Generic and Indexed Programming



Jeremy Gibbons
University of Oxford
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1. Background

- generic programming: *parametrization*
- datatype-generic programming: parametrization *by datatype*
- special-purpose languages and constructs: *GH*, *SyB*...
- *lightweight embeddings* in general-purpose languages

1.1. Capturing properties

Linguistic approaches to modelling: find new ways to express properties within programs.

Narrowing the *semantic gap* between the programmer's head and the program.

- type systems
- assertions and testing frameworks

(There are extra-linguistic modelling approaches too, but we won't discuss them here.)

1.2. Dependently-typed programming

- types classify values
- dependent types classify values more precisely: in particular, the way in which values depend on other values
- eg $Vector_n \mathbb{Z}$, the type of n-vectors of integers
- more generally, *dependent product* type $\Sigma n :: \mathbb{N}$. f(n) of pairs (n, x) with $n :: \mathbb{N}$ and x :: f(n)
- play a central role in constructive logics
 ('propositions as types', 'Curry-Howard isomorphism')

1.3. Generalized algebraic datatypes

Slight generalization of algebraic datatypes, allowing result type of constructor to be *strictly more specific* than declared datatype.

Allows use of types as indices, capturing program properties. A kind of lightweight dependently-typed programming, by lifting some index values to the type level.

Also known as *first-class phantom types*, *guarded recursive datatypes*, *indexed types*, *equality-constrained types*...apparently a good idea!

2. Generalizing algebraic datatypes

Standard algebraic datatypes, as in Haskell:

They can be polymorphic too, with type parameters:

```
data List \ a = Nil
| Cons \ a \ (List \ a)
```

2.1. Definitions by pattern-matching

```
data Result = NR Int \mid BR Bool

eval :: Expr \rightarrow Result

eval (N n) = NR n

eval (Add x y) = \mathbf{case} (eval x, eval y) \mathbf{of}

(NR m, NR n) \rightarrow NR (m + n)

eval (B b) = BR b

eval (IsZ x) = \mathbf{case} (eval x) \mathbf{of}

NR n \rightarrow NB (0 \equiv n)

eval (If x y z) = \mathbf{case} (eval x) \mathbf{of}

NB b \rightarrow \mathbf{if} b \mathbf{then} eval y \mathbf{else} eval z
```

Note the explicit tagging and untagging (and the lack of error-checking for ill-formed expressions!).

2.2. Extended syntax

New syntax, explicitly stating constructor types (and datatype kind):

```
data Expr :: * where

N :: Int \rightarrow Expr

Add :: Expr \rightarrow Expr \rightarrow Expr

B :: Bool \rightarrow Expr

IsZ :: Expr \rightarrow Expr \rightarrow Expr

If :: Expr \rightarrow Expr \rightarrow Expr \rightarrow Expr

data List :: * \rightarrow * where

Nil :: List a

Cons :: a \rightarrow List a \rightarrow List a
```

Note that for ordinary polymorphic algebraic datatypes, all constructors have the same (most general) result type.

2.3. GADT declaration

Make the datatype polymorphic, with a type parameter (in this case, expressing the represented type).

```
data Expr :: * \rightarrow * where

N :: Int \rightarrow Expr Int

Add :: Expr Int \rightarrow Expr Int \rightarrow Expr Int

B :: Bool \rightarrow Expr Bool

IsZ :: Expr Int \rightarrow Expr Int \rightarrow Expr Bool

If :: Expr Bool \rightarrow Expr Int \rightarrow Expr Int
```

Now constructors may have more specialized return types.

Note that the type parameter is a *phantom type*: a value of type *Expr a* need not contain elements of type *a*.

2.4. GADT use

Specialized return types of constructors induce type constraints, which are exploited in type-checking definitions.

```
eval :: Expr a \rightarrow a

eval (N \ n) = n

eval (Add \ x \ y) = eval \ x + eval \ y

eval (B \ b) = b

eval (IsZ \ x) = 0 \equiv eval \ x

eval (If \ x \ y \ z) = if \ eval \ x \ then \ eval \ y \ else \ eval \ z
```

Note that all the tagging and untagging has gone, and with it the possibility of run-time errors.

