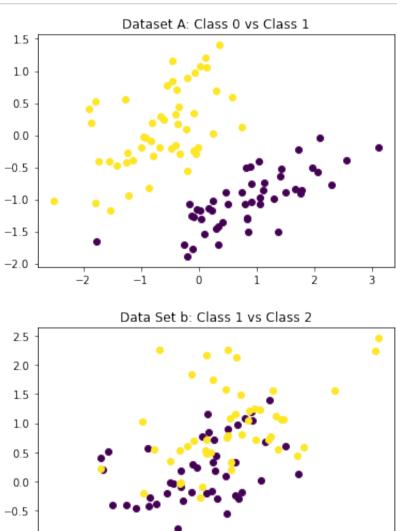
```
In [23]: import numpy as np
import mltools as ml
np.random.seed(0)
import matplotlib.pyplot as plt
```

## **Problem 1.1**

```
In [24]: iris = np.genfromtxt("data/iris.txt",delimiter=None)
    X, Y = iris[:,0:2], iris[:,-1]
    X,Y = ml.shuffleData(X,Y)
    X,_ = ml.transforms.rescale(X)
    XA, YA = X[Y<2,:], Y[Y<2]
    XB, YB = X[Y>0,:], Y[Y>0]
```

```
In [25]: plt.title("Dataset A: Class 0 vs Class 1")
    ml.plotClassify2D(None,XA,YA)
    plt.show()
    plt.title("Data Set b: Class 1 vs Class 2")
    ml.plotClassify2D(None,XB,YB)
    plt.show()
```



set A is linearly separable set B is not linearly separable.

-1

Ó

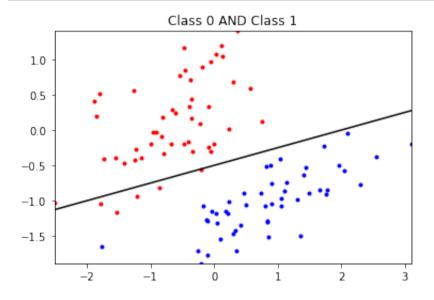
1

## Problem 1.2

-1.0

```
In [26]: from logisticClassify2 import *
    learnerA = logisticClassify2(); # create "blank" learner
    learnerA.classes = np.unique(YA) # define class labels using YA or
    wts = np.array([0.5, -0.25, 1.]); # TODO: fill in values
    learnerA.theta = wts;

plt.title("Class 0 AND Class 1")
    learnerA.plotBoundary(XA,YA)
    plt.show()
```



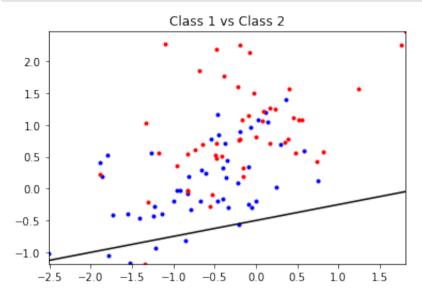
#### In [ ]:

```
My code

def plotBoundary(self,X,Y):
    if len(self.theta) != 3: raise ValueError('Data & model must
be 2D');
    ax = X.min(0),X.max(0); ax = (ax[0][0],ax[1][0],ax[0][1],ax[1]
[1]);
    x1b = np.array([ax[0],ax[1]]); # The X1 coordinates of the
two points
    x2b = (-self.theta[0]-self.theta[1]*x1b)/self.theta[2];
    A = Y==self.classes[0];
    plt.plot(X[A,0],X[A,1],'b.',X[~A,0],X[~A,1],'r.',x1b,x2b,'k-'); plt.axis(ax); plt.draw();
```

```
In [27]: learnerB = logisticClassify2();
    learnerB.classes = np.unique(YB)
    wts = np.array([0.5, -0.25, 1.])
    learnerB.theta = wts

    plt.title("Class 1 vs Class 2")
    learnerB.plotBoundary(XB,YB)
    plt.show()
```



### Problem 1.3

```
In [28]: learnerA = logisticClassify2()
    learnerA.classes = np.unique(YA)
    wts = np.array( [0.5,-0.25,1] )
    learnerA.theta = wts
    print("error rates is " + str(learnerA.err(XA, YA)))
```

error rates is 0.050505050505050504

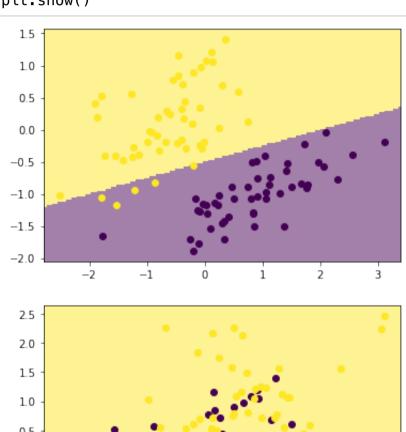
```
My code def predict(self, X):
    P = self.theta[0] + X.dot(self.theta[1:])
    Y01 = (P > 0).astype(int)
    Yhat = np.asarray(self.classes)[Y01]
    return Yhat
```

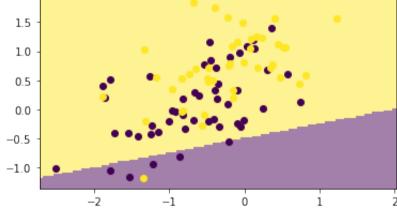
```
In [29]: learnerB = logisticClassify2()
    learnerB.classes = np.unique(YB)
    wts = np.array( [0.5,-0.25,1] )
    learnerB.theta = wts
    print("error rates is " + str(learnerB.err(XB, YB)))
```

error rates is 0.46464646464646464

## Problem 1.4

```
In [30]: ml.plotClassify2D(learnerA,XA,YA)
    plt.show()
    ml.plotClassify2D(learnerB,XB,YB)
    plt.show()
```





