

# Cryptography Reading Group

## Lossy Trapdoor Functions and Their Applications

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## 1 Trapdoor Functions and Lossy Trapdoor functions

Trapdoor functions provide the basis for public key cryptography. Essentially, they are one-way functions that provide a *trapdoor* – an easy way to invert (if you know the trapdoor). In other words, we require for trapdoor functions that:

1. They are easy to compute in one direction
2. They are difficult to compute in the reverse direction without the trapdoor

Multiplication is the most common example of a function we believe to be one-way, in that it is much easier to multiply than it is to factor (or at least, so we believe). This gives rise to several common problems used in cryptography.

**Example:** The Discrete Log Problem

Given:  $g$  a generator for some cyclic group  $G$  and  $g^x$ , for some  $x \in G$

Find:  $x$

**Example:** Computational Diffie-Hellman Problem

Given:  $g$  a generator for some cyclic group  $G$ ,  $g^x$ , and  $g^y$ , for  $x, y \in G$

Find:  $g^{xy}$

**Example:** Decisional Diffie-Hellman

Given:  $g$  a generator for some cyclic group  $G$ ,  $g^x$ ,  $g^y$ ,  $g^z$  for  $x, y, z \in G$

Find: Is  $z \equiv xy \pmod{|G|}$

**Example:** Factor Problem

Given:  $pq$ , for primes  $p, q$

Find: Find  $p$  and  $q$

### 1.1 Trapdoor Functions

Formally, we talk about collections of trapdoor functions. A collection of *trapdoor functions* is given by the triple of algorithms running in probabilistic-polynomial-time (PPT):  $(S, F, F^{-1})$ .

- $S \rightarrow (s, t)$ . Algorithm  $S$  produces a function index  $s$  and the trapdoor  $t$
- $F(s, \cdot) \rightarrow f_s(\cdot)$ . Algorithm  $F$  takes  $s$  and a message input  $(\cdot)$  and computes  $f_s(\cdot)$ , where  $f_s : \{0, 1\}^n \rightarrow \{0, 1\}^n$ . We require that for a given  $s$ , that  $F$  be injective.

- $F^{-1}(t, \cdot) \rightarrow f_s^{-1}(\cdot)$ . Computes the inverse of  $F$  as you would expect. Were  $f_s(\cdot)$  not injective,  $F^{-1}(t, \cdot)$  would be impossible.

Note that for any PPT inverter  $\mathcal{I}$ , we require  $\Pr(\mathcal{I}(s, f_s(x)) \rightarrow x)$  is negligible for a collection of functions to be trapdoor functions.

## 1.2 Lossy-Trapdoor Functions

Informally, we think of lossy-trapdoor functions as non-injective trapdoor functions (remember that we are thinking about collections of functions).

We specify a collection of Lossy-Trapdoor Functions by the 4-tuple:

$$(S_{\text{inj}}, S_{\text{loss}}, F_{\text{tdf}}, F_{\text{tdf}}^{-1})$$

We define:

$$\begin{aligned} \lambda &: \text{The security parameter} \\ n(\lambda) = \text{poly}(\lambda) &: \text{the input length of the function} \\ k(\lambda) \leq n(\lambda) &: \text{the lossiness} \\ r(\lambda) = n(\lambda) - k(\lambda) &: \text{the leakage} \end{aligned}$$

For a collection of functions to be deemed a collection of *Lossy-Trapdoor Functions*, three properties must hold:

1. Easy to sample injective functions with trapdoor:  $S_{\text{inj}} \rightarrow (s, t)$  where  $s$  is a function index and  $t$  is its trapdoor. When  $S_{\text{inj}}$  outputs such a pair,  $F_{\text{tdf}}$  and  $F_{\text{tdf}}^{-1}$  work as in standard trapdoor examples.
2. Easy to sample a lossy function:  $S_{\text{loss}} \rightarrow (s, \perp)$ , where  $s$  is a function index, and  $F_{\text{tdf}}$  computes  $f_s(\cdot)$ , where  $f_s : \{0, 1\}^n \rightarrow \{0, 1\}^r$  recalling that  $r = n - k$ .
3. Hard to distinguish injective from lossy: we require that  $S_{\text{inj}}$  and  $S_{\text{loss}}$  be computationally indistinguishable. Formally, if  $X_\lambda$  denotes the distribution of  $s$  from  $S_{\text{inj}}$  and if  $Y_\lambda$  denotes the distribution of  $s$  from  $S_{\text{loss}}$ , then  $\{X_\lambda\} \stackrel{c}{\approx} \{Y_\lambda\}$ .

Important note! We do explicitly require that an injective function be hard to invert.

## 1.3 Computational Indistinguishability

In the definition for lossy-TDFs, computational indistinguishability (CI) plays a key role – (represented by  $\{X_\lambda\} \stackrel{c}{\approx} \{Y_\lambda\}$ ). Here, as an aside, I present formally the requirements for CI.

