Multi-Layer Perceptron

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Outline

- Introduction
- Architecture & It's Implementation
- Learning Process & It's Implementation
- Training Set/Data Set
- Questions/Answers

Introduction

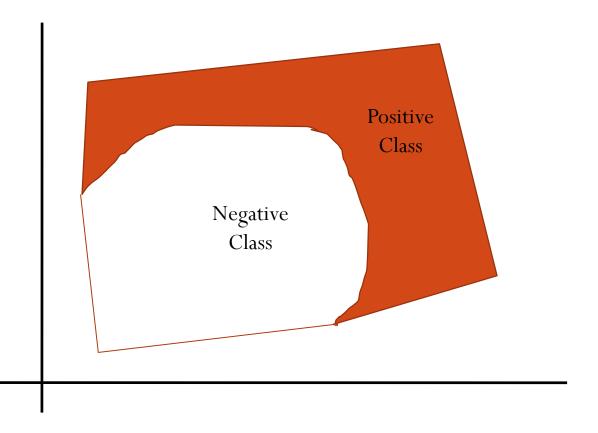
- Limitations in Perceptron:
- 1) Can't solve X-OR Problems
- 2) Can't solve Non-Linearly Separable Problems

Introduction

• XOR Problem

Introduction

• Nonlinear Separable Problem

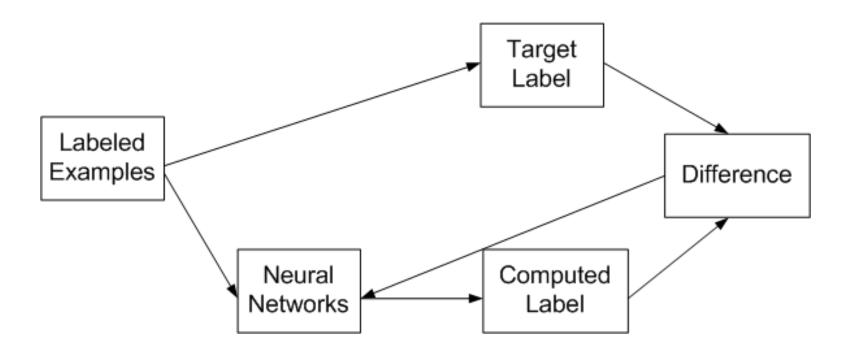


Motivations:

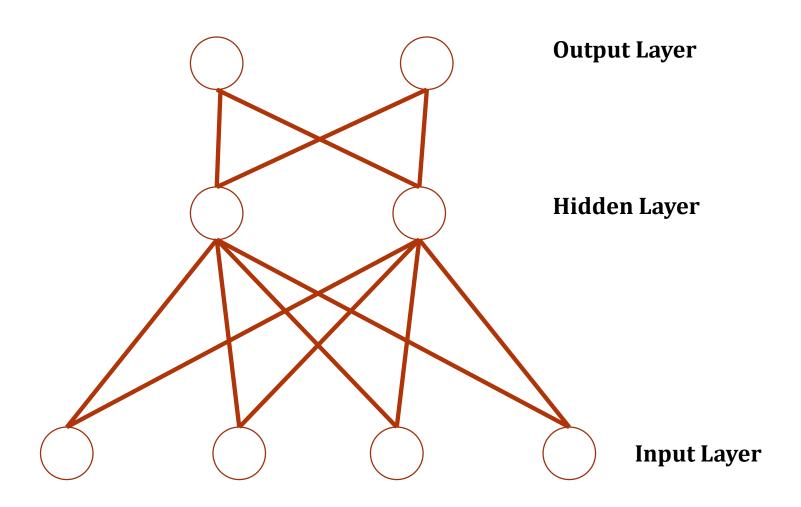
- 1) Addition of intermediate layer called hidden layer
- 1) Solvable even to Nonlinear Separable

