

Documentation for module `stacker`

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1 Introduction

This document describes version 1.0 of the module `stacker`. The module is designed to stack interferometric data. Primarily it was designed to allow stacking in the uv domain, but supports stacking in image domain.

2 Algorithm

The algorithms used by this code are described in Lindroos et al. (2014). The image based algorithm supports either mean or median stacking, where the flux from subimages are average with either the median or a weighted mean method. It works on a pixel-by-pixel basis in a defined stamp around the stacking positions.

The uv -stacking algorithm is based on aligning the phases of all visibilities to the target sources. Stacked visibilities are calculated as

$$V_{\text{stack}}(u, v, w) = V(u, v, w) \frac{\sum_{k=1}^N W_k \frac{1}{A_N(l_k, m_k)} e^{\frac{2\pi}{\lambda} i (ul_k + vm_k + w(\sqrt{1-l_k^2 - m_k^2}))}}{\sum_{k=1}^N W_k} \quad (1)$$

where (l_k, m_k) are the separation of stacking position k from the phase centre, (u, v, w) are the coordinates of the visibility in the uv plane, λ is the wavelength, $A_N(l_k, m_k)$ is the primary beam attenuation at stacking position k , and W_k is the weight of the stacking position.

3 Usage

This document provides a quick overview of the available functionalities in `stacker`. The module contains 3 packages: `pb`, `image` and `uv`. The packages `image` and `uv` provides functions to stack in the image and uv domain respectively. The package `pb` allows for describing the primary beam model. For a typical example of how `stacker` can be used see the provided example in “`example/stack_testdata.py`”.

3.1 Coordinates

The coordinates are described by a `coordList` object in the module. A `coordList` object can be generated from a csv file with the function `stacker.readCoords`, i.e.,

```
coord = stacker.readCoords(<path to coordinate file>)
```

Syntax of coordinate file should be

```
x1, y1(, weight1)
x2, y2(, weight2)
```

etc. For more info run `help(stacker.readCoords)` in casapy.

A coords object can also be built from scratch

```
coords = stacker.CoordList()
coords.append(stacker.Coord(x1, y1))
coords.append(stacker.Coord(x2, y2))
```

Note that coordinates here should be give in J2000 radians.

3.2 Primary beam model

The primary beam model can be defined by an instance of `stacker.pb.PrimaryBeamModel` or inherited classes. The c code only support `stacker.pb.MSPrimaryBeamModel` and `stacker.pb.PrimaryBeamModel`. A primary beam model can be generated from a measurement set with the function `stacker.pb.guesspb`.

```
pbmodel = stacker.pb.guesspb(<path to ms file>)
```

If *uv* stacking is run without specifying a primary beam model it will automatically attempt to use `stacker.pb.guesspb`.

3.3 uv

Submodule for stacking in the *uv* domain. Primarily provides two functions `stacker.uv.stack` and `stacker.uv.noise`. The first perform (`stacker.uv.stack`) the actual stacking, and requires an input *uv*-data file and a `coordsList` object as input.

```
import stacker, stacker.uv
coords = stacker.readCoords(<path to coordinate file>)
flux = stacker.uv.stack(coords, <path to ms data file>,
                        <path to save stacked ms file>)
```

For more info on usage run `help(stacker.uv.stack)` in casapy.

The second (`stacker.uv.noise`) calculates noise using a Monte Carlo where random positions are stacked to estimate the noise level. The function will try to recompute weights for the random positions. If you require variable weights which are not simply the primary beam or the noise in a local stamp you will have to re-implement the function.

3.4 image

Submodules for stacking in the image domain. Provides the same functions as the submodule `uv` except it works fully in the image domain.

```
import stacker, stacker.image
coords = stacker.readCoords(<path to coordinate file>)
flux = stacker.uv.stack(coords, <target file>,
                        <stamp size in pixels>, <list of image maps>)
```

The image maps are assumed to have been primary beam corrected. The package can handle a list of images as well as an individual image. An individual image should be specified as a one element list. For more details run `help(stacker.image.stack)` in `casapy`.

The `image` package also provides functions to calculate local weights for positions from the stamps surrounding them.

References

Lindroos L., Knudsen K. K., Vlemmings W., Conway J., Martí-Vidal I., 2014, in prep.