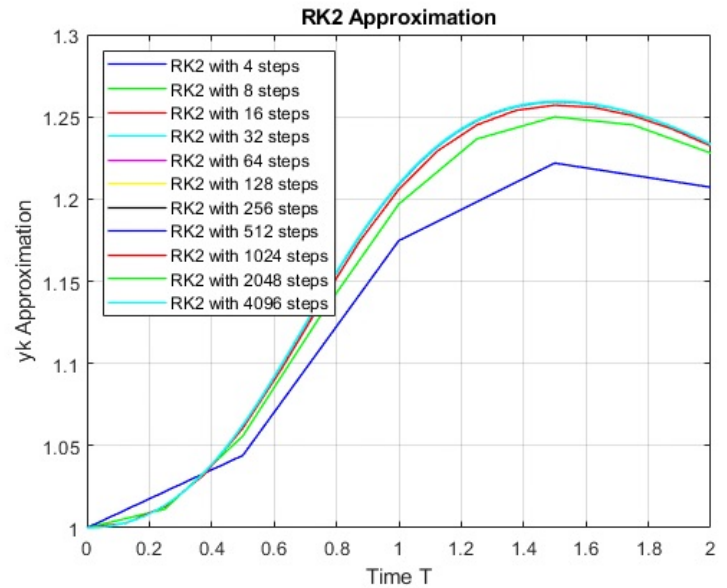
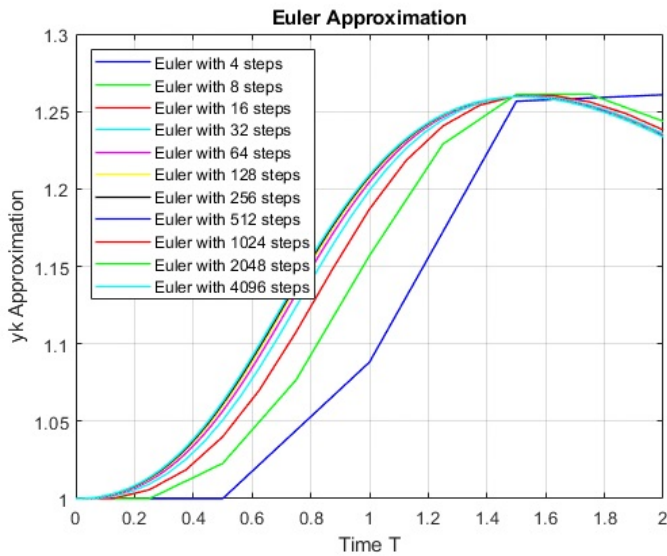
function [yk_values,t_values] = RK4(f, y, z, h)
%This is a Runge Kutta 4 function designed to find the root of a given
%numerical function.
%Note that this function includes the fixed point method used for solving
%the root of a function given 3 variables with 1 unknown.
%Run Runge Kuta 4 loop
i = 0; y(1) = y; z(1) = z;
for t = 0:h:6
i = i + 1;
k1 = h*f(z, t, y(i));
k2 = h*f(z, t+h/2, y(i)+k1/2);
k3 = h*f(z, t+h/2, y(i)+k2/2);
k4 = h*f(z, t+h, y(i)+k3);
y(i+1) = y(i) + 1/6*(k1+2*(k2+k3)+k4);
z = f(z, t, y(i));
end
yk_values = y(1:end-1);
t_values = 0:h:6;
end

```

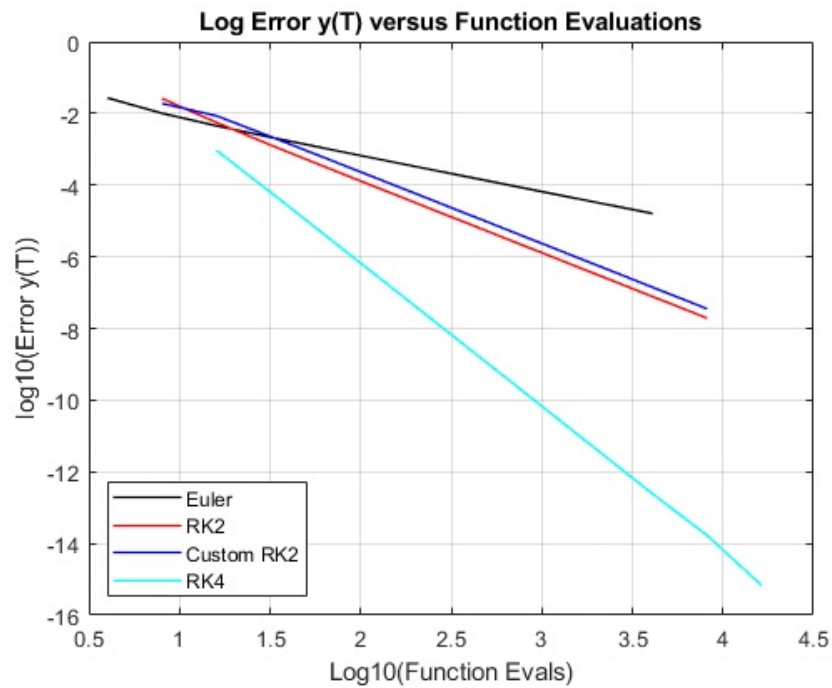
# Graph's produced:

Note: Functions converge to approximately 1.233

## Problem 1)



## Problem 2)



## Problem 3)

Note: Function converges to approximately 2.451

