

Lorentz Transformation

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- ✓ # Lorentz transformation derivation.
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 - # Idea behind a "Hyperbolic Geometry".
and "Flat Space-time"
-

Task: To find an acceptable solution to the problem of
"Relative Motion at higher velocities" based on
improving the Galilean Transformation Laws.

Generalizing the Problem to a Scenario

↳ There is an event of a "Light Pulse" flashed at
an instant in space and time.

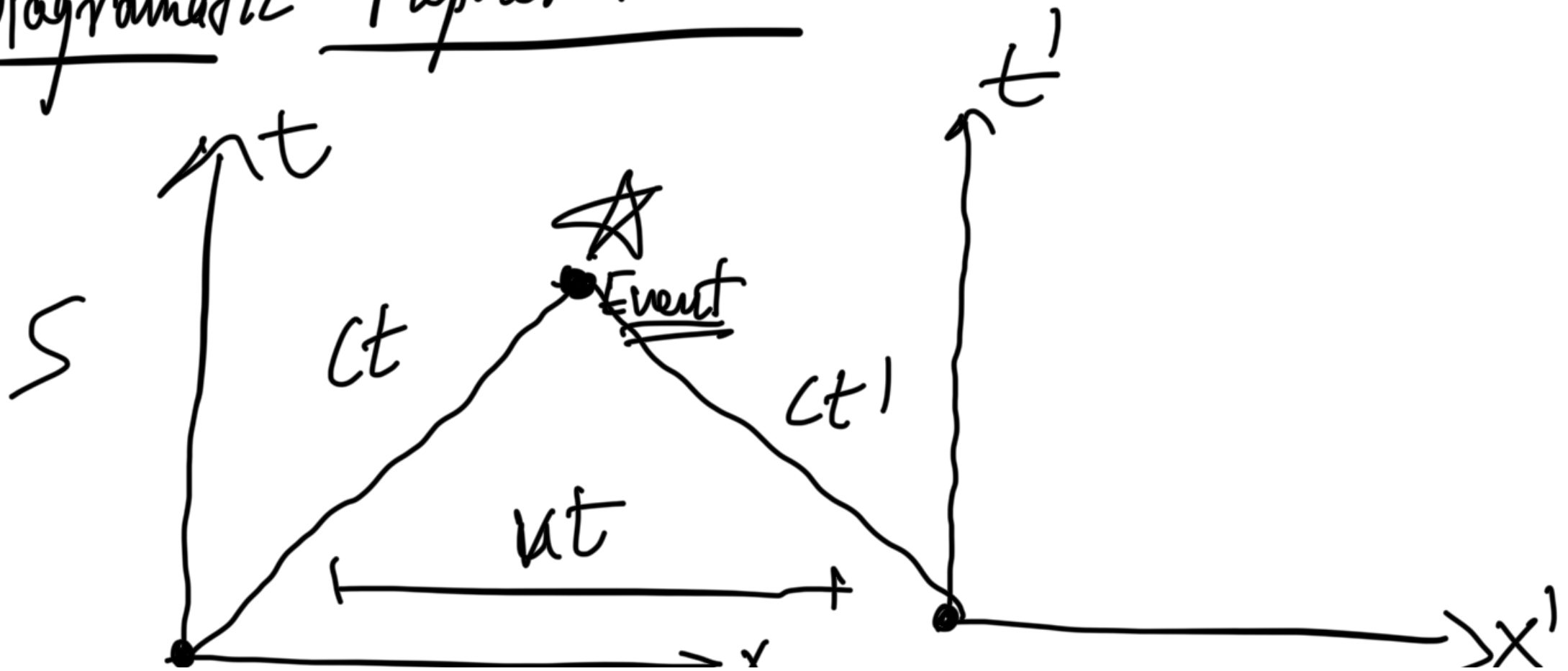
↳ This Event is measured by two different observers
traveling relative to each other at a constant

relative velocity (v).

↳ Let the two frames of reference be S and S' .

↳ Let their relative motion be only restricted to x -axis's direction. or y -axis's direction.

Diagrammatic Representations..



↳ We need to find the measuring coordinates of the event in one frame by using other frame as a reference.

$$\text{So, } x' = f(x, t)$$

$$t' = f(x, t)$$

But this cannot be equal to a general Galilean transformation.

