Numerical methods in phycics - week 2 assignment

By Oliver Sørensen (qzk375)

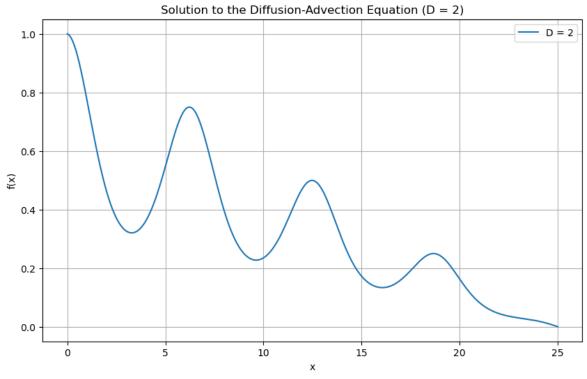
3.6 Diffusion-Advection

a

Use a second order finite difference scheme to solve the diffusion- advection with D=2 and v(x)=-sinx on [0,25] with boundary conditions f(0)=1 and f(25)=0. Use N=1000 grid points.

```
In [ ]: import numpy as np
        import matplotlib.pyplot as plt
        from scipy.linalg import solve
        def diffusion_advection(D):
            N = 1000
            L = 25
            dx = L / N
            x = np.linspace(0, L, N)
            # Velocity field
            v = -np.sin(x)
            \# diag(v(x))
            V = np.diag(v)
            A1 = np.zeros((N, N))
            # used: https://en.wikipedia.org/wiki/Finite difference coefficient
            # foward difference
            A1[0,0], A1[0,1], A1[0,2] = -3/2, 2, -1/2
            for i in range(1,N-1):
                # central difference
                A1[i,i-1], A1[i,i], A1[i,i+1] = -1/2, 0, 1/2
            # backward difference
            A1[N-1,N-3], A1[N-1,N-2], A1[N-1,N-1] = 1/2, -2, 3/2
            A1 = (1 / dx) * A1
            A2 = np.zeros((N, N))
            A2[0,0], A2[0,1], A2[0,2] = 1, -2, 1 # foward difference
            for i in range(1,N-1):
                # central difference
                A2[i,i-1], A2[i,i], A2[i,i+1] = 1, -2, 1
            # backward difference
            A2[N-1,N-3], A2[N-1,N-2], A2[N-1,N-1] = 1, -2, 1
            A2 = (D / dx**2) * A2
```

```
# T1 = A1 * V
   T1 = A1 @ V
   # second boundary condition (f(25) = 0)
    b = np.zeros(N)
    # first boundary condition (f(0) = 1),
   b[0] = 1
   A = A2 - T1
   A[0,:] = 0
   A[0,0] = 1
   A[-1,:] = 0
   A[-1,-1] = 1
    f = np.linalg.solve(A,b)
    return x, f
D = 2
x, f = diffusion_advection(D)
# Plotting the result
plt.figure(figsize=(10, 6))
plt.plot(x, f, label=f'D = \{D\}')
plt.xlabel('x')
plt.ylabel('f(x)')
plt.title('Solution to the Diffusion-Advection Equation (D = 2)')
plt.legend()
plt.grid(True)
plt.show()
```



b

Explain the shape of f(x). Does it make sense compared to the physical

interpretation of the diffusion-advection equation?

Diffusion Term that spreads particles: $Drac{d^2f(x)}{dx^2}$

Advection Term, particles are transported by the velocity field: $rac{d}{dx}(v(x)f(x))$

The shape of f(x) is determined by the balance between diffusion and advection. The strength of the diffusion is determined by D, therefore a high D would mean that diffusion will dominate. Whereas a lower D would mean that advection dominates. Since advection term transports particles by the velocity field it makes sense that we would see some sort of sinusoidal motion since v(x) = -sin(x). ForD = 2\$ we will stil see the effect of advection and therefore we would also expect some sinusoidal motion.

