(1)

why ROUTING PROTOCOLS?

STATIC ROUTING - To, much overhead

- Hust be configured monually
- Menual configuration on all rauters.
- No account for link failure
- Not used for large n/w
- Every n/w sequires new static saute

AUTONONOUS SYSTEM (AS) is an internetwork under the control of single

one routing Protocal Cannot handle the task of updating the sainting lables. For this Internet is duvided ente autonomous systems.

ROUTING PROTOCOLS

INTRA COMAIN

· Routing Inside on AS

Protocals like RIP, EIGRP, OSPF

Interior Gateway Bolocal

THTER DONAIN)

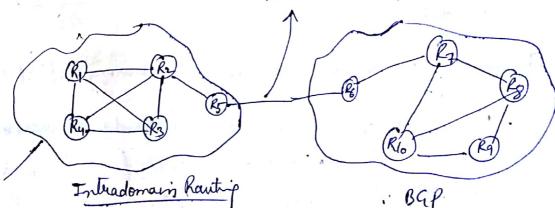
Ranting b/w A.S

· PROTOCOLS BGP (Broder Gateway

Protocal)

Externar Gateway Bolory

Interdomain Rauty



RIP

OSPF

EIGRP

TGRP

INTENDOMAIN ROUTING PROTOCOLS

DISTANCE VECTOR RIP

LINK STATE ROUTING OSPF

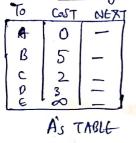
DISTANCE VECTOR ROUTING

- ' In DVR, the least cost soute b/w any two nodes is the soute with minimum distance.
- · Each node maintains a vector (table) of minimum distances to every nocle.

DVR works in 357EPS

1) Intelization - At the beginning, Each mode con know only the distance the its immediate neighbouris.

BELOW Figure shaws the initial table for each node.



COST NEXT

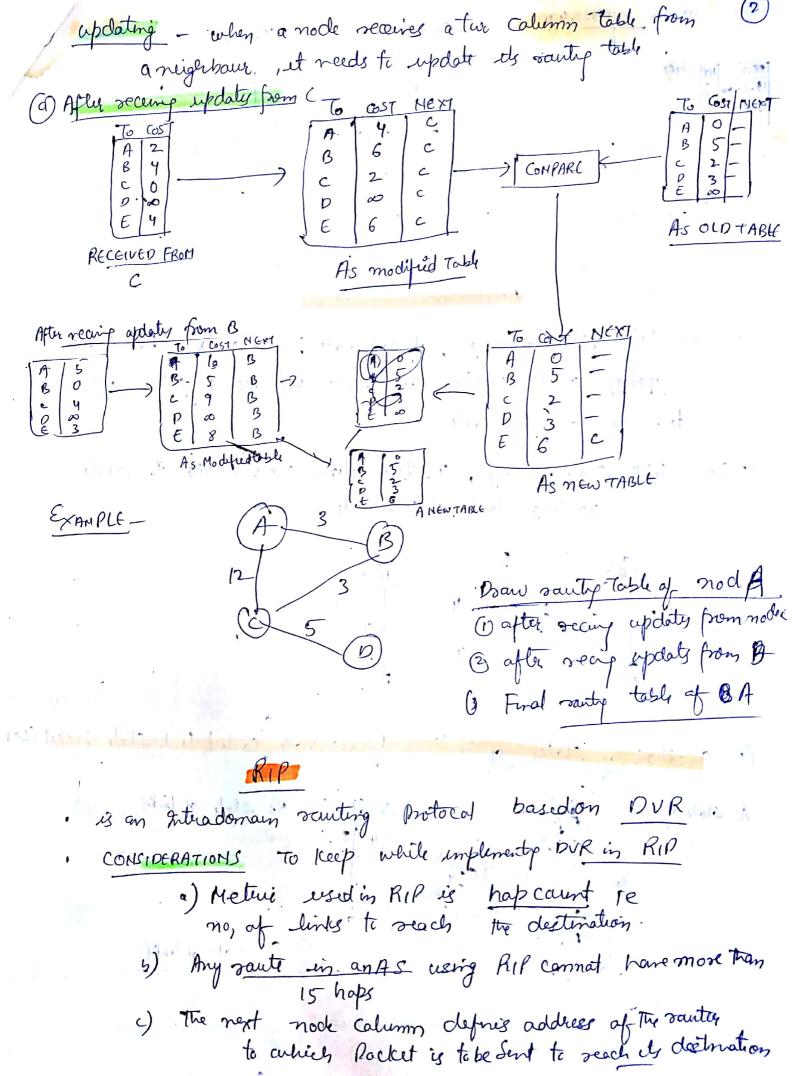
D'S TABLE

3	2	4 3
6.	B 4 0 0	4
Ystory	E 41-	

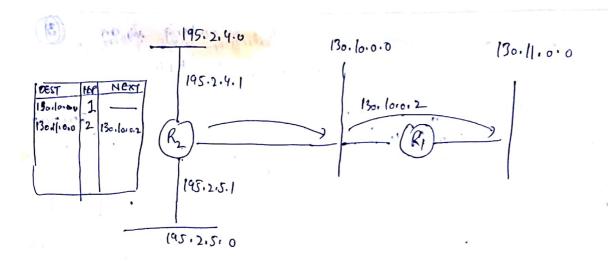
SHARING - whale idea of DVR is sharing of inform b/w neighbours.