So, let's write it as a linear transformation.

$$\text{So } \begin{bmatrix} x' \\ t' \end{bmatrix} = \begin{bmatrix} a & b \\ d & f \end{bmatrix} \begin{bmatrix} x \\ t \end{bmatrix} ; \text{ we need to solve for the coefficients } a, b, d, f.$$

$$\text{So, } x' = ax + bt$$

$$t' = dx + ft$$

Initial condition

Event $(x, y, z), t$

$$S: x = vt, y = 0, z = 0, t$$

$$S': x' = 0, y = 0, z = 0, t'$$

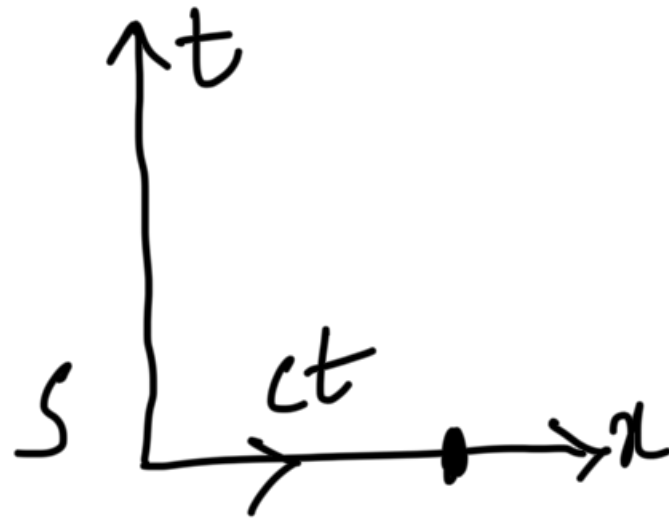
$$x' = ax + bt$$

$$\Rightarrow 0 = avt + bt \Rightarrow (av + b)t = 0$$

$$av + b = 0 \Rightarrow \boxed{b = -av}$$

Situation - 1

↳ From origin, a light ray has travelled for time t in $\underline{\underline{S}}$ frame.



$$\text{So, } x = ct; y = 0, z = 0; t$$

↳ The same situation is observed from $\underline{\underline{S'}}$ reference and the equations are as follows:

$$x' = a(x - vt) \Rightarrow x' = a(ct - vt) = at(c - v).$$

↳ But from " S' " frame of reference, ($x' = ct'$) because light travels the same distance ct' in t' .

so, $ct' = at(c-v)$

also, $t' = dx + ft$

$= dxt + ft \Rightarrow (dct + f)t = t'$

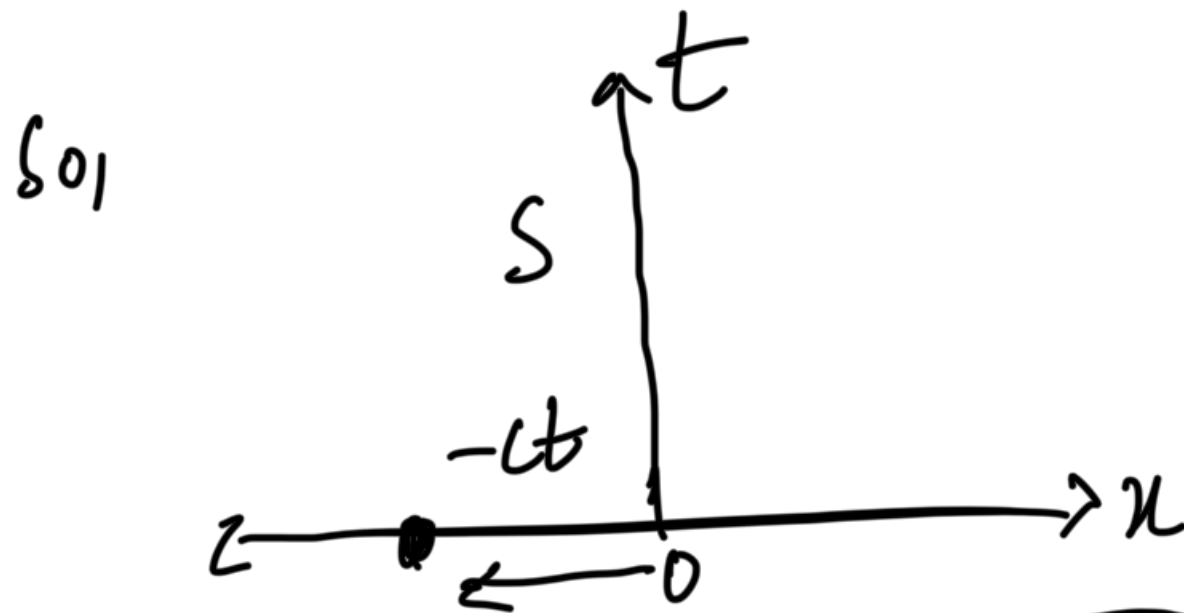
$\Rightarrow (dct + f)t = at(c-v) \Rightarrow$

$\Rightarrow \boxed{dc^2 + fc = a(c-v)} \quad (1)$

Situation - 2

$S: x = -ct, y = 0, z = 0, t$
 $S': x' = -ct', y' = 0, z' = 0, t'$

↳ Now, the light beam is travelling from the Origin of the 'S' frame to its left (i.e. -ve x-axis) direction.