Introduction: Multilayer Perceptron

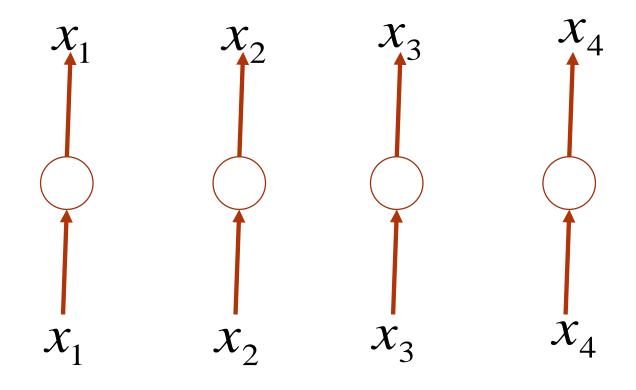
Supervised Neural Networks



Architecture



Architecture: Input Node



Implementation: Input Layer

```
15
      public class InputLayer implements Layer{
16
          int dinput;
17
          NeuralVector inputLayerValues;
18
   public InputLayer(int inputLength) {
19
                inputNodes = nodes;
20
              dinput=inputLength;
21
22
23
          @Override
          public void setInputNodesValues(NeuralVector inputVector) {
25
              inputLayerValues = inputVector;
26
27
          public NeuralVector getOutputValuesOfLayer() {
29
              return inputLayerValues;
30
31
32
33
```

Implementation: Input Node

```
public void setValues(List<Double> value) {
    input = (Vector) value ;
@Override
public List<Double> getValues() {
    return input;
@Override
public double get(int i) {
    return input.elementAt(i);
```

Architecture: Hidden Node

$$h_{1} = f\left(\sum_{i=1}^{4} x_{i} w_{1i}^{1}\right) = \left(1 + \exp\left(-\sum_{i=1}^{4} x_{i} w_{1i}^{1}\right)\right)^{-1} \quad h_{2} = f\left(\sum_{i=1}^{4} x_{i} w_{2i}^{1}\right) = \left(1 + \exp\left(-\sum_{i=1}^{4} x_{i} w_{2i}^{1}\right)\right)^{-1}$$

$$w_{11}^{1} \qquad w_{12}^{1} \qquad w_{13}^{1} \qquad w_{22}^{1} \qquad w_{23}^{1}$$

$$x_{1} \qquad x_{2} \qquad x_{3} \qquad x_{4} \qquad x_{1} \qquad x_{2} \qquad x_{3} \qquad x_{4}$$

Implementation: Hidden Layer

```
16
     public class HiddenLayer implements Layer {
17
18
         List<HiddenNode> hiddenNodes;
19
          InputLayer inputValues;
20
          int dinput;
          double learningRate;
21
22
23
          int mhidden:
24
25
          public HiddenLayer(int numberOfHiddenNodes, int inputLength, double hiddenLayerLearingRate, InputLayer inputLayerValue
26
              dinput = inputLength;
27
              inputValues = inputLayerValue;
28
              learningRate = hiddenLayerLearingRate;
              hiddenNodes = new Vector<HiddenNode>();
             mhidden = numberOfHiddenNodes;
30
32
                      inputNodes=inputnodes;
33
```

Implementation:

Hidden Layer

```
34
35
   public void initilize() {
36
37
              for (int j = 0; j < mhidden; j++) {
38
                  for (int i = 0; i < dinput; i++) {
39
                      Random r = new Random();
40
                      MultiLayerPerceptron.hiddenLayerWeights[j][i] = ((r.nextDouble() * (-0.1)) + 0.1);
41
42
43
44
              for (int i = 0; i < mhidden; i++) {
45
                  hiddenNodes.add(new HiddenNode(dinput, mhidden, this));
46
47
67
          @Override
1
          public NeuralVector getOutputValuesOfLayer() {
              InputVector vectorFromInputLayer = (InputVector) inputValues.getOutputValuesOfLayer();
70
              int nodeIndex = 0;
71
              double[] hiddenLayerOutput = new double[mhidden];
              for (HiddenNode hiddenNode : hiddenNodes) {
                  hiddenNode.calculateNetInput(vectorFromInputLayer, nodeIndex);
                  hiddenLayerOutput[nodeIndex] = hiddenNode.getOutput();
                  nodeIndex++;
              return new HiddenLayerVector(hiddenLayerOutput);
82
```

Implementation: Hidden Node

```
@Override
void calculateNetInput(NeuralVector input, int nodeSubscript) {
    netInput = 0;
    for (int i = 0; i < inputLayerSize; i++) {
        netInput += (input.get(i) * MultiLayerPerceptron.hiddenLayerWeights[nodeSubscript][i]);
    }
}
@Override
public double getOutput() {
    outPutOfCurrentNode = (1 / (1 + Math.exp(-(netInput))));
    return outPutOfCurrentNode;
}</pre>
```