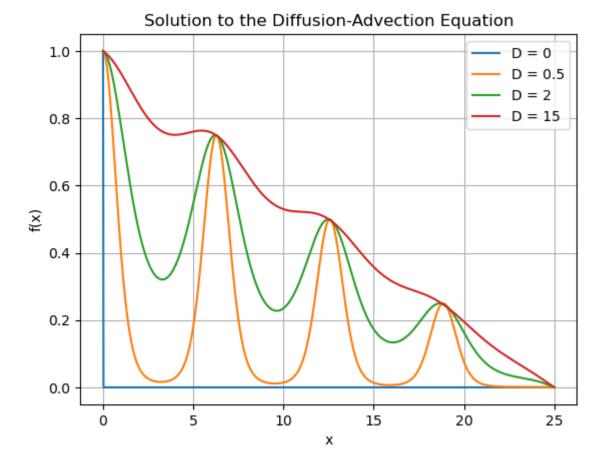
Because of the boundary case we would expect f(0)=1 and f(25)=0

C

Explain what happens for D o 0 and $D o \infty$. Plot for instance D=0.5 and D=15 and compare to D=2. Would your code work for D = 0?

```
In []: D_values = [0, 0.5, 2, 15]

for D in D_values:
    x, f = diffusion_advection(D)
    plt.plot(x, f, label=f'D = {D}')
    plt.xlabel('x')
    plt.ylabel('f(x)')
    plt.title('Solution to the Diffusion-Advection Equation')
    plt.legend()
    plt.grid(True)
plt.show()
```



For D o 0 Diffusion term disappears, the equation becomes dominated by advection, leading to a sharp and discontinuous solution. However the code still works for D=0, we see f(x)=0 across the entire domain. This is because the equation becomes

$$-\frac{d}{dx}(v(x)f(x)) = 0$$

This means that

$$v(x)f(x) = C$$

Where C is a constant.

For v(x)f(x)=C , f(x) must be equal to 0 across the entire domain.

For $D o \infty$ Diffusion dominates, leading to a much smoother solution and less sinusodial motion.

4.1 1D Heat Equation

а

Use a second order finite difference scheme to turn the above into a linear algebra problem using N = 1000 grid points.

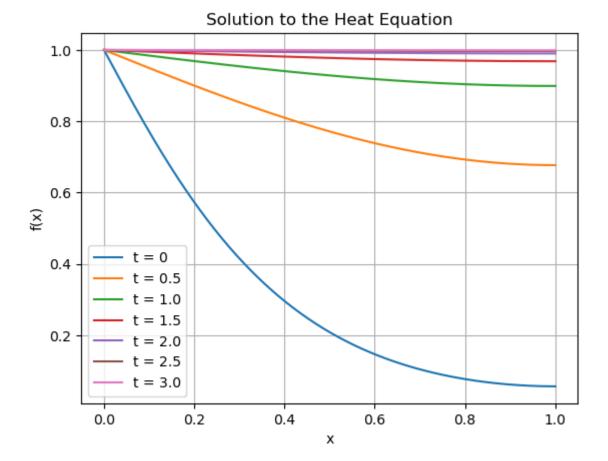
In []: def heat_equation(dt = 0.05, t_values = [0, 0.5, 1, 1.5, 2, 2.5, 3]):

```
N = 1000
x = np.linspace(0, 1, N)
dx = x[1] - x[0]
t = 0
A1 = np.eye(N, N) # identity matrix
A2 = np.zeros((N, N))
# foward difference
A2[0,0], A2[0,1], A2[0,2] = 1, -2, 1
for i in range(1, N-1):
    # central difference
    A2[i,i-1], A2[i,i], A2[i,i+1] = 1, -2, 1
# backward difference
A2[N-1,N-3], A2[N-1,N-2], A2[N-1,N-1] = 1, -2, 1
A2 = (dt / dx**2) * A2
A = A1 - A2
A[0,:] = 0
A[0,0] = 1
A[-1,:] = 0
A[-1,-1] = 3/2
A[-1,-2] = -2
A[-1,-3] = 1/2
f = np.exp(-5*x)
b = f.copy()
# boundary conditions
b[0] = 1
b[-1] = 0
while t <= 3:
    t = round(t, 2)
    f = np.linalg.solve(A,b)
    b = f.copy() # update each time step
    b[0] = 1 # first boundary condition
    b[-1] = 0 # second boundary condition
    if t in t_values:
        plt.plot(x, f, label=f't = \{t\}')
    t += dt # update time step
plt.xlabel('x')
plt.ylabel('f(x)')
plt.title('Solution to the Heat Equation')
plt.legend()
plt.grid(True)
plt.show()
```

b

Solve the system using Δt = 0.05 for $t\in[0,3]$ and plot curves for $t\in\{0.0,0.5,1.0,1.5,2.0,2.5,3.0\}.$

```
In [ ]: heat_equation(dt = 0.05, t_values = [0, 0.5, 1.0, 1.5, 2.0, 2.5, 3.0])
```