**Definition 1 (Statistical distance).** *Let  $X$  and  $Y$  be random variables over a countable set  $S$ . Then, we define statistical distance (notated  $\Delta(X, Y)$ ) as:*

$$\Delta(X, Y) := \frac{1}{2} \sum_{s \in S} |\Pr[X = s] - \Pr[Y = s]|$$

**Definition 2 (Statistical Indistinguishability).** Let  $\mathcal{X} = \{X_\lambda\}_{\lambda \in \mathbb{N}}, \mathcal{Y} = \{Y_\lambda\}_{\lambda \in \mathbb{N}}$  be two ensembles of random variables indexed by  $\lambda$ . Then  $\mathcal{X}$  and  $\mathcal{Y}$  are statistical indistinguishability (notated  $\{X_\lambda\} \stackrel{s}{\approx} \{Y_\lambda\}$ ) when the statistical distance is negligible. In symbols:

$$\{X_\lambda\} \stackrel{s}{\approx} \{Y_\lambda\} \quad \text{if} \quad \Delta(X, Y) = \text{negl}(\lambda)$$

For the following, I assume familiarity with the *advantage* for an algorithm (adversary)  $\mathcal{A}$ .

**Definition 3 (Computational Indistinguishability).** Let  $\mathcal{X}, \mathcal{Y}$  be defined as above and also let there be some probabilistic polynomial time algorithm  $\mathcal{A}$ . Then, we say that  $\mathcal{X}, \mathcal{Y}$  are computationally indistinguishable (notated  $\{X_\lambda\} \stackrel{c}{\approx} \{Y_\lambda\}$ ) if the advantage of any PPT algorithm  $\mathcal{A}$  is  $\text{negl}(\lambda)$ .

## 2 Lossy Trapdoor Functions are Trapdoor Functions

**Lemma 1.** Let  $(S_{\text{ltdf}}, F_{\text{ltdf}}, F_{\text{ltdf}}^{-1})$  give a collection of  $(n, k)$ -lossy trapdoor functions. Let  $k \geq \omega(\log \lambda)$ . Then,  $(S_{\text{inj}}, F_{\text{ltdf}}, F_{\text{ltdf}}^{-1})$  give a collection of injective-trapdoor functions (in the conventional sense).

**Proof:** By hypothesis,  $f_s(\cdot) = F_{\text{ltdf}}(s, \cdot)$  is injective for any  $s$  generated by  $S_{\text{inj}}$ , and  $F^{-1}$  inverts  $f_s(\cdot)$  for a given trapdoor  $t$ .

The rest of the proof proceeds by way of contradiction. Suppose that  $\mathcal{I}$  is PPT inverter for the collection of functions described above. Then, we can use  $\mathcal{I}$  to build a distinguisher  $\mathcal{D}$  that distinguishes injective functions and lossy ones. This is a contradiction, since we require that the lossy-functions and injective-functions be indistinguishable.

More formally: If  $\mathcal{I}$  is an inverter, then  $\mathcal{I}(s, f_s(x))$  outputs  $x$  with a non-negligible probability. From inverter  $\mathcal{I}$  we construct  $\mathcal{D}$  as follows:

**Algorithm  $\mathcal{D}$  :**

On input (i.e. a function index  $s$ ), choose  $x \rightarrow \{0, 1\}^n$ .

Compute  $y = F_{\text{ltdf}}(s, x)$

Let  $x' \leftarrow \mathcal{I}(s, y)$

If  $x' = x$ , output 1 (injective); otherwise, output 0 (lossy).

Now, we need to analyze  $\mathcal{D}$ .

(1) If  $s$  is generated by  $S_{\text{inj}}$ ,  $\mathcal{D}$  outputs 'injective' since, by assumption,  $\mathcal{I}$  outputs  $x$  with non-negligible probability

(2) The slipperiness comes in the case in which we let  $s$  be any fixed function index generated by  $S_{\text{loss}}$ . The probability that even an unbounded  $\mathcal{I}$  predicts  $x$  is given by the average *min-entropy* of  $x$  conditioned on  $f_s(x)$ . In other words, the predictability is given by at most  $2^{-\tilde{H}_\infty(x|f_s(x))}$ . Since  $f_s(\cdot)$  takes at most  $2^{n-k}$  values. The Entropy Approx. Lemma gives us:

$$\tilde{H}_\infty(x|f_s(x)) \geq H_\infty(x) - (n - k) = n - (n - k) = k$$

Since  $k = \omega(\log \lambda)$ , the probability that  $\mathcal{I}(s, y)$  outputs  $x$ , and  $\mathcal{D}$  outputs "injective" is  $\text{negl}(\lambda)$ ; By averaging, the same is true for  $s$  chosen at random by  $S_{\text{loss}}$ . ♦

## 2.1 Reference

**Definition 4 (Min-entropy).** *Let  $X$  be random variable over a domain  $S$ . We define the min-entropy as:*

$$H_{\infty}(X) = -\log(\max_{s \in S} \Pr[X = s]).$$

**Lemma 2 (Entropy Approximation Lemma).** *If  $Y$  takes at most  $2^r$  possible values and  $Z$  is any random variable, then*

$$\tilde{H}_{\infty}(X|Y) \geq H_{\infty}(X) - r.$$