Lab 1
ICS423 - Internet of Things

Jayant Kolapkar - 2021BCS0132

Question

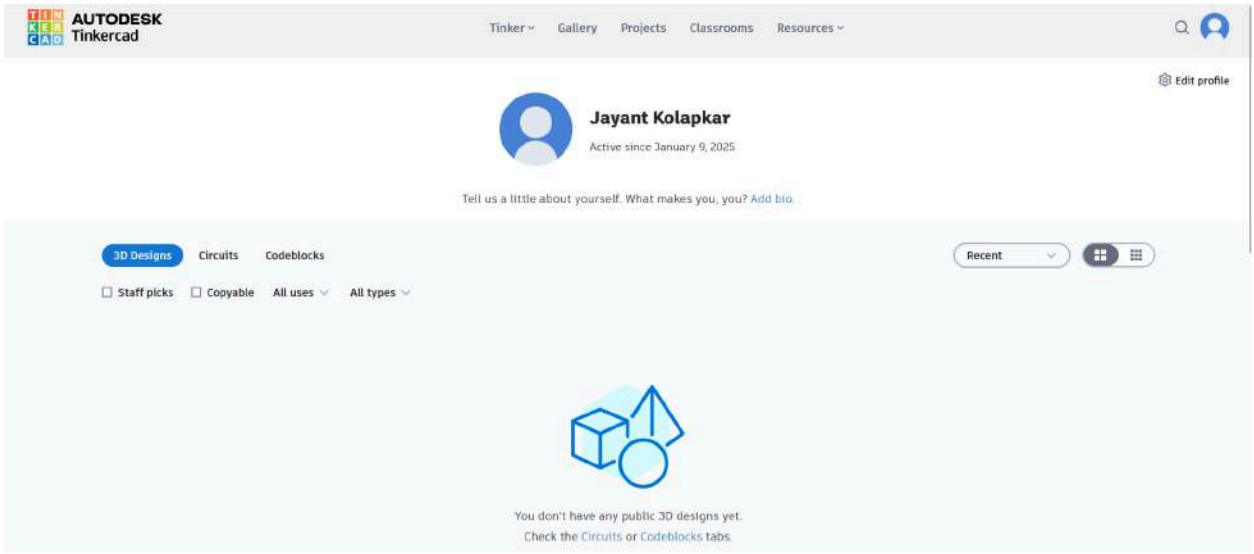
Task 1: Create an account in Tinkercad.

Task 2: Explore IoT components using Tinkercad circuits.

Task 3: Explore an LED blink exercise using Tinkercad circuits.

Task 1

Sign up to TinkerCAD using email.

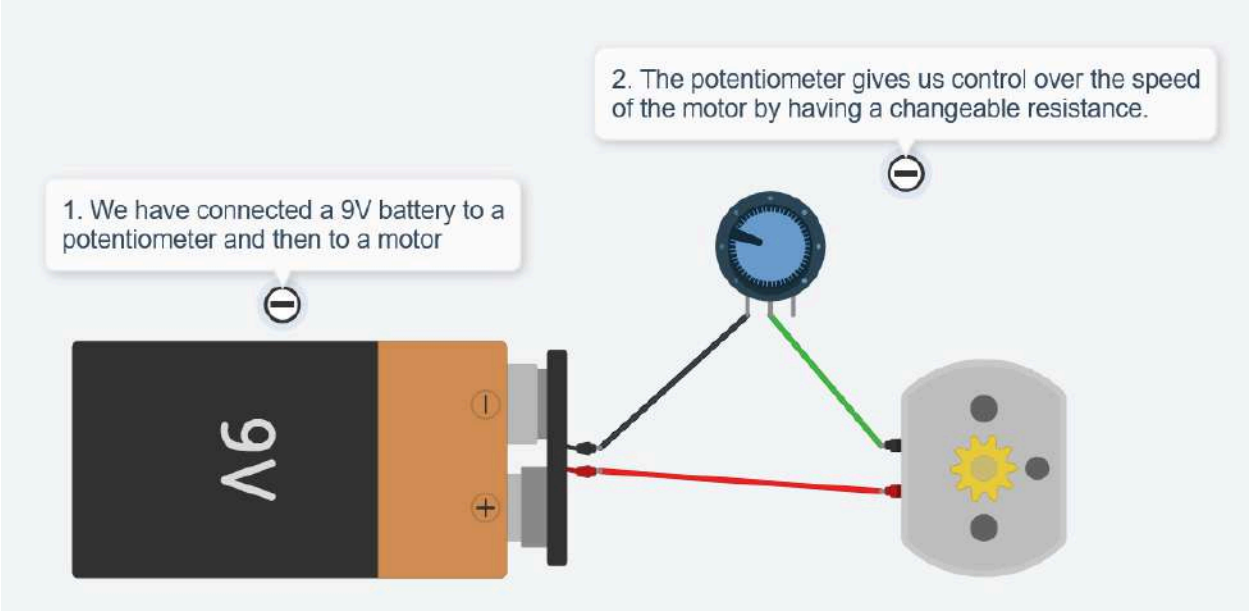


Task 2

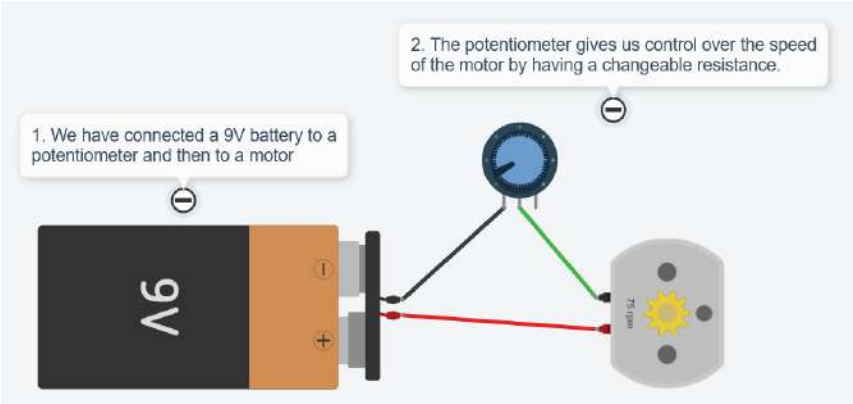
We made a simple circuit to control the speed of a DC motor using a potentiometer.

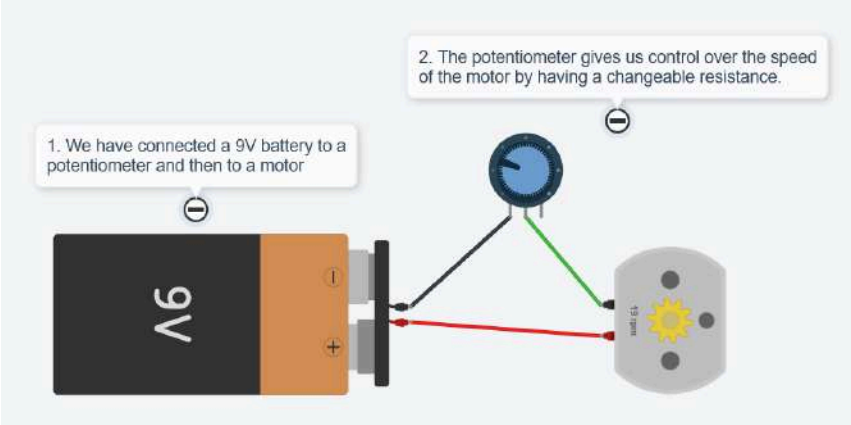
1. **Power Source:** A 9V battery provides the electrical energy to power the motor.
2. **Potentiometer:** This variable resistor acts as a voltage divider. By turning the knob, you change the resistance, which in turn adjusts the voltage supplied to the motor.
3. **Motor:** The DC motor receives the variable voltage from the potentiometer. As the voltage increases, the motor spins faster. Conversely, decreasing the voltage slows down the motor.

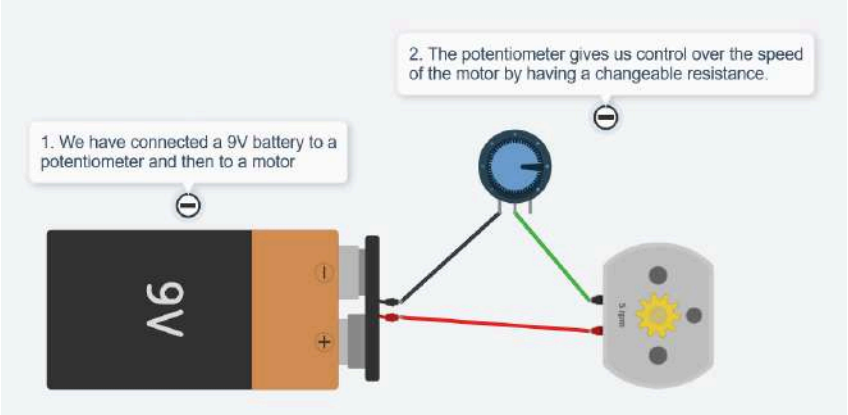
In essence, the potentiometer acts as a speed controller for the motor, allowing us to fine-tune its rotation speed.



Output for various settings







Task 3

We use Arduino UNO, breadboard and LED to make the LED light up and turn off repeatedly. We connect the LED to the Arduino board using wires and a resistor. The Arduino has a tiny program that tells it to

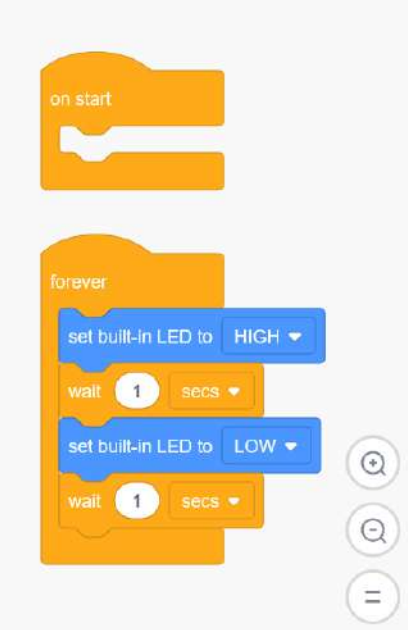
- Turn the LED on for a short time.
- Turn the LED off for a short time.
- Repeat these steps over and over.

The resistor protects the LED from getting too much electricity.

In essence, the Arduino acts like a tiny brain that controls the LED's on/off behavior.

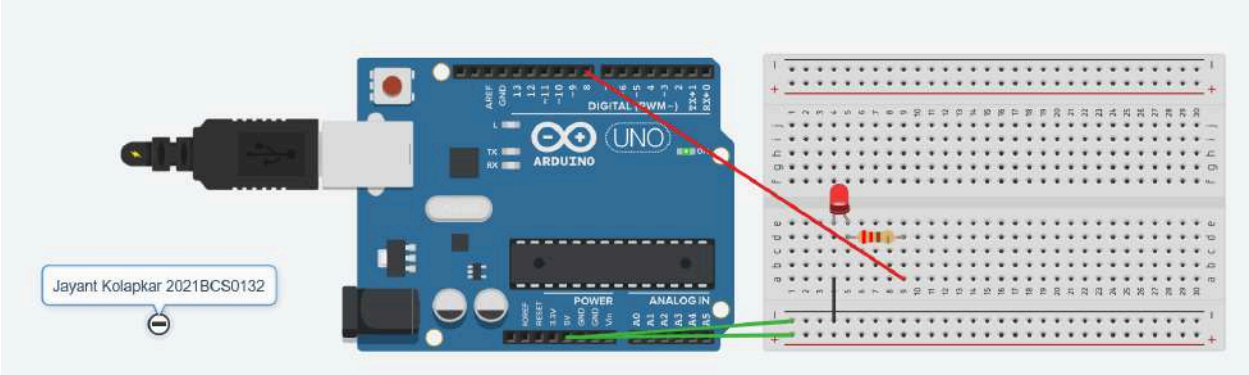
Code

```
void setup()
{
  pinMode(LED_BUILTIN, OUTPUT);
}

void loop()
{
  digitalWrite(LED_BUILTIN, HIGH);
  delay(1000); // Wait for 1000 millisecond(s)
  digitalWrite(LED_BUILTIN, LOW);
  delay(1000); // Wait for 1000 millisecond(s)
}
```

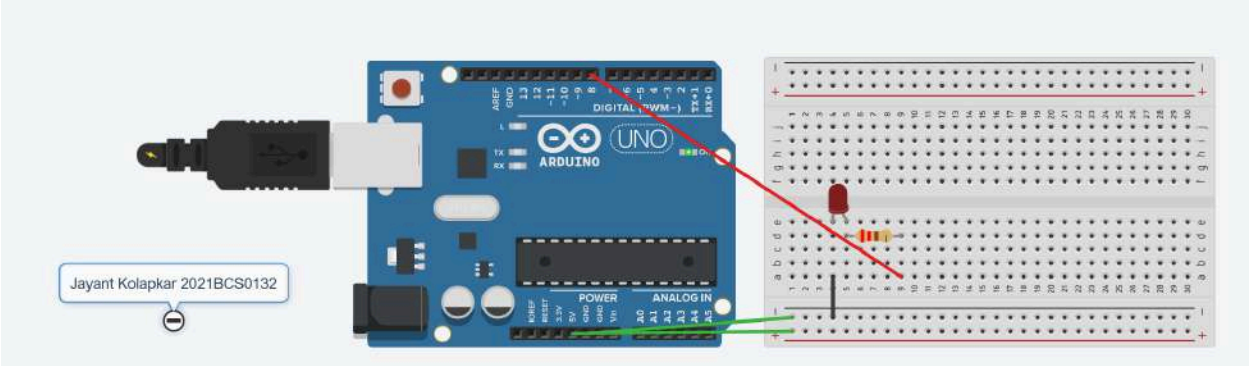


Output

Blinking on



Blinking off



Lab 2
ICS423 - Internet of Things

Jayant Kolapkar - 2021BCS0132

Question

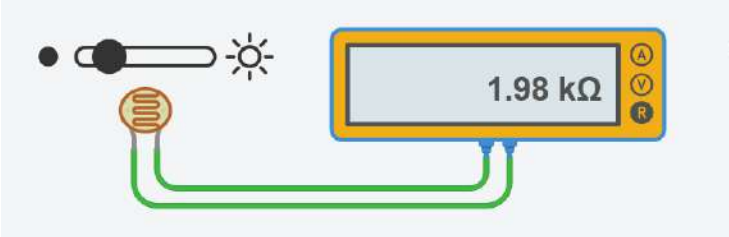
Task 1: Explore the application of sensors or actuators (atleast 4 from Tinkercad circuits)

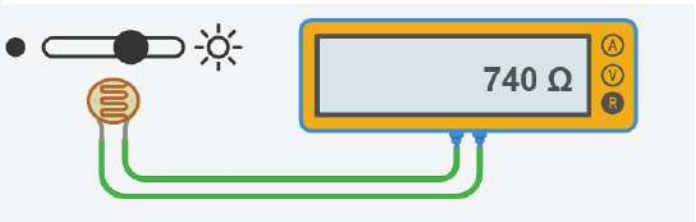
Task 2: Switch ON a bulb based on the light intensity using Tinkercad circuits.

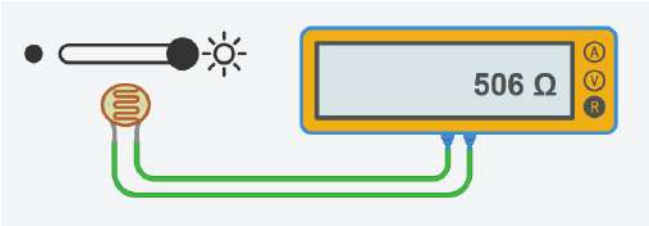
Task 1

1. Light Dependent Resistor (LDR) - Sensor

Description: The LDR detects light intensity and adjusts circuit behavior based on ambient lighting conditions. It is used for energy-saving devices like automatic streetlights.
Application: In this circuit, the LDR turns on a bulb when the light intensity falls below a threshold and turns it off when the intensity increases.

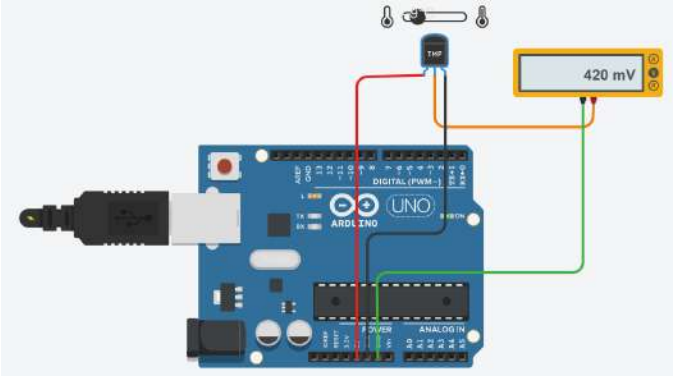


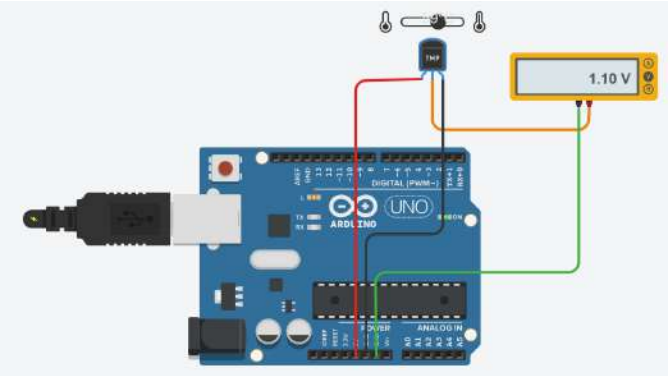


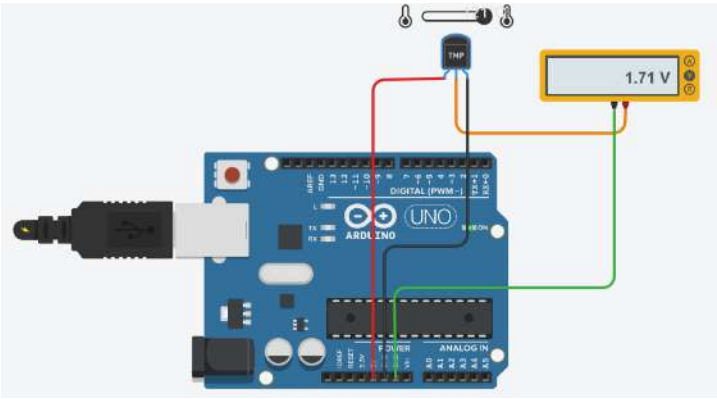


2. Temperature Sensor - Sensor

Description: A temperature sensor detects the surrounding temperature and converts it into a readable analog signal. It's useful in thermostats and weather monitoring systems.
Application: In this circuit, the temperature sensor provides analog readings to indicate environmental temperature, which can control heating or cooling devices.

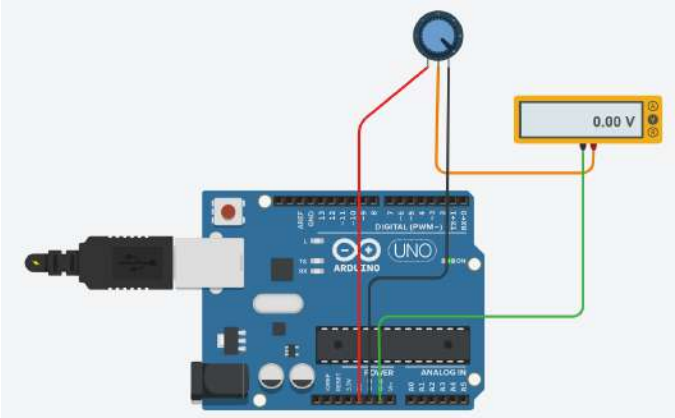


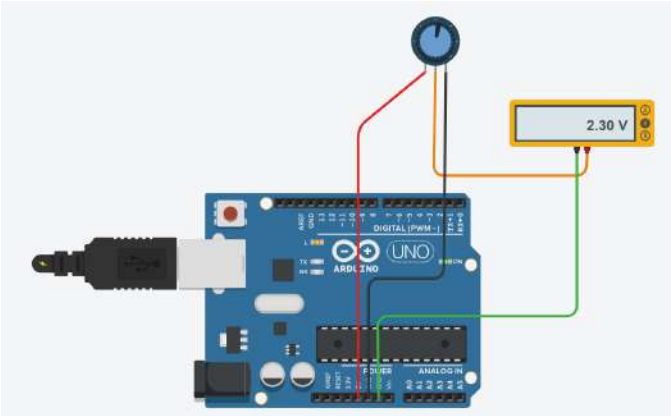


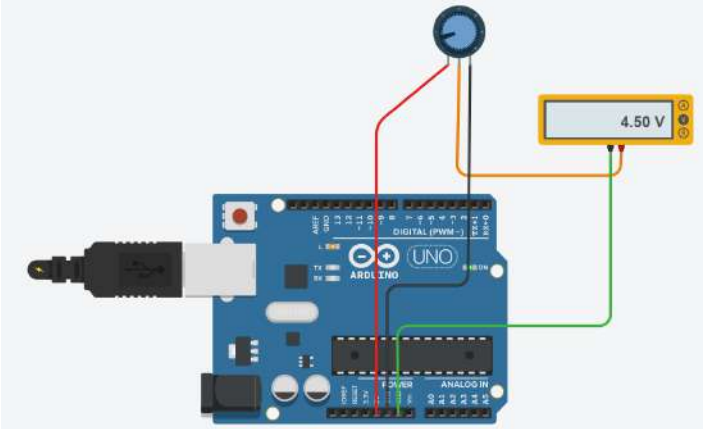


3. Potentiometer - Sensor/Controller

Description: A potentiometer is a variable resistor used to manually adjust the resistance in a circuit, providing control over voltage or current. It's commonly used in devices like volume knobs or brightness controls.
Application: In this setup, the potentiometer simulates an adjustable analog input, which can control the brightness of an LED.







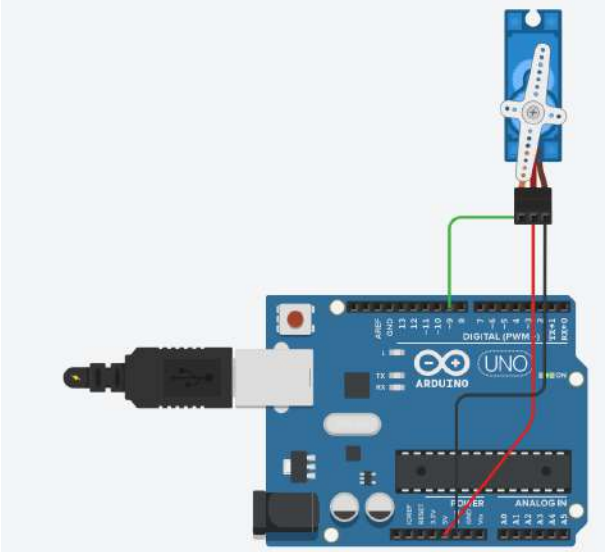
4. Servo Motor - Actuator

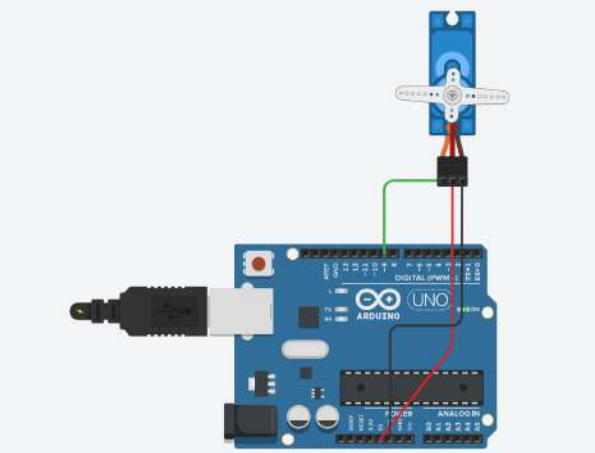
Description: A servo motor is an actuator capable of precise angular movement. It's widely used in robotics, home automation, and control systems.
Application: The servo motor rotates to specific angles (0°, 90°, and 180°) to demonstrate control and movement capabilities. This can simulate turning dials or opening/closing mechanisms.

Code

```
#include <Servo.h>
Servo myServo;

void setup() {
  myServo.attach(9); // Attach servo to pin 9
}

void loop() {
  myServo.write(0);   // Rotate to 0 degrees
  delay(1000);
  myServo.write(90);  // Rotate to 90 degrees
```

```
  delay(1000);
  myServo.write(180); // Rotate to 180 degrees
  delay(1000);
}
```





Task 2

In this lab, we will simulate an **Arduino-based light intensity lamp** using Tinkercad Circuits. The objective is to turn on a light bulb when the light intensity is low and turn it off when the light intensity is high, helping conserve energy.

Overview

The system uses an **LDR (Light Dependent Resistor)** to detect light intensity and control a light bulb accordingly. A relay is employed to handle the power difference between the bulb (120V) and the Arduino (5V).

Required Components

1. **LDR** (Light Dependent Resistor): To detect light and dark conditions.
2. **Arduino Microcontroller**: To process the input from the LDR and control the output.
3. **Light Bulb**: The output device that turns ON or OFF based on light intensity.
4. **Relay**: To switch the light bulb since it operates at a higher voltage.
5. **Power Source**: To supply power to the circuit.
6. **Breadboard** (Optional but recommended): For easier and cleaner wiring.

Instructions

Step 1: Setup the Circuit

- Open Tinkercad and create a new circuit project.
- Drag all the required components (LDR, Arduino, relay, light bulb, power source, and optional breadboard) into the workspace.

Step 2: Arrange Components

- Place the components on the breadboard for better organization and easy wiring. Position the Arduino, LDR, relay, and light bulb logically to minimize clutter.

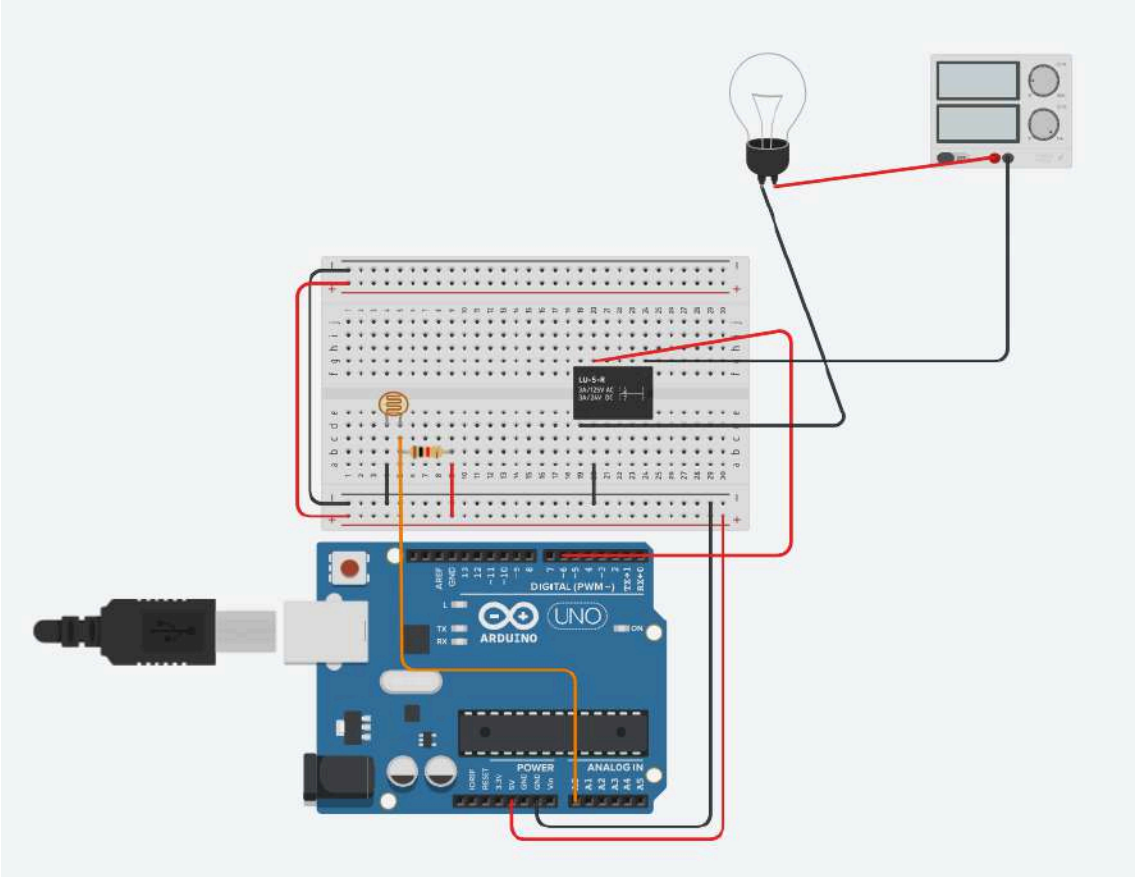
Step 3: Connect the Wires

A. Wiring the Relay and Light Bulb

1. Connect the **5V pin** of the Arduino to the **power rail** on the breadboard.
2. Connect the **GND pin** of the Arduino to the **ground rail**.
3. Attach the **positive terminal** of the power source to **Terminal 2** of the light bulb.
4. Connect the **negative terminal** of the power source to **Terminal 1** of the relay.
5. Link the **negative terminal** of the light bulb to **Terminal 7** of the relay.
6. Connect **Terminal 8** of the relay to the **ground rail**.
7. Finally, connect **Terminal 5** of the relay to any **digital pin** on the Arduino.

B. Wiring the Photoresistor

1. Connect **Terminal 1** of the LDR to the **ground rail**.
2. Connect **Terminal 2** of the LDR to an **analog pin** on the Arduino (e.g., A0) and to the **power rail** using a **1kΩ resistor**.

