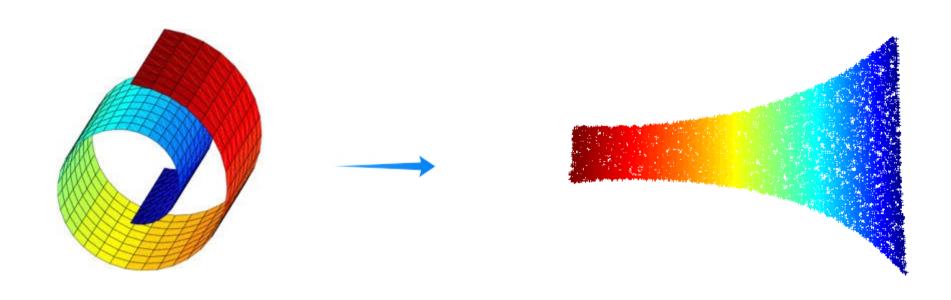
NonLinear Dimensionality Reduction in Pattern Recognition Applications



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Introduction

- Introduction about Dimensionality Reduction
- Presentation sections
 - Why we need information compression
 - Dimensionality Reduction Algorithms (PCA, SVD, ISOMAP, Laplassian Eigenmaps, LLE)
 - The Locally Linear Embeddings Algorithm (LLE)
 - Surpass LLE limitations with two new variations of LLE algorithm
 - Experiments using native LLE and the two new methods
 - Datasets: MNIST, SVHN, Arcene
 - Results visualization and explanation
 - Future work
 - Conclusion

Why we need information compression

- Example: Image with size [480,640]
 - That is equal to a vector with size: 480x640 = 307200.
 - For a "small" dataset, N = 100K we have a matrix of size: 100.000 x 307200
- Very large Computational complexity
- Very large memory requirements
- A large amount of these pixels are just Noise, affecting negative machine learning or image processing algorithms.
- Why dont we just simulate the Human brain ...
- How? Using keypoints into each image
 - Features like SIFT, HoG, PFH etc ...
 - Find out which pixels have meaningful information
- Dimensionality reduction techniques are able to extract d (ex. 8<d<256, from 480x640) meaningful key points

Dimensionality Reduction Algorithms

• Linear:

- Principal Component Analysis (PCA)
 - Minimize a mean square error equation (sum of eigenvalues)
 - Produces statistical independent features
- Multi Dimensional Scaling (MDS)
- Singular Value Decomposition (SVD)
 - Solving the equation: $X = U_r \Lambda^{(\frac{1}{2})} V_r^H$
- Non-Linear:
 - Isometric Mapping (ISOMAP)
 - Laplassian-Eigenmaps
 - Locally Linear Embeddings

NonLinear Dimensionality Reduction – Locally Linear Embeddings

- Step-1: Find K-Nearest Neighbors for each data (Adjacency matrix)
 - Executed in CUDA
- Step-2: Find Weighs matrix (W)
 - Minimize cost function: $argmin E_w = \sum_{i=1}^{N} ||X_i \sum_{j=1}^{N} W(i, j)X_j||^2$

$$E = |\vec{x} - \sum_{j} w_{j} \vec{x}_{j}|^{2} = |\sum_{j} w_{j} (\vec{x} - \vec{x}_{j})|^{2} = \sum_{jk} w_{j} w_{k} C_{jk}$$

- Figure 3. Gram matrix: $C_{jk} = (\vec{x} \vec{x}_j) \cdot (\vec{x} \vec{x}_k)$
- Solve the system: $\sum_{j} Cjk \cdot w_k = 1$

NonLinear Dimensionality Reduction – Locally Linear Embeddings

- Step-3: Find the embedding coordinates, using the weights matrix W
 - $\qquad \qquad \text{Minimize cost function:} \quad \arg\min E_{y} = \sum_{i=1}^{N} \left\| Y_{i} \sum_{j=1}^{N} W(i,j) Y_{j} \right\|^{2}$

$$\rightarrow E_y = |(I - W)Y|^2 = Y_T M Y$$

- Find eigen-values of the square [NxN] sparse matrix
 - $M = (I W)^T (I W)$
- Step-4: Keep the final embedded coordinates
 - > Discard the λ_0 eigenvalue (equal to zero)
 - Keep the rest d eigen-values. The eigen-vectors are the final embedded d coordinates

