

# Gaussian Process for Time Series Analysis

Dr. Juan Orduz

PyData Berlin 2019



# Overview

Introduction

Regularized Bayesian Linear Regression

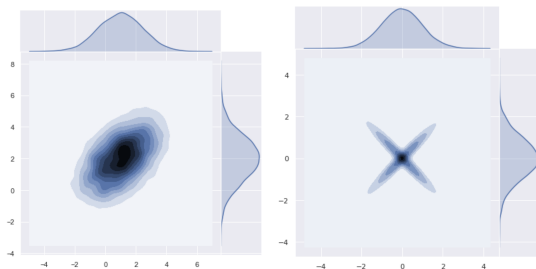


# Multivariate Normal Distribution

$X = (X_1, \dots, X_d)$  has a **multivariate normal distribution** if every linear combination is normally distributed. In this case it has density of the form

$$p(x|m, K_0) = \frac{1}{\sqrt{(2\pi)^d |K_0|}} \exp \left( -\frac{1}{2} (x - m)^T K_0^{-1} (x - m) \right)$$

where  $m \in \mathbb{R}^d$  is the **mean vector** and  $K_0 \in M_d(\mathbb{R})$  is the (symmetric, positive definite) **covariance matrix**.



**Figure:** Left: Multivariate Normal Distribution, Right: Non-Multivariate Normal Distribution

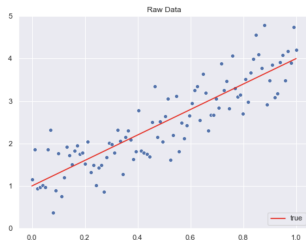


# Regularized Bayesian Linear Regression

Let  $x_1, \dots, x_n \in \mathbb{R}^d$  and  $y_1, \dots, y_n$  be a set of observations (data). We want to fit the linear model

$$f(x) = x^T b \quad \text{and} \quad y = f(x) + \varepsilon, \quad \text{with} \quad \varepsilon \sim N(0, \sigma_n^2)$$

where  $b \in \mathbb{R}^d$  denotes the parameter vector. Let  $X \in M_{d \times n}$  be denote the observation matrix.



We want to compute  $p(b|X, y)$  using the Bayes theorem

$$p(b|X, y) = \frac{p(y|X, b)p(b)}{p(y|X)} \propto \text{likelihood} \times \text{prior}$$



# Prior Distribution

## ► Likelihood

$$p(y|X, b) = \prod_{i=1}^n p(y_i|x_i, b) = N(X^T b, \sigma_n^2 I)$$

## ► Prior

$$b \sim N(0, \Sigma_p), \quad \Sigma_p \in M_d(\mathbb{R})$$

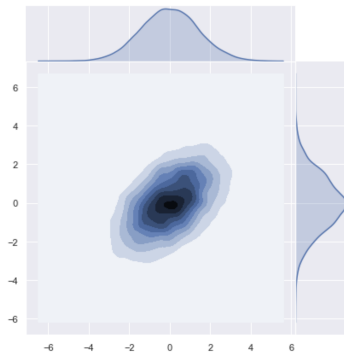


Figure: Prior Distribution



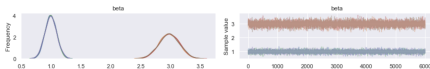
# Posterior Distribution

## ► Posterior

$$p(b|y, X) = N\left(\bar{b} = \frac{1}{\sigma_n^2} A^{-1} X y, A^{-1}\right)$$

where  $A = \sigma_n^{-2} X X^T + \Sigma_p^{-1}$

```
pm.traceplot(trace);
```



```
pm.plot_posterior(trace);
```

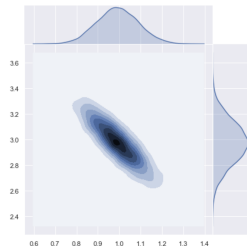
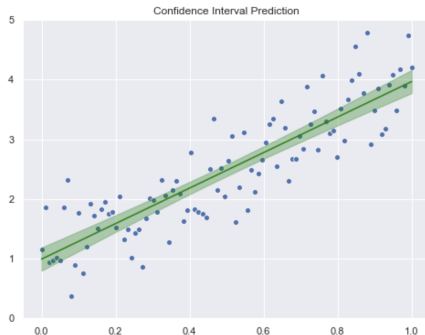


Figure: Posterior Distribution



# Predictive Distribution

$$\begin{aligned} p(f_*|x_*, X, y) &= \int p(f_*|x_*, b)p(b|X, y)db \\ &= N\left(\frac{1}{\sigma_n^2}x_*^T A^{-1} X y, x_*^T A^{-1} x_*\right) \end{aligned}$$



**Figure:** Left: Joint Posterior Distribution, Right: Prediction + Confidence Interval



# References

Slides and notebook available at [juanitorduz.github.io](https://juanitorduz.github.io)

