Agenda

- , BST intro and its properties
- 2) Search in BST (TC comparison with BT)
- 3) Insert in BST
- 4) 95 BST
- s) Sorted array to balanced BST
- 6) Recover BST (1) possible)

Binary Search Tree (Introduction)

A binary tree is a BST if

au nodes < node. val < au nodes

coming in

dyt subtree

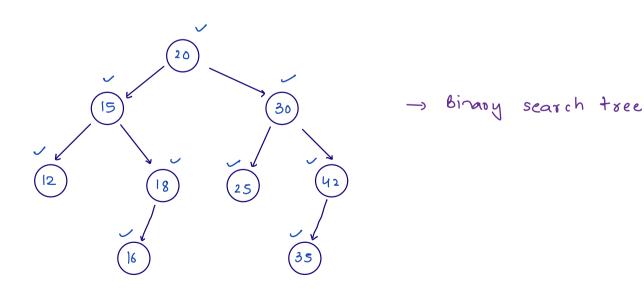
This condition

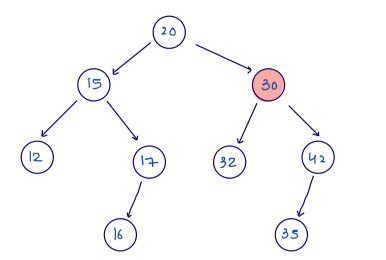
showld be

true for

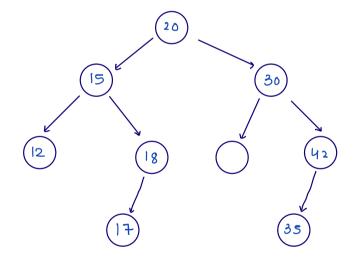
all nodes

au nodes



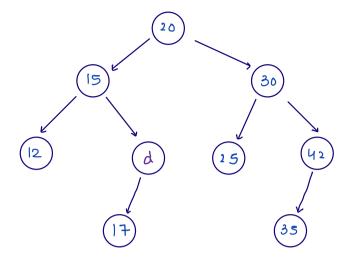


not a BST



0-29 ×

21-29 0



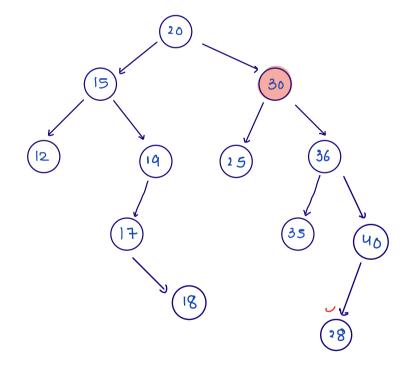
due to 20

and 15

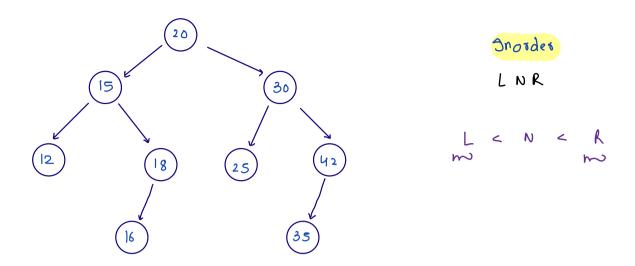
15 < d < 20

On left d there
is 17 so
d can be only

18 \$19



Not a BST

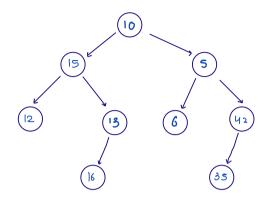


morder: 12 15 16 18 20 25 30 35 42

on a Bot inorder is always sorted

Binary tree VS Binary Search tree

Binary tree



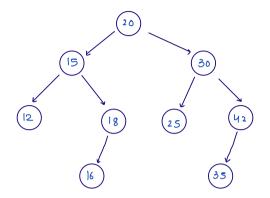
Scarch Jor K

TC: 0(n)

sc: o(h)

height of Birary tree

Binary Search tree

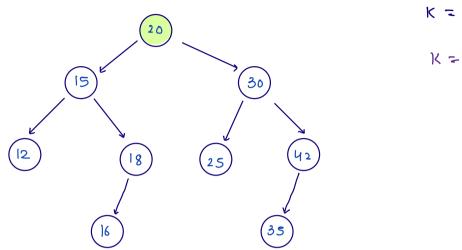


Scarch for K

o(h) Sc:

Tc: o(h) { travelling admax dength of longest branch3

0.1 biven root node of a BST, Search ij k exists or not.



