Objective

Design a driver that can be used to configure an ADXL345 Accelerometer and read data from it using the **SPI** protocol.

SPI API Design

Initializing SPI

SPI Module: SPI1

Alternate function: *AF05*

1. Enable clock access to GPIO A.

- 2. Set pins to alternate function mode and set the alternate function to AF05.
- 3. Enable Clock access for SPI1 module. (APB2 bus).
- 4. Set it to master.
- 5. Set data size.
- 6. Set CPOL = 1 and CPHA = 1.
- 7. Set MSB first.
- 8. Set clock frequency.
- 9. Set NSS to software slave management.
- 10. Enable SPI1.

GPIO Configuration

SPI connection	GPIO pin	
NSS	PA4	
SCK	PA5	
MISO	PA6	
MOSI	PA7	

<u>SPI Mode</u>: CPOL = 1 and CPHA = 1(Refer to ADXL345 Datasheet)

Write function

Arguments

- 1. Data array.
- 2. Data size (Number of bytes).

Code design

- 1. Check if the bus is busy.
- 2. Ensure that TXE is set to 1.
- 3. Write first data item to transmit to the DR register.
- 4. Wait until TXE=1 and write the second data item to be transmitted.
- 5. After all data items are written ensure that TXE=1, Bus is free and clear OVR flag.

The software must ensure that the TXE flag is set to 1 before attempting to write to the Tx buffer. Otherwise, it overwrites the data previously written to the Tx buffer.

Read function

<u>Arguments</u>

- 1. Data array.
- 2. Data size (Number of bytes).

Code design

- 1. Check if the bus is busy??
- 2. Wait until RXNE=1 and read DR to get data.

ADXL345 API Design

Initializing ADXL345

- 1. Initialize SPI1.
- 2. Set data format to +/- 4g.
- 3. Reset all bits.
- 4. Set ADXL to measuring mode.

Writing to ADXL345

Function arguments

- 1. Memory address
- 2. Data

Code design:

- 1. Set the multiple-byte bit, located after the R/W bit in the first byte transfer for multi-byte read/write in a single transmission, (Refer to Figure 37 in ADXL345 datasheet).
- 2. Pull CS low.
- 3. Call SPI write function.
- 4. Pull CS high.

Reading from ADXL345

Arguments:

- 1. Memory address.
- 2. Data.

Code design:

- 1. Set R-bit and multiple byte bits.
- 2. Pull CS low.
- 3. Send address.
- 4. Read data (6 bytes).
- 5. Pull CS high.

SPI and ADXL345 API interaction sequence diagram