By explicitly stating a property formerly implicit in the code, we have gained both in safety and in efficiency.

3. Application: indexing by size

Empty datatypes as indices (so S(SZ)) is a type).

data Z data S n

Size-indexed type of vectors:

```
data Vector :: * \rightarrow * \rightarrow * \mathbf{where}
VNil :: Vector a Z
VCons :: a \rightarrow Vector a n \rightarrow Vector a (S n)
```

Size constraint on *vzip* is captured in the type:

```
vzip:: Vector\ a\ n \rightarrow Vector\ b\ n \rightarrow Vector\ (a,b)\ n
vzip\ VNil\ VNil = VNil
vzip\ (VCons\ a\ x)\ (VCons\ b\ y) = VCons\ (a,b)\ (vzip\ x\ y)
```

4. Application: indexing by shape

Red-black trees are binary search trees in which:

- every node is coloured either red or black
- every red node has only black children
- every path from the root to a leaf contains the same number of black nodes (enforcing approximate balance)

In *RBTree a c n*, type *a* is the element type, *c* the root colour, and *n* the black height.

```
data R
data B

data RBTree :: * \rightarrow * \rightarrow * \rightarrow * \text{ where}

Empty :: RBTree \ a \ B \ n \rightarrow a \rightarrow RBTree \ a \ B \ n \rightarrow RBTree \ a \ R \ n

Black :: RBTree \ a \ c \ n \rightarrow a \rightarrow RBTree \ a \ c' \ n \rightarrow RBTree \ a \ B \ (S \ n)
```

5. Application: indexing by unit

Suppose dimensions of non-negative powers of metres and seconds:

```
data Dim :: * \rightarrow * \rightarrow * where D :: Float \rightarrow Dim \ m \ s distance :: Dim \ (S \ Z) \ Z distance = D \ 3.0 time :: Dim \ Z \ (S \ Z) time = D \ 2.0
```

A dimensioned value is a *Float* with two type-level tags.

```
dadd :: Dim \ m \ s \rightarrow Dim \ m \ s \rightarrow Dim \ m \ s
dadd \ (D \ x) \ (D \ y) = D \ (x + y)
```

Now *dadd time time* is well-typed, but *dadd distance time* is ill-typed. (More interesting to allow negative powers too, but for brevity...)

5.1. Type-level functions

Proofs of properties about indices:

```
data Add :: * \rightarrow * \rightarrow * \text{ where}
AddZ :: Add \ Z \ n \ n
AddS :: Add \ m \ n \ p \rightarrow Add \ (S \ m) \ n \ (S \ p)
```

Used to constrain the type of dimensioned multiplication:

```
dmult :: (Add m_1 m_2 m, Add s_1 s_2 s) \rightarrow
Dim m_1 s_1 \rightarrow Dim m_2 s_2 \rightarrow Dim m s
dmult (\_, \_) (D x) (D y) = D (x \times y)
```

Thus, type-index of product is computed from indices of arguments.

5.2. Inferring proofs of properties

Capture the proof as a type class (multi-parameter, with functional dependency; essentially a function on types).

```
class Add \ m \ n \ p \mid m \ n \rightarrow p

instance Add \ Z \ n \ n

instance Add \ m \ n \ p \Rightarrow Add \ (S \ m) \ n \ (S \ p)
```

Now the proof can be (type-)inferred rather than passed explicitly.

```
dmult :: (Add \ m_1 \ m_2 \ m, Add \ s_1 \ s_2 \ s) \Rightarrow
Dim \ m_1 \ s_1 \rightarrow Dim \ m_2 \ s_2 \rightarrow Dim \ m \ s
dmult \ (D \ x) \ (D \ y) = D \ (x \times y)
```

Note that the type class has no methods, so corresponds to an empty dictionary; it can be optimized away.

closed

shake

6. Application: indexing by state

The 'ketchup problem':

```
close
data O
                                            opened
data C
data Edge :: * \rightarrow * \rightarrow * where
                                                           open
  Open :: Edge O C
  Close :: Edge C O
  Shake :: Edge C C
data Path :: * \rightarrow * \rightarrow * where
  Empty :: Path s s
  PCons :: Edge x y \rightarrow Path y z \rightarrow Path x z
scenario:: Path O O
scenario = PCons Open (PCons Shake (PCons Close Empty))
```

7. Application: indexing by type

Generic programming is about writing programs parametrized by datatypes; for example, a generic data marshaller.