# Problem 1.5

```
negative log-likelihood loss is  Jj(\theta) = -\log(\sigma(x^{(j)} \cdot \theta)) \text{ if } y^{(j)} = 1   Jj(\theta) = -\log(1 - \sigma(x^{(j)} \cdot \theta)) \text{ if } y^{(j)} = 0
```

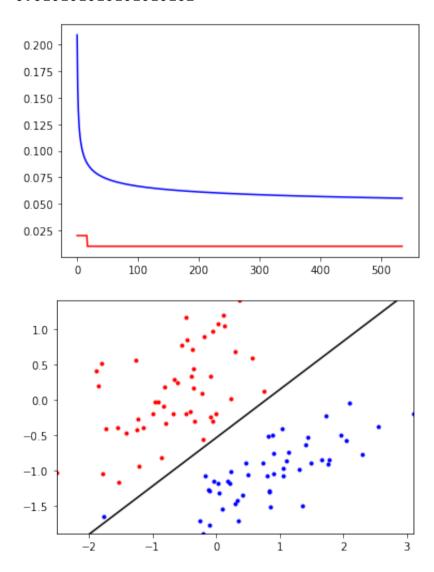
```
The gradient is: \nabla Jj(\theta) = - (1 - \sigma(x^{(j)} \cdot \theta)) \ x^{(j)} \ \text{if} \ y^{(j)} = 1 \nabla Jj(\theta) = -\sigma(x^{(j)} \cdot \theta) \ x^{(j)} \ \text{if} \ y^{(j)} = 0
```

```
My train function:
def train(self,X,Y, initStep=1.,stopTol=1e-
4,stopEpochs=5000,plot=None):
    M.N = X.shape:
    self.classes = np.unique(Y);
    XX = np.hstack((np.ones((M,1)),X))
    YY = ml.toIndex(Y,self.classes);
    if len(self.theta)!=N+1: self.theta=np.random.rand(N+1);
    epoch=0; done=False; Jnll=[]; J01=[];
    while not done:
        stepsize, epoch = initStep*2.0/(2.0+epoch), epoch+1;
        for i in np.random.permutation(M):
            ri = XX[i].dot(self.theta)
            si = 1./(1.+np.exp(-ri))
            gradi = -(1-si)*XX[i,:] if YY[i] else si*XX[i,:]
            self.theta -= stepsize * gradi;
        J01.append( self.err(X,Y) )
        S = 1./(1.+np.exp(-(XX.dot(self.theta))))
        Jsur = -np.mean(YY*np.log(S)+(1-YY)*np.log(1-S))
        Jnll.append( Jsur )
        plt.pause(.01);
        done = epoch>=stopEpochs or (epoch>1 and abs(Jnll[-1]-
Jnll[-2])<stopTol)</pre>
    plt.figure(1); plt.clf(); plt.plot(Jnll, 'b-', J01, 'r-');
plt.draw();
    if N==2: plt.figure(2); plt.clf(); self.plotBoundary(X,Y);
plt.draw():
```

### Problem 1.6

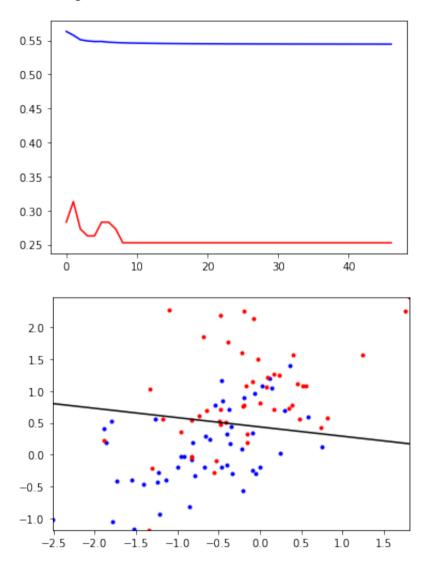
```
In [31]: learnerA = logisticClassify2()
    learnerA.theta = np.array([0.,0.,0.]);
    learnerA.train(XA,YA,initStep=1e-1,stopEpochs=1000,stopTol=1e-5);
    print(learnerA.err(XA,YA))
    plt.show()
```

#### 0.010101010101010102



```
In [32]: learnerB = logisticClassify2()
    learnerB.theta = np.array([0.,0.,0.])
    learnerB.train(XB,YB,initStep=1e-1,stopEpochs=1000,stopTol=1e-5)
    print("training error rate: " + str(learnerB.err(XB,YB)))
    plt.show()
```

training error rate: 0.252525252525254



## Problem2.1

T(a+bx1)is a vertical or horizontal linear classifier which is a line. This learner can shatter dataset (a) and (b) but not (c) or (d) because (a) and (b) can be separated. While (c) and (d), there are different points on the same side.

# Problem 2.2

T((a \* b)x1 + (c/a)x2) is a linear classifier passes through the origin. It is same as 2.1 that it can shatter data points in (a) and (b) but not shatter the data points in (c) or (d) because (a) and (b) can be separated. While (c) and (d), there are different points on the same side

### Problem 2.3

 $T((x1-a)^2+(x2-b)^2+c)$ , is a random ciclre classifer. It can shatter data points in (a), (b) and (c) We can separate points in (a), Because in (d) dataset, it may have different values on the same side.

### Problem 2.4 ec

 $T(a+bx1+cx2)\times T(d+bx1+cx2)$  is parrelal linear classifier Learner C can shatter data points in (a), (b) and (c), but not shatter the data points in (d). The classifier creates three regions.

### **Problem 3**

I did this homework independently.