So the equations will be

$$x' = a(x - vt)$$

$$x' = -(c + v)at$$

Also $x' = -ct' \Rightarrow ct' = (c + v)at$

Also $ct' = dx + ft$ $ct' = (c + v)at$

$$= -dct + ft$$

$$= t(f - dc)$$

$$c \cancel{f}(f - dc) = a \cancel{f}(c + v)$$

$$\boxed{-dc^2 + fc = a(c + v)} \longrightarrow (2)$$

Situation-3

The light ray now is passed from the origin of the frame "S" for time "t" in Y axis direction.

$\uparrow ct = y.$
 $S: x=0, y=ct, z=0, t$



$$S': x'=0, y'=y, z'=0, t'$$

$$\text{So } x' = a(x - vt)$$

$$x' = a(0 - vt)$$

$$\underline{x' = -avt}$$

$$t' = dx + ft$$

$$t' = 0 + ft \Rightarrow \underline{t' = ft}$$

calculating the distance of the event from S' frame

$$S^2 = x'^2 + y'^2 + z'^2 = a^2 v^2 t^2 + c^2 t^2$$

Also $S = \text{distance of the light pulse} = ct'$

$$c^2 t'^2 = a^2 v^2 t^2 + c^2 t^2$$

$$\text{Also, } t' = \gamma t$$

$$\text{So, } c^2 \gamma^2 t^2 = a^2 v^2 t^2 + c^2 t^2$$

$$\boxed{c^2 \gamma^2 = a v^2 + c^2} \quad (3)$$

Summarizing Our Equations:

$$\cancel{d}^2 + \gamma L = a(L - v) \quad (1)$$

$$-a \cancel{L}^2 + \gamma L = a(L + v) \quad (2)$$

①+②

$$0 + 2\gamma L = 2aL \Rightarrow \boxed{a = \gamma}$$

$$\textcircled{4} \leftarrow \boxed{\therefore a=f} \Rightarrow d c^2 + f c = a c - a v$$

$$d c^2 + a f = a c - a v$$

$$\boxed{c^2 f^2 = a^2 v^2 + c^2} \quad (3)$$

$$\boxed{d = -\frac{a v}{c^2}} \quad (5)$$

$$c^2 a^2 = a^2 v^2 + c^2$$

$$\Rightarrow a^2 (c^2 - v^2) = c^2$$

$$\Rightarrow a^2 = \frac{c^2}{c^2 - v^2} \Rightarrow \text{dividing and multiplying by } c^2 \text{ on RHS.}$$

$$\Rightarrow a^2 = \frac{1}{1 - \frac{v^2}{c^2}} \Rightarrow a = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\therefore a = f = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\text{and } d = \frac{-av}{c^2}$$

$$\Rightarrow d = -\frac{v}{c^2} \times \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\Rightarrow d = \frac{-v}{\sqrt{c^2 - v^2}}$$

$$\therefore x' = \frac{x - vt}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$t' = \left(t - \frac{vx}{c^2}\right) \left(1 - \frac{v^2}{c^2}\right)^{-\frac{1}{2}}$$

$$\text{Let } \gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\text{So, } x' = \gamma(x - vt)$$

$$\therefore t' = \gamma\left(t - \frac{vx}{c^2}\right)$$

$$t' = \gamma \left(t - \frac{v}{c^2} x \right)$$

Since Lorentz Transformation is a linear transformation we can write it as follows.

$$\begin{bmatrix} x' \\ t' \end{bmatrix} = \begin{bmatrix} \gamma & -\gamma v \\ -\frac{\gamma v}{c^2} & \gamma \end{bmatrix} \begin{bmatrix} x \\ t \end{bmatrix}$$

Concepts of Invariants in Special Relativity.

↳ In special relativity, we use Lorentz transformations to find out the position and time between

reference frames.

↳ The spatial and temporal coordinates change with respect to relative velocity.

But there will be some geometric objects and measurements that remain constant even after applying a Lorentz transform.

These are called Invariants. Examples of invariants would be:

↳ Angles b/w two vectors.

↳ Their Dot products.

↳ The locus of equidistant points (across at $x \leq t$).