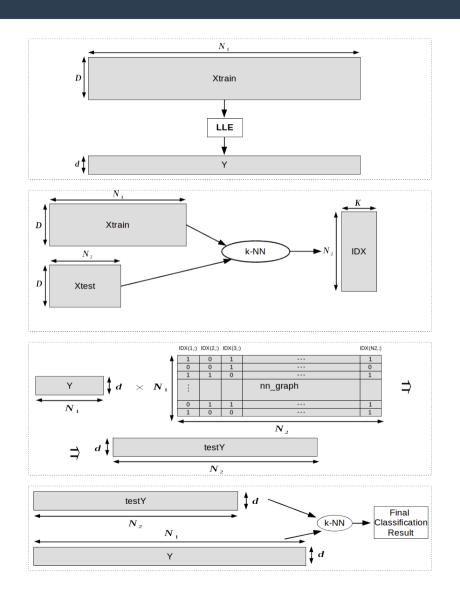
LLE Limitations

- Eigen-value decomposition step has complexity $k \cdot O(N^2)$
 - For sparse matrix M, solving with Lanczos algorithm
- We must run LLE algorithm with both train and test datasets as input data
 - Dimensionality reduction on train and separate on test produces spaces with different base vectors
 - We cannot find any realation between the low dimensional test and train data

Method-1: LLE with Test-Projection

- Apply LLE dimensionality reduction on Train dataset [DxN1]
 - Result: matrix Y of size [dxN1]
- K-NN between Test dataset [DxN2] and Train dataset
 - Result: matrix IDX of size [N2xK]
- Create the adjacency zero matrix nn_graph of size [N1xN2]
- For every column in nn_graph set IDX(column,1:K) elements equal to ones
- Execute the matrix multiplication: Y[dxN1] x nn_graph[N1xN2]
 - Result: matrix testY of size [dxN2]
- Final step, execute classification algorithm (k-NN) between dimansional reduced test (testY) and train (Y) datasets

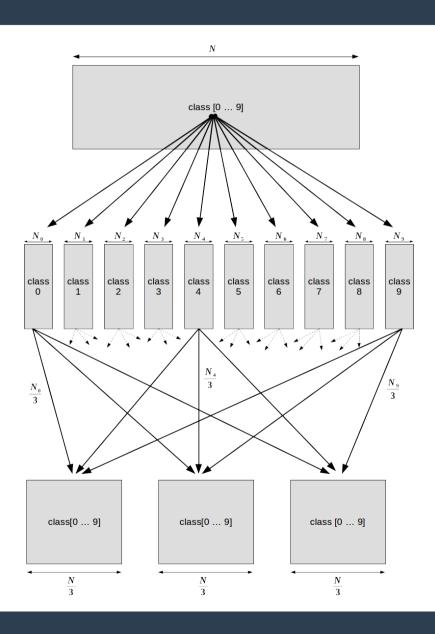
Method-1: LLE with Test-Projection



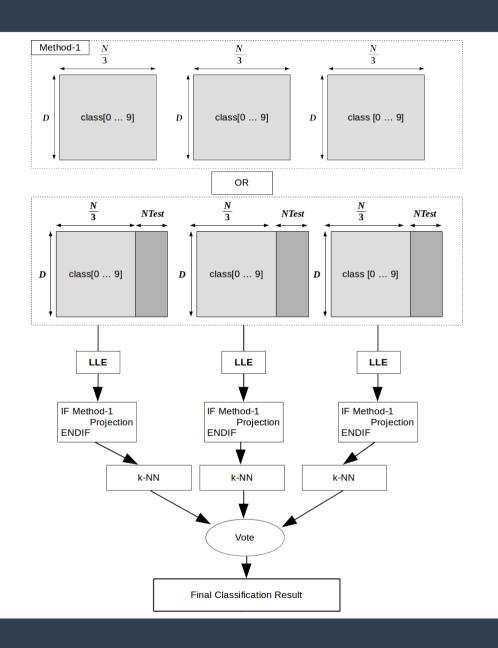
Method-2: LLE with SubSpace Voting

- Split Train dataset into sub-sets
 - Sub-sets MUST contain equal information for every class
- Execute dimensions reduction using LLE on every sub-set
 - Method-1 can be used, in order to avoid including Test data into each sub-dataset
- Execute classification process (k-NN) for every Test data
- The final classification result depends from the majority class after each sub-space voting

Method-2: LLE with SubSpace Voting



Method-2: LLE with SubSpace Voting



Experiments

- <u>Datasets</u>: MNIST, SVHN, ARCENE
 - MNIST: Gray scale images of handwritten digits.
 - 60K Train data, 10K Test data, D=[28x28]
 - SVHN: Google street view house numbers [32x32] RGB images.
 - > 73257 Train data, 26032 Test data, D=[32x32] (531131 additional, somewhat less difficult Train data)
 - > Arcene: Cancer dataset with a large number of predefined features for each patient.
 - 200 Train data, 700 Test data, D = 10K.
- Classification algorithm: k-NearestNeighbors
- Classification metric: Mean average % error

MNIST Experiments

- LLE parameters k, d. Method-2 parameter: batch_size
 - 1st-Exp: K = [6, 7, 8, 9, 10, 12, 16, 20, 24, 32, 64], d = [10, 16, 20, 24, 32, 40, 52, 64, 96, 128, 256], subSet_size=[60000,30000,20000] of Train dataset
 - Classification error using k-NN (k=2): K=12, d=128, subSet_size=60K, qual to 3.06%
 - Classification error using k-NN (k=2) without dimensionality reduction: 3.5%
 - This is also a VERY important result: K=8, d=10, subSet_size=60K equal to 3.31%
 - From the above results, we can say that LLE algorithm can be used as a feature extraction process with great data compression ability.