Architecture: Output Node

$$o_{1} = f\left(\sum_{i=1}^{4} h_{i} w_{1i}^{2}\right) = \left(1 + \exp\left(-\sum_{i=1}^{4} h_{i} w_{1i}^{2}\right)\right)^{-1} \quad o_{2} = f\left(\sum_{i=1}^{4} h_{i} w_{2i}^{2}\right) = \left(1 + \exp\left(-\sum_{i=1}^{4} h_{i} w_{2i}^{2}\right)\right)^{-1}$$

$$w_{11}^{2} \quad w_{12}^{2} \quad w_{23}^{2}$$

$$h_{1} \quad h_{2} \quad h_{3} \quad h_{4} \quad h_{1} \quad h_{2} \quad h_{3} \quad h_{4}$$

$$h_{1} \quad h_{2} \quad h_{3} \quad h_{4}$$

Architecture: Output Layer

```
16
     public class OutputLayer extends LearnableLayer {
17
18
          List<OutputNode> outputNodes;
19
          HiddenLayer hiddenLayer;
20
          int mhidden:
          int coutput;
          //double[][] weights;
23
          double learningRate;
24
   25
          public OutputLayer(int outputLength, int hiddenLength, double hiddenLayerLearningRate, HiddenLayer hiddenLayerValue)
26
              mhidden = hiddenLength;
27
              coutput = outputLength;
28
              hiddenLayer = hiddenLayerValue;
29
              learningRate = hiddenLayerLearningRate;
              outputNodes = new Vector<OutputNode>();
```

Architecture: Output Layer

```
34
  public void initilize() {
35
36
37
              for (int j = 0; j < coutput; j++) {
                   for (int i = 0; i < mhidden; i++) {
38
                       Random r = new Random();
39
                       MultiLayerPerceptron.outputLayerWeight[j][i] = ((r.nextDouble() * (-0.1)) + 0.1);
40
41
42
43
44
              for (int i = 0; i < coutput; i++) {
45
                   outputNodes.add(new OutputNode(/*hiddenLayerValue,*/mhidden, coutput, this,0.52));
46
47
48
          @Override
          public NeuralVector getOutputValuesOfLayer() {
              HiddenLaverVector vectorFromHiddenLaver = (HiddenLaverVector) hiddenLaver.getOutputValuesOfLaver();
              int nodeIndex = 0:
70
              double[] finalOutput = new double[coutput];
              for (OutputNode outputNode : outputNodes) {
                  outputNode.calculateNetInput(vectorFromHiddenLayer, nodeIndex);
74
                  finalOutput[nodeIndex] = outputNode.getActivationFunctionOutput();
75
                  nodeIndex++:
76
              return new OutputVector(finalOutput);
79
80
```

Implementation: Output Node

```
@Override
void calculateNetInput(NeuralVector input, int nodeSubscript) {
   netInput = 0;
   for (int i = 0; i < hiddenLayerSize; i++) {
       netInput += (input.get(i) * MultiLayerPerceptron.outputLayerWeight[nodeSubscript][i]);
   }
}</pre>
```

```
public double getActivationFunctionOutput() {
    activationFunctionOutput = (1 / (1 + Math.exp(-(netInput))));
    System.out.println("Finaloutput: " +outputOfCurrentNode+"Bias"+bias );
    return activationFunctionOutput;
}
```

Learning Rule: Back Propagation

• Update weight between output and hidden

$$E = \frac{1}{2} \sum_{k=1}^{c} (t_k - o_k)^2 \quad o_j = \left[1 + \exp(-net_j^o) \right]^{-1} \quad net_j^o = \sum_{k=1}^{m} h_k w_{jk}^2$$

$$\frac{\partial E}{\partial w_{jj}^2} = \frac{\partial E}{\partial o_j} \frac{\partial o_j}{\partial net_j^o} \frac{\partial net_j^o}{\partial w_{jj}^2}$$

$$\frac{\partial o_j}{\partial net_j^o} = \left[\left(1 + \exp(-net_j^o) \right)^{-1} \right]' = o_j (1 - o_j)$$

$$\frac{\partial E}{\partial o_j} = -(t_j - o_j) \quad \frac{\partial net_j^o}{\partial w_{jj}^2} = h_j$$

