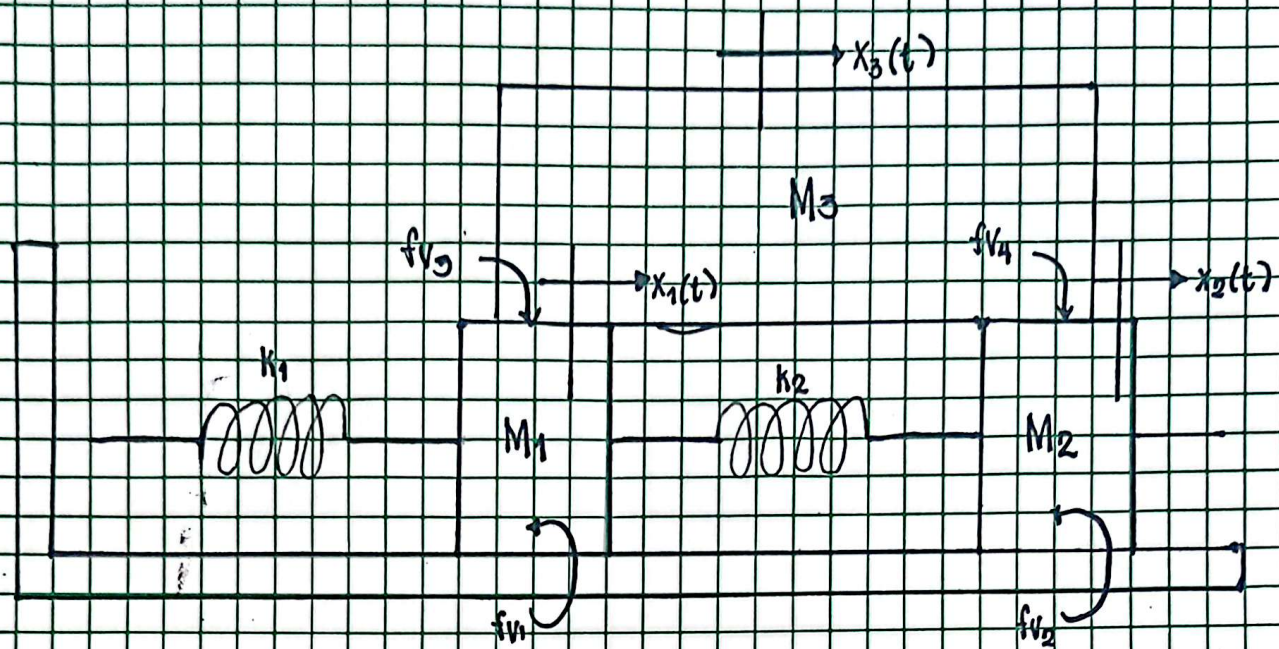


# PROBLEM 1



FOR  $M_1$

$$0 = M_1 \ddot{x}_1 + B_1 \dot{x}_1 + B_3 \dot{x}_1 + k_1 x_1 + k_2 x_1 - B_3 \dot{x}_3 - k_2 x_2$$

$$f(t) = M_2 \ddot{x}_2 + B_2 \dot{x}_2 + B_1 \dot{x}_2 + k_2 x_2 - B_1 \dot{x}_3 - k_2 x_1$$

$$0 = M_3 \ddot{x}_3 + B_3 \dot{x}_3 + B_4 \dot{x}_3 - B_1 \dot{x}_1 - B_2 \dot{x}_2$$

$$x_1 = x_1(t)$$

$$x_3 = x_2(t)$$

$$x_5 = x_3(t)$$

$$x_2 = \dot{x}_1(t)$$

$$x_4 = \dot{x}_2(t)$$

$$x_6 = \dot{x}_3(t)$$

$$\dot{x}_1 = \dot{x}_1(t) = x_2$$

$$\dot{x}_3 = \dot{x}_2(t) = x_4$$

$$\dot{x}_5 = \dot{x}_3(t) = x_6$$

$$x_2 = \ddot{x}_1(t)$$

$$\dot{x}_4 = \ddot{x}_2(t)$$

$$x_6 = \ddot{x}_3$$

$$\dot{x} = 0x_1 + x_2 + 0x_3 + 0x_4 + 0x_5 + 0x_6 + 0u_1$$

$$\dot{x}_2 = -\left(\frac{k_1 + k_2}{M_1}\right)x_1 - \left(\frac{B_1 + B_3}{M_1}\right)x_2 + \left(\frac{k_2}{M_1}\right)x_3 + 0x_4 + 0x_5 + \left(\frac{B_3}{M_1}\right)x_6 + 0u_1$$

$$\dot{x}_3 = 0x_1 + 0x_2 + 0x_3 + x_4 + 0x_5 + 0x_6 + 0u_1$$

$$\dot{x}_4 = \left(\frac{k_2}{M_2}\right)x_1 + 0x_2 - \left(\frac{k_2}{M_2}\right)x_3 - \left(\frac{B_2 + B_4}{M_2}\right)x_4 - 0x_5 + \left(\frac{B_4}{M_2}\right)x_6 + 0u_1$$

$$\dot{x}_5 = 0x_1 + 0x_2 + 0x_3 + 0x_4 + 0x_5 + x_6 + 0u_1$$

$$\dot{x}_6 = 0x_1 + \left(\frac{B_1}{M_3}\right)x_2 - 0x_3 + \left(\frac{B_2}{M_3}\right)x_4 + 0x_5 - \left(\frac{B_3 + B_4}{M_3}\right)x_6 + 0u_1$$



$$Y_1 = X_3 + 0U_1$$

$$Y_2 = X_5 + 0U_1$$

$$Y_3 = X_6 + 0U_1$$

### STATE SPACE EQUATION

|             | $x_1$                      | $x_2$                      | $x_3$              | $x_4$                    | $x_5$ | $x_6$                    |                       |   |
|-------------|----------------------------|----------------------------|--------------------|--------------------------|-------|--------------------------|-----------------------|---|
| $\dot{x}_1$ | 0                          | 1                          | 0                  | 0                        | 0     | 0                        | $x_1$                 | 0 |
| $\dot{x}_2$ | $-\frac{(K_1 + K_2)}{M_1}$ | $-\frac{(B_1 + B_2)}{M_1}$ | $\frac{K_2}{M_1}$  | 0                        | 0     | $\frac{B_2}{M_1}$        | $x_2$                 | 0 |
| $\dot{x}_3$ | 0                          | 0                          | 0                  | 1                        | 0     | 0                        | $x_3 + \frac{1}{M_2}$ |   |
| $\dot{x}_4$ | $\frac{K_2}{M_2}$          | 0                          | $-\frac{K_2}{M_2}$ | $-\frac{B_2 + B_4}{M_2}$ | 0     | $\frac{B_4}{M_2}$        | $x_4$                 | 0 |
| $\dot{x}_5$ | 0                          | 0                          | 0                  | 0                        | 0     | 1                        | $x_5$                 | 0 |
| $\dot{x}_6$ | 0                          | $\frac{B_1}{M_3}$          | 0                  | $\frac{B_2}{M_3}$        | 0     | $-\frac{B_2 + B_4}{M_3}$ | $x_6$                 | 0 |

$U_1$

$$Y = \begin{bmatrix} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} U_1$$

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