K=28 (Jalse)
K=18 (toue)

```
search In BST ( Node node, int K) &
boolean
       if I node = = null) {
                                               Tc: o(h)
              octurn jalse;
        3
                                               SC: 0(h)
       ij (node. val = - K) }
              reduin true;
         3
         else ij (node. val < K) {
                 boolean va = Search In BST (node vight, K);
                 return sa;
          3
          else 3
                 boolean da = searchon BST (node. Jest, k);
                 return la;
           7
```

3

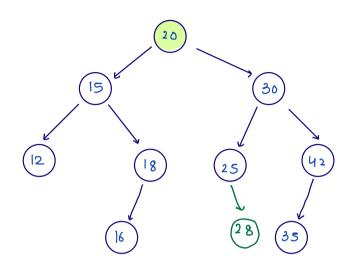
```
8a = F
boolean search In BST (Node node, int K) &
                                                                                         K-28
                                                                     20
   if I node = = nul) }
          octum jalse:
                                                                                        1a = F
                                                                                    30
                                                           15
   if (node. val = - K) }
          reduin true;
                                                  12
                                                                   18
    else if (node. val < K) {
            boolean Ta = SeaTch In BST (node Tight, K);
             return va;
     3
      else 3
            boolean la = search In BST (node. Jest, k);
             return la;
3
```

```
Ja=T
                                                                                         K=18
                                                                    20
boolean search In BST (Node node, int K) &
   if I node = = null) {
                                                               γa= T
                                                         15
                                                                                   30
          octurn jalse;
   ij (node. val = - K) }
           reduin true;
                                                 12
                                                                 18
    else if (node. val < 15) }
            boolean va = Search In BST (node vight, K);
                                                             16
             return sa;
      3
      else 3
            boolean la = search In BST (node. Jest, k);
             return la;
      7
3
```

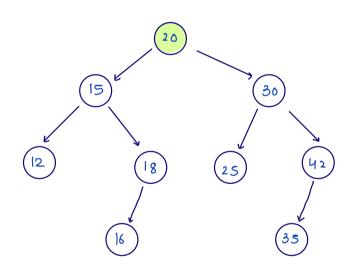
0.2 hiven root of a BST, insert node with data K in this BST.

(Insertion should be done

without shulling the existing node)



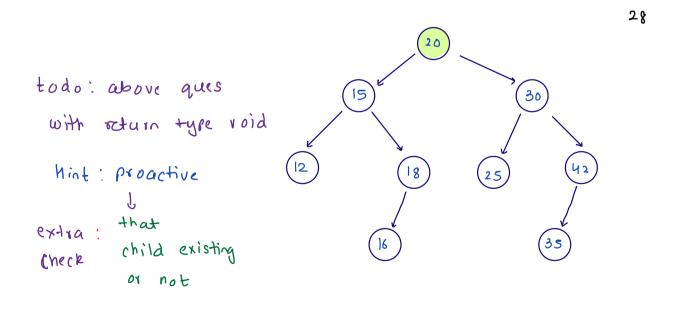
k = 28



k = 17

```
Node insert (Node node, in+ K) {
   if ( node = = nau) {
        Node nn = new Node (k);
         return nn;
    3
   ig(node.val == K) }
         return node; Il no need of work
    3
    else ij (node. val < 19) }
         Node ra = insert (node. right, K);
          node. right = ra;
          redurn node;
     3
     else 2
           Node da = insert (node. 14+, K);
           node- Jet = Ja;
           return node;
      3
3
```

```
K=17
       insert (node node, in+ k) {
Node
                                                                   Ja=(15
  if ( node = = nau) }
                                                               20
        Node nn = new Node (k);
        return nn;
                                                           ra = (8)
                                                      15
                                                                            30
  ij ( node . val = = K) }
        return node; Il no need of work
                                              12
    else if (node val < 10) }
         Node sa = insest (node. right, K);
         node. right = ra;
         redurn node;
     3
     else 2
          Node la - insert (node. let, K);
          node. Jet = Ja;
           return node;
      3
3
```

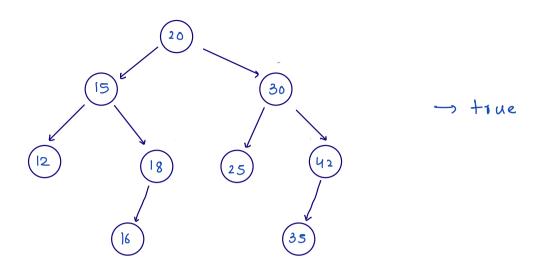


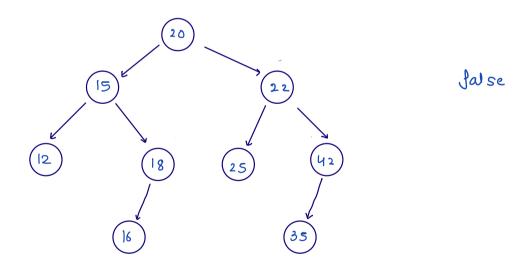
```
Dry run
```

3

```
K = 29
                                                                     1a = 30
                                                                 20
       insert (node node, in+ k) {
Node
  if ( node = = nall ) }
                                                                                  Ja=(25)
        Node nn = new Node (k);
                                                       15
        return nn;
   ij ( node . val = = K) }
        return node; Il no need of work
                                               12
    3
    else ij (node val < 14) }
         Node sa = insest (node. right, K);
         node. right = ra;
          redurn node;
     3
     else 2
          Node da = insert (node. 14+, K);
           node- Jet = Ja;
           return node;
      3
```

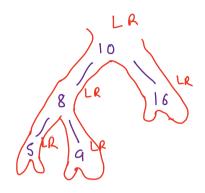
0.3 hiven root of a binary tree, theck if it is BST or not.