$$W_{ii}^2 = W_{ii}^2 + \eta (t_i - o_i) o_i (1 - o_i) h_i$$

Implementation: Learning Rule: Back Propagation

Update weight between output and hidden

Learning Rule: Back Propagation

Update weight between hidden and input

$$\begin{split} \frac{\partial E}{\partial w_{ji}^{1}} &= \sum_{k=1}^{c} \frac{\partial E}{\partial o_{k}} \frac{\partial o_{k}}{\partial net_{k}^{o}} \frac{\partial net_{k}^{o}}{\partial h_{j}} \frac{\partial h_{j}}{\partial net_{j}^{h}} \frac{\partial net_{j}^{h}}{\partial w_{ji}^{1}} \\ h_{j} &= \left[1 + \exp\left(-net_{j}^{h}\right)\right]^{-1} \qquad net_{j}^{h} &= \sum_{i=1}^{d} x_{k} w_{ji}^{1} \\ \frac{\partial E}{\partial o_{k}} &= -\left(t_{k} - o_{k}\right) \qquad \frac{\partial o_{k}}{\partial net_{k}^{o}} &= o_{k} \left(1 - o_{k}\right) \\ \sum_{k=1}^{c} \frac{\partial net_{k}^{o}}{\partial h_{j}} &= \sum_{k=1}^{c} w_{kj}^{2} \qquad \frac{\partial h_{j}}{\partial net_{j}^{h}} &= \left(1 - h_{j}\right) h_{j} \qquad \frac{\partial net_{i}^{h}}{\partial w_{ji}^{1}} &= x_{i} \\ w_{ji}^{1} &= w_{ji}^{1} + \eta \sum_{k=1}^{c} \left(t_{k} - o_{k}\right) o_{k} \left(1 - o_{k}\right) w_{kj}^{2} \left(1 - h_{j}\right) h_{j} x_{i} \end{split}$$

Implementation: Learning Rule: Back Propagation

Update weight between hidden and input

```
void learn(double[] expectedOutputValues, OutputVector outputValues, NeuralVector input, int nodeSubscript) {
        getOutput();
        for (int i = 0; i < inputLayerSize; i++) {</pre>
           double multipleOfLearningRate = 0;
           //Why no increment in output index?
            for(int outputIndex = expectedOutputValues.length - outputValues.length();
                    outputIndex < expectedOutputValues.length; outputIndex++) {//How we separate the target velue ?
                int c=outputIndex-inputLayerSize;
                double outputValue = outputValues.get(c);//We don't iterating output?
                double expectedVale = expectedOutputValues[outputIndex];
                //System.out.println("c Index:"+c+"output Index:"+outputIndex
                multipleOfLearningRate += (expectedVale - outputValue) * outputValue * (1 - outputValue) *
MultiLayerPerceptron.outputLayerWeight[c][nodeSubscript] * (1 - outPutOfCurrentNode)*outPutOfCurrentNode * input.get (i);
```

Learning Rule: Back Propagation

Interactive Learning

Output: Optimized Weights

```
Input: Training Examples
                                      E = \sum_{i=1}^{c} (t_i - o_i)^2
Initialize Weights at Random
Iterate T times
  for each training example{
     compute values of hidden nodes
     compute value of output nodes
     compute average error
     update weights between output and hidden
     update weights between hidden and input
```

Implementation : Learning Rule Back Propagation

Interactive Learning

```
public void train(ArrayList<double[]> trainingExamples, int trainingIterations) throws Exception {
    if (trainingExamples.size() < 1) {</pre>
        throw new Exception ("training examples must have some values.");
    if (trainingExamples.get(0).length != numberOfInputNodes + numberOfOutputNodes) {
        throw new Exception ("Length of training Example is not consistant with dimensions of MLP.");
    //why this running for 1 time
    for (int i = 0; i < trainingIterations; i++) {//How many time inner loop will this run?29
        for (int j = 0; j < trainingExamples.size(); j++) {</pre>
            InputVector iv = new InputVector(trainingExamples.get(j), numberOfInputNodes);
            iv.printScreen();
            inputLayer.setInputNodesValues(iv);
            OutputVector ov = (OutputVector) outputLayer.getOutputValuesOfLayer();
            outputLayer.learn(trainingExamples.get(j));
            hiddenLayer.learn(trainingExamples.get(j),ov);
            ov.printScreen();
```

