

$$\begin{array}{cccccccccccccccc}
\mathbf{P} & \mathbf{X}_1(u_1, v_1) & u_1 & v_1 & \mathbf{K}_1(v_1) & \frac{\partial}{\partial u_1} \mathbf{X}_1(0, v_1) & \frac{\partial}{\partial v_1} \mathbf{X}_1(0, v_1) & = & \frac{\partial}{\partial u_2} \mathbf{X}_2(u_2, 0) & \frac{\partial}{\partial v_2} \mathbf{X}_2(u_2, 0) \\
\mathbf{X}_2(u_2, v_2) & u_2 & v_2 & \mathbf{K}_2(v_2) & \mathbf{X}_3(u_3, v_3) & u_3 & v_3 & u_4 & v_{N-1} & u_N & v_N & \mathbf{K}_3(v_3) & \mathbf{K}_4(v_4) \\
\mathbf{K}_N(v_N) & \mathbf{K}_{N-1}(v_{N-1}) & & & & & & & & & & & \\
T_1 & T_2 & & & & & & & & & & &
\end{array}$$