MNIST Experiments

- Method-2 results are very impressive:
 - K=16, d=256, batch_size=20K. Best classification error equal to 3.27%.
 - K=10, d=128, batch size=10K. Best classification error equal to 3.31%.
 - Huge reduction both in time and space. (Step-3 of LLE has $O(N^2)$ complexity)
- Method-1: Not impressive results, but this is the only realistic use of LLE dimensionality reduction in "Real time" application
 - K=8, d=256, batch_size=60K. Best classification error equal to 3.85%.

SVHN Experiments

- Extract HoG features due to noise and light distortions.
 - Split image into sub sections and calculate the gradient of pixel intensity.
- 1st-Exp: K = [8, 10, 12], d = [16, 20, 32, 64, 96, 128, 164, 196, 256], 30K of SVHN Train data-set
 - HoG features parameters: Kernels size: [2x2], [4x4], [8x8] produce features of length: 8100, 1764. 324.
 - Best parameters for SVHN dataset: K=12, d=32, kernel=[4x4].
- 2nd-Exp: K=12, d=32, kernel=[4x4]. Full SVHN dataset (73257 Train data, 26032 Test data)
 - Classification error with LLE dimensionality reduction is equal to: 16.67%.
 - Classification without dimensionality reduction (D=1024) is equal to: 17.00%.
 - The above classification results came from k-NN Classification algorithm and k=8.

SVHN Experiments

- 3rd-Exp Method-1: LLE parameters: K=12, d=32, kernel=[4x4]. 42K of SVHN Train dataset
 - Classification error with LLE dimensionality reduction on Train data and projection for Test data is equal to 18.34%
 - Classification error with LLE dimensionality reduction on Train+Test data is equal to 16.67%
 - Classification error without dimensionality reduction is equal to 17.00%
- 4th-Exp Method-2: LLE parameters: K=12, d=32, kernel=[4x4]. 30K of SVHN Train dataset.
 Method-2 parameters: 3 subspaces
 - Classification results for each of 3 subspaces: 20.19%, 19.05%, 19.97%
 - Classification after subspace voting: 18.30%

SVHN Experiments

- 5th-Exp Method-2: LLE parameters: K=12, d=32, kernel=[4x4]. 30K of SVHN Train dataset.
 Method-2 parameters: 5 subspaces
 - Classification results for each of 5 subspaces: 20.28%, 21.11%, 20.93%, 20.92%, 21.11%
 - Classification error after subspace voting: 18.37%
 - Classification error for 3 subspaces (4th-Exp) is equal to 18.30%
- 6th-Exp Method-2: LLE parameters: K=12, d=32, kernel=[4x4]. 30K of SVHN Train dataset.
 Method-2 parameters: 10 subspaces
 - Classification error after subspace voting: 18.58%
- 7th-Exp Method-2: LLE parameters: K=12, d=32, kernel=[4x4]. 30K of SVHN Train dataset.
 Method-2 parameters: 20 subspaces
 - Classification error after subspace voting: 19.13%

ARCENE Experiments

- 1st-Exp: K = [10, 12, 16, 20, 24, 32, 64], d = [10,16, 20, 24, 32, 40, 52, 64, 96, 128]
 - Lack of test labels. 150 Train patients and 50 Test patients and 10K features for each one.
 - For every K and d (<=96) combinations, classification error after LLE dimensionality reduction is by far better than the D=10K dimensional space
 - Best classification error for parameters (K=10, d=10), (K=10, d=52), (K=12, d=128) equal to **10**%
 - Classification error without dimensionality reduction (D=10K) equal to 76%.
 - With 10 of 10K features, we gain a boost of 14% classification accuracy.
 - Accurate classification result with 90% probability

Future Work

- Parallelization: Even though k-NN algorithm both in LLE and in Classification process is executed in CUDA, further parallelization can be achieved from sub-set splitting into threads.
- Extend to large datasets and invest the behaviour of subspace voting
- Find the cutting edge between number of subsets-Train dataset size and Test data size
- Maybe a very accurate dimensionality reduction algorithm for Medical image retreival.

Conclusion

- LLE produces impressive results after huge dimensionality reduction.
- Huge space and time savings at Final Classification Step
- Method-1 can give as real time Classification into the low dimensional Train and Test spaces
- Method-2 achieves dramatically reduction on execution sources. Both space and time.
- Method-1 and Method-2 makes the execution of LLE algorithm available for normal PCs.
- LLE algorithm can be used both as feature extraction and feature selection process.
- LLE has the ability to remove noise-data, producing very accurate classification results

Thank You