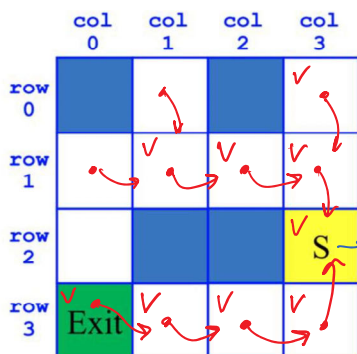


PA2 due tomorrow

2D Search

Breadth-First Search (BFS)

Guaranteed shortest path



SearchForTheExit

```

Initialize a Queue to hold Squares as we search
Mark starting square as visited
Enqueue starting square on Queue
While Queue is not empty
  Dequeue square sq from Queue
  Mark sq as visited
  If sq is the Exit, we're done!
  For each of square's unvisited neighbors (S, W, N, E):
    Set neighbor's previous to sq
    Enqueue neighbor to Queue
  
```

```

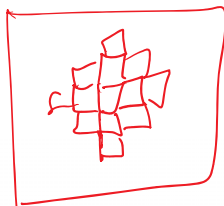
class Square {
  boolean visited;
  Square previous;
}

class Node {
  boolean visited;
  Node next;
}
  
```

Run through the SearchForTheExit algorithm. Draw the queue.

Front → ~~(2,0)~~ ~~(3,3)~~ ~~(1,3)~~ ~~(3,2)~~ ~~(1,2)~~ ~~(0,3)~~ ~~(3,1)~~
~~(1,1)~~ (3,0) ~~(1,0)~~ ~~(0,1)~~

$(3,0) \rightarrow (3,1) \rightarrow (3,2) \rightarrow (3,3) \rightarrow (2,3) \rightarrow \text{Null}$
 5 4 3 2 1
 Exit start } use stack to reverse



How many nodes were visited?

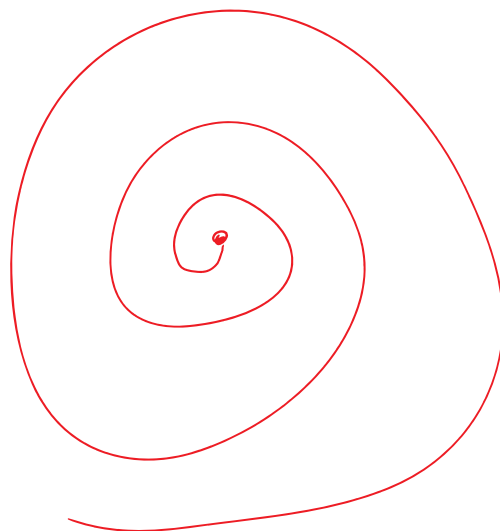
9

How many total squares were added to the queue?

11

Was this the shortest path?

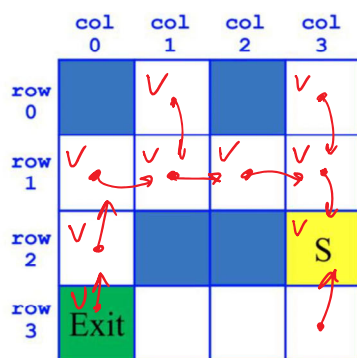
true



Depth-First Search (DFS)

Will always find a path. Possibly faster.

```
class Square {
    boolean visited;
    Square previous;
}
```



SearchForTheExit

Initialize a **Stack** to hold Squares as we search

Mark starting square as visited

Push starting square on **Stack**

While **Stack** is not empty

Pop square sq from **Stack**

 Mark sq as visited

 If sq is the Exit, we're done!

 For each of square's unvisited neighbors (S, W, N, E):

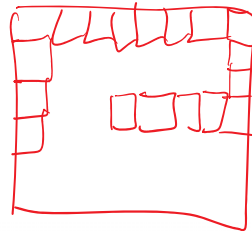
 Set neighbor's previous to sq

Push neighbor to **Stack**

S W N E
4 3 2 1

Run through the SearchForTheExit algorithm. Draw the stack.

bottom → ~~(2,3)~~ ~~(3,3)~~ ~~(1,3)~~ ~~(1,2)~~ ~~(0,3)~~ ~~(1,1)~~ ~~(1,0)~~ ~~(2,0)~~ ~~(3,0)~~ ← top



How many nodes were visited?

9

How many total squares were added to the stack?

10

Was this the shortest path?

No