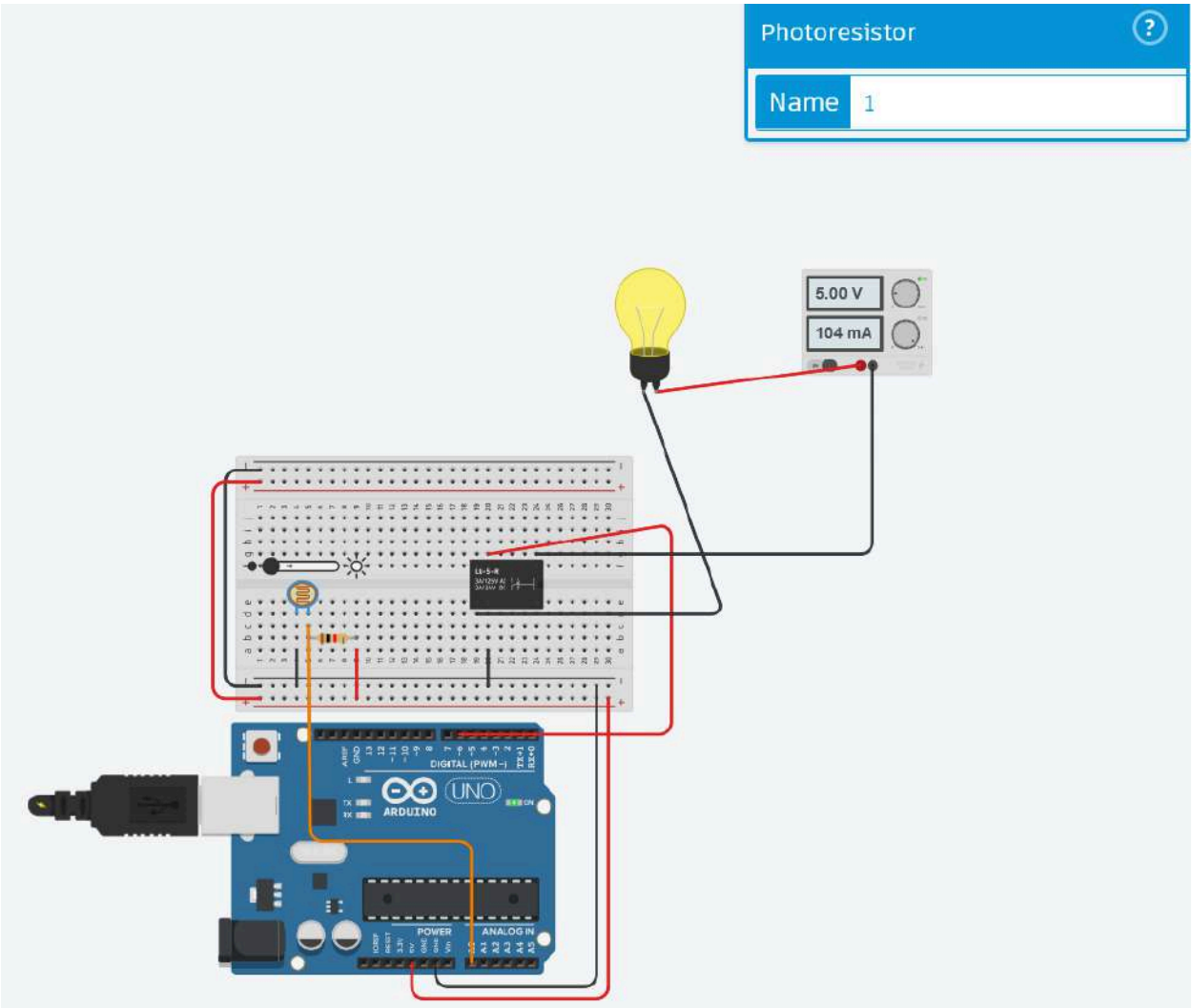


Code

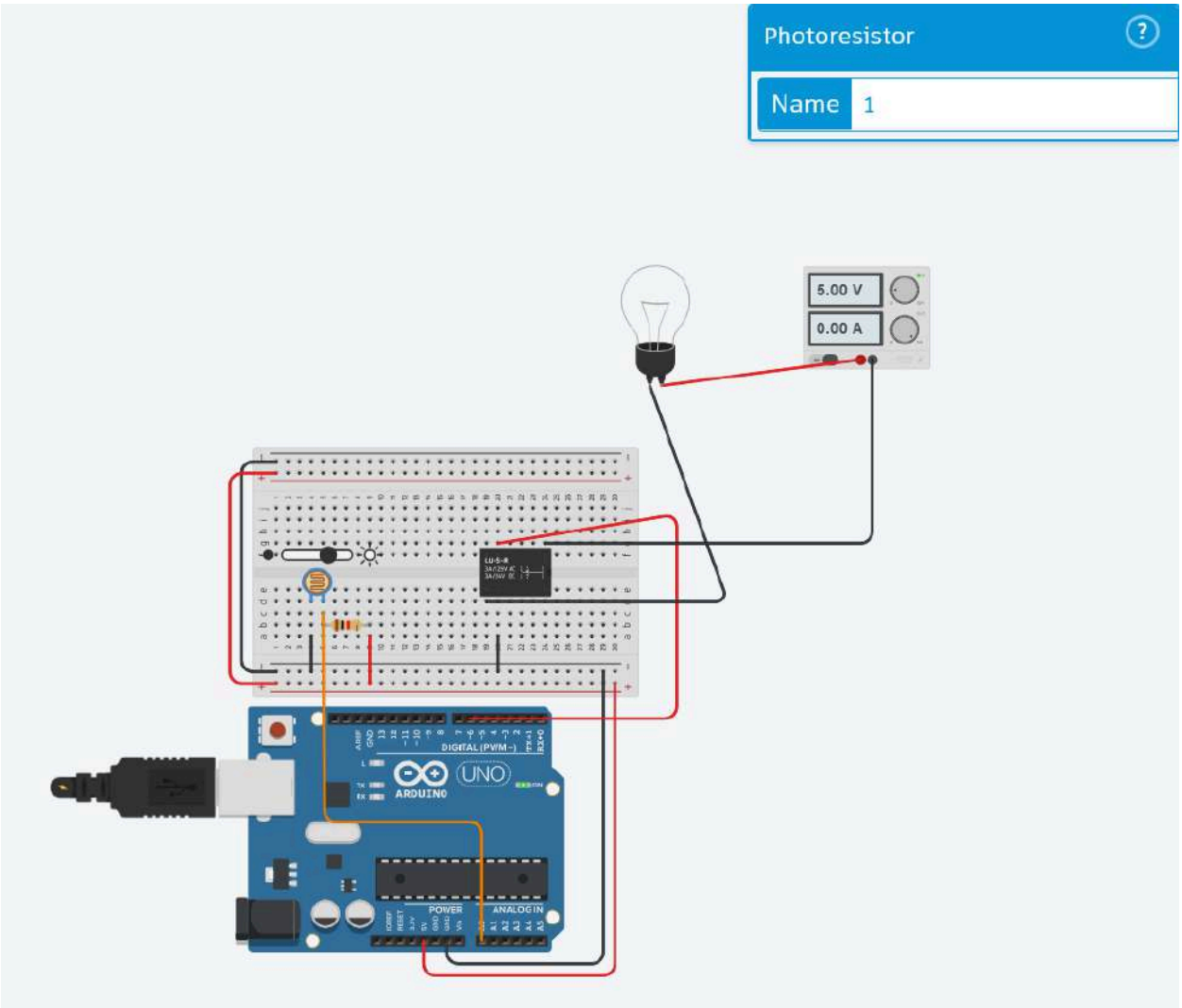
```
void setup()
{
  pinMode(A0, INPUT);
  pinMode(6, OUTPUT);
}

void loop()
{
    Serial.println(analogRead(A0));
  if (analogRead(A0) > 500)
    {
        digitalWrite(6, LOW);
    }
  else
    {
      digitalWrite(6, HIGH);
    }
    delay(10);
}
```

Output

LDR in low light



LDR in high light



We can see the behavior of the circuit for different light conditions. The light bulb will automatically turn ON when the light intensity drops and turn OFF when the light intensity rises, simulating an energy-efficient system for real-world applications.

Lab 3
ICS423 - Internet of Things

Jayant Kolapkar - 2021BCS0132

Question

Task 1 : write a sketch that uses 10 LED strips (make the 10 LEDs to blink).

Task 2: Write a sketch that sequentially blinks LED strips (20 numbers) in three different colors.

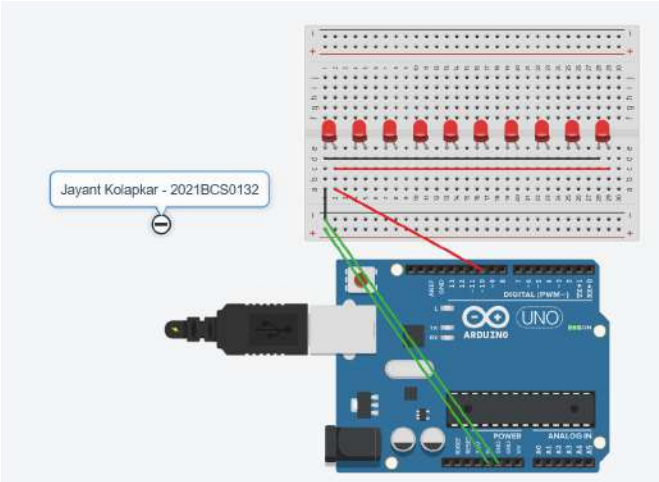
Task 3: Identify a unique pattern to blink LED strips to use in your study room.

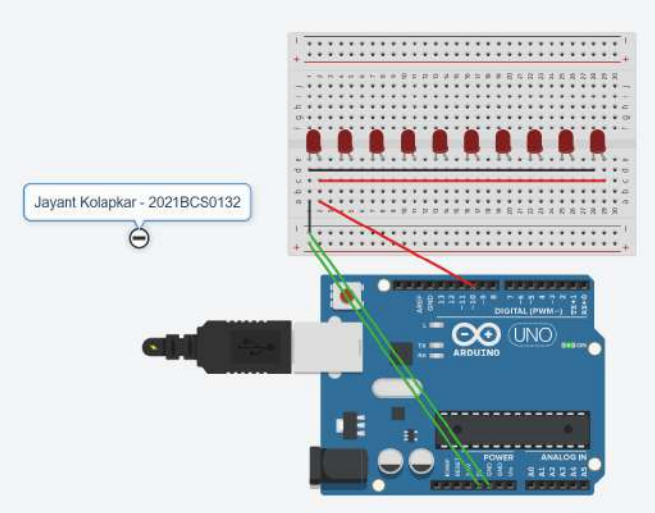
Task 1

Code

```
int ledPin=10; //definition digital 8 pins as pin to control the LED
void setup()
{
    pinMode(ledPin,OUTPUT);     //Set the digital 8 port mode, OUTPUT:
Output mode
}
void loop()
{
    digitalWrite(ledPin,HIGH); //HIGH is set to about 5V PIN8
    delay(1000);               //Set the delay time, 1000 = 1S
    digitalWrite(ledPin,LOW);  //LOW is set to about 5V PIN8
    delay(1000);               //Set the delay time, 1000 = 1S
}
```

Output





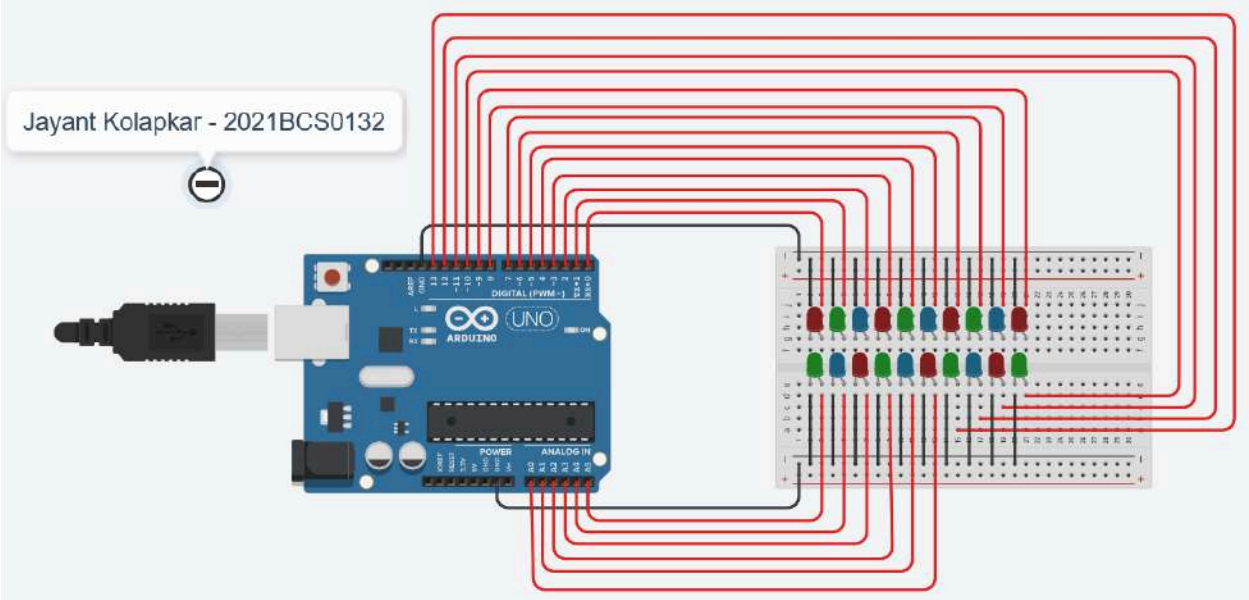
Task 2

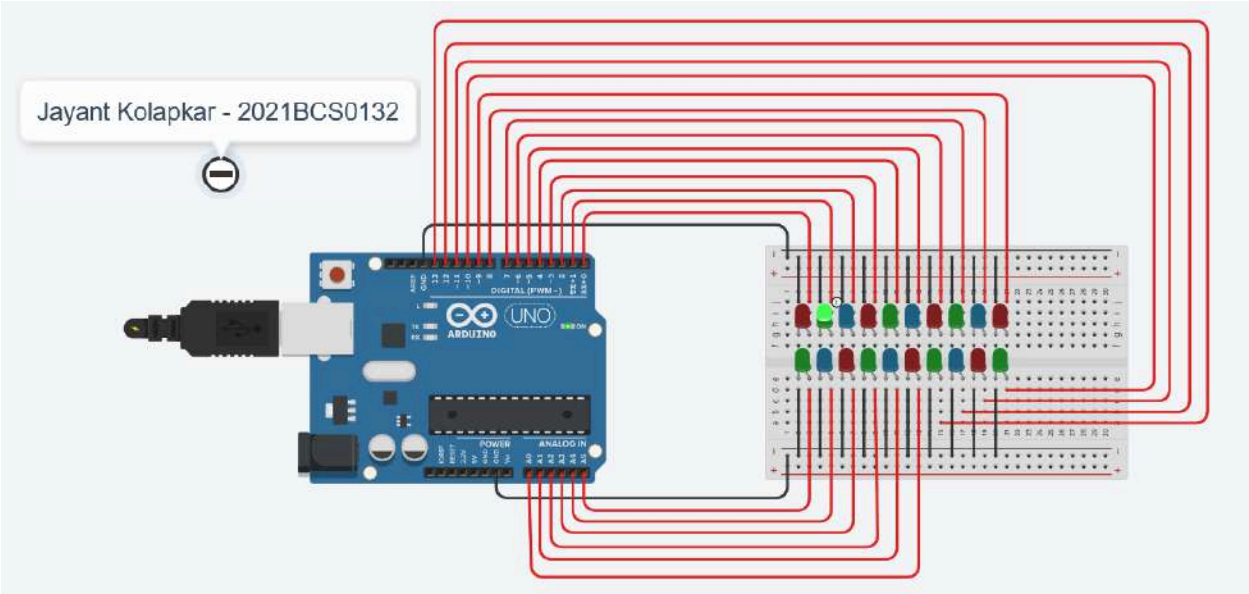
Code

```
void setup()
{
  for (int pin = 0; pin <= 13; pin++)
  {
    pinMode(pin, OUTPUT);
  }
  for (int pin = A0; pin <= A5; pin++)
  {
    pinMode(pin, OUTPUT);
  }
}
void loop()
{
  for (int pin = 0; pin <= 13; pin++)
  {
    digitalWrite(pin, HIGH);
    delay(1000);
    digitalWrite(pin, LOW);
```

```
  }
  for (int pin = A0; pin <= A5; pin++)
  {
    digitalWrite(pin, HIGH);
    delay(1000);
    digitalWrite(pin, LOW);
  }
}
```

Output

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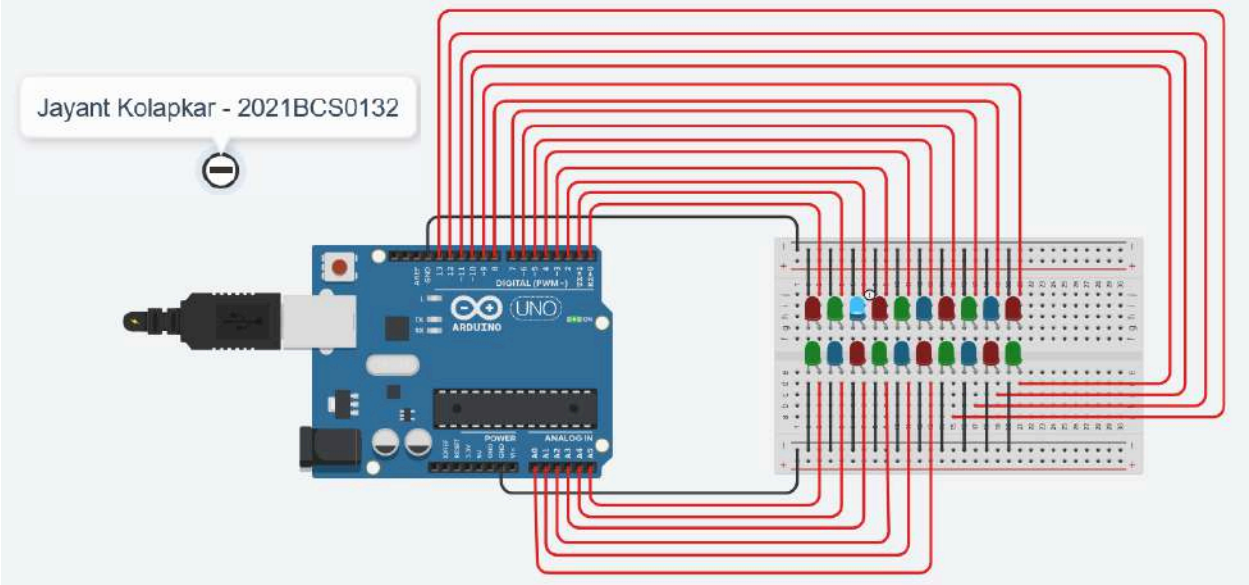
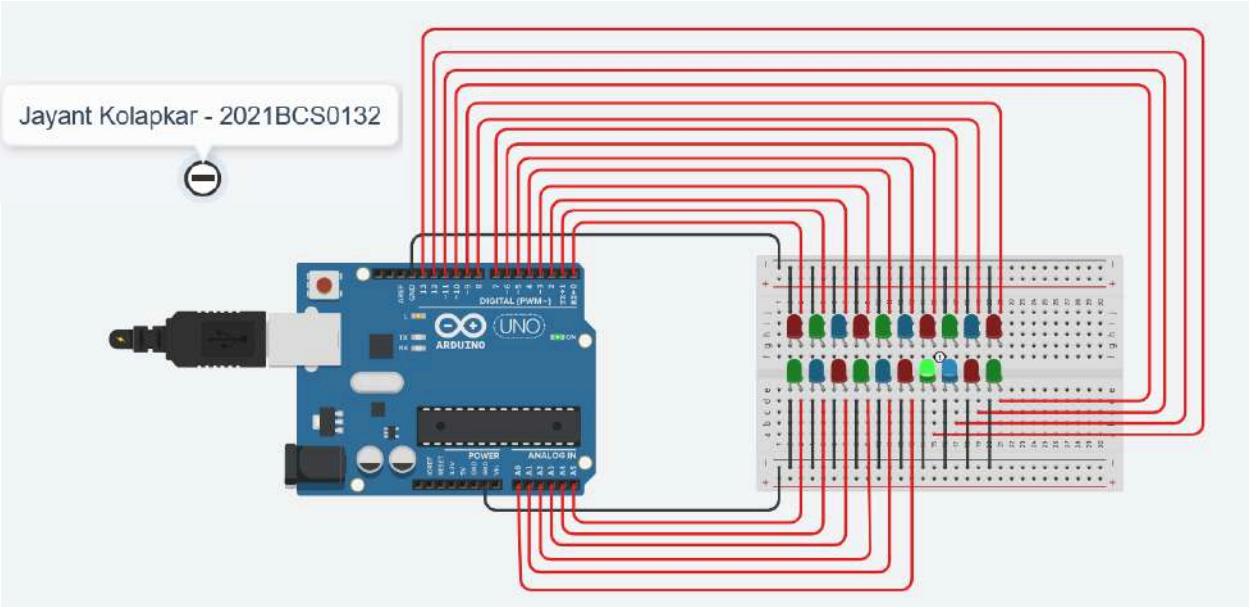
DIGITAL (PWM~)
UNO
ARDUINO
POWER
ANALOG IN


Jayant Kolapkar - 2021BCS0132
DIGITAL (PWM~)
UNO
ARDUINO
POWER
ANALOG IN

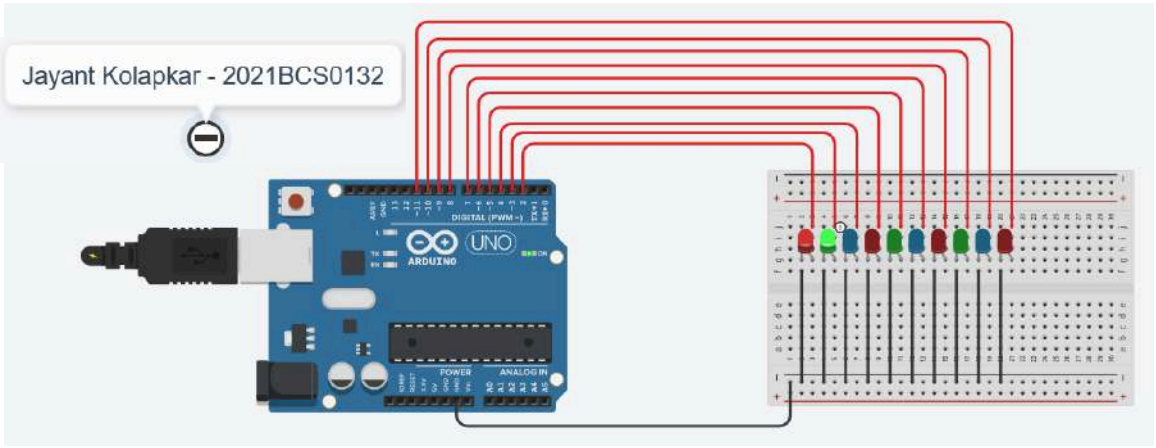

Jayant Kolapkar - 2021BCS0132
DIGITAL (PWM~)
UNO
ARDUINO
POWER
ANALOG IN

Task 3

Code

```
void setup()
{
  for (int i = 2; i < 12; i++)
  {
    pinMode(i, OUTPUT);
  }
}
void loop()
{
  for (int k = 0; k < 10; k++)
  {
    for (int i = 2; i < 12; i++)
    {
      for (int j = i; j <= min(i + k, 11); j++)
        digitalWrite(j, 1);
      delay(500);
      for (int j = i; j <= min(i + k, 11); j++)
        digitalWrite(j, 0);
    }
  }
}
```

Output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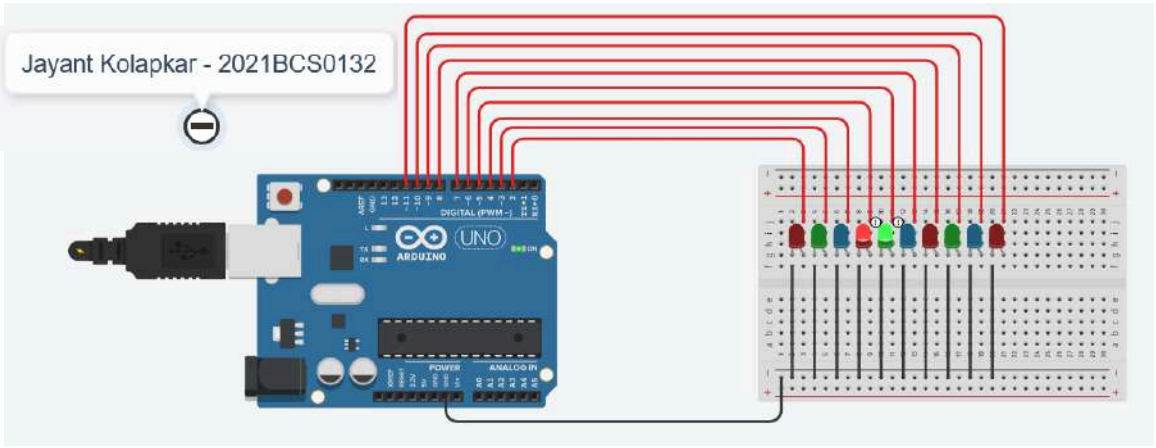
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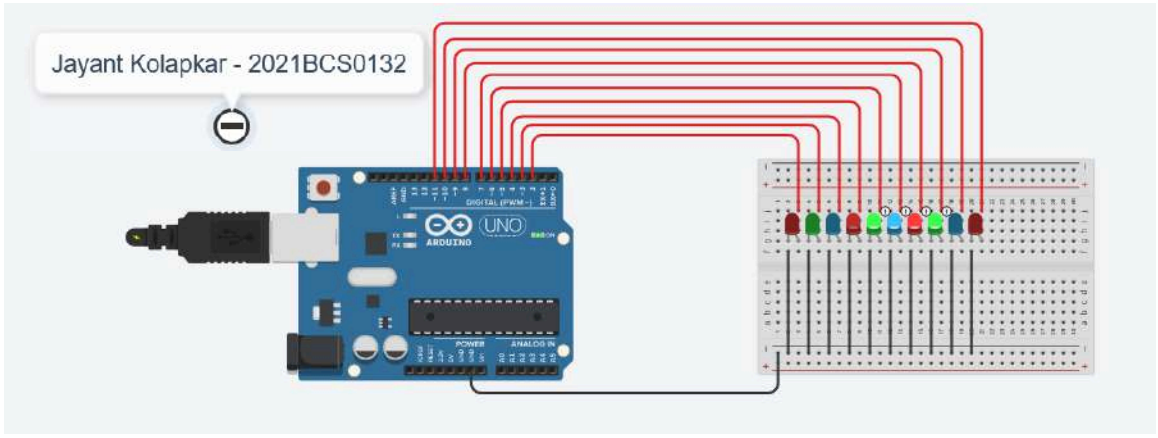
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Lab 4

ICS423 - Internet of Things

Jayant Kolapkar - 2021BCS0132

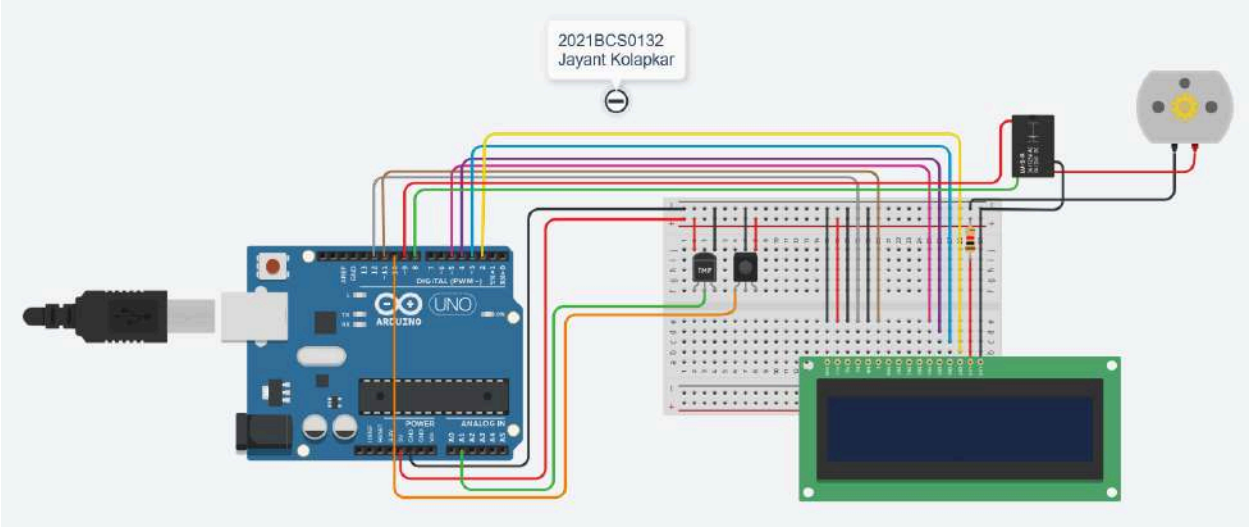
Question

Task 1: Assume that three blades of a fan are connected to a rotary motor. Design an IoT system that automatically controls the speed of the fan based on the input temperature.

Task 2: Assume a DC motor is used to pump water. Design an irrigation system that pumps water to three water channels based on the soil moisture content of those locations.

Task 1

Diagram



Code

```
#include <LiquidCrystal.h>

LiquidCrystal lcd(12, 11, 5, 4, 3, 2);

float temp;
int tempPin = A1;
```

```
int relayPin = 8;

#define fan 9

void setup(){
  pinMode(fan, OUTPUT);
    pinMode(relayPin, OUTPUT);

    lcd.begin(16, 3);

    lcd.setCursor(1, 1);
    lcd.print("2021BCS0132");
    delay(1000);
    lcd.clear();
    lcd.setCursor(3,0);
    lcd.print("Jayant Kolapkar");
    delay(1000);
    lcd.clear();
    lcd.print("AUTO TEMPERATURE");
    delay(2000);
    lcd.clear();

}

void loop()
{
  lcd.setCursor(3,0);
    lcd.print("Recording");
  lcd.setCursor(2, 1);
  lcd.print("Temperature..");
  delay(3000);
  lcd.clear();
  lcd.setCursor(0,2);
  temp = analogRead(tempPin);
  //temp = temp*0.48828125;
  float voltage = temp * 5.0;
```

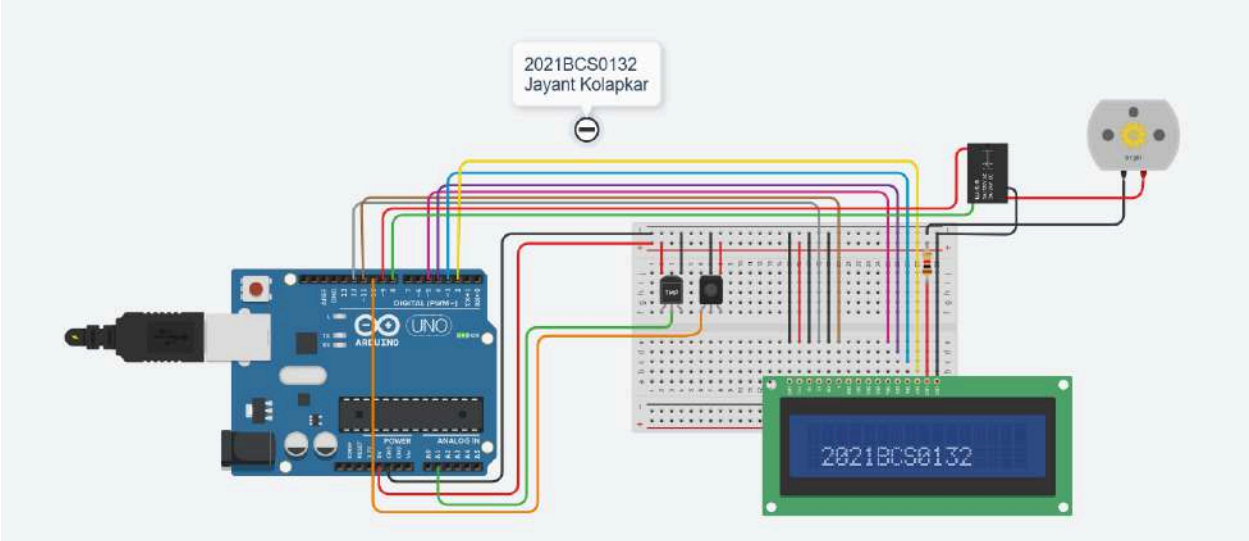
```
  voltage /= 1024.0;

  // print out the voltage
  lcd.print(voltage); lcd.println(" volts");

  // now print out the temperature
  float temperatureC = (voltage - 0.5) * 100 ;  //converting from 10 mv
per degree wit 500 mV offset
                                                //to degrees ((voltage -
500mV) times 100)

  lcd.setCursor(0, 0);
  lcd.print("Temperature = ");
  lcd.setCursor(2,1);
  //lcd.print(temp);
  lcd.print(temperatureC); lcd.println(" degrees C");
  delay(3000);
  lcd.clear();

  if(temperatureC >= 20)
  {
    poweronRelay();
    if(temperatureC >= 20 && temperatureC <= 25)
    {
      analogWrite(fan,51);
      lcd.print("Fan Speed: 20% ");
      delay(2000);
      lcd.clear();
    }
    else if(temperatureC <= 35)
    {
      analogWrite(fan,102);
      lcd.print("Fan Speed: 40% ");
      delay(2000);
      lcd.clear();
    }
```