Ideal: fill the inorder of binary tree using inorder traversal, now check if this list is sooted or not.

AL < Integer > Wist = New AL <> ();



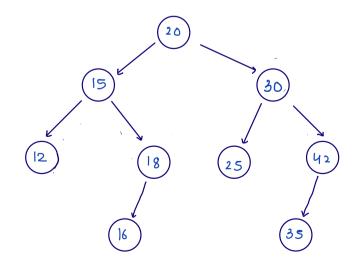
Wist: 5 8 9 10 16

Tc; o(n)

Sc:
$$O(h) + o(n) = > o(n)$$
 $\int_{-1}^{1} dx$
 $\int_{-1}^{1} dx$

List

can you do it by taking by recursion space?



PTEV=

In: LWR

Prev 2 node. val Good else ans=false

```
boolean ans = true;

int prov = -as;

void travel (Node node) ?

if (node == null) ?

return;

}

travel (node. Jett);

ans = false;

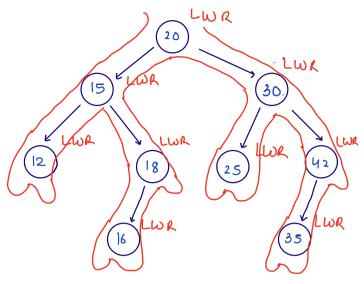
return;

return;

return;

3

Prev = node. val;
```



ans = true

```
boolean ans = true;

int prev = -0;

void trave (Node node) ?

ij (node == null) ?

return;

}

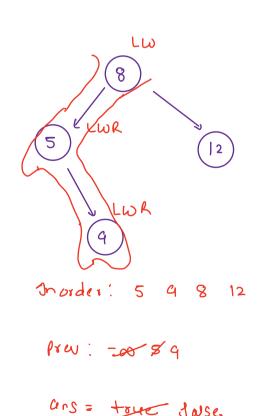
travel (node. Jet);

ans = Jalse;

return;

prev = node.val;
```

3



```
note: boolean solve (Node node) ?

ans = + sue;

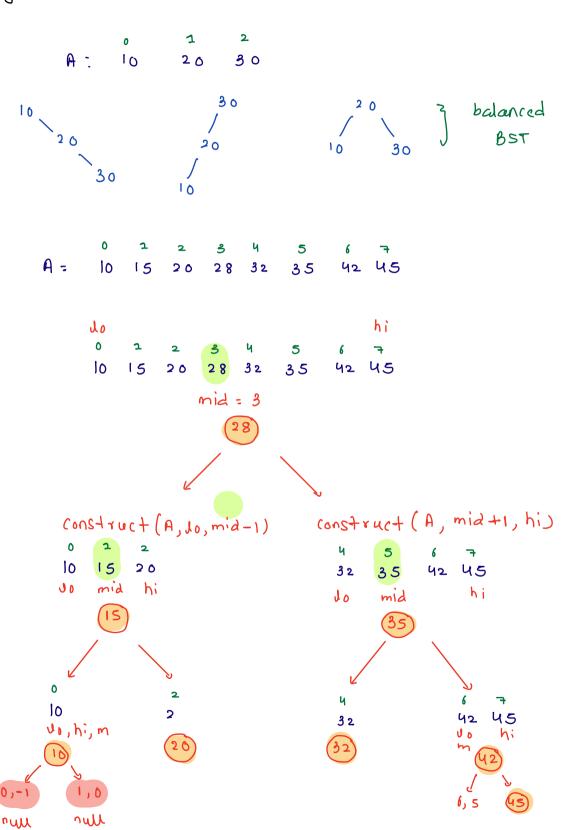
prev = -∞;

+ savel (node);

return ons;
```

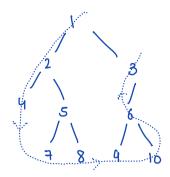
Jest should be strictly less than node.val and right should be strictly greater:

Ou triven a sosted array, construct balanced BST using this array and return its root node.



```
Node solve (int []A) ?
     return construct (A, O, A·lingth-1)'s
3
Node construct (int EDA, int do, int hi) }
        ij (10 > hi) {
             return null;
         3
        int mid = (lothi)/2;
        Node nn = nw Node (A[mid])
        nn. left = (onstruct (A, Jo, mid-1);
        nn. right = construct (A, midtl, hi);
         return nn;
5
```

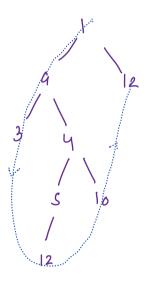
Doubts



lest boundary: 1 2

Jean nodes : 4 7 8 9 10

right boundary: 3 6 100 6 3



16: 1 9

Max: 3 12 10 12

16:

lest boundary Yord traver (Node node) ?

i) (node = = null) ? return3;

i) (node is nonlead)? ub. add (node.var)

i) (node - lest! = null)?

traver (node - lest);

else ?

traver (node - right);

3