Training Data Set

```
traningExamples.add(new double[]{68, 29, 82, 0, 1, 0});
                                                               traningExamples.add(new double[]{1,0 , 1});
traningExamples.add(new double[]{43, 34, 42, 1, 0, 0});
                                                               traningExamples.add(new double[]{1,1 , 0});
                                                               traningExamples.add(new double[]{0,0 , 0});
traningExamples.add(new double[]{8, 91, 37, 0, 1, 1});
                                                               traningExamples.add(new double[]{0,1 , 1});
traningExamples.add(new double[]{71, 16, 95, 1, 0, 1});
                                                              traningExamples.add(new double[]{1,1 , 0});
traningExamples.add(new double[]{91, 15, 49, 1, 1, 1});
                                                               traningExamples.add(new double[]{1,0 , 1});
traningExamples.add(new double[]{26, 44, 24, 0, 0, 0});
                                                               traningExamples.add(new double[]{1,1 , 0});
traningExamples.add(new double[]{71, 94, 22, 1, 0, 0});
                                                               traningExamples.add(new double[]{0,0 , 0});
traningExamples.add(new double[]{74, 45, 64, 0, 1, 0});
                                                               traningExamples.add(new double[]{1,0 , 1});
traningExamples.add(new double[]{89, 37, 77, 1, 1, 1});
                                                              traningExamples.add(new double[]{0,1 , 1});
traningExamples.add(new double[]{69, 76, 53, 1, 0, 1});
```

```
24
                  traningExamples.add(new double[]{96, 95, -3, 1, 0, 0});
25
                  traningExamples.add(new double[]{102, 102, 3, 1, 0, 0});
                  traningExamples.add(new double[]{101, 100, -4, 1, 0, 0});
26
                  traningExamples.add(new double[]{97, 99, 2, 1, 0, 0});
27
                  traningExamples.add(new double[]{102, 96, -2, 1, 0, 0});
28
                  traningExamples.add(new double[]{3, 97, 105, 0, 1, 0});
29
Q
                  traningExamples.add(new double[] {-5, 99, 97, 0, 1, 0});
31
                  traningExamples.add(new double[]{5, 105, 102, 0, 1, 0});
32
                  traningExamples.add(new double[]{0, 96, 101, 0, 1, 0});
33
                  traningExamples.add(new double[]{5, 101, 103, 0, 1, 0});
                  traningExamples.add(new double[]{0, 103, 98, 0, 1, 0});
34
                  traningExamples.add(new double[] {-1, 99, 95, 0, 1, 0});
35
                  traningExamples.add(new double[] {-4, 98, 96, 0, 1, 0});
```

Output Results:

```
Usages
         Output - MLPClass (run) X
\square
     output: 0.6839953832380323 0.3642024538651048 0.40010949319260186
     input: 3.0 97.0 105.0
     output: 0.7057351234625642 0.33543245687028955 0.3660777840132758
     input: -5.0 99.0 97.0
     output: 0.6581158773973538 0.3866311980137963 0.3370429308216462
%3
     input: 5.0 105.0 102.0
     output: 0.6065452744694959 0.4394678223552267 0.312281905431864
     input: 0.0 96.0 101.0
     output: 0.5537139396911628 0.49094971515415603 0.2910963364126225
     input: 5.0 101.0 103.0
     output: 0.5026116961376481 0.5385786839989182 0.27285714120695836
     input: 0.0 103.0 98.0
     output: 0.4556111860254098 0.580937017863102 0.2570472789667228
     input: -1.0 99.0 95.0
     output: 0.4139827115667947 0.6176641112638019 0.24323998286531912
     input: -4.0 98.0 96.0
     output: 0.3779717638921623 0.6490972937388158 0.23109268716330417
     input: 0.0 101.0 104.0
     output: 0.34717813780057244 0.6758940809817994 0.22032728310736738
     input: 5.0 103.0 104.0
     output: 0.3209310531145426 0.6987737494083545 0.21072913641661511
     input: -5.0 4.0 4.0
     output: 0.38618361104279814 0.6248748264376521 0.3206502693886243
     input: 1.0 4.0 2.0
     output: 0.3656514870912087 0.618115878875692 0.3229143470810782
     input: 0.0 -4.0 2.0
     output: 0.3795826670930059 0.5843807957618913 0.36554329913143646
     input: -5.0 -5.0 1.0
     output: 0.40441740636236184 0.5537517723981625 0.4082931377424167
     input: -5.0 -2.0 1.0
     output: 0.3945788979035574 0.5487902244378303 0.41128832012429584
     input: 1.0 2.0 -1.0
     output: 0.34680598931904877 0.5571782741568988 0.38754313000128393
     BUILD SUCCESSFUL (total time: 0 seconds)
```

Result

• Can be used as supervised network, or for classification.

Questions?