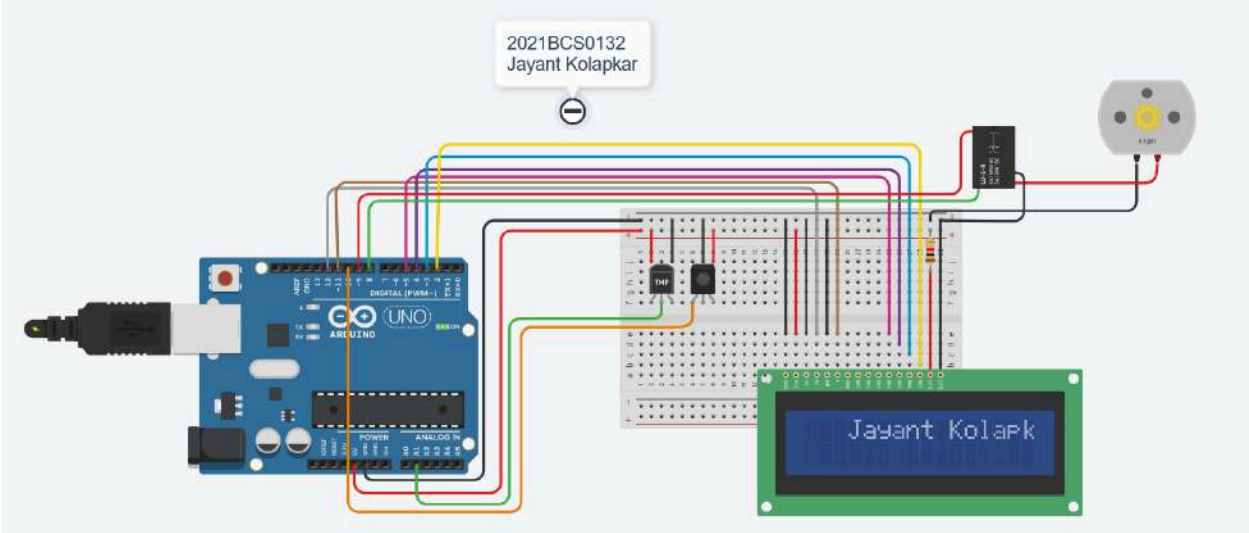
```
    else if(temperatureC <= 40)
    {
      analogWrite(fan,153);
      lcd.print("Fan Speed: 60% ");
      delay(2000);
      lcd.clear();
    }
    else if(temperatureC <= 44)
    {
      analogWrite(fan,200);
      lcd.print("Fan Speed: 80% ");
      delay(2000);
      lcd.clear();
    }
    else if(temperatureC >= 45)
    {
      analogWrite(fan,255);
      lcd.print("Fan Speed: 100% ");
      delay(2000);
      lcd.clear();
    }
  }
  else if(temperatureC < 20)
  {
    poweroffRelay();
  }


}

void poweronRelay()
  {
    digitalWrite(relayPin, HIGH);
    lcd.print("Fan ON");
    delay(2000);
    lcd.clear();
```

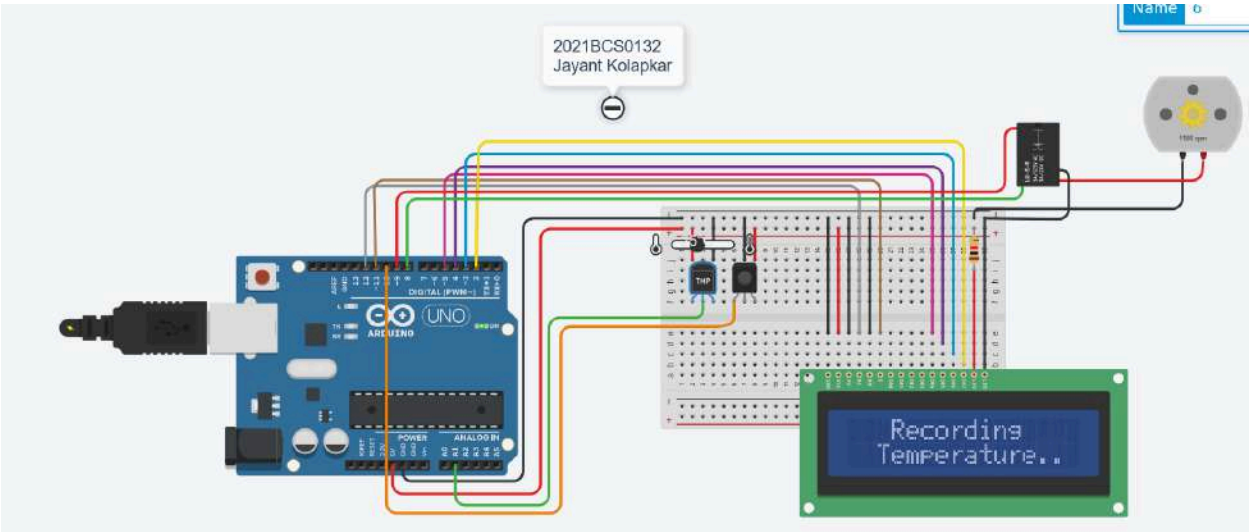
```
  }

void poweroffRelay()
  {
    digitalWrite(relayPin, LOW);
    analogWrite(fan,0);
    lcd.print("Fan OFF");
    delay(2000);
    lcd.clear();
  }
```

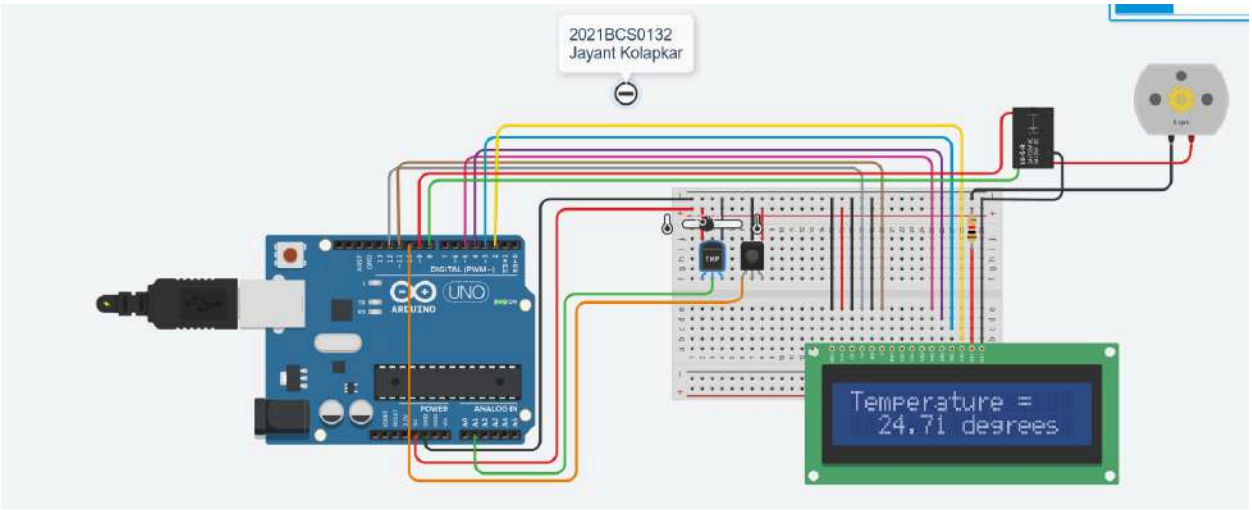
The system continuously reads temperature data from the analog sensor connected to pin A1. The raw analog values are converted into voltage, which is further translated into temperature in Celsius. The measured temperature is displayed on the LCD along with real-time updates. Based on the recorded temperature, the system adjusts the fan speed accordingly. If the temperature is **20°C or higher**, the relay is activated, and the fan is turned on with varying speeds. The fan operates at **20% speed** between **20°C and 25°C**, **40% speed** between **25°C and 35°C**, **60% speed** between **35°C and 40°C**, **80% speed** between **40°C and 44°C**, and at **full speed (100%)** for temperatures **45°C and above**. Each speed change is displayed on the LCD before being cleared for the next reading.

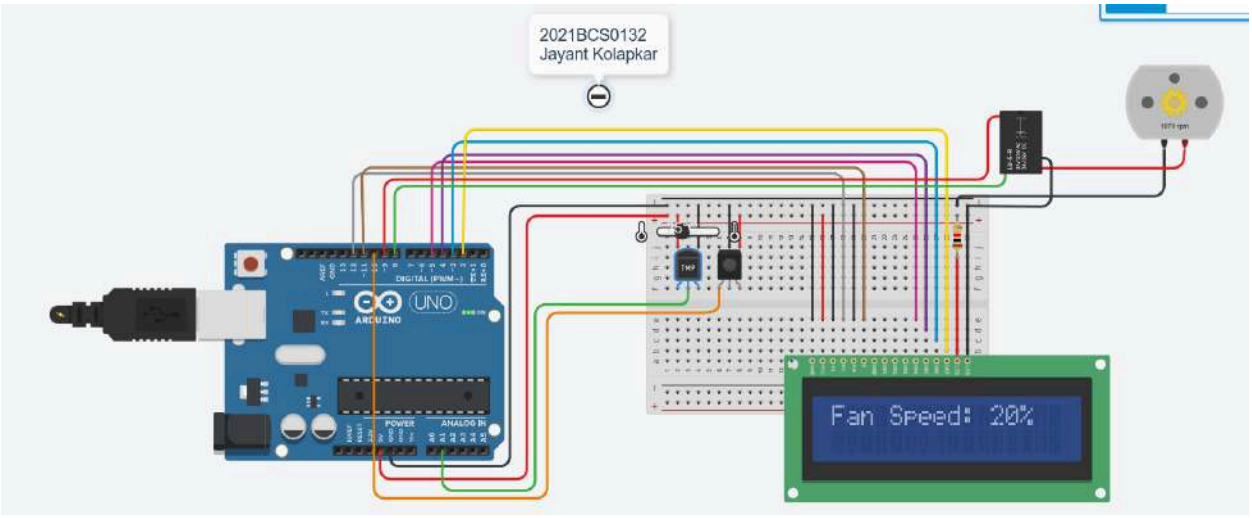
Output



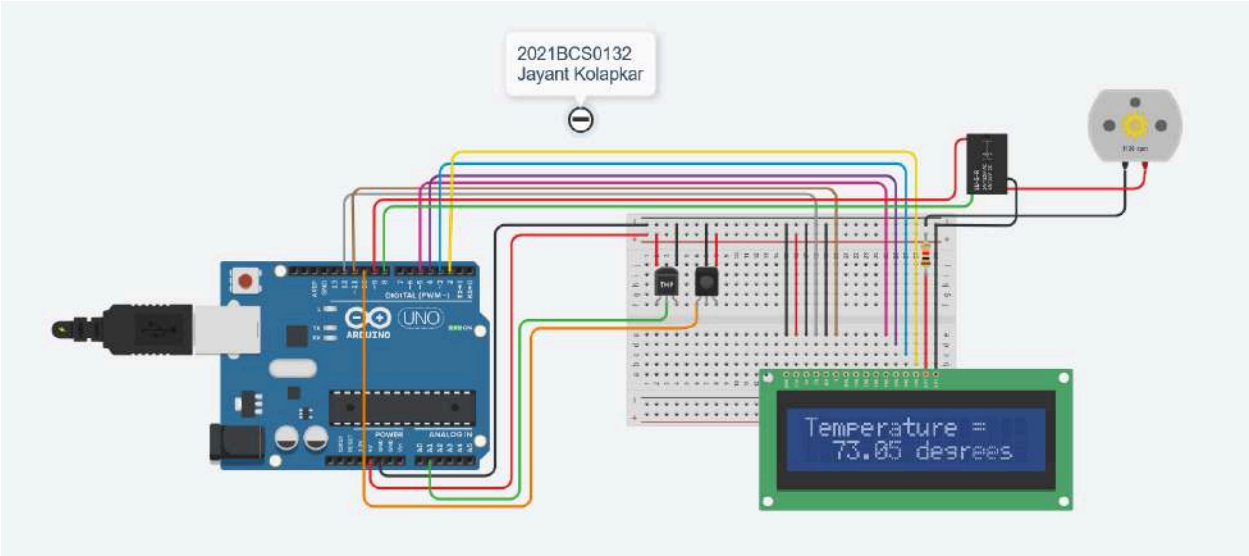

2021BCS0132
Jayant Kolapkar
UNO
ARDUINO
Jayant Kolapk

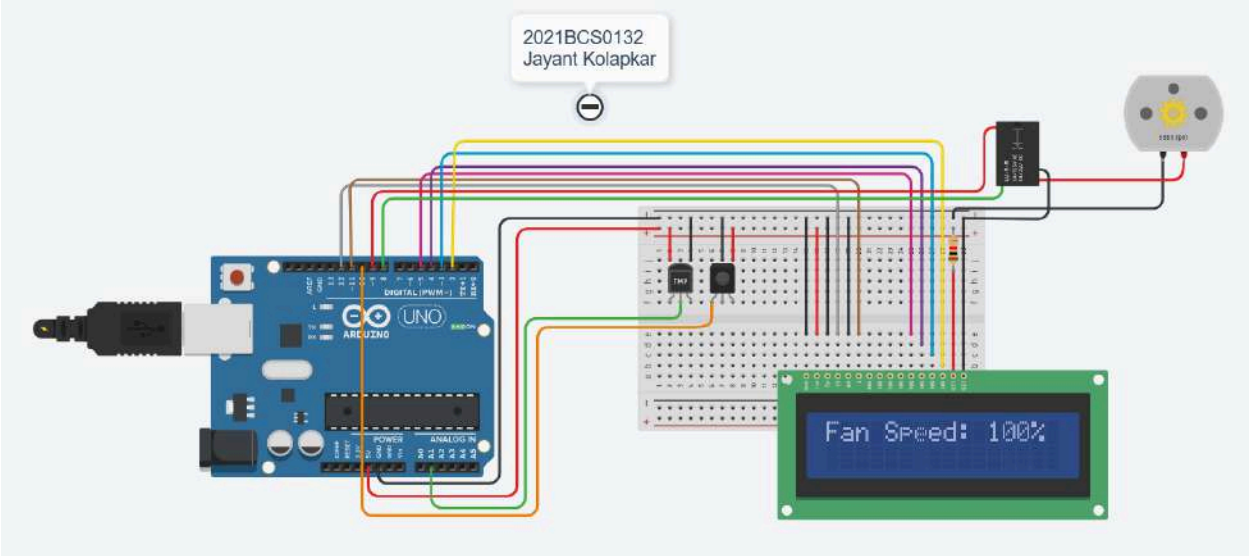

2021BCS0132
Jayant Kolapkar
UNO
ARDUINO
Recording
Temperature..





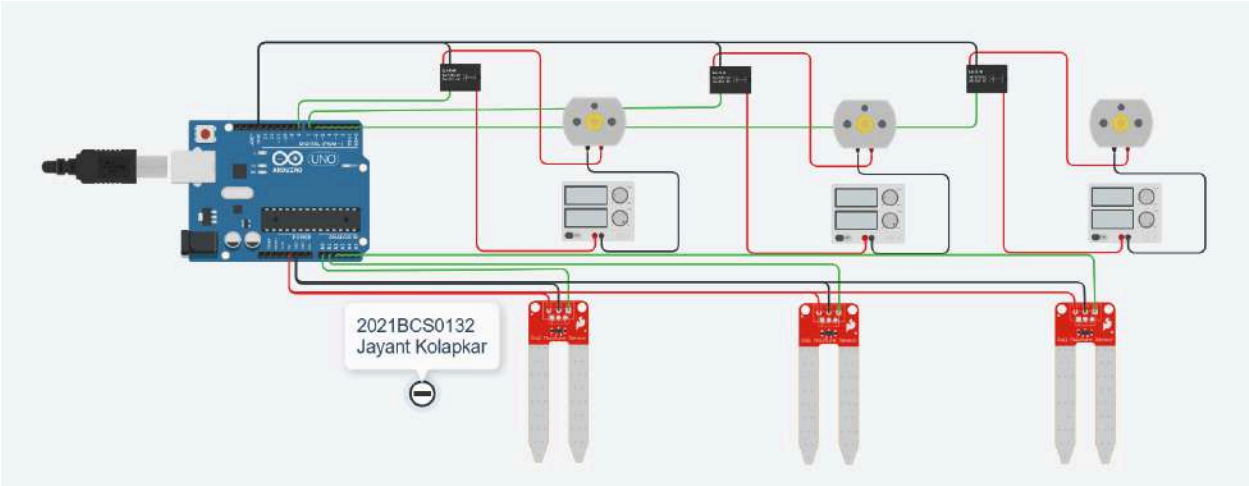
Now we change the temperature.


2021BCS0132
Jayant Kolapkar
UNO
Temperature =
73.05 degrees


2021BCS0132
Jayant Kolapkar
UNO
Fan Speed: 100%

Task 2

Diagram



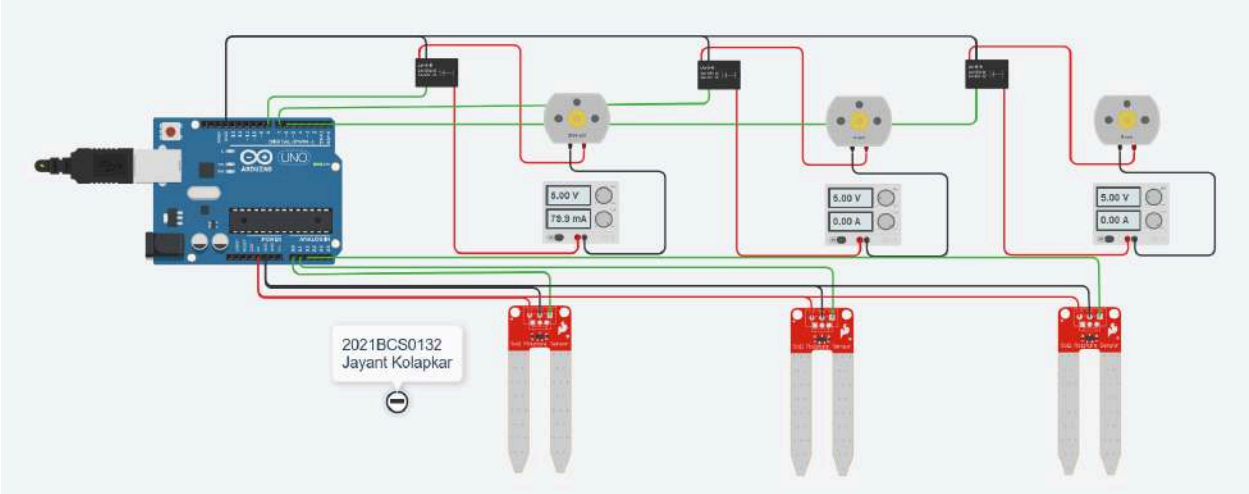
Code

```
const int moistureSensorPins[] = {A0, A1, A2}; // Moisture sensors
const int relayPins[] = {8, 7, 6};             // Relay-controlled motors
const int moistureThreshold = 300;             // Threshold for dryness

void setup() {
  Serial.begin(9600);

  for (int i = 0; i < 3; i++) {
    pinMode(relayPins[i], OUTPUT);
    digitalWrite(relayPins[i], LOW); // Ensure motors are off initially
  }
}

void loop() {
  for (int i = 0; i < 3; i++) {
    int moistureLevel = analogRead(moistureSensorPins[i]);
    Serial.print("Soil Moisture Level (Sensor ");
    Serial.print(i + 1);
    Serial.print("): ");
```

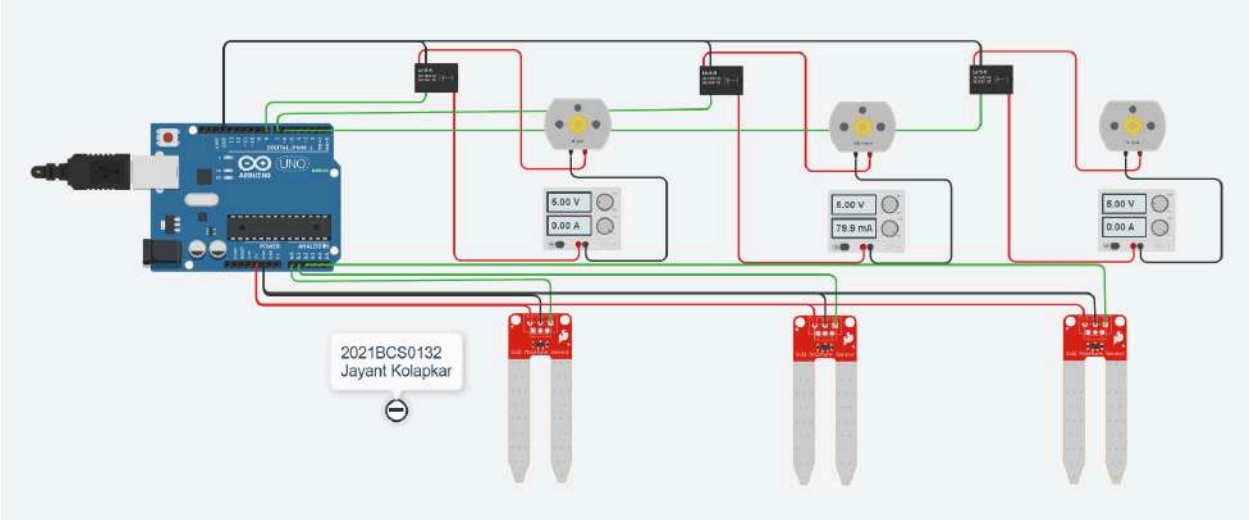
```
    Serial.println(moistureLevel);

    if (moistureLevel < moistureThreshold) {
      Serial.print("Soil is dry at Sensor ");
      Serial.print(i + 1);
      Serial.println("! Watering the plant...");
      digitalWrite(relayPins[i], HIGH);
      delay(5000);
      digitalWrite(relayPins[i], LOW);
      Serial.println("Watering complete.");
    } else {
      Serial.print("Soil moisture is sufficient at Sensor ");
      Serial.println(i + 1);
    }
  }

  delay(10000); // Wait before the next reading
}
```

This code will check the moisture levels of three sensors and activate the corresponding motor if the soil is too dry. Each motor runs independently for 5 seconds when needed, and the system waits 10 seconds before checking again.

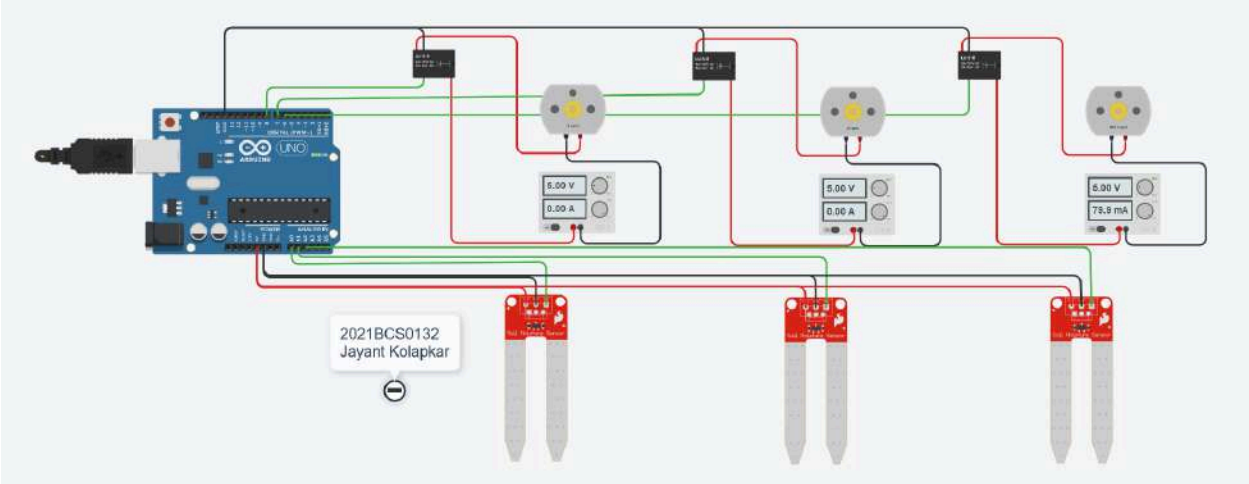
Output



First motor runs as it’s soil moisture level is low.



Then the 2nd sensor is checked and the motor is run.



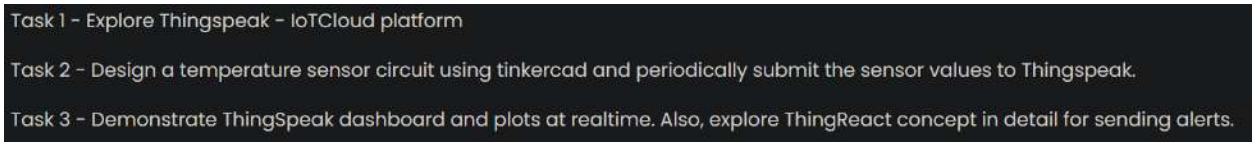
At last the 3rd sensor is checked and the motor is run.

The loop then repeats infinitely, and if the soil moisture level is sufficient, that channel is skipped.

Lab 5
ICS423 - Internet of Things

Jayant Kolapkar - 2021BCS0132

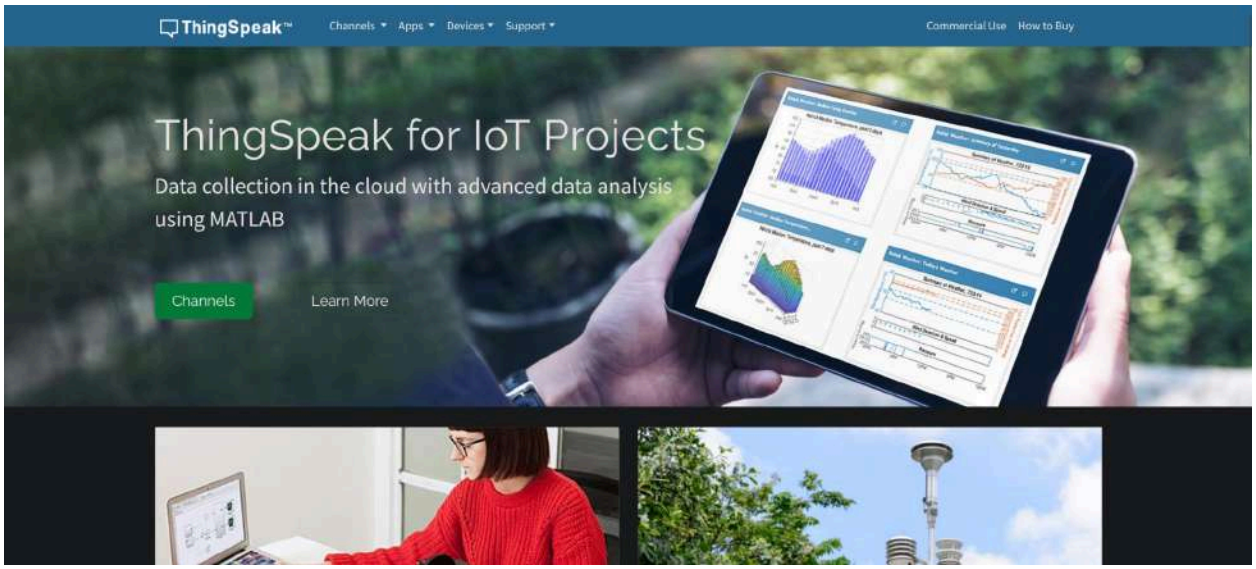
Question



Task 1

Introduction to ThingSpeak - IoT Cloud Platform

1. **Cloud-Based IoT Analytics** – ThingSpeak is an open-source IoT platform designed for real-time collection, analysis, and visualization of sensor data.
2. **MATLAB Integration** – It seamlessly integrates with MATLAB, enabling advanced data processing, machine learning, and predictive analytics.
3. **RESTful API Support** – ThingSpeak offers RESTful APIs for reading and writing data, allowing easy connectivity with IoT devices, web applications, and cloud services.
4. **Data Storage & Visualization** – Users can store sensor data in channels and visualize it through built-in graphs and charts for deeper insights.
5. **Triggers & Alerts** – It supports event-driven automation, allowing users to trigger actions such as notifications or device control based on sensor readings.


ThingSpeak™
Channels
Apps
Devices
Support
Commercial Use
How to Buy
ThingSpeak for IoT Projects
Data collection in the cloud with advanced data analysis using MATLAB
Channels
Learn More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My Image Channels
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Data collection in the cloud with advanced data analysis using MATLAB
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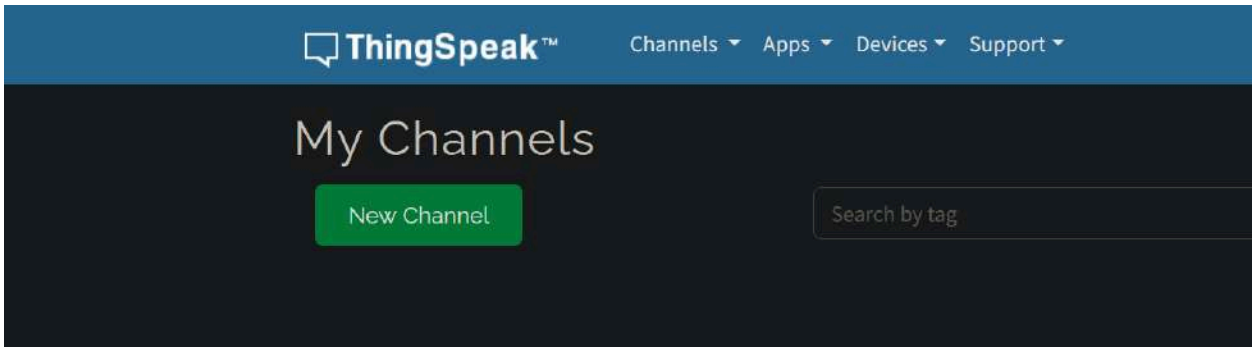
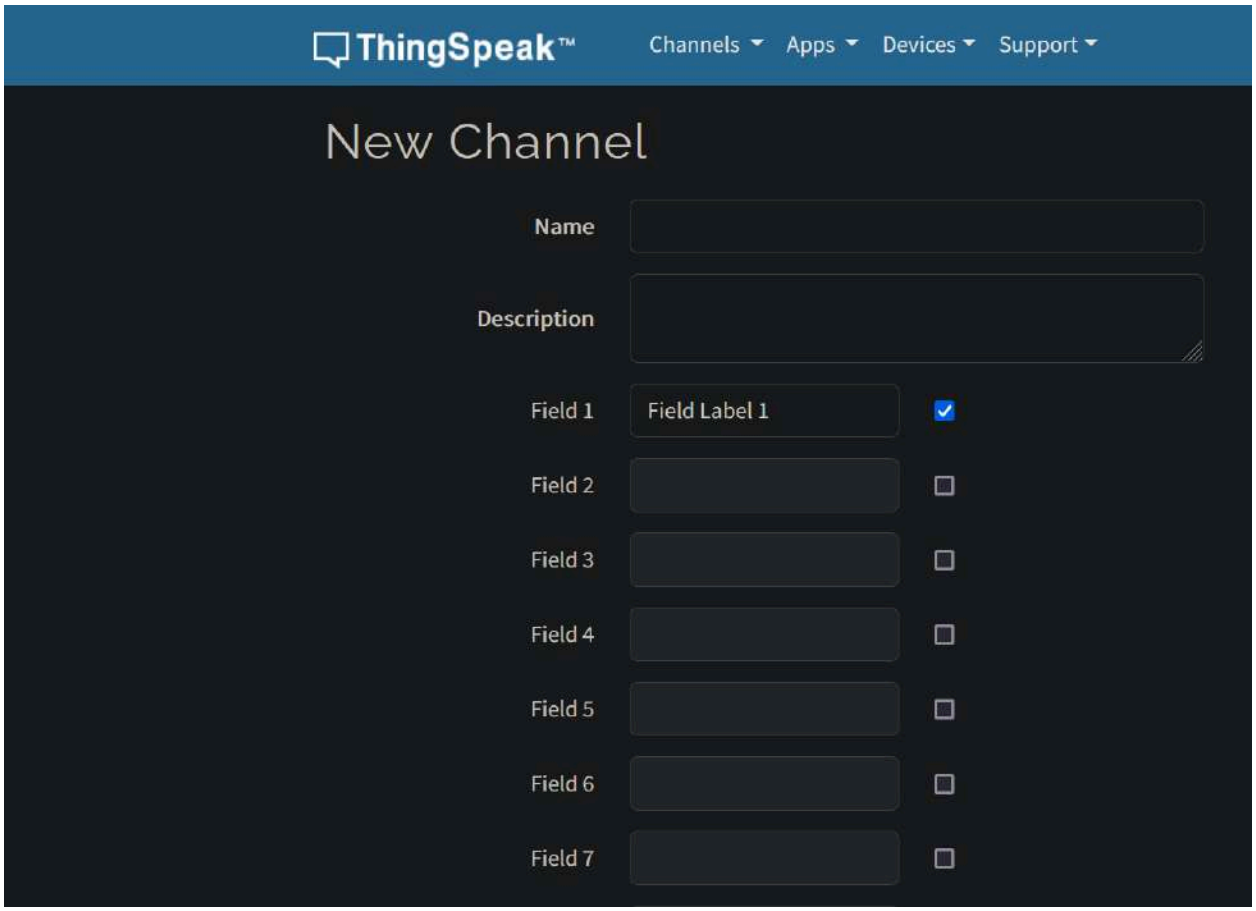
Learn More


ThingSpeak™
Channels
Apps
Devices
Support
My Channels
New Channel
Search by tag



Task 2

Design a Temperature Sensor Circuit Using Tinkercad & Transmit Data to ThingSpeak

Algorithm:

1. **Initialize Serial Communication & Wi-Fi Connection**
    - Start serial communication at 115200 baud rate.
    - Send AT commands to verify ESP8266 response.
    - Connect to the Wi-Fi network using the `AT+CWJAP` command.
2. **Establish Connection with ThingSpeak**

- Use the `AT+CIPSTART` command to create a TCP connection to ThingSpeak's API server (`api.thingspeak.com`) on port 80.