· How much of table must be shared with each preybour? · The best salution for each node es

to Sind uts entere table to the neighbour of let the neighbour decide

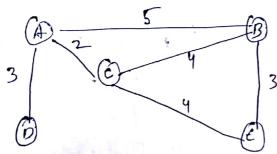


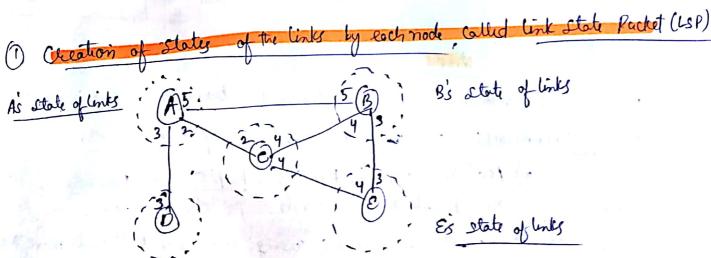
Scanned by CamScanner

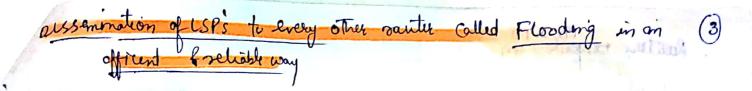


LINK STATE ROUTING

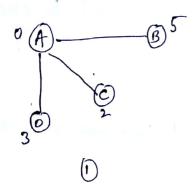
- h Link state raining, if each mode in the domain has Entire topology of the domain, the node can use Dijkstra's algarithm to build a routing table
- · In link state souting, a sets of actions are required to create routing table at each node.

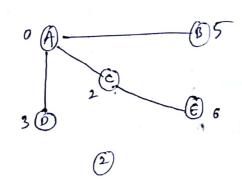






(3) Formation of Shoutest Path tree: Dijkstras olganithm





(i) Calculation of smallest Routing Table Bosed on the shortest Patritee Each mode cases the shortest Patritee Protocol to construct its routing table

Rauting table for node A

None	COST	NEXT ROUTER
A	U	
B	5	
c	2	
0	2	_
ϵ	6	

State souting.

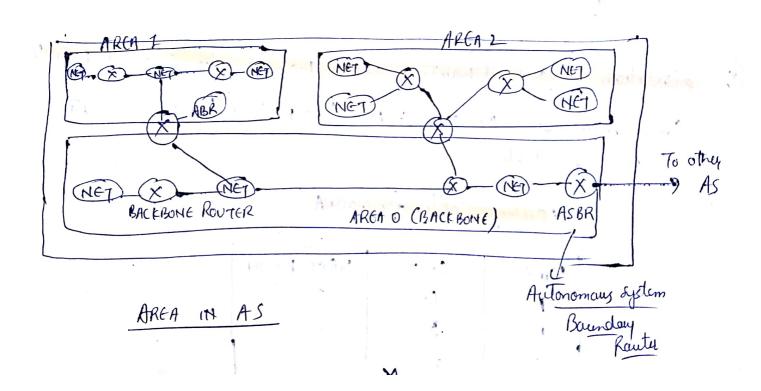
Area - OSPF dunded on autonomous System into areas. An area is a calletton of n/w hasts & rauter's all within an autonomous system.

· An autonomous system can be dunded into differ areas

- . Rauteis inside an area flood area with santing inform
- · At the Booder of an area, special south's called area barder southisting deserminate inform to other areas:
- Among the area's enside As es a special area called backbone.

 Backbone seemes as a frimary, area. I other areas called

 Secondary areas.
- · Ranteis inside the backbone area are called Backbone santeis



Distance vector Routing - designed to run on small n/w (usually beautition (overauter's).

Example RIP & IGRP

higher che & bandwidth utilization

. They also take longer to converge than do link state Protoconts

convergence time is amount of time it takes to hopogode changes in n/w topology

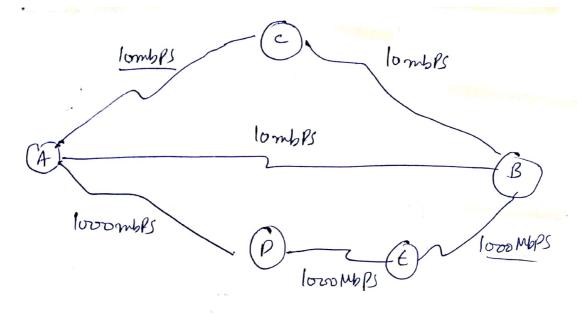
but when it comes to enterprise m/w, you must deplay

lent state lautig - designed to operate in large enterprize arimply - OSPF

- . This algorithm takes into account bandwidth as well as other factoris when calculating the best Path for a Packet to trained anyw.
- Additionally link state convergence occurs faster than distance vector convergence.

In DVR protocal - uses hop count as a meture to select the

In link state Rauty Proteol - reses bandwith as ameteric for develope a calculate materix to south the do santig decisions



In the abase tapalogy, if me follow

a) Distance Vector Rauting olgorithm Then optimal Rath is A lombes, B because
of less hop counts, but if we fullow

because link state routing (OSPF) - The aptimal Paths is

because link state routing cases bandwidth as a

meteur to take routing decisions.