One implementation of generic programming manifests the parameters as some family of *type representations*.

For example, C's *sprintf* is generic over a family of *format specifiers*.

```
data Format :: * \rightarrow * where

I :: Format \ a \rightarrow Format \ (Int \rightarrow a)
B :: Format \ a \rightarrow Format \ (Bool \rightarrow a)
S :: String \rightarrow Format \ a \rightarrow Format \ a
F :: Format \ String
```

A term of type *Format a* is a representation of the type *a*, for various types *a* appropriate for *sprintf*, such as $Int \rightarrow Bool \rightarrow String$.

7.1. Type-indexed dispatching

The function *sprintf interprets* that representation.

```
sprintf:: Format a \rightarrow a

sprintf fmt = aux id fmt where

aux:: (String \rightarrow String) \rightarrow Format \ a \rightarrow a

aux \ f \ (I \ fmt) = \lambda n \rightarrow aux \ (f \circ (show \ n++)) \ fmt

aux \ f \ (B \ fmt) = \lambda b \rightarrow aux \ (f \circ (show \ b++)) \ fmt

aux \ f \ (S \ s \ fmt) = aux \ (f \circ (s++)) \ fmt

aux \ f \ (F) = f""
```

For example, $sprintf\ f\ 13\ True =$ "Int is 13, bool is True.", where

```
f :: Format (Int \rightarrow Bool \rightarrow String)

f = S "Int is " (I(S", bool is "(B(S"."F))))
```

8. Application: indexing by proof

The game of *Mini-Nim*:

- a pile of matchsticks
- players take turns to remove one match or two
- player who removes the last match wins

Annotate positions with their size and destiny.

data Win data Lose

data Position n r where

Empty :: *Position Z Lose*

 $Take1 :: Position \ n \ Lose \rightarrow Position \ (S \ n) \ Win$

 $Take2 :: Position \ n \ Lose \rightarrow Position \ (S \ (S \ n)) \ Win$

Fail :: Position $n \ Win \rightarrow Position \ (S \ n) \ Win \rightarrow Position \ (S \ (S \ n)) \ Lose$

9. Adding weight

We have shown some examples in Haskell with small extensions.

This is a very lightweight approach to dependently-typed programming.

Lightweight approaches have low entry cost, but relatively high continued cost: encoding via type classes etc is a bit painful.

Tim Sheard's Ω *mega* is a cut-down version of Haskell with explicit support for GADTs:

- kind declarations
- type-level functions
- statically-generated witnesses

Xi and Pfenning's *Dependent ML* provides natural-number indices, and incorporates decision procedures for discharging proof obligations.

There are more heavyweight approaches still, such as McBride and McKinna's *Epigram*.

9.1. Transfer to the mainstream

Kennedy and Russo (OOPSLA 2005) showed that Java and C#

'can express GADT definitions, and a large class of GADT-manipulating programs, through the use of generics, subclassing and virtual dispatch'

(with a few casts, that they propose ways around).

10. The GIP project at Oxford

- EPSRC-funded, about £500k
- three and a half years, from November 2006
- Jeremy Gibbons, principal investigator
- Bruno Oliveira, postdoctoral researcher
- Meng Wang, doctoral student

10.1. Workpackages

- capturing properties
 case studies as benchmarks
- *generics for GADTs*GADTs no longer sums of products: spine views, idioms
- extensible generic functions expression problem, combining structural and nominal views
- design patterns as a library
 GADTs in Scala, Java and C#
- type classes and GADTs
 inferring proof objects
- *impedence transformers* statically-checked metaprogramming; multi-tier