3. **Read Sensor Data**

   - Capture analog input from pin A0, corresponding to the temperature sensor.
   - Convert the analog reading to a temperature value using the `map()` function.

4. **Transmit Data to ThingSpeak**

   - Construct an HTTP GET request containing the API key and temperature value.
   - Send the request using `AT+CIPSEND`, followed by the actual HTTP request.

5. **Repeat Data Transmission**

   - Continuously send sensor readings within the `loop()` function at intervals of 100 milliseconds.

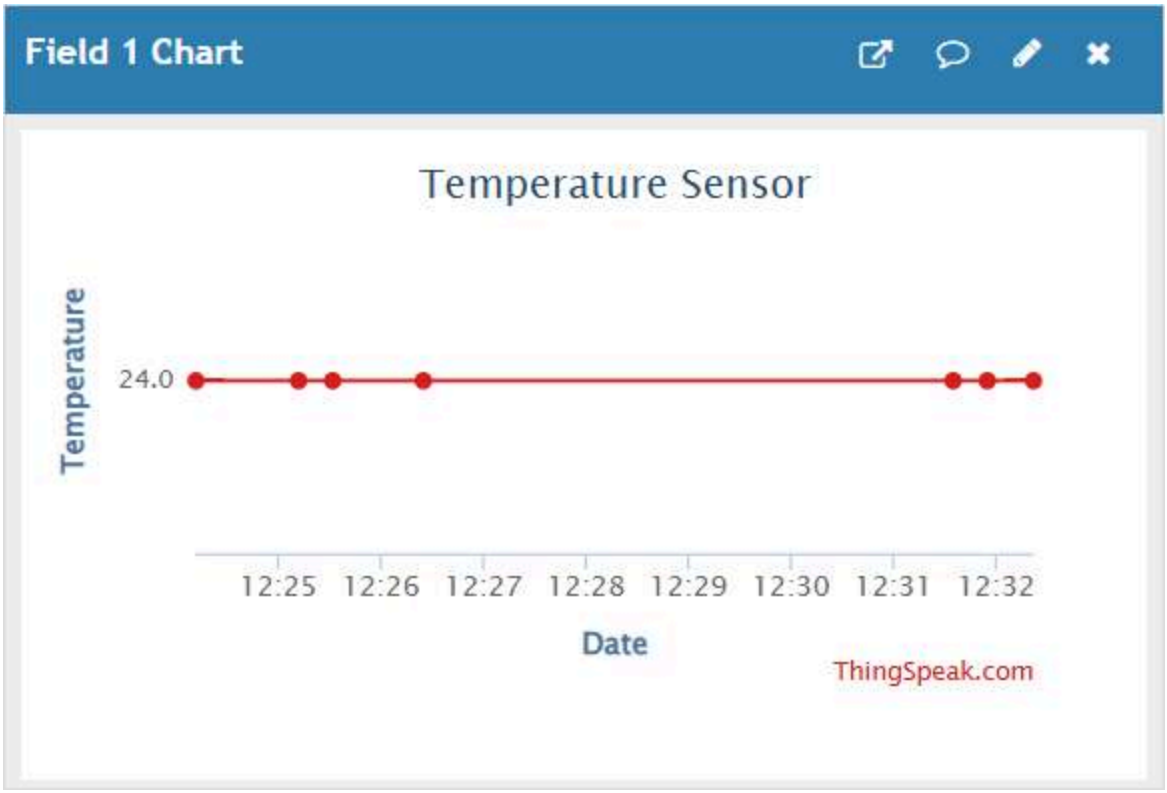
Code:

```
//Make sure to subscribe Technomekanics:)
String ssid     = "Simulator Wifi";  // SSID to connect to
String password = ""; // Our virtual wifi has no password
String host     = "api.thingspeak.com"; // Open Weather Map API
const int httpPort   = 80;
String url     = "/update?api_key=IQ4BKS2FGBIQS943&field1=";

int setupESP8266(void) {
  // Start our ESP8266 Serial Communication
  Serial.begin(115200);   // Serial connection over USB to computer
  Serial.println("AT");   // Serial connection on Tx / Rx port to ESP8266
  delay(10);        // Wait a little for the ESP to respond
  if (!Serial.find("OK")) return 1;

  // Connect to 123D Circuits Simulator Wifi
  Serial.println("AT+CWJAP=\"" + ssid + "\",\"" + password + "\"");
  delay(10);        // Wait a little for the ESP to respond
  if (!Serial.find("OK")) return 2;

  // Open TCP connection to the host:
  Serial.println("AT+CIPSTART=\"TCP\",\"" + host + "\"," + httpPort);
  delay(50);        // Wait a little for the ESP to respond
  if (!Serial.find("OK")) return 3;

  return 0;
}

void anydata(void) {

  int temp = map(analogRead(A0),20,358,-40,125);

  // Construct our HTTP call
  String httpPacket = "GET " + url + String(temp) + " HTTP/1.1\r\nHost: " + host + "\r\n\r\n";
  int length = httpPacket.length();

  // Send our message length
  Serial.print("AT+CIPSEND=");
  Serial.println(length);
  delay(10); // Wait a little for the ESP to respond if (!Serial.find(">")) return -1;
```

```
  // Send our http request
  Serial.print(httpPacket);
  delay(10); // Wait a little for the ESP to respond
  if (!Serial.find("SEND OK\r\n")) return;


}


void setup() {

  setupESP8266();

}

void loop() {

 anydata();

  delay(100);
}
```

Output:

- Temperature data is periodically submitted to ThingSpeak for real-time monitoring.



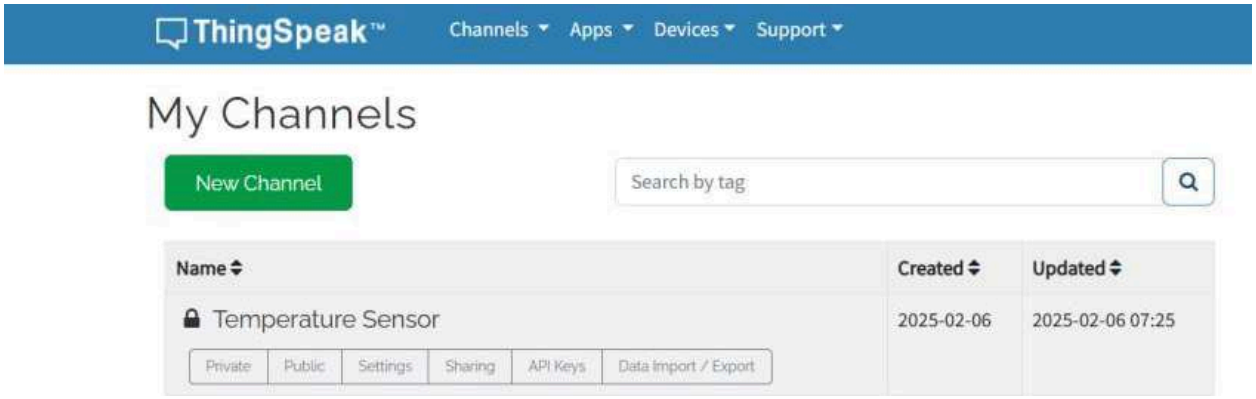
Task 3

Real-Time Data Visualization & ThingReact Alerts

ThingSpeak enables real-time visualization of sensor data through customizable dashboards.

Steps to Create a ThingSpeak Channel:

1. **Create a New Channel** – Define a name and specify fields (e.g., Temperature, Humidity).
2. **Send Sensor Data** – Use an ESP8266, ESP32, or Arduino to transmit data using an API key.
3. **Visualize Data** – Access the “Private View” or “Public View” tab to observe live graphs.
4. **Customize Widgets** – Utilize widgets like line charts, gauges, and histograms to analyze trends.



ThingReact – Event-Based Trigger System

ThingReact enables automated responses based on sensor data thresholds.

How ThingReact Works:

- Continuously monitors real-time data from a ThingSpeak channel.
- Triggers a response when a predefined condition is met (e.g., temperature surpassing 50°C).
- Sends notifications via email, tweets, or HTTP requests to external services like IFTTT or Telegram.

Steps to Use ThingReact:

1. Navigate to **Apps → ThingReact** on ThingSpeak.
2. Click **Create New Reaction** and set conditions:
    - **Example Condition:** If Temperature (Field1) starts with “2”.
    - **Example Action:** Send an email alert or trigger a webhook.
3. Select an Action Type (HTTP Request, Twitter Post, Email Notification).
4. Enable the Reaction and monitor real-time alerts.

Practical Use Cases:

- **Smart Agriculture:** Send SMS alerts when soil moisture drops below a threshold.
- **Industrial Safety:** Trigger an alarm if gas levels exceed safe limits.
- **Home Automation:** Automatically switch on a fan when room temperature crosses a set value.

Name:	React 1
Condition Type:	String
Test Frequency:	On data insertion
Last Ran:	2025-02-06 07:25
Channel:	Temperature Sensor
Condition:	Field 1 (Temperature) starts with "2"
ThingHTTP:	Request 220236
Run:	Each time the condition is met
Created:	2025-02-06 7:24 am

Lab 6
ICS 423: Internet Of Things

Jayant Kolapkar - 2021BCS0132

Task 1: Design an alarm system that triggers warning if a package gets damaged. Use force sensor and a buzzer alarm.

Algorithm

1. Initialize Components

- Define force sensor pin (Analog A0).
- Define buzzer pin (Digital 9).
- Define LED pin (Digital 7).
- Set the threshold value for the force sensor.

2. Setup Function (Runs Once)

- · Start the Serial Monitor for debugging.
- Set LED and Buzzer as OUTPUT.

3. Loop Function (Repeats Continuously)

- Read the force sensor value from A0.
- Print the sensor value to the Serial Monitor.
- Compare the sensor value with the threshold:
    - If the value is greater than the threshold:
        - Turn ON the LED.
        - Turn ON the Buzzer.
    - Else:
        - Turn OFF the LED.
        - Turn OFF the Buzzer.

- Add a small delay for stability.

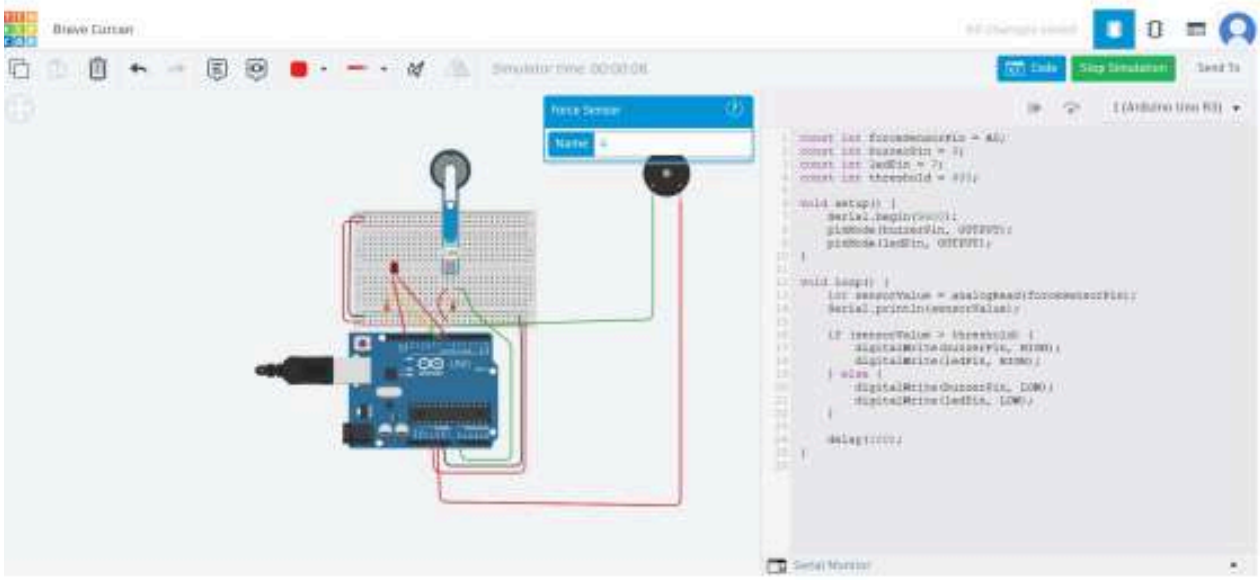
Code

```
const int forceSensorPin = A0;

const int buzzerPin = 9;

const int ledPin = 7;

const int threshold = 400;


void setup() {

        Serial.begin(9600);

        pinMode(buzzerPin, OUTPUT);

        pinMode(ledPin, OUTPUT);

}


void loop() {

        int sensorValue = analogRead(forceSensorPin);

        Serial.println(sensorValue);


        if (sensorValue > threshold) {

        digitalWrite(buzzerPin, HIGH);
```

```
        digitalWrite(ledPin, HIGH);
        } else {
        digitalWrite(buzzerPin, LOW);
        digitalWrite(ledPin, LOW);
        }

        delay(100);
}
```

Output

The alarm and the LED bulb are off when the force applied is below the threshold.



The alarm rings and the LED bulb glows when the force crosses the threshold limit.

Task 2: Develop a smoke detecting system for a building consisting of three floors. Notify the real-time value of the floors to thingspeak IoT cloud platform.

1. Initialize Components:

- Start Serial Communication at 115200 baud.
- Connect ESP8266 to WiFi using AT+CWJAP.
- Set up pin modes:
  - A0, A1, A2 → Smoke sensors for Floors 1, 2, and 3.
  - Pin 7 → Buzzer.

2. Read Sensor Data:

- Collect readings from A0, A1, and A2.
- Display sensor values on the Serial Monitor.

3. Send Data to ThingSpeak:

- Establish a TCP connection using AT+CIPSTART.
- Construct an HTTP GET request including the API key and sensor values.
- Transmit the request using AT+CIPSEND.

4. Activate Buzzer on High Smoke Detection:

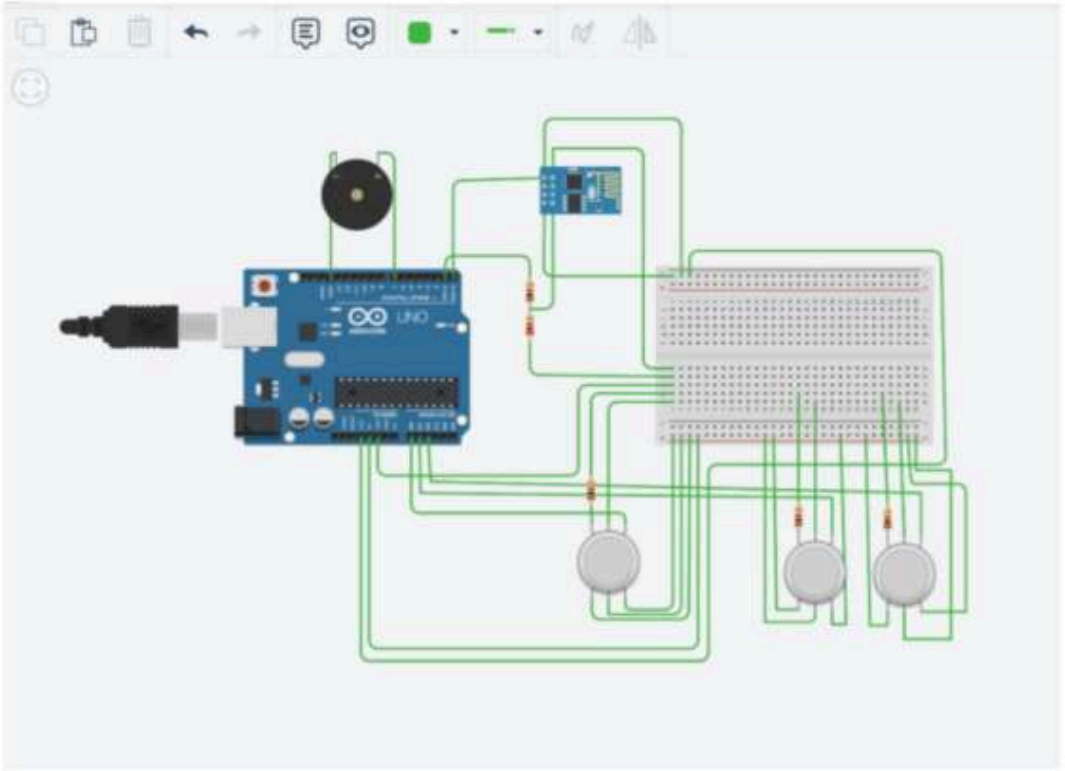
- If any sensor reading exceeds 85, activate the buzzer (tone(7, 1000)).
- Otherwise, turn OFF the buzzer (noTone(7)).

5. Close Connection & Repeat:

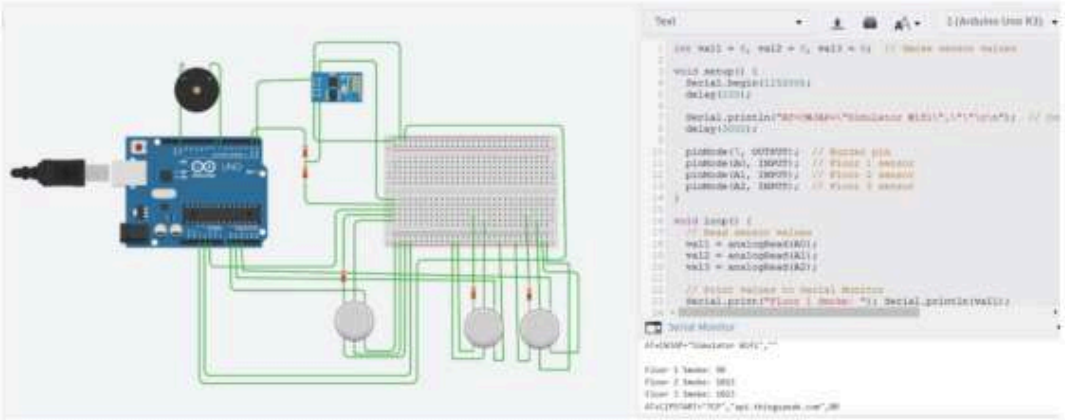
- Terminate the TCP connection using AT+CIPCLOSE.
- Wait 10 seconds (due to ThingSpeak's free-tier limit).
- Repeat the process continuously.

```
int val1 = 0, val2 = 0, val3 = 0;

void setup() {
  delay(100);
  Serial.begin(115200);

  Serial.println("AT+CWJAP=\"Simulator Wifi\",\"\"\r\n");
  delay(3000);

  pinMode(7, OUTPUT);
  pinMode(A0, INPUT);
  pinMode(A1, INPUT);
  pinMode(A2, INPUT);
}

void loop() {
  val1 = analogRead(A0);
  val2 = analogRead(A1);
  val3 = analogRead(A2);

  Serial.print("Floor 1 Smoke: "); Serial.println(val1);
  Serial.print("Floor 2 Smoke: "); Serial.println(val2);
  Serial.print("Floor 3 Smoke: "); Serial.println(val3);
  delay(1000);

  Serial.println("AT+CIPSTART=\"TCP\",\"api.thingspeak.com\",80\r\n");
  delay(3000);

  String request = "GET /update?api_key=7FMOOFSORT938HZF&field1=";
  request += String(val1) + "&field2=" + String(val2) + "&field3=" + String(val3);

  Serial.print("AT+CIPSEND=");
  Serial.println(request.length() + 2);
  delay(1000);
  Serial.print(request);
  delay(1000);

  if (val1 > 85 || val2 > 85 || val3 > 85) {
    tone(7, 1000);
  } else {
    noTone(7);
  }

  Serial.println("AT+CIPCLOSE=0\r\n");
  delay(10000);
```

Output



Simulation



Graph visualization on ThingSpeak


Field 1 Chart
Building Smoke Detection
Smoke Level - Floor 1
58.0
23:21
23:22
23:23
23:24
23:25
Date
ThingSpeak.com


Field 2 Chart
Building Smoke Detection
Smoke Level - Floor 2
1.02k
23:21
23:22
23:23
23:24
23:25
Date
ThingSpeak.com


Field 3 Chart
Building Smoke Detection
Smoke Level - Floor 3
1.02k
23:21
23:22
23:23
23:24
23:25
Date
ThingSpeak.com

Lab 7

ICS423 - Internet of Things

Jayant Kolapkar - 2021BCS0132

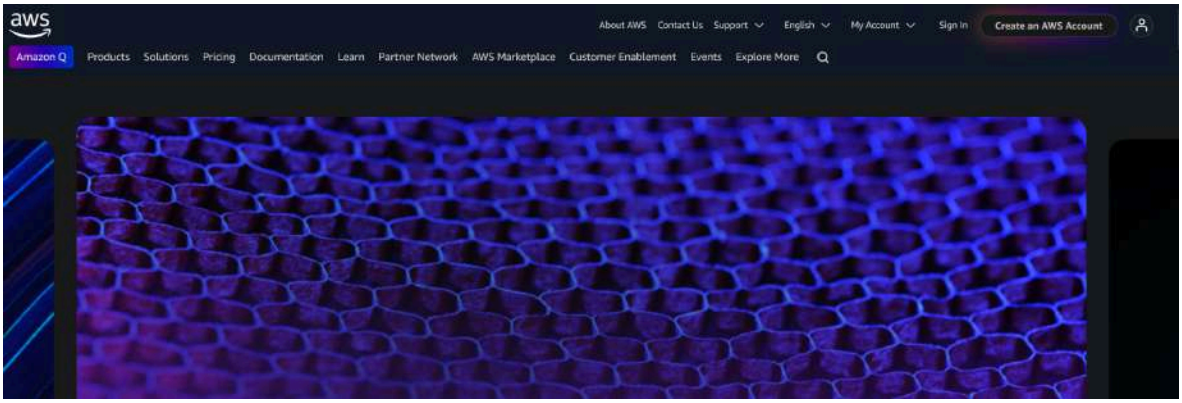
Question

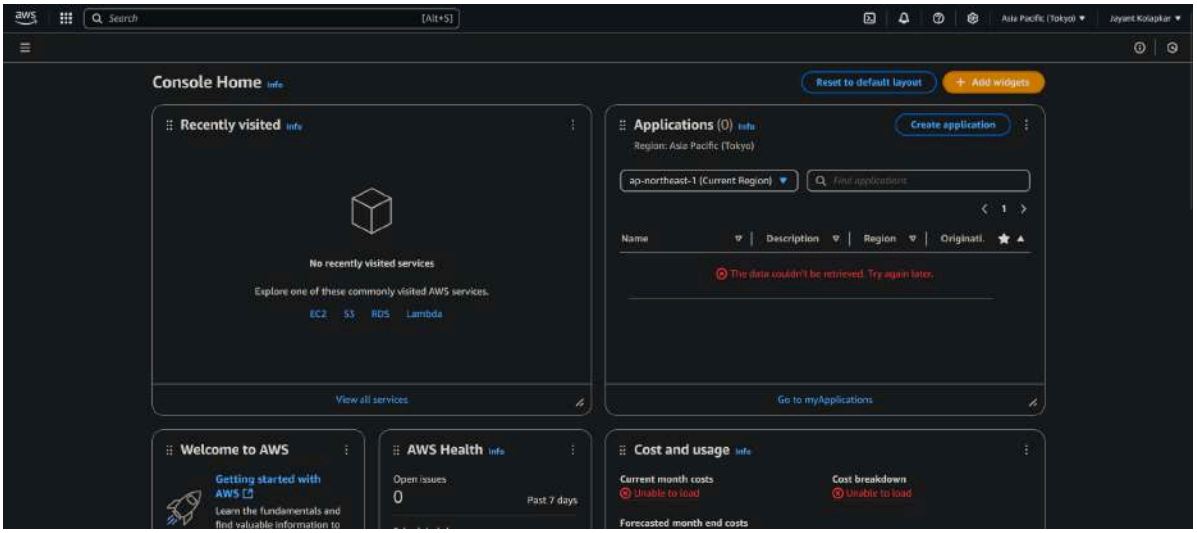
Task 1: Establish an AWS account and run one EC2 instance on your name. (Don't forget to shutdown the VM instance before logging out of AWS account; only use free-tier versions)

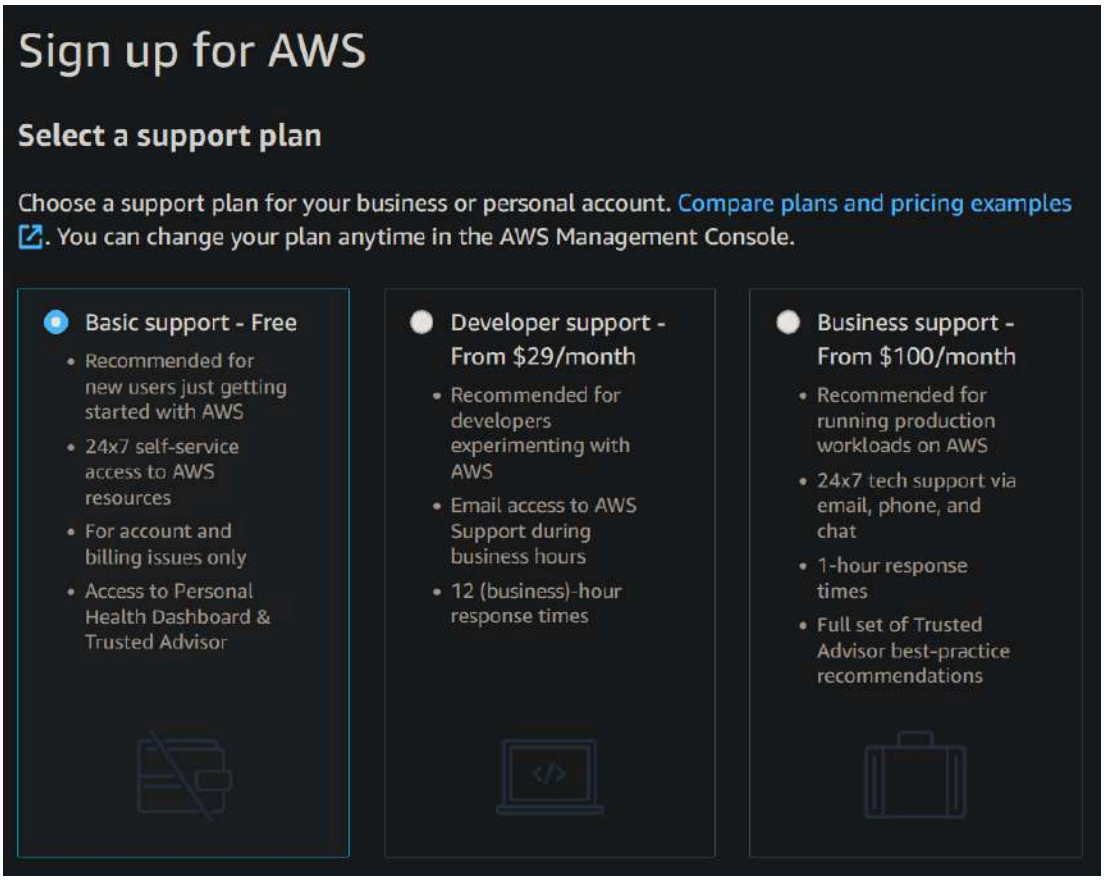
Task 2: Connect your laptop as IoT device to AWS IoT core.

