

ARTIFICIAL NEURAL NETWORK

Unit-2: Perceptron

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BPA: Heuristics to make performance better

Sequential v/s Batch mode:

- For large data sequential processing is faster
- For smaller data and network, batch processing is faster
- Maximizing the information content
- Every traning example presented to the BPA should be choosen on the basis that its information content is the largest possible for the task at hand
- This can be achieved in 2 ways
 - a. use of an example that results in the largest traing error
 - b. the use of example that is radially different from all those previously used



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Activation Function:

• A M.L.P trained with the back-propagation algorithm may, in general, learn faster when the asymmetric sigmoidal activation function are used in neuron model, for example tanh(.).

Target Value: it is important to choose the target value within the activation function range i.e +1 and -1

Normalization of the inputs:

The training samples must be preprocessed before presenting to the neural network. the preprocessing steps are

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- a. subtracting each input from mean
- b.decorrelate the training samples
- c. covariance: it ensures the different synaptic weight in the networks learn at same speed.

Learning Rate

Initialization

Artificial Neural Network-Perceptron BPA-Output representation and decision rule

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Consider a M-class classification problems, which means each input pattern belong to one of the M-distinct classes.

Therefore, we will have M number outputs in the network.



Xj denotes the jth input pattern. and it is m-dimensional input vector

The output is M-dimensional vector. ykj is the kth ouput of network in correspondence to the jth input

BPA-Output representation and decision rule



Therefore, block diagram can be repressented as

$$y_{kj} = F_k(x_j)$$

Let the output vector y_i

$$y_{j} = \begin{bmatrix} y_{1j} & y_{2j} & \dots & y_{kj} & \dots & y_{Mj} \end{bmatrix}^{T}$$

$$y_{j} = \begin{bmatrix} F_{1}(x_{j}) & F_{2}(x_{j}) & \dots & F_{k}(x_{j}) & \dots & F_{M}(x_{j}) \end{bmatrix}^{T}$$

$$y_{j} = F(x_{j})$$

BPA-Output representation and decision rule



F(.) is continuous function and minimizes the emprical risk function

$$R = \frac{1}{2N} \sum_{j=1}^{N} \|d_{j} - F(x_{j})\|^{2}$$

Now train the network with binary values as follows:

- The output space has M dimension
- An input Xj belongs to class Ck
- let d_k=1 when Xj belongs to class C_k otherwise 0

Output Decision Rule stated as follows:

Classify the random vector X as belonging to C_k if

 $F_k(X) > F_i(X)$ for all $k \neq j$



THANK YOU

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