4.3 Shade sail

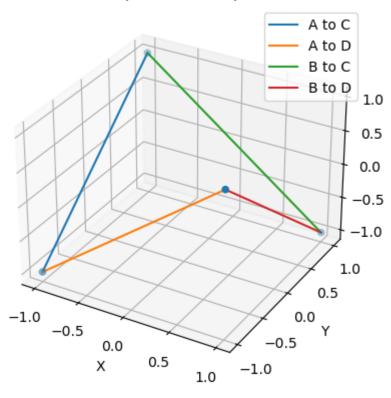
a

Plot the four ropes in a 3D plot.

```
In [ ]: import numpy as np
        import matplotlib.pyplot as plt
        def plot_ropes(ax):
            A = np.array([-1, -1, -1])
            B = np.array([1, 1, -1])
            C = np.array([-1, 1, 1])
            D = np.array([1, -1, 1])
            # Plotting the ropes
            ax.plot([A[0], C[0]], [A[1], C[1]], [A[2], C[2]], label='A to C')
            ax.plot([A[0], D[0]], [A[1], D[1]], [A[2], D[2]], label='A to D')
            ax.plot([B[0], C[0]], [B[1], C[1]], [B[2], C[2]], label='B to C')
            ax.plot([B[0], D[0]], [B[1], D[1]], [B[2], D[2]], label='B to D')
            ax.legend()
            ax.scatter([A[0], B[0], C[0], D[0]], [A[1],
            B[1], C[1], D[1]], [A[2], B[2], C[2], D[2]])
            ax.set_xlabel('X')
            ax.set_ylabel('Y')
            ax.set_zlabel('Z')
```

```
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
plot_ropes(ax)
ax.set_title('3D plot of the ropes')
plt.show()
```

3D plot of the ropes



b

Write down the boundary conditions.

all values at the edge of the domain are known function. looking at each rope, we see the following:

$$f_1(x=-1,y)=x+y$$
 (A to C) $f_2(x,y=-1)=x+y$ (A to D) $f_3(x,y=1)=-x+y$ (B to C) $f_4(x=1,y)=x-y$ (B to D)

The domain of x,y is: $x,y \in [(-1,-1);(1,1)]$ Therefore we get the following boundary conditions:

$$egin{aligned} f(-1,y) &= y, & ext{for } y \in [-1,1], \ f(x,-1) &= x, & ext{for } y \in [-1,1], \ f(x,1) &= -x, & ext{for } x \in [-1,1], \ f(1,y) &= -y, & ext{for } x \in [-1,1]. \end{aligned}$$

C

Solve Eq. (4.8) with the boundary conditions.

```
In [ ]: import numpy as np
        import matplotlib.pyplot as plt
        # Finite difference method, 4 points.
        def laplace(N = 4):
            x = np.linspace(-1, 1, N)
            y = np.linspace(-1, 1, N)
            dx = x[1] - x[0]
            X, Y = np.meshgrid(x, y)
            A = np.zeros((N**2, N**2))
            b = np.zeros(N**2)
            for i in range(N):
                 for j in range(N):
                     n = i * N + j
                     # Boundary conditions:
                     if i == 0: \# \times = -1
                         A[n,n] = 1
                         b[n] = y[j]
                     elif j == 0: \# y = -1
                         A[n,n] = 1
                         b[n] = x[i]
                     elif j == N-1: # y = 1
                         A[n,n] = 1
                         b[n] = -x[i]
                     elif i == N-1: \# \times = 1
                         A[n,n] = 1
                         b[n] = -y[j]
                     else:
                         # Interior points
                         # Using equation 4.27
```

```
A[n,n] = - 4/dx**2 # center -4f(xi, yj)
A[n, n + N] = 1/dx**2 # up f(xi, yj+1)
A[n, n - N] = 1/dx**2 # down f(xi, yj-1)
A[n, n+1] = 1/dx**2 # right f(xi+1, yj)
A[n, n-1] = 1/dx**2 # left f(xi-1, yj)
b[n] = 0
f = np.linalg.solve(A, b)
return X, Y, f

X, Y, f = laplace(4)
Z = f.reshape(X.shape)
```

d

Plot your solution together with the ropes.

```
In [ ]: fig = plt.figure()
    ax = fig.add_subplot(projection='3d')
    ax.plot_surface(X, Y, Z)
    plot_ropes(ax)
    plt.show()
```