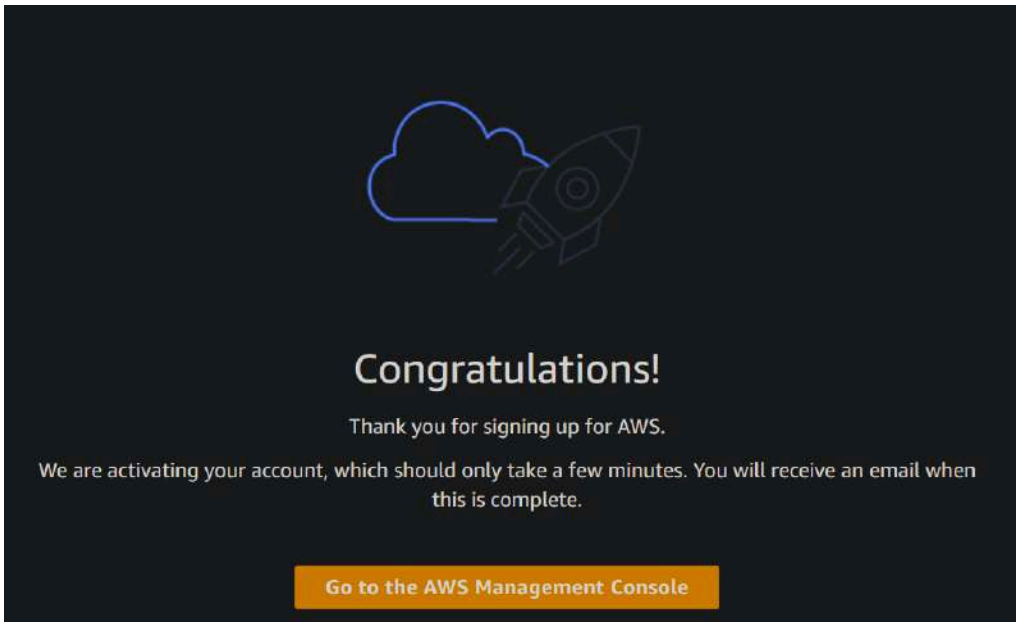
Task 1

Create an AWS account and sign up for the free plan

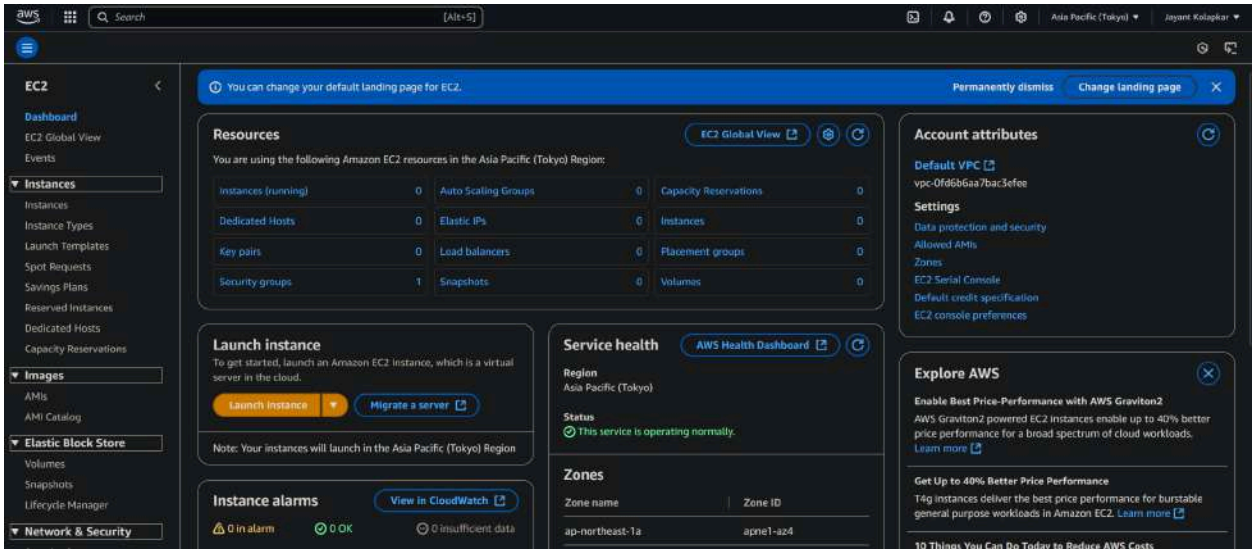


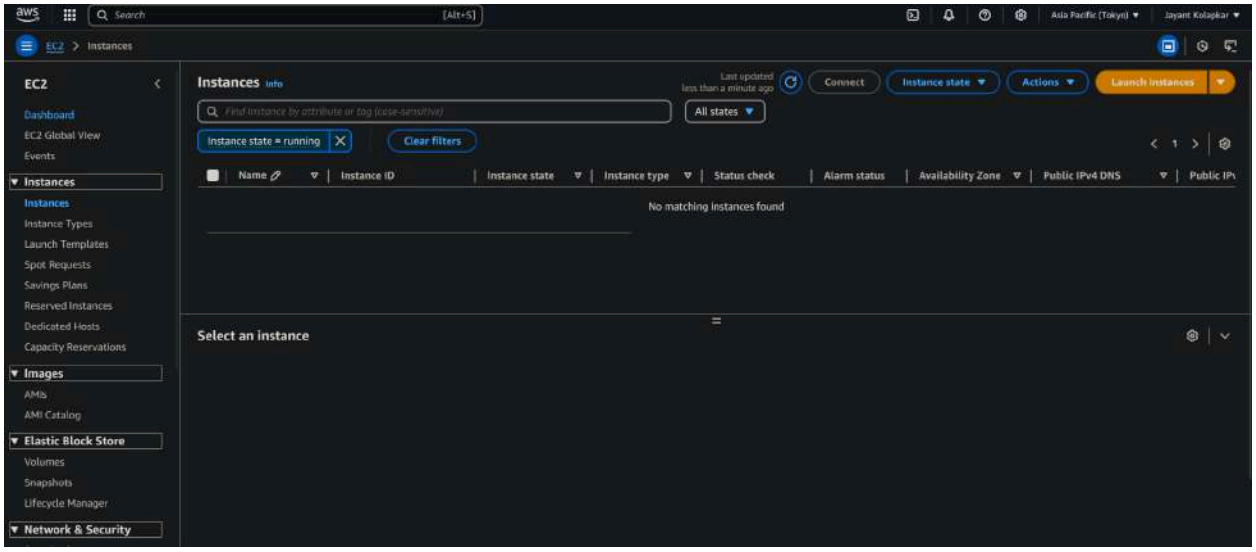


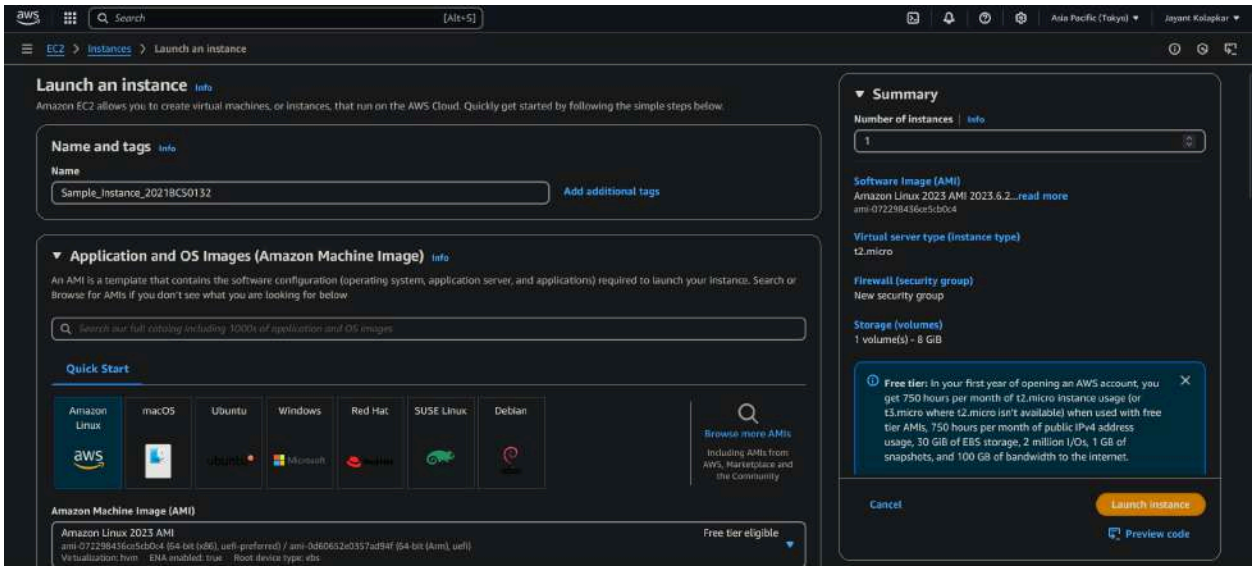

Sign up for AWS
Select a support plan
Choose a support plan for your business or personal account. Compare plans and pricing examples. You can change your plan anytime in the AWS Management Console.
Basic support - Free
Recommended for new users just getting started with AWS
24x7 self-service access to AWS resources
For account and billing issues only
Access to Personal Health Dashboard & Trusted Advisor
Developer support - From $29/month
Recommended for developers experimenting with AWS
Email access to AWS Support during business hours
12 (business)-hour response times
Business support - From $100/month
Recommended for running production workloads on AWS
24x7 tech support via email, phone, and chat
1-hour response times
Full set of Trusted Advisor best-practice recommendations


Congratulations!
Thank you for signing up for AWS.
We are activating your account, which should only take a few minutes. You will receive an email when this is complete.
Go to the AWS Management Console

Launch a new instance using the given attributes






Search [Alt+S]
Asia Pacific (Tokyo)
Jayant Kolapkar
EC2 > Instances > Launch an instance
Launch an instance Info
Amazon EC2 allows you to create virtual machines, or instances, that run on the AWS Cloud. Quickly get started by following the simple steps below.
Name and tags Info
Name
Sample_Instance_20218CS0132
Add additional tags
Application and OS Images (Amazon Machine Image) Info
An AMI is a template that contains the software configuration (operating system, application server, and applications) required to launch your instance. Search or Browse for AMIs if you don't see what you are looking for below
Search our full catalog including 1000s of application and OS images
Quick Start
Amazon Linux
macOS
Ubuntu
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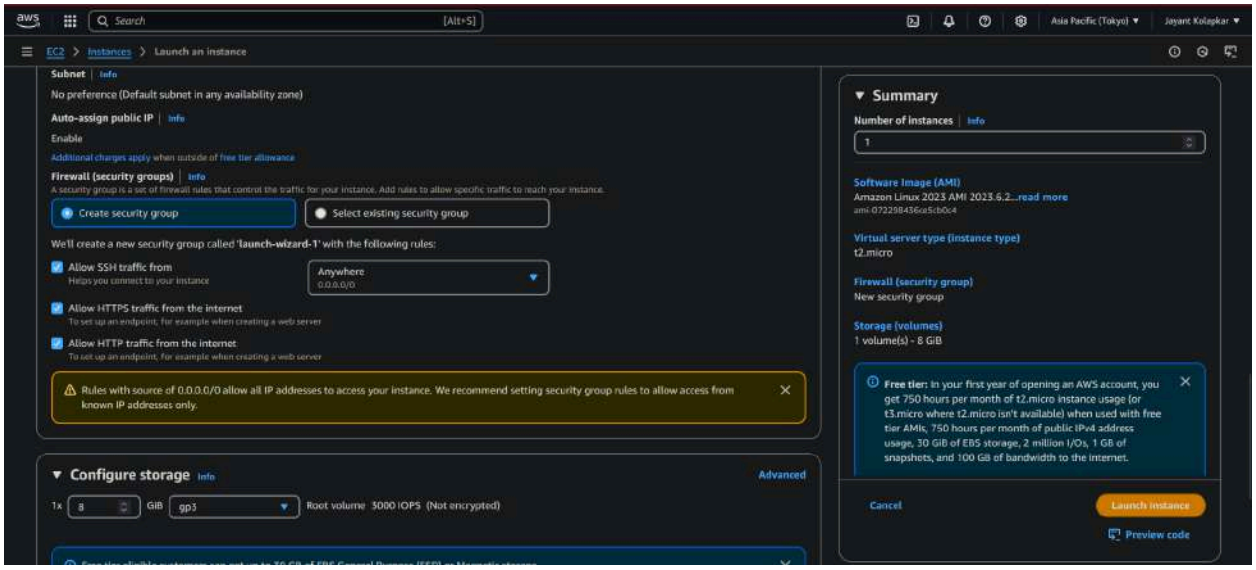
Amazon Machine Image (AMI)
Amazon Linux 2023 AMI
ami-07229843 6ce5cb0c4 (64-bit (x86), uefi-preferred) / ami-0d60652e0357ad94f (64-bit (Arm), uefi)
Virtualization: hvm ENA enabled: true Root device type: ebs
Free tier eligible
Summary
Number of instances Info
1
Software Image (AMI)
Amazon Linux 2023 AMI 2023.6.2...read more
ami-07229843 6ce5cb0c4
Virtual server type (instance type)
t2.micro
Firewall (security group)
New security group
Storage (volumes)
1 volume(s) - 8 GiB
Free tier: In your first year of opening an AWS account, you get 750 hours per month of t2.micro instance usage (or t3.micro where t2.micro isn't available) when used with free tier AMIs, 750 hours per month of public IPv4 address usage, 30 GiB of EBS storage, 2 million I/Os, 1 GB of snapshots, and 100 GB of bandwidth to the internet.
Cancel
Launch instance
Preview code


Search [Alt+S]
Asia Pacific (Tokyo)
Jayant Kolapkar
EC2 > Instances > Launch an instance
Subnet Info
No preference (Default subnet in any availability zone)
Auto-assign public IP Info
Enable
Additional charges apply when outside of free tier allowance
Firewall (security groups) Info
A security group is a set of firewall rules that control the traffic for your instance. Add rules to allow specific traffic to reach your instance.
Create security group
Select existing security group
We'll create a new security group called 'launch-wizard-1' with the following rules:
Allow SSH traffic from
Helps you connect to your instance
Anywhere
0.0.0.0/0
Allow HTTPS traffic from the internet
To set up an endpoint, for example when creating a web server
Allow HTTP traffic from the internet
To set up an endpoint, for example when creating a web server
Rules with source of 0.0.0.0/0 allow all IP addresses to access your instance. We recommend setting security group rules to allow access from known IP addresses only.
Configure storage Info
Advanced
1x
8
GiB
gp3
Root volume 3000 IOPS (Not encrypted)
Summary
Number of instances Info
1
Software Image (AMI)
Amazon Linux 2023 AMI 2023.6.2...read more
ami-07229843 6ce5cb0c4
Virtual server type (instance type)
t2.micro
Firewall (security group)
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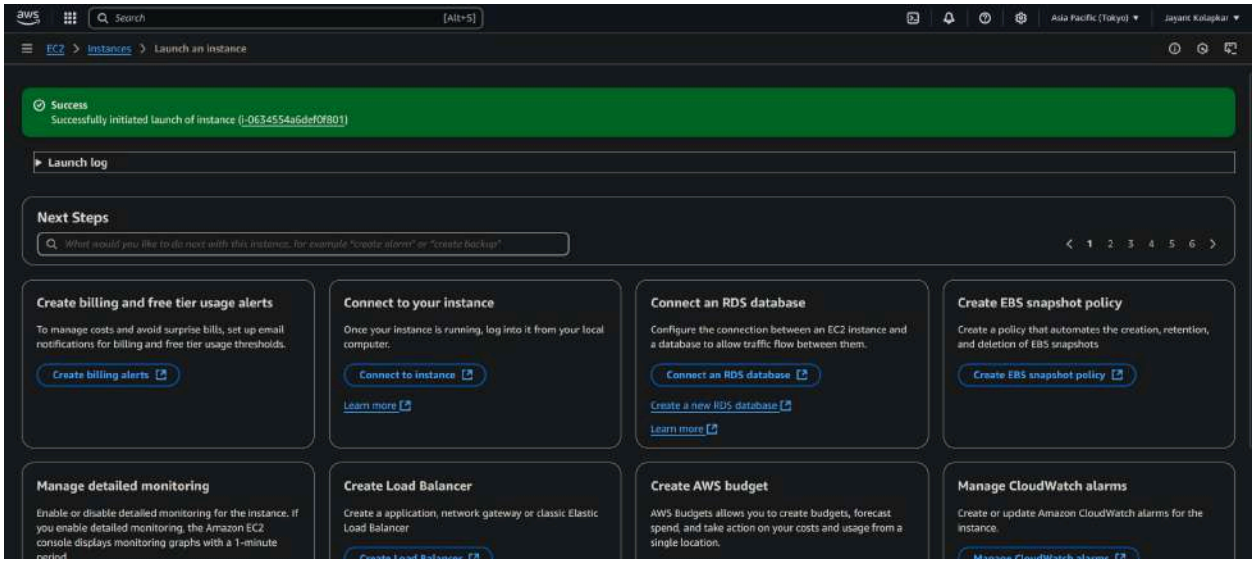
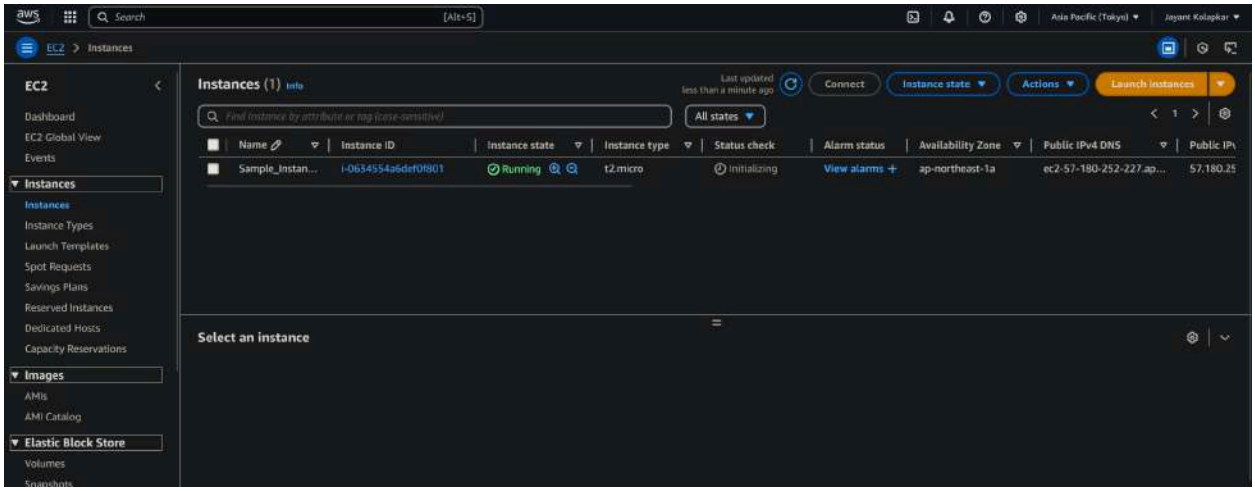
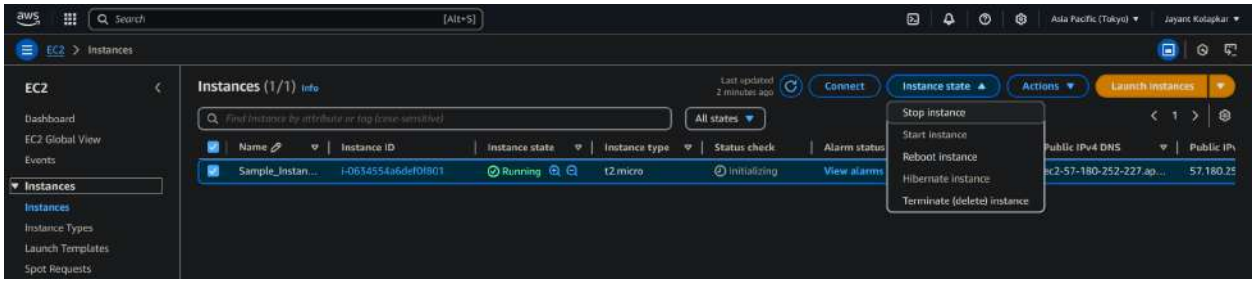
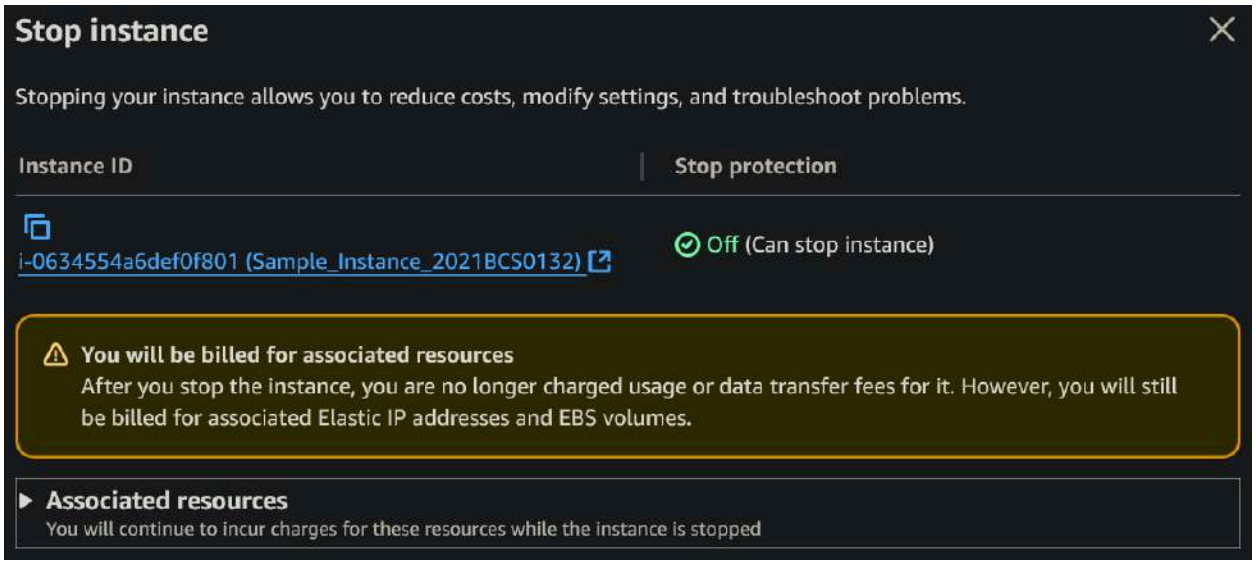
Cancel
Launch instance
Preview code

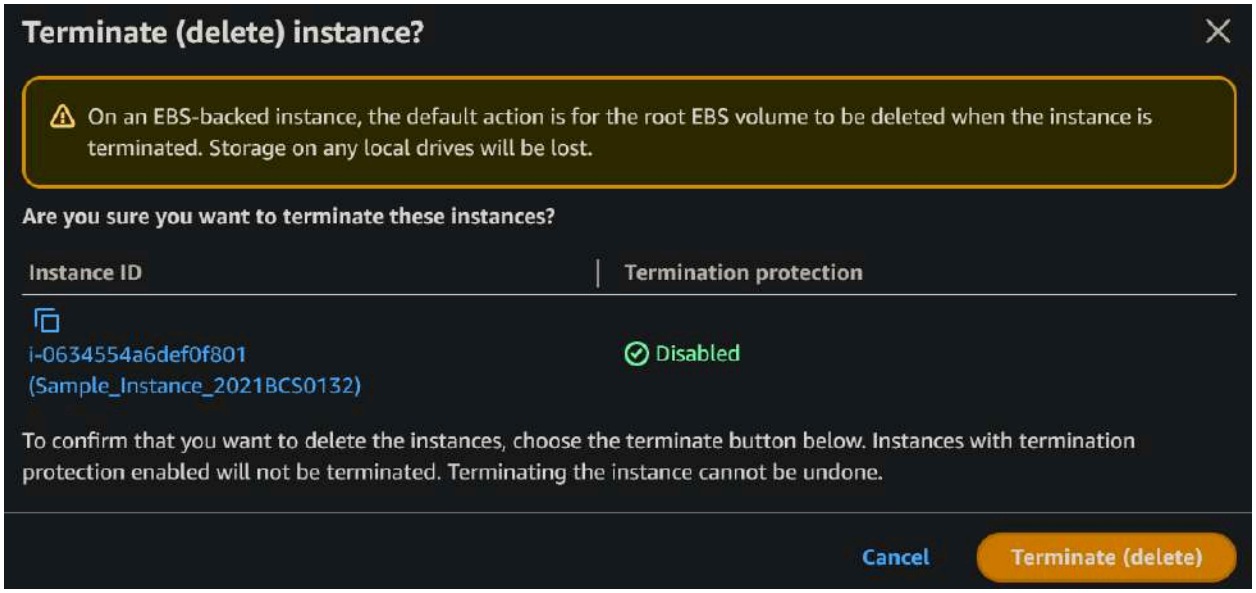
Here we see that our instance has been created







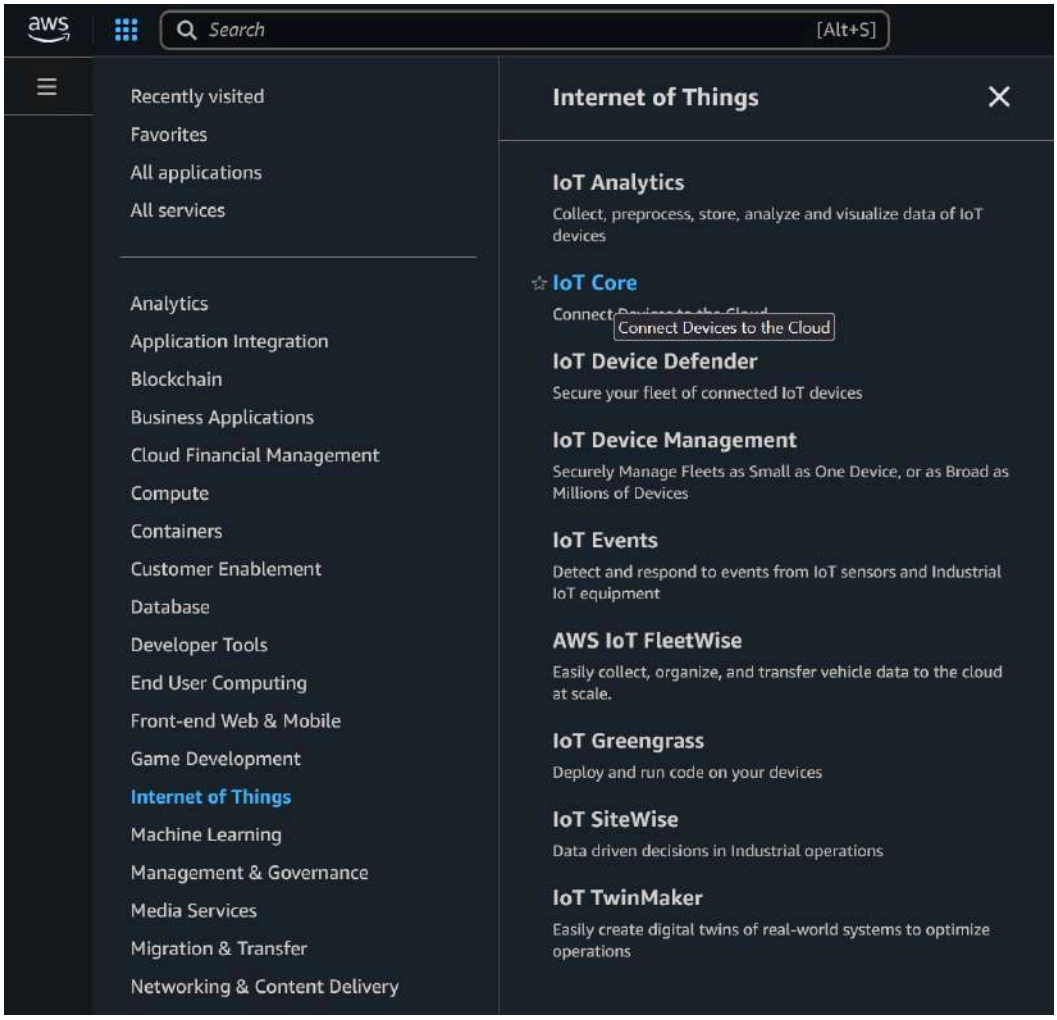




The instance is now terminated and will not be billed.

Task 2

Go to IoT core and create a new ‘Thing’



1. Set Up Your Laptop

- **Install Git**: Verify if Git is installed by running `git --version` in your command line. If not installed, download and install it from the Git website.
- **Install Python**: Check for Python installation with `python -V`. AWS IoT Core requires Python version 3.7 or later. If not installed, download and install the latest version from the Python website.

2. Install the AWS IoT Device SDK for Python

The AWS IoT Device SDK for Python enables your laptop to communicate with AWS IoT Core using MQTT.

```
jayant@Jayant-sAcerP:~$ git --version
git version 2.34.1
jayant@Jayant-sAcerP:~$ python3 -V
Python 3.10.12
jayant@Jayant-sAcerP:~$ pip install awsiotsdk
Defaulting to user installation because normal site-packages is not writeable
Collecting awsiotsdk
  Downloading awsiotsdk-1.22.1-py3-none-any.whl (75 kB)
     ━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━ 75.3/75.3 KB 1.2 MB/s eta 0:00:00
Collecting awscrt==0.23.5
  Downloading awscrt-0.23.5-cp310-cp310-manylinux_2_17_x86_64.manylinux2014_x86_64.whl (8.7 MB)
     ━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━━ 8.7/8.7 MB 4.2 MB/s eta 0:00:00
Installing collected packages: awscrt, awsiotsdk
Successfully installed awscrt-0.23.5 awsiotsdk-1.22.1
jayant@Jayant-sAcerP:~$
```

Prepare your device

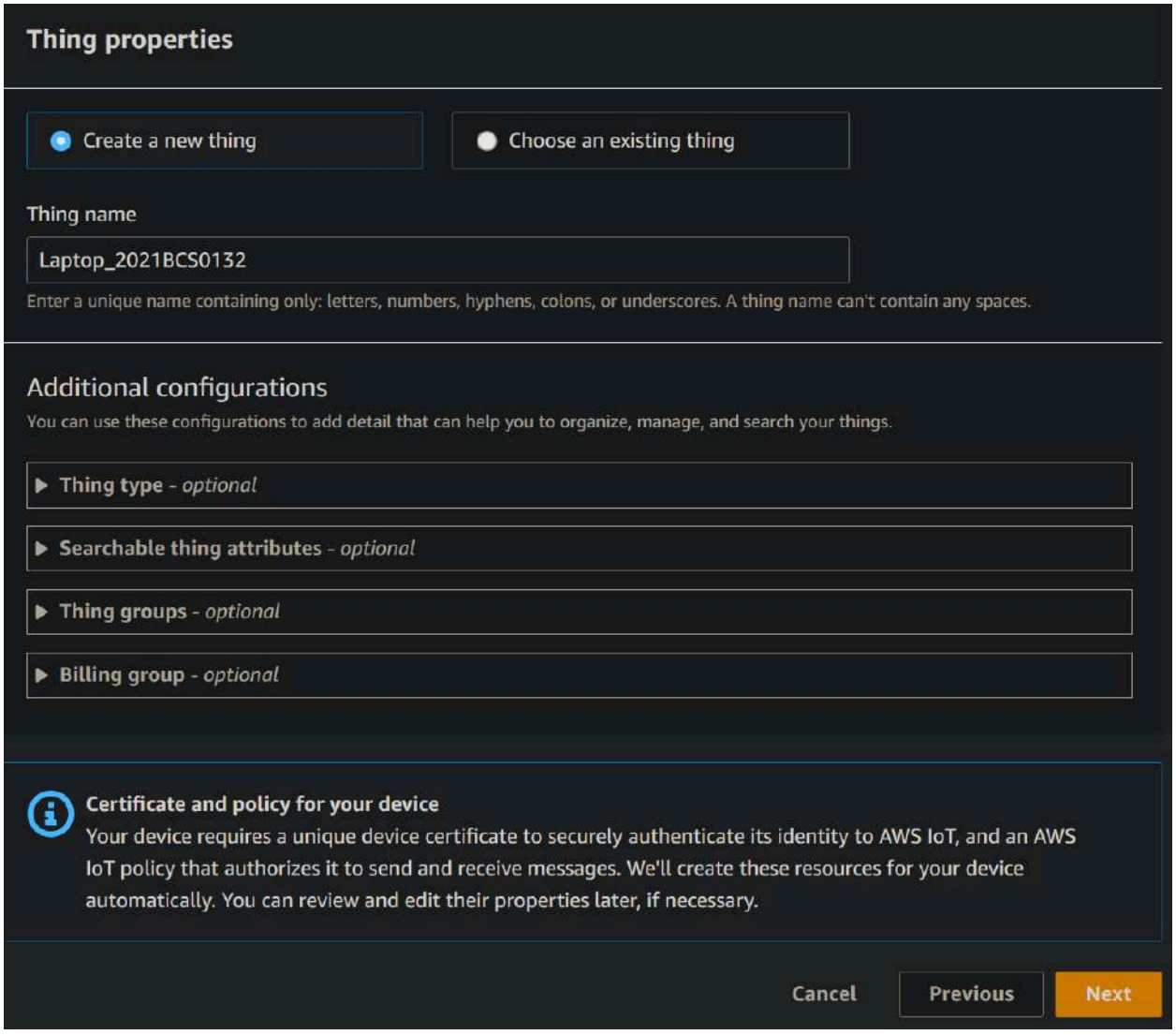
1. Turn on your device and make sure it's connected to the internet.
2. Choose how you want to load files onto your device.
   1. If your device supports a browser, open the AWS IoT console on your device and run this wizard. You can download the files directly to your device from the browser.
   2. If your device doesn't support a browser, choose the best way to transfer files from the computer with the browser to your device. Some options to transfer files include using the file transfer protocol (FTP) and using a USB memory stick.
3. Make sure that you can access a command-line interface on your device.
   1. If you're running this wizard on your IoT device, open a terminal window on your device to access a command-line interface.
   2. If you're not running this wizard on your IoT device, open an SSH terminal window on this device and connect it to your IoT device.
4. From the terminal window, enter this command:

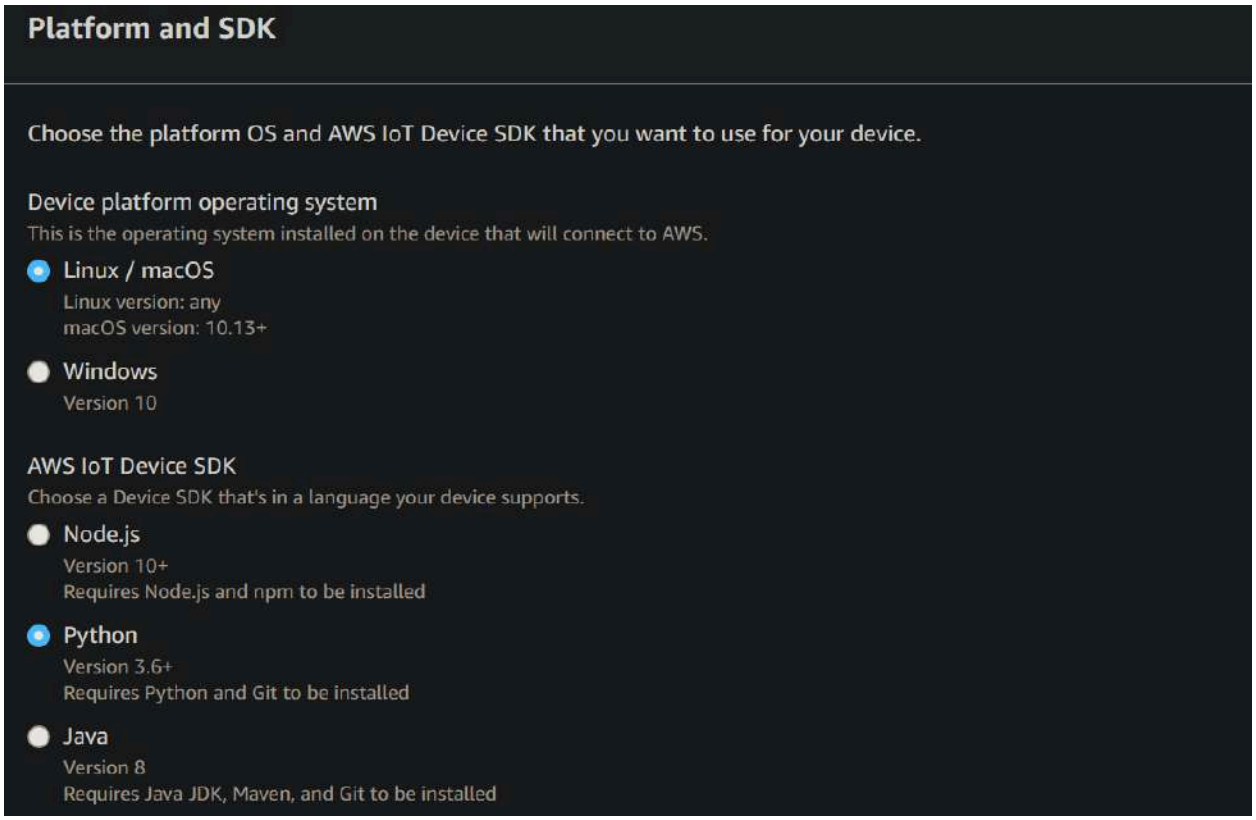
```
ping a14gmez3k91qqg-ats.iot.ap-northeast-1.amazonaws.com
```

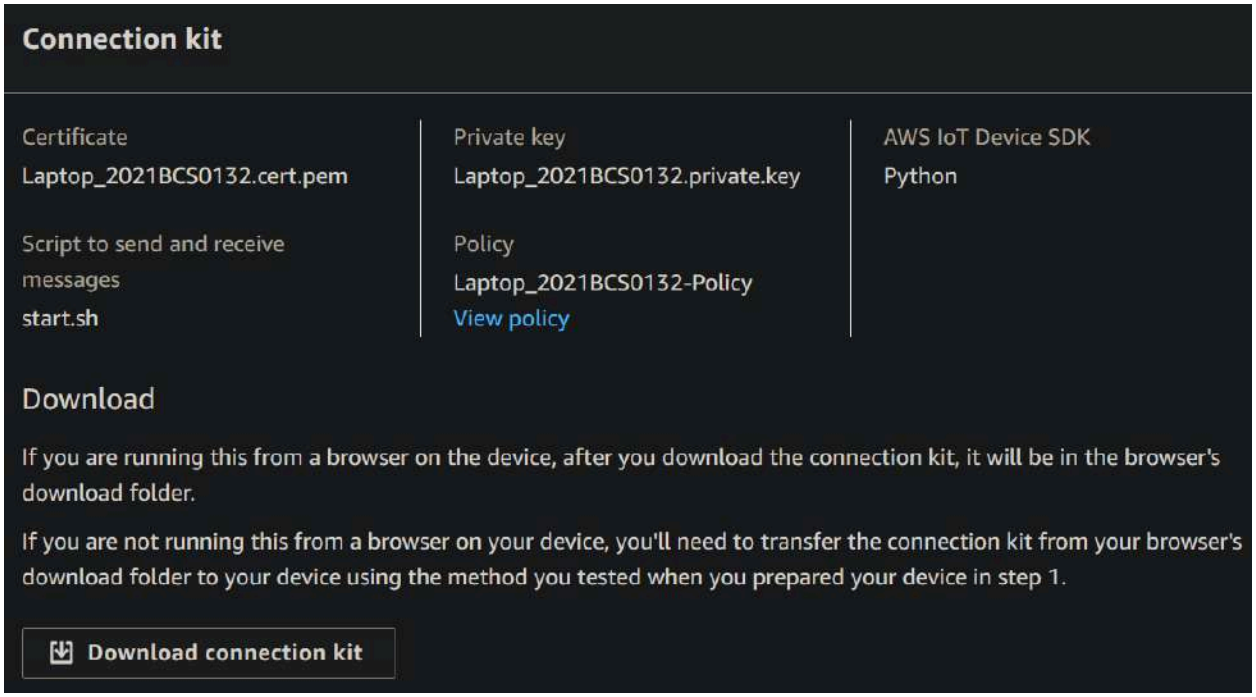
Copy

After you complete these steps and get a successful ping response, you're ready to continue and connect your device to AWS IoT.

```
jayant@Jayant-sAcerP:~$ ping a14gmez3k91qqg-ats.iot.ap-northeast-1.amazonaws.com
PING a14gmez3k91qqg-ats.iot.ap-northeast-1.amazonaws.com (3.114.240.159) 56(84) bytes of data.
64 bytes from ec2-3-114-240-159.ap-northeast-1.compute.amazonaws.com (3.114.240.159): icmp_seq=1 ttl=242 time=119 ms
64 bytes from ec2-3-114-240-159.ap-northeast-1.compute.amazonaws.com (3.114.240.159): icmp_seq=2 ttl=242 time=119 ms
64 bytes from ec2-3-114-240-159.ap-northeast-1.compute.amazonaws.com (3.114.240.159): icmp_seq=3 ttl=242 time=119 ms
64 bytes from ec2-3-114-240-159.ap-northeast-1.compute.amazonaws.com (3.114.240.159): icmp_seq=4 ttl=242 time=119 ms
64 bytes from ec2-3-114-240-159.ap-northeast-1.compute.amazonaws.com (3.114.240.159): icmp_seq=5 ttl=242 time=119 ms
64 bytes from ec2-3-114-240-159.ap-northeast-1.compute.amazonaws.com (3.114.240.159): icmp_seq=6 ttl=242 time=120 ms
^C
--- a14gmez3k91qqg-ats.iot.ap-northeast-1.amazonaws.com ping statistics ---
6 packets transmitted, 6 received, 0% packet loss, time 5007ms
rtt min/avg/max/mdev = 118.870/119.199/119.640/0.270 ms
jayant@Jayant-sAcerP:~$
```

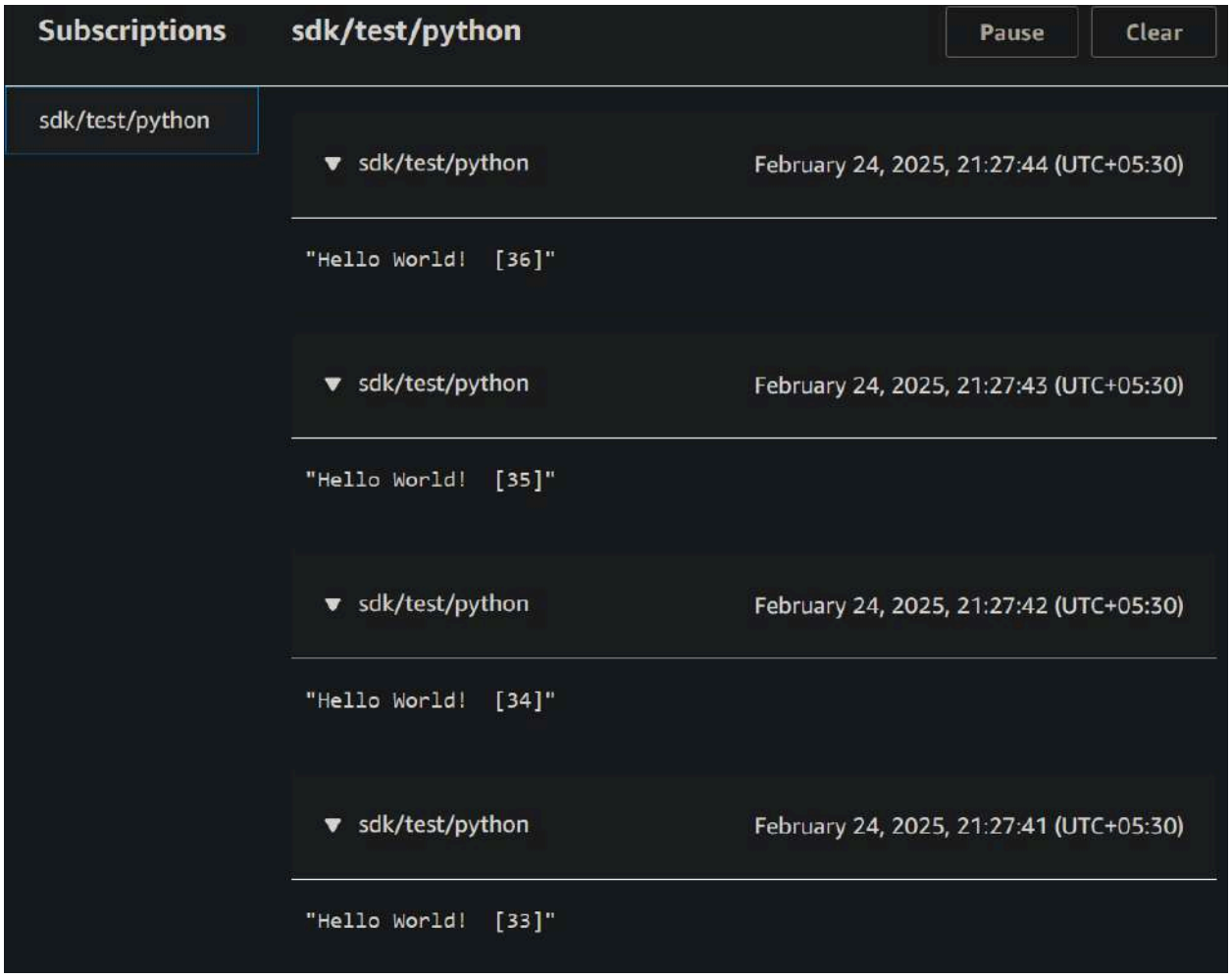


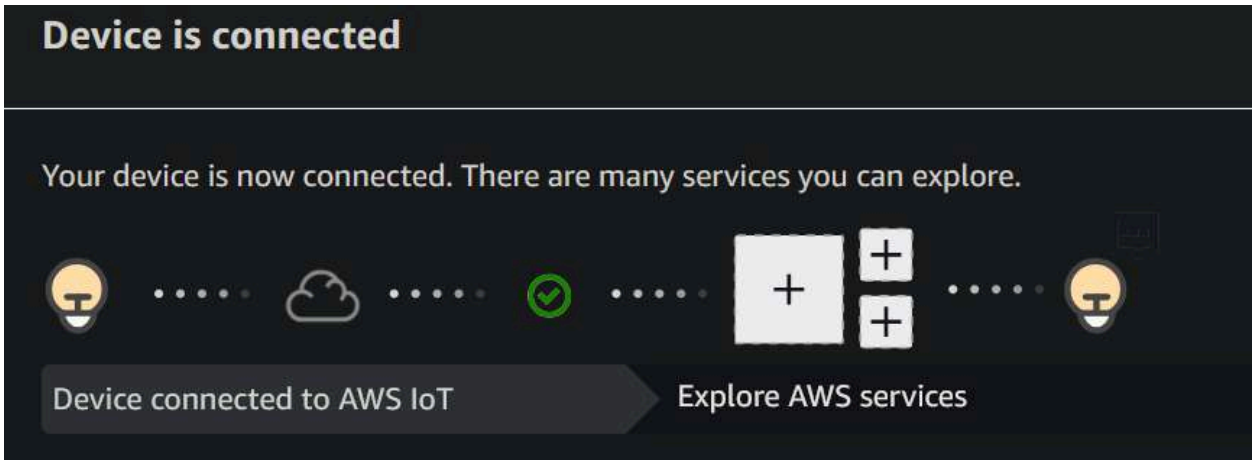

Platform and SDK
Choose the platform OS and AWS IoT Device SDK that you want to use for your device.
Device platform operating system
This is the operating system installed on the device that will connect to AWS.
Linux / macOS
Linux version: any
macOS version: 10.13+
Windows
Version 10
AWS IoT Device SDK
Choose a Device SDK that's in a language your device supports.
Node.js
Version 10+
Requires Node.js and npm to be installed
Python
Version 3.6+
Requires Python and Git to be installed
Java
Version 8
Requires Java JDK, Maven, and Git to be installed


Connection kit
Certificate
Laptop_2021BCS0132.cert.pem
Private key
Laptop_2021BCS0132.private.key
AWS IoT Device SDK
Python
Script to send and receive messages
start.sh
Policy
Laptop_2021BCS0132-Policy
View policy
Download
If you are running this from a browser on the device, after you download the connection kit, it will be in the browser's download folder.
If you are not running this from a browser on your device, you'll need to transfer the connection kit from your browser's download folder to your device using the method you tested when you prepared your device in step 1.
Download connection kit

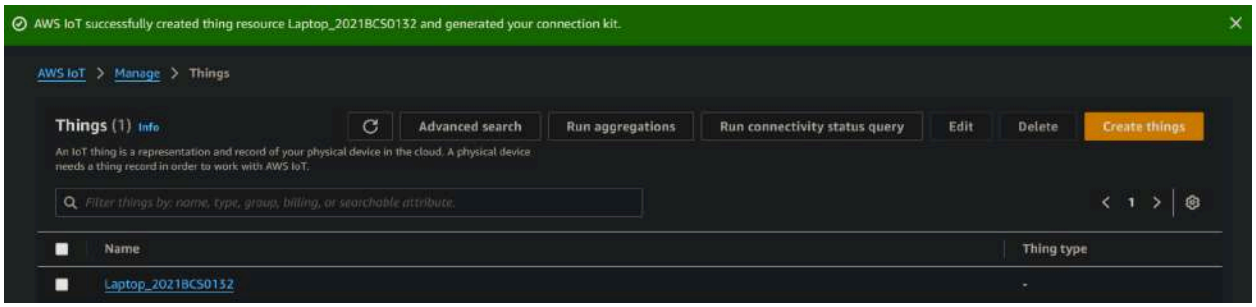

```
jayant@Jayant-sAcerP:~$ cd /mnt/c/Users/Jayant/Downloads
jayant@Jayant-sAcerP:/mnt/c/Users/Jayant/Downloads$ unzip connect_device_package.zip
Archive:  connect_device_package.zip
 extracting: Laptop_2021BCS0132.cert.pem
 extracting: Laptop_2021BCS0132.public.key
 extracting: Laptop_2021BCS0132.private.key
 extracting: Laptop_2021BCS0132-Policy
 extracting: start.sh
```

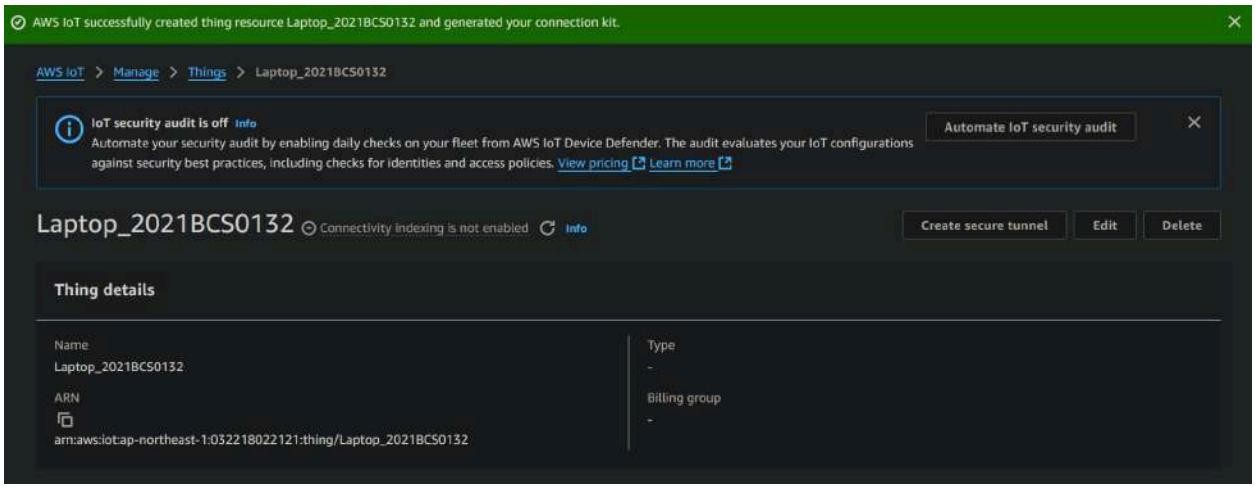
```
jayant@Jayant-sAcerP:/mnt/c/Users/Jayant/Downloads$ chmod +x start.sh
jayant@Jayant-sAcerP:/mnt/c/Users/Jayant/Downloads$ ./start.sh

Downloading AWS IoT Root CA certificate from AWS...
  % Total    % Received % Xferd  Average Speed   Time    Time     Time  Current
                                 Dload  Upload   Total   Spent    Left  Speed
100  1188  100  1188    0     0   6188      0 --:--:-- --:--:-- --:--:--  6219

Cloning the AWS SDK...
Cloning into 'aws-iot-device-sdk-python-v2'...
remote: Enumerating objects: 2715, done.
remote: Counting objects: 100% (957/957), done.
remote: Compressing objects: 100% (263/263), done.
remote: Total 2715 (delta 826), reused 710 (delta 694), pack-reused 1758 (from 3)
Receiving objects: 100% (2715/2715), 2.32 MiB | 7.51 MiB/s, done.
Resolving deltas: 100% (1742/1742), done.
Updating files: 100% (188/188), done.

Running pub/sub sample application...
Connecting to a14gmez3k91qqg-ats.iot.ap-northeast-1.amazonaws.com with client ID 'basicPubSub'...
Connection Successful with return code: 0 session present: False
Connected!
Subscribing to topic 'sdk/test/python'...
Subscribed with QoS.AT_LEAST_ONCE
Sending messages until program killed
Publishing message to topic 'sdk/test/python': Hello World!  [1]
Received message from topic 'sdk/test/python': b'"Hello World!  [1]"'
Publishing message to topic 'sdk/test/python': Hello World!  [2]
Received message from topic 'sdk/test/python': b'"Hello World!  [2]"'
Publishing message to topic 'sdk/test/python': Hello World!  [3]
Received message from topic 'sdk/test/python': b'"Hello World!  [3]"'
Publishing message to topic 'sdk/test/python': Hello World!  [4]
Received message from topic 'sdk/test/python': b'"Hello World!  [4]"'
```


Subscriptions
sdk/test/python
Pause
Clear
sdk/test/python
sdk/test/python
February 24, 2025, 21:27:44 (UTC+05:30)
"Hello World! [36]"
sdk/test/python
February 24, 2025, 21:27:43 (UTC+05:30)
"Hello World! [35]"
sdk/test/python
February 24, 2025, 21:27:42 (UTC+05:30)
"Hello World! [34]"
sdk/test/python
February 24, 2025, 21:27:41 (UTC+05:30)
"Hello World! [33]"

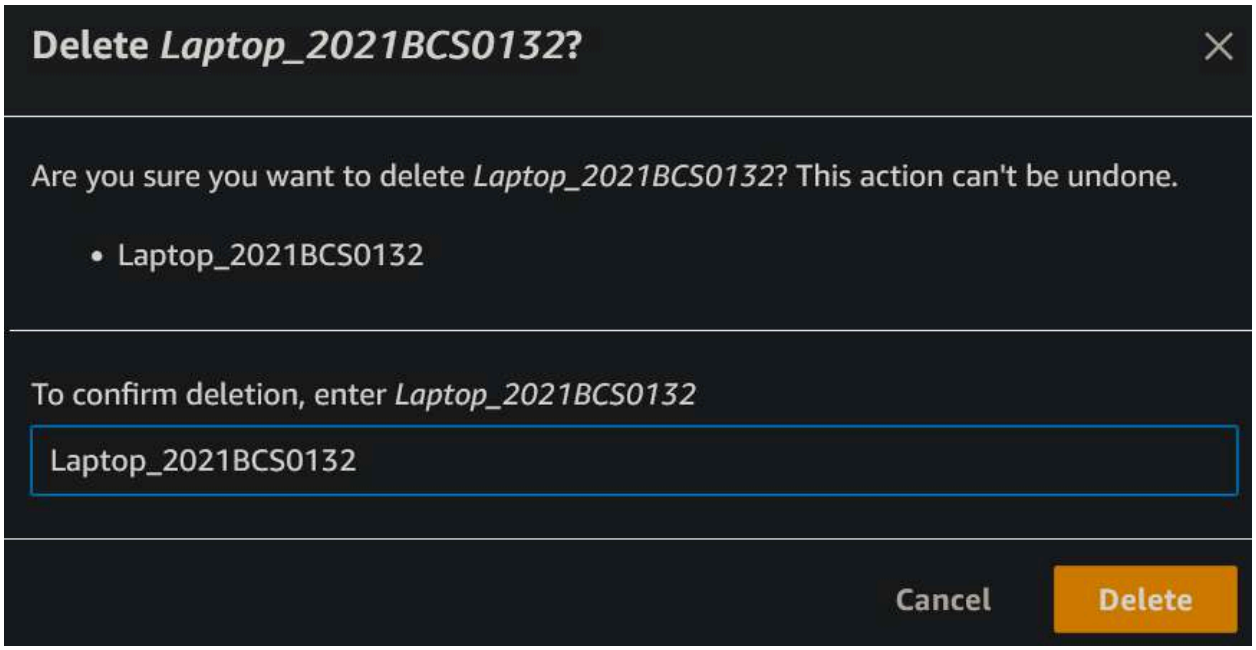

Device is connected
Your device is now connected. There are many services you can explore.
Device connected to AWS IoT
Explore AWS services

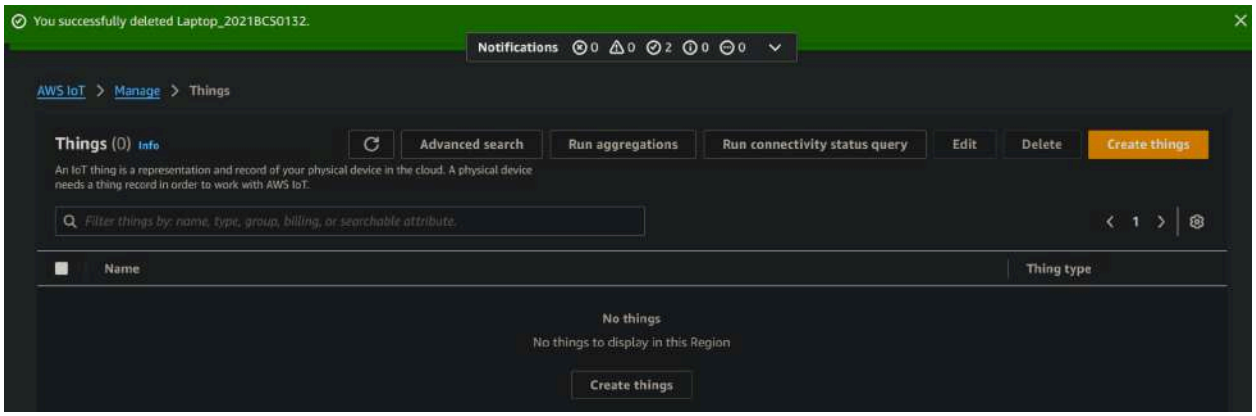
As we see, the laptop is connected as a ‘Thing’ under AWS IoT Core





To delete the thing, follow these steps



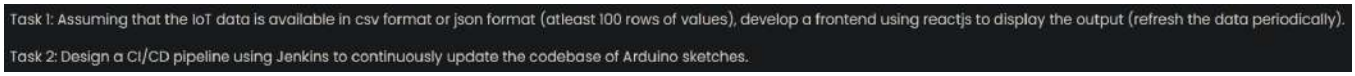


The Thing has been deleted and no longer exists.

Lab 8
ICS423 - Internet of Things

Jayant Kolapkar - 2021BCS0132

Question



Task 1

Algorithm and Code

1. Create a node server which generates the IOT (temperature data) periodically and

stores the data in a CSV file.

Code: server.js

```
const express = require("express");
const fs = require("fs");
const cors = require("cors");
const fastCsv = require("fast-csv");
const app = express();
const PORT = 5000;
const FILE_PATH = "iot_data.csv";
```

```
// Enable CORS
app.use(cors());

// Function to generate random IoT data
const generateData = () => {
    const timestamp = new Date().toISOString();
```

```
    const temperature = (Math.random() * 15 + 20).toFixed(2); // Random
temp between 20-35°C
    return `${timestamp},${temperature}\n`;
};

// Function to write data to CSV file every 2 seconds
const appendData = () => {
    const header = "timestamp,temperature\n";
    if (!fs.existsSync(FILE_PATH)) {
        fs.writeFileSync(FILE_PATH, header);
    }
    setInterval(() => {
    fs.appendFileSync(FILE_PATH, generateData());
    }, 2000);
};

// API endpoint to get the last 100 rows
app.get("/data", (req, res) => {
    const rows = [];
    fs.createReadStream(FILE_PATH)
        .pipe(fastCsv.parse({ headers: true }))
        .on("data", (row) => rows.push(row))
        .on("end", () => {
            res.json(rows.slice(-100)); // Send last 100 rows
        });
});

// Start the server and begin data generation
app.listen(PORT, () => {
    console.log(`Server running on http://localhost:${PORT}`);
    appendData();
});
```

2. Start the server. You will observe that the data will get stored in the CSV file continuously.

3. Create React dashboard by creating the react app and installing the necessary dependencies.

4. Fetch the data from the CSV file on the server and fetch the data using the GET api by integrating the react frontend with node backend.

Code: App.js

```
import React, { useState, useEffect } from "react";
import axios from "axios";
import "./App.css"; // Import external CSS

const API_URL = "http://localhost:5000/data";

const App = () => {
  const [data, setData] = useState([]);
  const [lastUpdated, setLastUpdated] = useState(null);
  const [rowCount, setRowCount] = useState(0);

  useEffect(() => {
    const fetchData = () => {
      axios.get(API_URL)
        .then((response) => {
          setData(response.data);
          setLastUpdated(new Date().toLocaleTimeString()); // Set last
update time
          setRowCount(response.data.length); // Set row count
        })
        .catch((error) => console.error("Error fetching data:", error));
    };

    fetchData(); // Initial fetch
    const interval = setInterval(fetchData, 5000); // Fetch every 5
seconds

    return () => clearInterval(interval); // Cleanup on unmount
  }, []);

  return (
    <div className="container">
```

```
      <h2 className="title">IoT Sensor Data</h2>
      <p className="info">
        <strong>Last Updated:</strong> {lastUpdated || "Fetching..."} |
        <strong> Rows Fetched:</strong> {rowCount}
      </p>
      <div className="table-container">
        <table className="styled-table">
          <thead>
            <tr>
              <th>Timestamp</th>
              <th>Temperature (°C)</th>
            </tr>
          </thead>
          <tbody>
            {data.map((row, index) => (
              <tr key={index}>
                <td>{row.timestamp}</td>
                <td>{row.temperature}</td>
              </tr>
            ))}
          </tbody>
        </table>
      </div>
    </div>
  );
};

export default App;
```

5. Open the localhost and view the updated data on the dashboard.

IoT Sensor Data

Last Updated: 10:10:20 pm | **Rows Fetched:** 100

Timestamp	Temperature (°C)
2025-03-03T16:37:00.111Z	25.83
2025-03-03T16:37:02.115Z	32.79
2025-03-03T16:37:04.121Z	23.91
2025-03-03T16:37:06.125Z	26.60
2025-03-03T16:37:08.130Z	27.01
2025-03-03T16:37:10.138Z	34.09
2025-03-03T16:37:12.146Z	20.39
2025-03-03T16:37:14.161Z	26.70
2025-03-03T16:37:16.162Z	21.89
2025-03-03T16:37:18.169Z	21.13
2025-03-03T16:37:20.173Z	26.54
2025-03-03T16:37:22.181Z	28.86
2025-03-03T16:37:24.189Z	31.66

IoT Sensor Data

Last Updated: 10:10:35 pm | **Rows Fetched:** 100

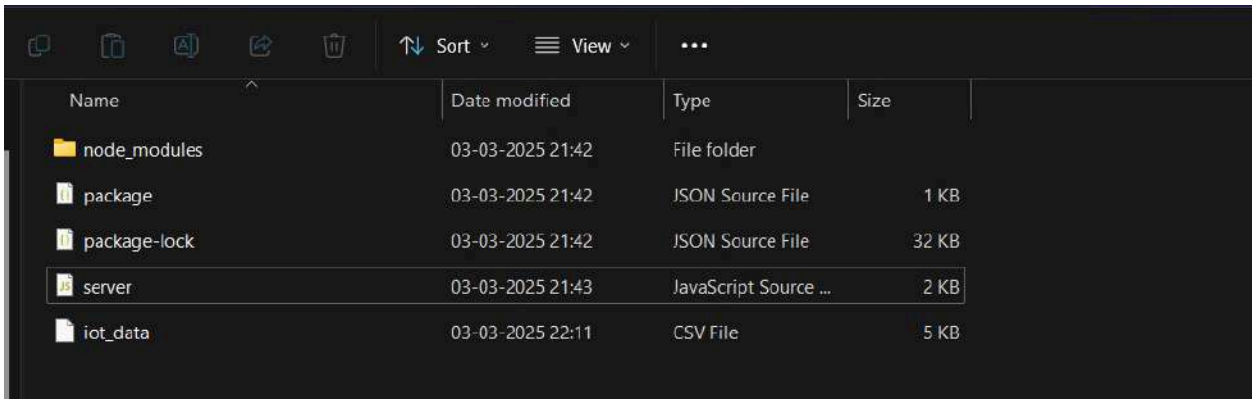
Timestamp	Temperature (°C)
2025-03-03T16:37:16.162Z	21.89
2025-03-03T16:37:18.169Z	21.13
2025-03-03T16:37:20.173Z	26.54
2025-03-03T16:37:22.181Z	28.86
2025-03-03T16:37:24.189Z	31.66
2025-03-03T16:37:26.189Z	28.12
2025-03-03T16:37:28.197Z	20.26
2025-03-03T16:37:30.201Z	23.31
2025-03-03T16:37:32.209Z	33.66
2025-03-03T16:37:34.218Z	34.76
2025-03-03T16:37:36.222Z	20.85
2025-03-03T16:37:38.229Z	32.67
2025-03-03T16:37:40.239Z	20.56

IoT Sensor Data

Last Updated: 10:10:56 pm | **Rows Fetched:** 100

Timestamp	Temperature (°C)
2025-03-03T16:37:36.222Z	20.85
2025-03-03T16:37:38.229Z	32.67
2025-03-03T16:37:40.239Z	20.56
2025-03-03T16:37:42.240Z	30.03
2025-03-03T16:37:44.241Z	21.59
2025-03-03T16:37:46.244Z	32.51
2025-03-03T16:37:48.251Z	21.99
2025-03-03T16:37:50.251Z	28.78
2025-03-03T16:37:52.254Z	23.69
2025-03-03T16:37:54.269Z	30.00
2025-03-03T16:37:56.274Z	33.65
2025-03-03T16:37:58.283Z	29.83
2025-03-03T16:38:00.288Z	24.92

6. View and verify the Data getting stored in CSV file.



	A	B	C	D
1	timestamp	temperature		
2	2025-03-03	30.38		
3	2025-03-03	25.83		
4	2025-03-03	32.79		
5	2025-03-03	23.91		
6	2025-03-03	28.6		
7	2025-03-03	27.01		
8	2025-03-03	34.09		
9	2025-03-03	20.39		
10	2025-03-03	26.7		
11	2025-03-03	21.89		
12	2025-03-03	21.13		
13	2025-03-03	26.54		
14	2025-03-03	28.86		
15	2025-03-03	31.66		
16	2025-03-03	28.12		
17	2025-03-03	20.26		
18	2025-03-03	23.31		
19	2025-03-03	33.66		
20	2025-03-03	34.76		
21	2025-03-03	20.85		
22	2025-03-03	32.67		
23	2025-03-03	20.56		
24	2025-03-03	30.03		
25	2025-03-03	21.59		
26	2025-03-03	32.51		
27	2025-03-03	21.99		
28	2025-03-03	28.78		
29	2025-03-03	23.69		

	A	B	C	D
120	2025-03-03	22.53		
121	2025-03-03	28.86		
122	2025-03-03	32.57		
123	2025-03-03	23.9		
124	2025-03-03	23.58		
125	2025-03-03	35		
126	2025-03-03	21.02		
127	2025-03-03	32.49		
128	2025-03-03	24.45		
129	2025-03-03	26.8		
130	2025-03-03	33.56		
131	2025-03-03	27.57		
132	2025-03-03	21.69		
133	2025-03-03	21.51		
134	2025-03-03	34.26		
135	2025-03-03	26.45		
136	2025-03-03	20.76		
137	2025-03-03	24.94		
138	2025-03-03	27.45		
139	2025-03-03	22.09		
140	2025-03-03	21.28		
141	2025-03-03	27.2		
142	2025-03-03	21.65		
143	2025-03-03	30.92		
144	2025-03-03	27.35		
145	2025-03-03	28.51		
146	2025-03-03	27.01		
147	2025-03-03	20.19		
148	2025-03-03	27.33		

iot_data

Task 2

Algorithm:

1. Install Java version 17 or 21. (For our case we will proceed with Java version 17)

```
C:\Users\kanak>java -version
java version "17.0.12" 2024-07-16 LTS
Java(TM) SE Runtime Environment (build 17.0.12+8-LTS-286)
Java HotSpot(TM) 64-Bit Server VM (build 17.0.12+8-LTS-286, mixed mode, sharing)
```

2. Install Jenkins.

3. Start jenkins using CMD (as administrator)

```
C:\Windows\System32>C:\Users\kanak>net start jenkins
```

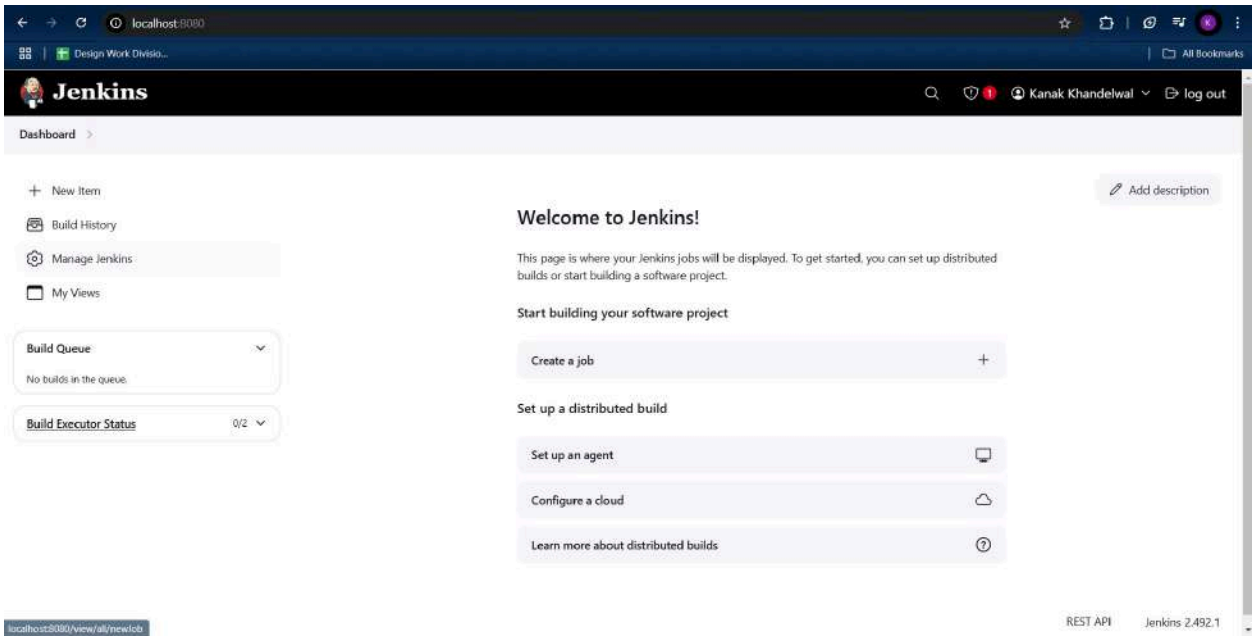
```
C:\Windows\System32>net start jenkins
The requested service has already been started.
```

4. Start your localhost (port 8080 which was added during installation).

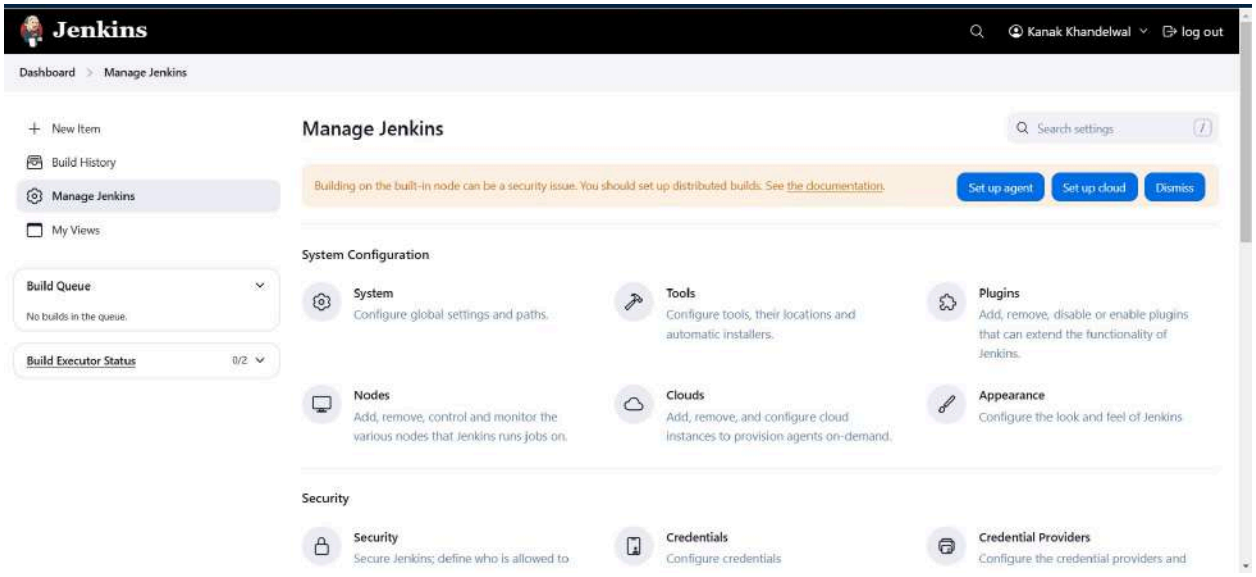
http://localhost:8080

5. Install necessary plugins and setup admin.

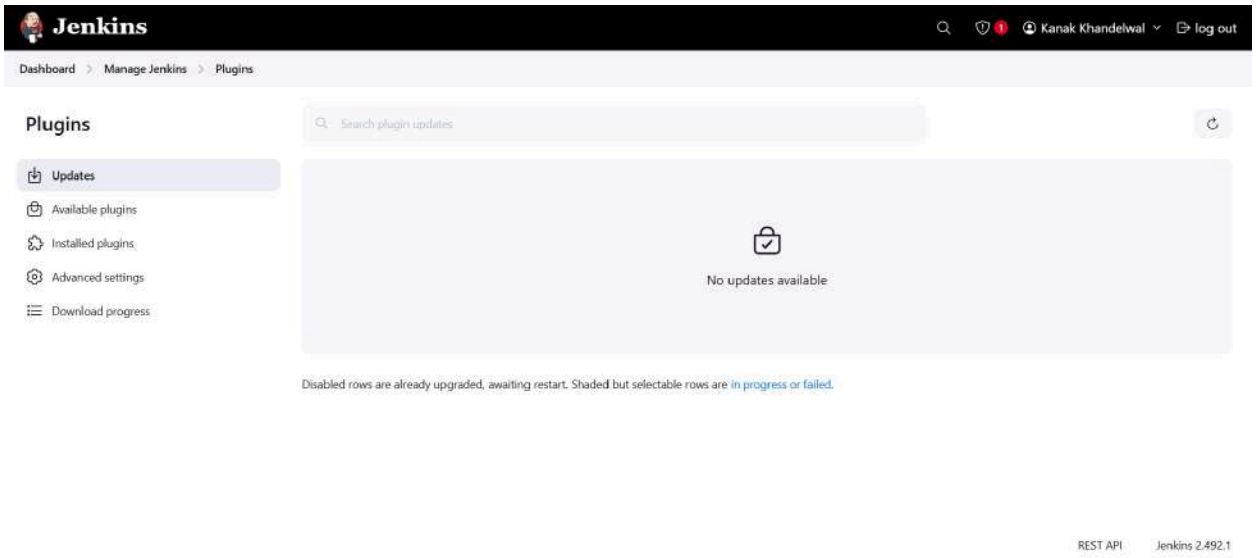
Login to jenkins. Go to dashboard



7. Go to manage jenkins from the left panel.

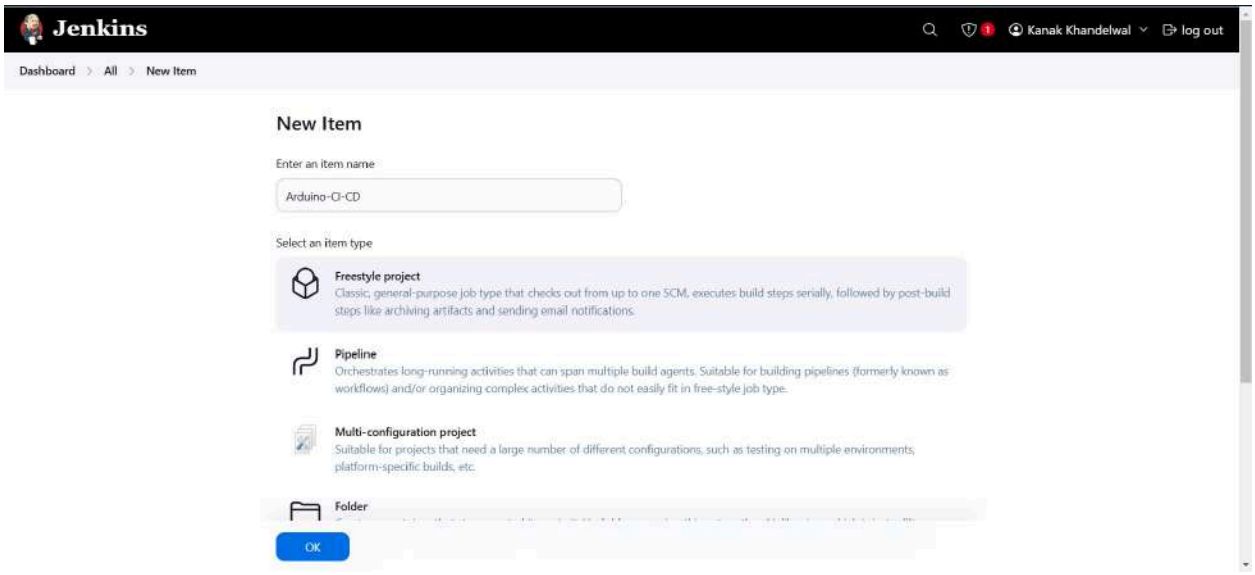


8. Go to plugins

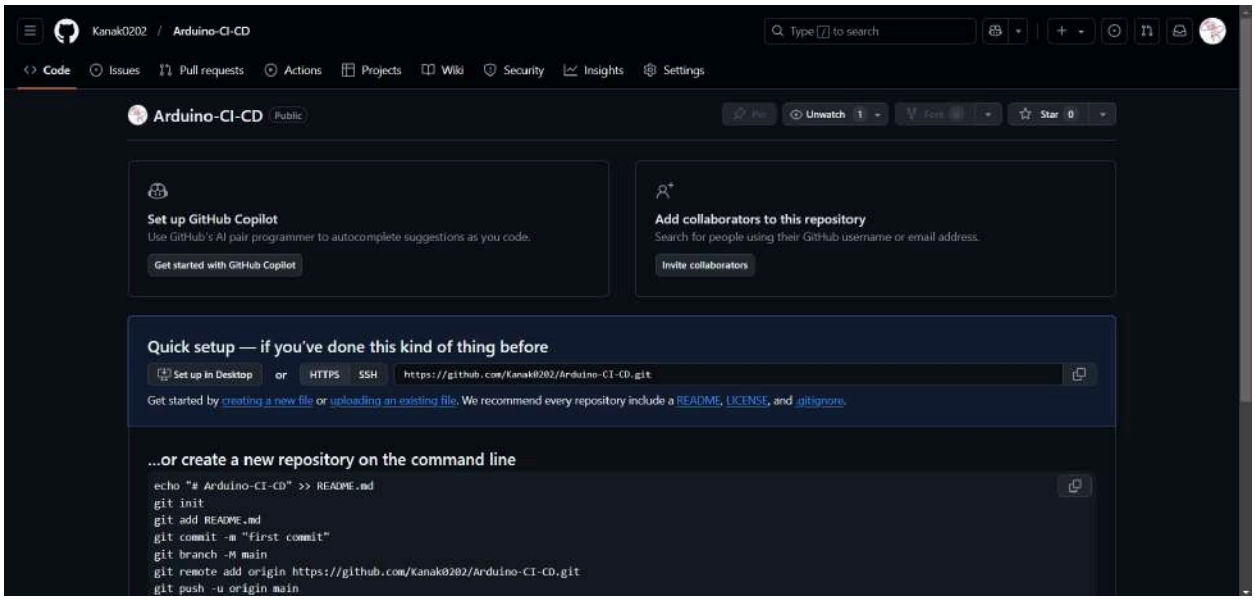


9. Install and enable Git Plugin and Pipeline Plugin.

10. Create a new jenkins job, enter desired name and select pipeline.



11. Create git repository for arduino.

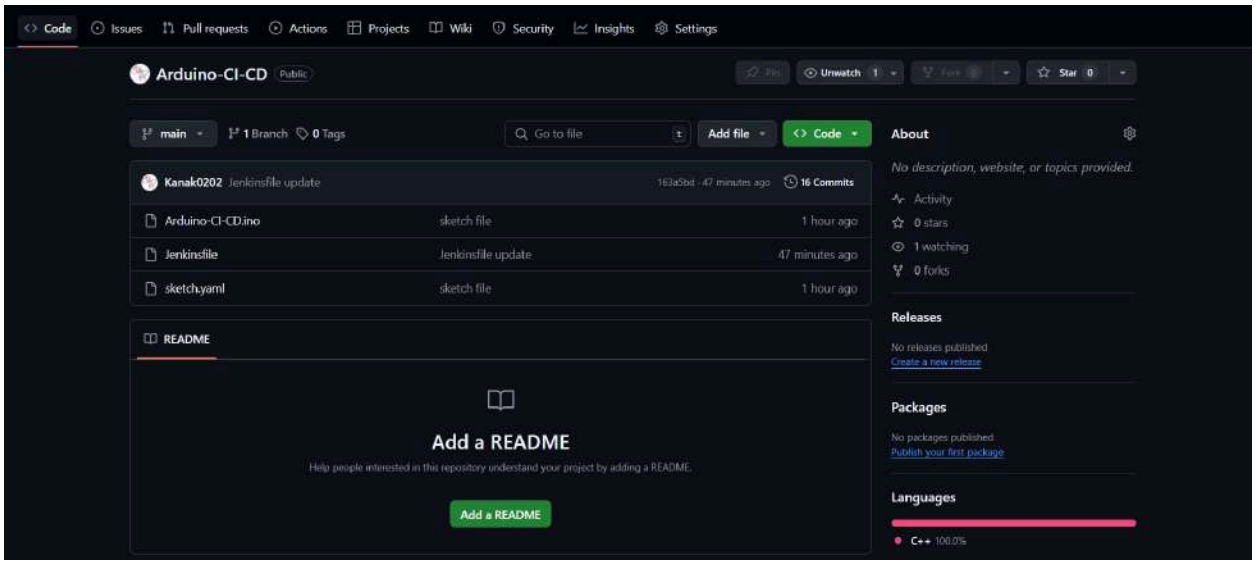


12. Setup project on local.

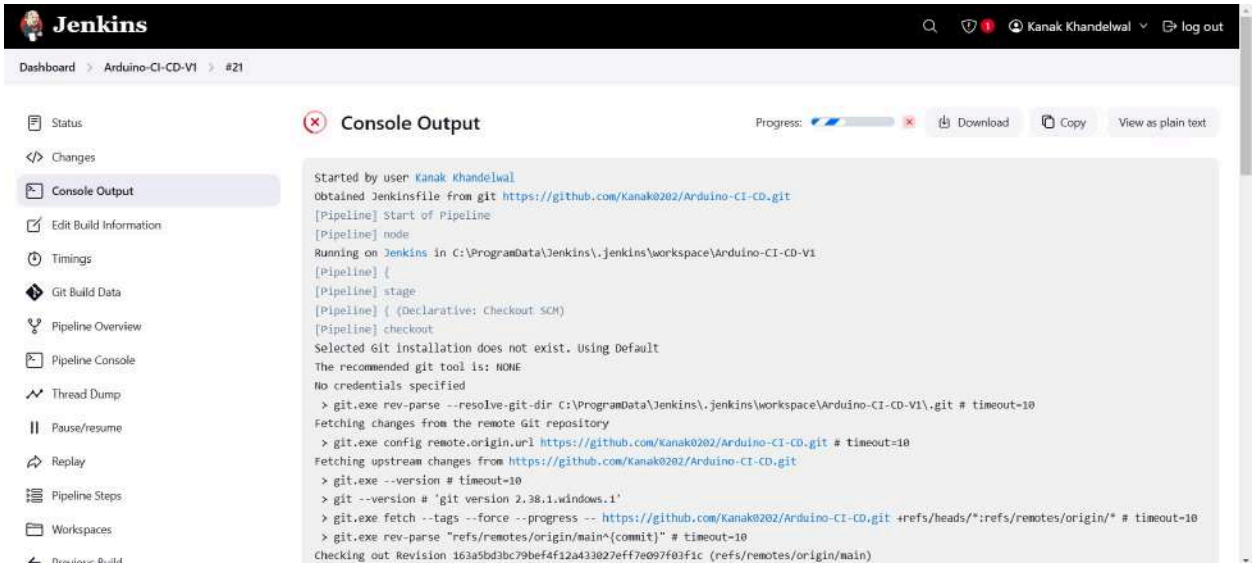
```
PS D:\KANAK\SEM-VIII\IOT\Arduino-CI-CD> git init
Initialized empty Git repository in D:/KANAK/SEM-VIII/IOT/Arduino-CI-CD/.git/
PS D:\KANAK\SEM-VIII\IOT\Arduino-CI-CD> git remote add origin https://github.com/Kanak0202/Arduino-CI-CD.
PS D:\KANAK\SEM-VIII\IOT\Arduino-CI-CD>
```

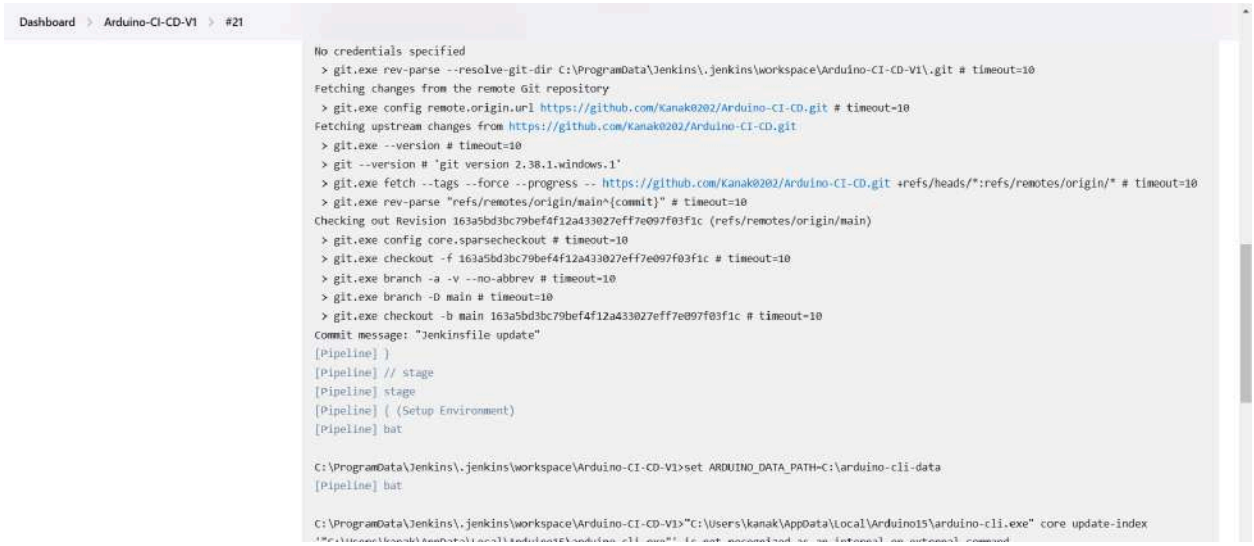
```
Administrator: C:\WINDOWS\system32\cmd.exe
Microsoft Windows [Version 10.0.22631.4974]
(c) Microsoft Corporation. All rights reserved.

C:\Windows\System32>mkdir C:\arduino-cli-data
A subdirectory or file C:\arduino-cli-data already exists.

C:\Windows\System32>arduino-cli config init
Config file written to: C:\Users\kanak\AppData\Local\Arduino15\arduino-cli.yaml

C:\Windows\System32>arduino-cli config set directories.data C:\arduino-cli-data

C:\Windows\System32>arduino-cli config dump
board_manager:
    additional_urls: []
directories:
    data: C:\arduino-cli-data


C:\Windows\System32>
```

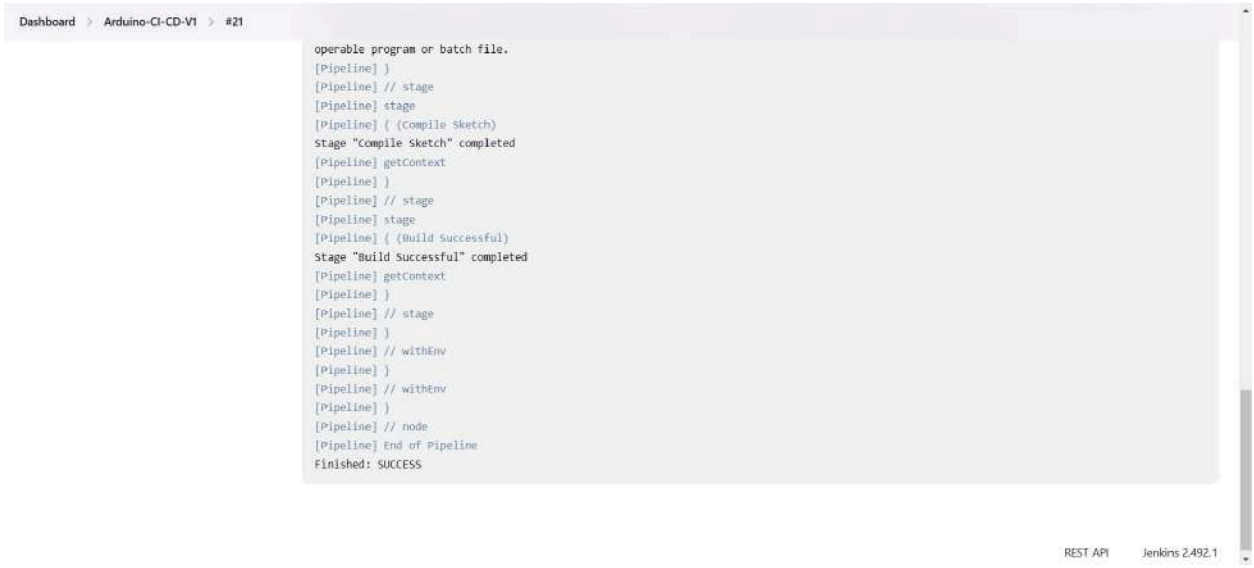
Push the code to github onto your repository.



Run your build.







Code

Arduino-CI-CD.ino

```
// Simple Blink Sketch

#define LED_PIN 13
void setup() {
    pinMode(LED_PIN, OUTPUT);
}
```

```
void loop() {
    digitalWrite(LED_PIN, HIGH); // Turn LED on
    delay(1000);
    digitalWrite(LED_PIN, LOW); // Turn LED off
    delay(1000);
}
```

Jenkinsfile

```
pipeline {
    agent any

    environment {
        ARDUINO_CLI =
"C:\\Users\\kanak\\AppData\\Local\\Arduino15\\arduino-cli.exe"
        ARDUINO_DATA_PATH = "C:\\arduino-cli-data"
    }

    stages {
        stage('Checkout Code') {
        steps {
            git branch: 'main', url:
'https://github.com/Kanak0202/Arduino-CI-CD.git'
        }
    }

        stage('Setup Environment') {
            steps {
                bat 'set ARDUINO_DATA_PATH=C:\\arduino-cli-data'
                bat '"%ARDUINO_CLI%" core update-index'
                bat '"%ARDUINO_CLI%" core install arduino:avr'
            }
        }

        stage('Compile Sketch') {
            steps {
                bat '"%ARDUINO_CLI%" compile --fqbn arduino:avr:uno .'
            }
```

```
        }

        stage('Build Successful') {
            steps {
                echo 'Build completed successfully!'
            }
        }
    }
}
```

Lab 9
ICS423 - Internet of Things

Jayant Kolapkar - 2021BCS0132

Question

Task 1: Write golang-based services (2 numbers) on docker containers

Task 2: Write nodejs-based services (2 numbers) on docker containers

Task 1

1. Introduction

This project involves developing two microservices using Golang, containerizing them using Docker, and orchestrating them with Docker Compose. The microservices perform basic arithmetic operations:

- Service A: Addition (/add)
- Service B: Multiplication (/multiply)

Each service runs independently in a Docker container, ensuring scalability and ease of deployment.

---

2. Methodology

The following steps were followed:

1. Developed two Golang microservices using net/http.
2. Containerized each service using Docker.
3. Created a Docker Compose file to orchestrate the services.
4. Built and deployed the containers.
5. Tested the endpoints using curl.

3. Implementation

3.1. Service A: Addition Microservice

1. Create serviceA/go.mod

module serviceA

go 1.24

2. Create serviceA/main.go

```
package main

import (
    "encoding/json"
    "fmt"
    "net/http"
)
type Request struct {
    A float64 `json:"a"`
    B float64 `json:"b"`
}

type Response struct {
    Result float64 `json:"result"`
}

func addHandler(w http.ResponseWriter, r *http.Request) {
    var req Request
    err := json.NewDecoder(r.Body).Decode(&req)
    if err != nil {
        http.Error(w, "Invalid request", http.StatusBadRequest)
        return
```

```
    }

    result := req.A + req.B
    resp := Response{Result: result}

    w.Header().Set("Content-Type", "application/json")
    json.NewEncoder(w).Encode(resp)
}

func main() {
    http.HandleFunc("/add", addHandler)
    fmt.Println("Adder Service running on port 8081...")
    http.ListenAndServe(":8081", nil)
}
```

3. Create serviceA/Dockerfile

```
FROM golang:1.24

WORKDIR /app

COPY . .

RUN go mod tidy && go build -o main .

CMD ["/app/main"]
```

3.2. Service B: Multiplication Microservice

1. Create serviceB/go.mod

module serviceB

go 1.24

2. Create serviceB/main.go

```
package main

import (
    "encoding/json"
    "fmt"
    "net/http"
)

type Request struct {
    A float64 `json:"a"`
    B float64 `json:"b"`
}

type Response struct {
    Result float64 `json:"result"`
}

func multiplyHandler(w http.ResponseWriter, r *http.Request) {
    var req Request
    err := json.NewDecoder(r.Body).Decode(&req)
    if err != nil {
        http.Error(w, "Invalid request", http.StatusBadRequest)
        return
    }

    result := req.A * req.B
    resp := Response{Result: result}

    w.Header().Set("Content-Type", "application/json")
    json.NewEncoder(w).Encode(resp)
}

func main() {
    http.HandleFunc("/multiply", multiplyHandler)
    fmt.Println("Multiplier Service running on port 8082...")
```

```
    http.ListenAndServe(":8082", nil)
}
```

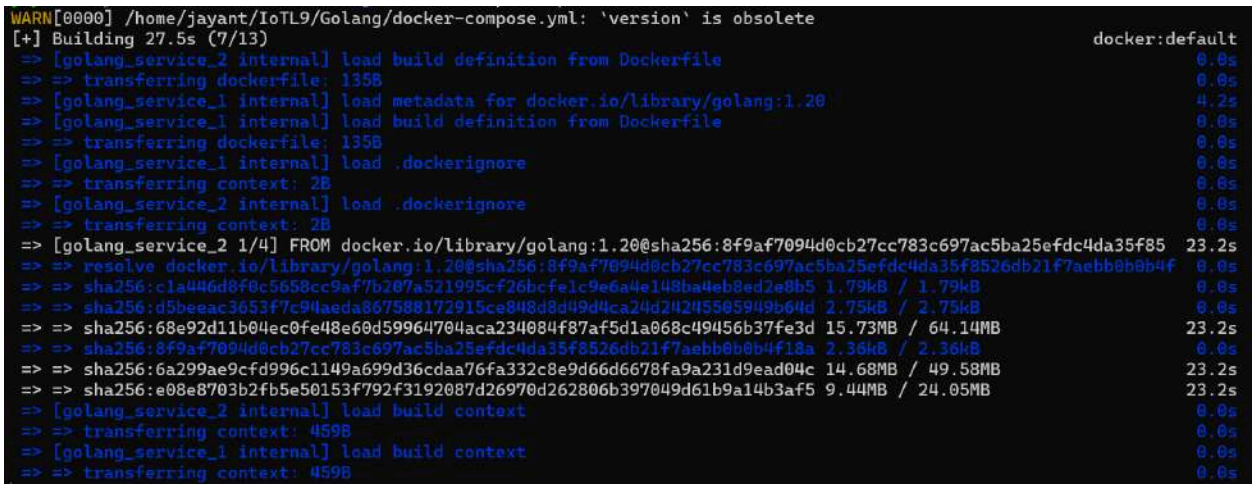
3. Create serviceB/Dockerfile

```
FROM golang:1.24

WORKDIR /app

COPY . .

RUN go mod tidy && go build -o main .

CMD ["/app/main"]
```

4. Deployment Steps

Step 1: Build and Start Containers

docker-compose up –build



```
[+] Building 75.6s (15/15) FINISHED
 => [serviceb internal] load build definition from Dockerfile
 => => transferring dockerfile: 145B
 => [serviceb internal] load .dockerignore
 => => transferring context: 2B
 => [servicea internal] load metadata for docker.io/library/golang:1.24
 => [servicea internal] load build definition from Dockerfile
 => => transferring dockerfile: 147B
 => [servicea internal] load .dockerignore
 => => transferring context: 2B
 => [servicea 1/4] FROM docker.io/library/golang:1.24@sha256:c5adecdb7b3f8c5ca3c88648a861882849cc8b02fed68ece31e25de88ad13418
 => => resolve docker.io/library/golang:1.24@sha256:c5adecdb7b3f8c5ca3c88648a861882849cc8b02fed68ece31e25de88ad13418
 => => sha256:29616a01ff27428aaf681f7abd8439b6aca78cadb73fac0475196cb261a34b91 2.80kB / 2.80kB
 => => sha256:155ad54a8b2812a0ec559ff82c0c6f0f0dddb337a226b11879f09e15f67b69fc 48.48MB / 48.48MB
 => => sha256:1d281e50d3e435595c266df06531a7e8c2ebb0c185622c8ab2eed8d760e6576b 64.39MB / 64.39MB
 => => sha256:c5adecdb7b3f8c5ca3c88648a861882849cc8b02fed68ece31e25de88ad13418 10.06kB / 10.06kB
 => => sha256:7ebae3e990ad9a8406da7ec4cd127decc408c98f8a88d0f2bef629bcaff691cd 2.32kB / 2.32kB
 => => sha256:8031108f3cda87bb32f090262d0109c8a0db99168050967becefad502e9a681b 24.06MB / 24.06MB
 => => sha256:ec6bde4714ee6491f090f4367e5c540e43ac6f9b238b25b0838f2a9d1d10f577 92.33MB / 92.33MB
 => => extracting sha256:155ad54a8b2812a0ec559ff82c0c6f0f0dddb337a226b11879f09e15f67b69fc
 => => sha256:178cc98ff0842a2601bbc4e7db3db70a323469849a03684d1b9b21e7f825b7e4 78.93MB / 78.93MB
 => => extracting sha256:8031108f3cda87bb32f090262d0109c8a0db99168050967becefad502e9a681b
 => => sha256:c10ccacbd8ad4103e29b0a10e17fcfdbc768b1361d50b2c9222d457544de4cb1 126B / 126B
 => => extracting sha256:1d281e50d3e435595c266df06531a7e8c2ebb0c185622c8ab2eed8d760e6576b
```

```
 => [serviceb] exporting to image
 => => exporting layers
 => [servicea 4/4] RUN go mod tidy && go build -o main .
 => [serviceb] exporting to image
 => [servicea 4/4] RUN go mod tidy && go build -o main .
 => [servicea 4/4] RUN go mod tidy && go build -o main .
 => [serviceb] exporting to image
 => => exporting layers
 => => writing image sha256:7ef4a56d00356d335aff47b605d71c353899ccf21433b8a012c89249bf3c7bb4
 => => naming to docker.io/library/lab9-serviceb
 => [servicea] exporting to image
 => => exporting layers
 => => writing image sha256:69351b7e070abb7338dcb0d377b00c6e1391e1bb68f16e46bd2d03ca64a7b7f2
 => => naming to docker.io/library/lab9-servicea
[+] Running 3/3
 ✓ Network lab9_default       Created
 ✓ Container lab9-serviceb-1  Created
 ✓ Container lab9-servicea-1  Created
Attaching to servicea-1, serviceb-1
servicea-1  | Adder Service running on port 8081...
serviceb-1  | Multiplier Service running on port 8082...
```

5. Testing the Services

5.1. Test Service A (Addition)

curl -X POST http://localhost:8081/add -H "Content-Type: application/json" -d "{\"a\":5, \"b\":3}"

Expected Response:

{"result":8}

5.2. Test Service B (Multiplication)

curl -X POST http://localhost:8082/multiply -H "Content-Type: application/json" -d "{\"a\":5, \"b\":3}"

Expected Response:

{"result":15}

Task 2

1. Introduction

This project involves developing two microservices using Node.js, containerizing them using Docker, and orchestrating them with Docker Compose. The microservices perform basic arithmetic operations:

Service A: Addition (/add)

Service B: Multiplication (/multiply)

Each service runs independently in a Docker container, ensuring scalability and ease of deployment.

2. Methodology

The following steps were followed:

1. Developed two Node.js microservices using express.

2. Containerized each service using Docker.

3. Created a Docker Compose file to orchestrate the services.

4. Built and deployed the containers.

5. Tested the endpoints using curl.

3. Implementation

3.1. Service A: Addition Microservice

1. Create serviceA/package.json

```
{
    "name": "servicea",
    "version": "1.0.0",
    "description": "Addition service",
    "main": "index.js",
    "dependencies": {
      "express": "^4.18.2",
      "body-parser": "^1.20.2"
    }
  }
```

2. Create serviceA/index.js const

```
const express = require("express");
const bodyParser = require("body-parser");

const app = express();
app.use(bodyParser.json());

app.post("/add", (req, res) => {
  const { a, b } = req.body;
  if (typeof a !== "number" || typeof b !== "number") {
    return res.status(400).json({ error: "Invalid input. Please provide numbers."
});
  }
  res.json({ result: a + b });
});

const PORT = 8081;
app.listen(PORT, () => console.log(`ServiceA (Addition) running on port
${PORT}`));
```

3. Create serviceA/Dockerfile

```
FROM node:22

WORKDIR /app
COPY package.json .
RUN npm install
COPY . .

CMD ["node", "index.js"]
```

3.2. Service B: Multiplication Microservice

1. Create serviceB/package.json

```
{
    "name": "serviceb",
    "version": "1.0.0",
    "description": "Multiplication service",
    "main": "index.js",
    "dependencies": {
      "express": "^4.18.2",
      "body-parser": "^1.20.2"
    }
}
```

2. Create serviceB/index.js

```
const express = require("express");
const bodyParser = require("body-parser");

const app = express();
app.use(bodyParser.json());

app.post("/multiply", (req, res) => {
  const { a, b } = req.body;
  if (typeof a !== "number" || typeof b !== "number") {
    return res.status(400).json({ error: "Invalid input. Please provide numbers."
});
  }
  res.json({ result: a * b });
});

const PORT = 8082;
app.listen(PORT, () => console.log(`ServiceB (Multiplication) running on port
${PORT}`));
```

3.3. Docker Compose Configuration

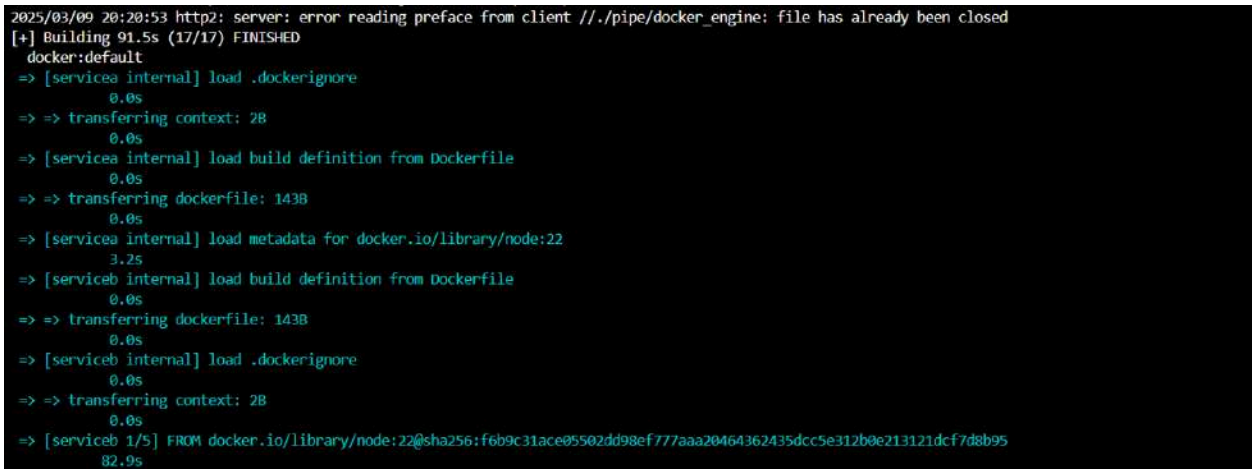
Create docker-compose.yml

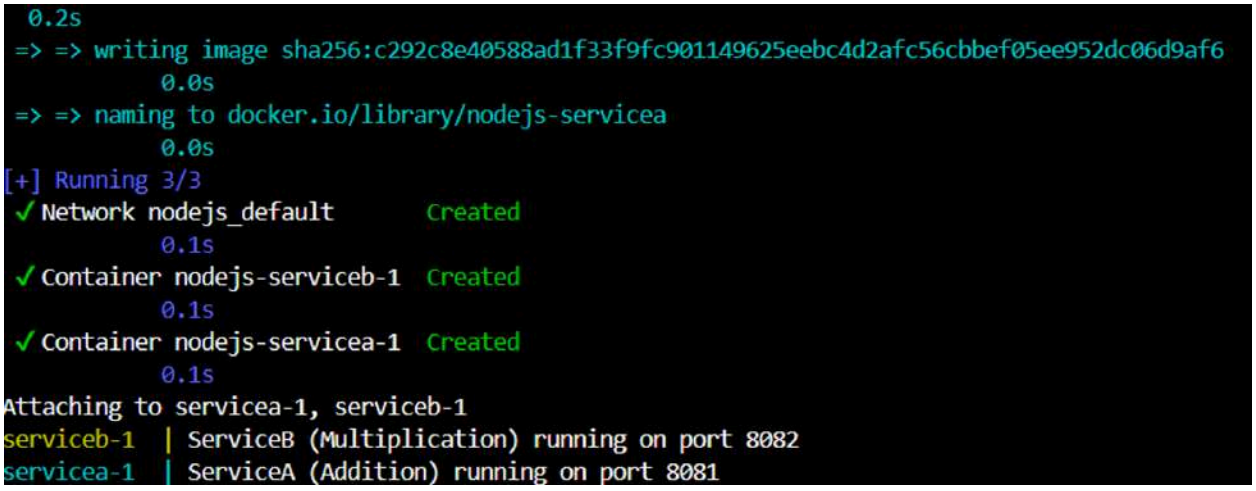
```
version: "3"
services:
  servicea:
    build: ./serviceA
    ports:
      - "8081:8081"

  serviceb:
    build: ./serviceB
    ports:
      - "8082:8082"
```

4. Deployment Steps

Step 1: Build and Start Containers

docker-compose up –build





5. Testing the Services

5.1. Test Service A (Addition)

curl -X POST http://localhost:8081/add -H "Content-Type: application/json" -d "{\"a\":5, \"b\":3}"

Expected Response:

{"result":8}

5.2. Test Service B (Multiplication)

curl -X POST http://localhost:8082/multiply -H "Content-Type: application/json" -d "{\"a\":5, \"b\":3}"

Expected Response:

{"result":15}

Conclusion

This project successfully implemented two microservices using Node.js, deployed them in Docker containers, and managed them using Docker Compose. The services were tested using curl commands to verify their functionality.

Through this implementation, we demonstrated how to create, containerize, and orchestrate microservices efficiently using Docker. This approach can be extended to build scalable and distributed applications.

Lab 10
ICS423 - Internet of Things

Jayant Kolapkar - 2021BCS0132

Question

```
Task 1: Install node red

Task 2: Write a simple node-red flow based code.

Task 3: Write a simple node-red pattern
```

Task 1

Algorithm

1. Install node.js

```
jayant@Jayant-sAcerP:~$ node -v
v12.22.9
```

2. Install npm

```
jayant@Jayant-sAcerP:~$ npm -v
8.5.1
```

3. Install node-red dependency

```
jayant@Jayant-sAcerP:~$ npm install -g --unsafe-perm node-red

added 311 packages in 24s
```

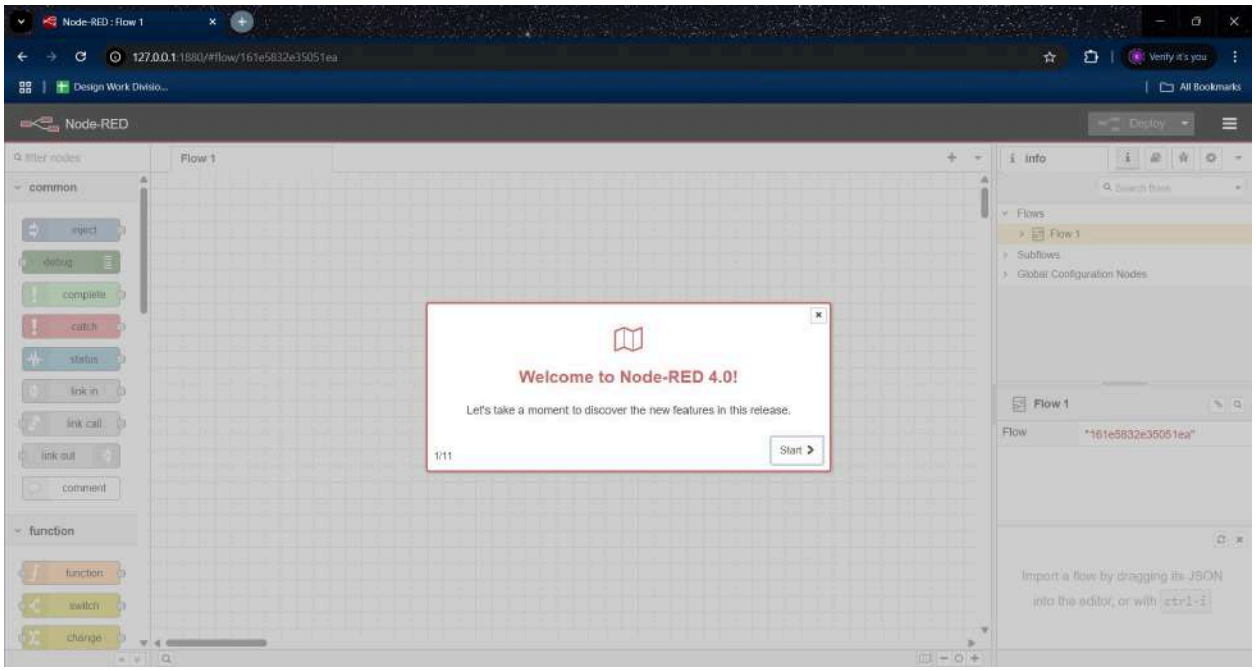
4. Create a folder for NodeRed

```
jayant@Jayant-sAcerP:~$ mkdir NodeRed
jayant@Jayant-sAcerP:~$ cd NodeRed
jayant@Jayant-sAcerP:~/NodeRed$
```

5. Start node-red using the node-red command. This will create a new flow.

```
jayant@Jayant-sAcerP:~/NodeRed$ node-red
17 Mar 12:19:02 - [info]

Welcome to Node-RED
===================

17 Mar 12:19:02 - [info] Node-RED version: v4.0.9
17 Mar 12:19:02 - [info] Node.js  version: v20.10.0
17 Mar 12:19:02 - [info] Windows_NT 10.0.22631 x64 LE


---------------------------------------------------------------------
Your flow credentials file is encrypted using a system-generated key.

If the system-generated key is lost for any reason, your credentials
file will not be recoverable, you will have to delete it and re-enter
your credentials.

You should set your own key using the 'credentialSecret' option in
your settings file. Node-RED will then re-encrypt your credentials
file using your chosen key the next time you deploy a change.
---------------------------------------------------------------------

17 Mar 12:19:15 - [warn] Encrypted credentials not found
17 Mar 12:19:15 - [info] Server now running at http://127.0.0.1:1880/
17 Mar 12:19:15 - [info] Starting flows
17 Mar 12:19:15 - [info] Started flows
```

6. Now open your browser and visit http://127.0.0.1:1880/. Your node-red will be running here.

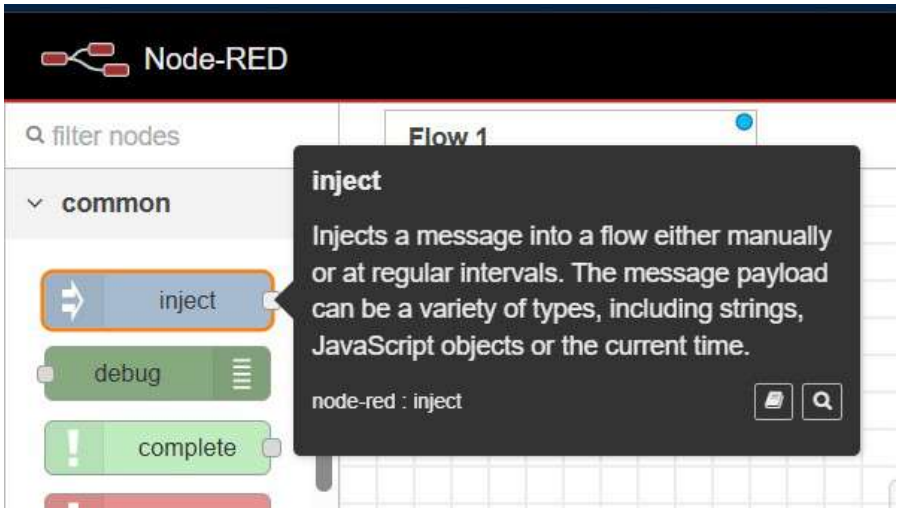


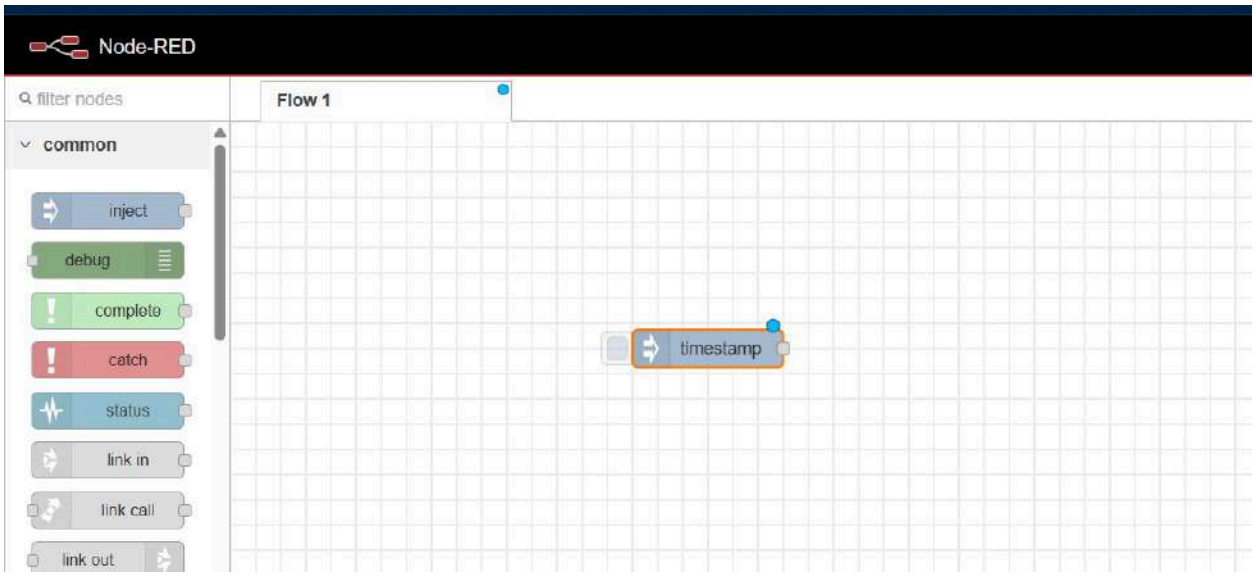
Task 2

Algorithm

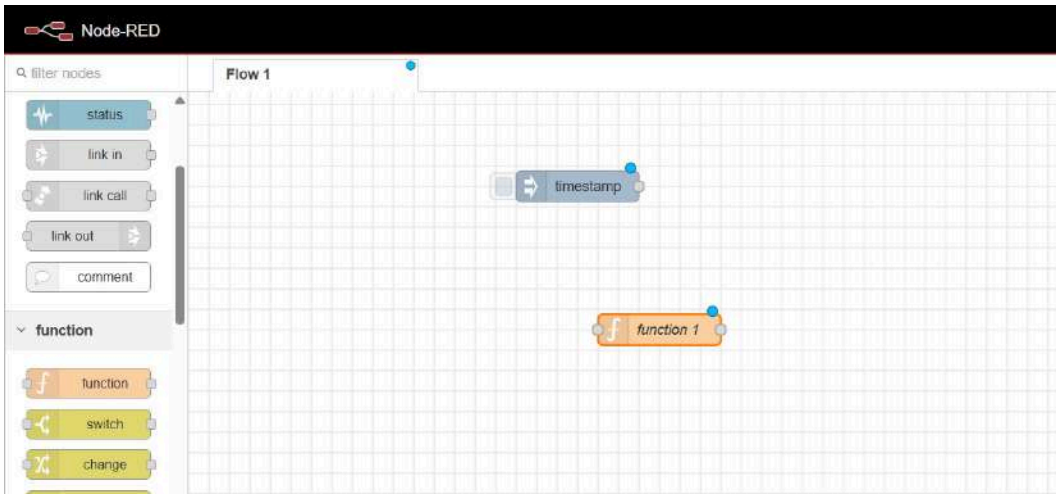
1. Open the node-red editor at http://127.0.0.1:1880/.

2. Drag inject node to trigger the flow manually.

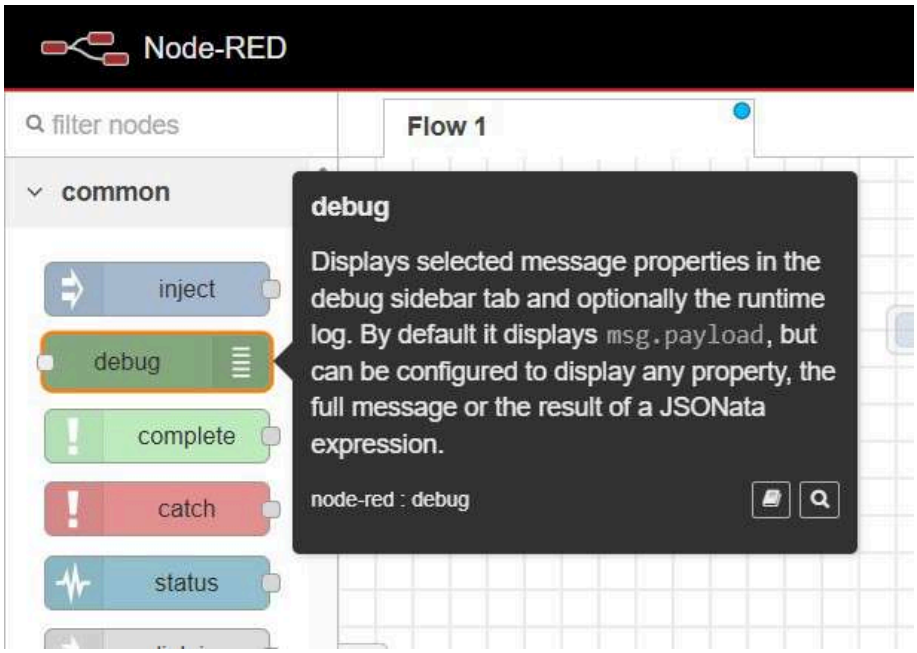


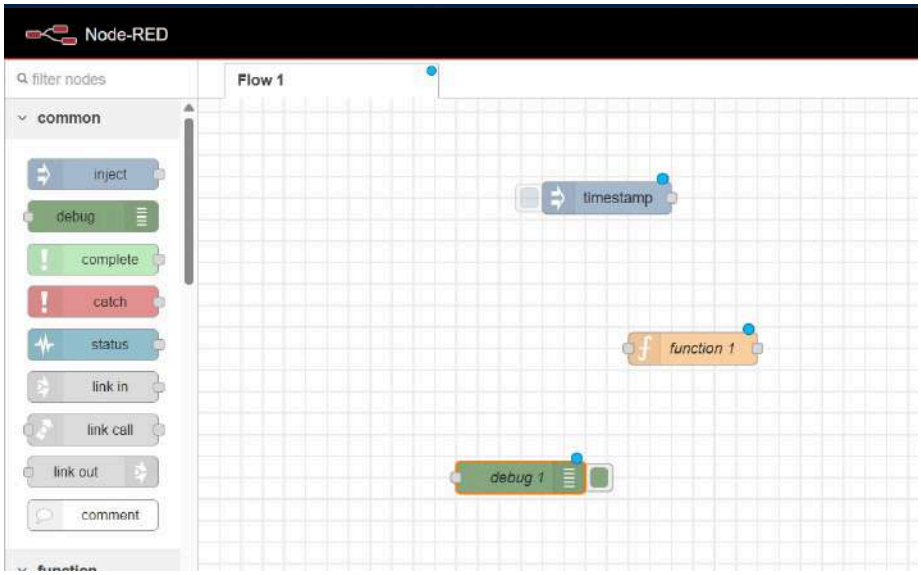


3. Drag a function node to process the data.



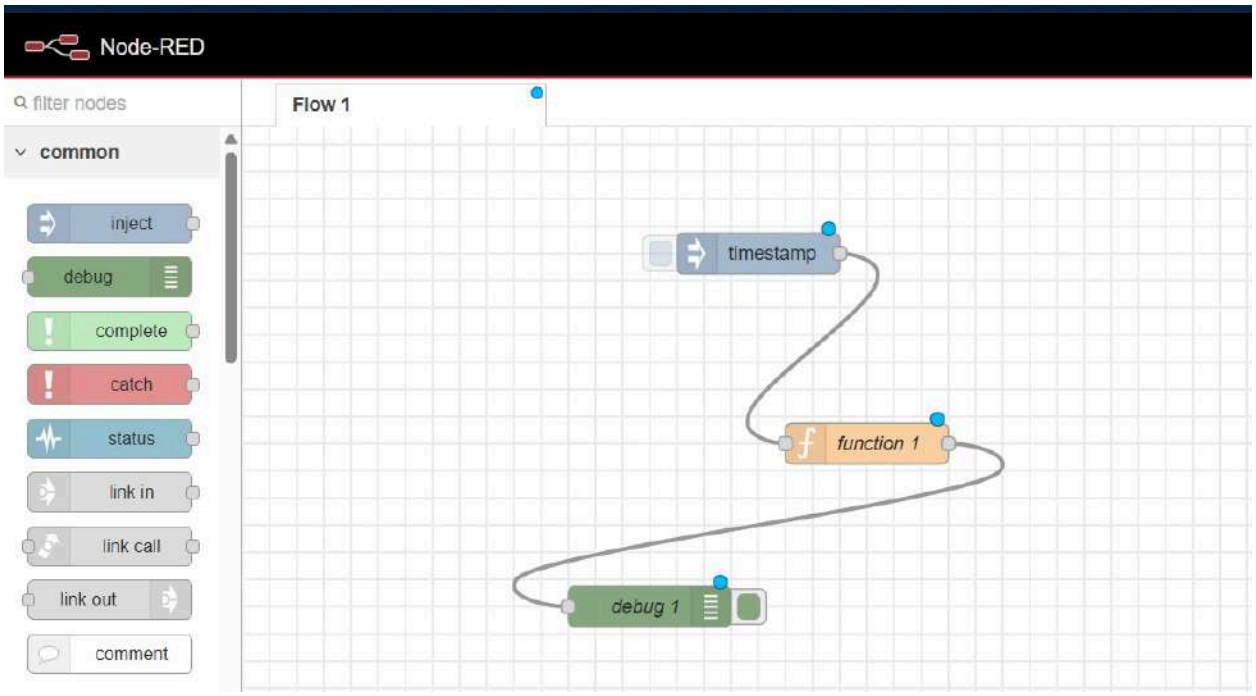
4. Drag a Debug node to log the output.





5. Connect the nodes in the following manner.

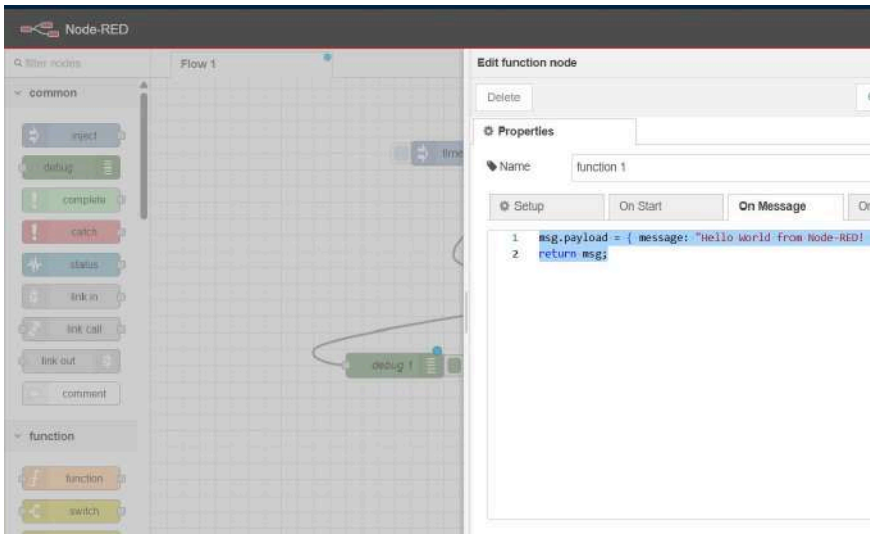
Inject -> Function -> Debug



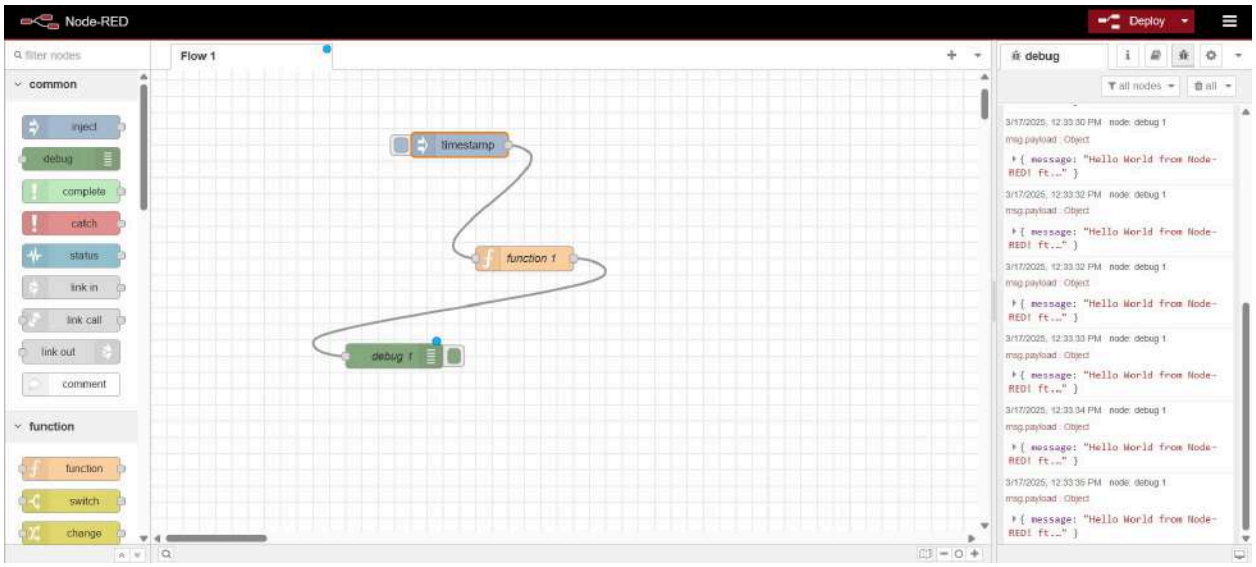
6. Configure the function with the following js code.

Code

```
msg.payload = { message: "Hello World from Node-RED! ft.Jayant" };

return msg;
```



7. Click on the inject node to trigger the flow. Output can be viewed on the debug panel.



Task 3

Algorithm

1. We will start with creating a flow for the pattern which processes data from a sensor.

2. Flow will be:

- Inject node to simulate sensor data
- Random node to generate random temperature values
- Switch node to check if temp > 50°C
- Change node to format alert message
- Debug node to log the alert

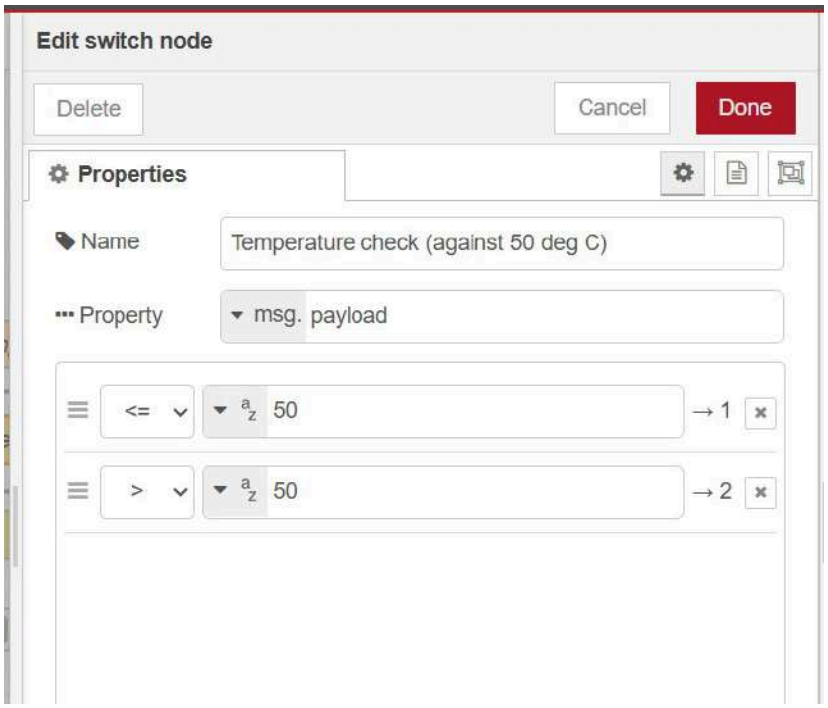
3. The nodes will do the following job.

Random Temp Generator: Generates random temperature values between 10 and

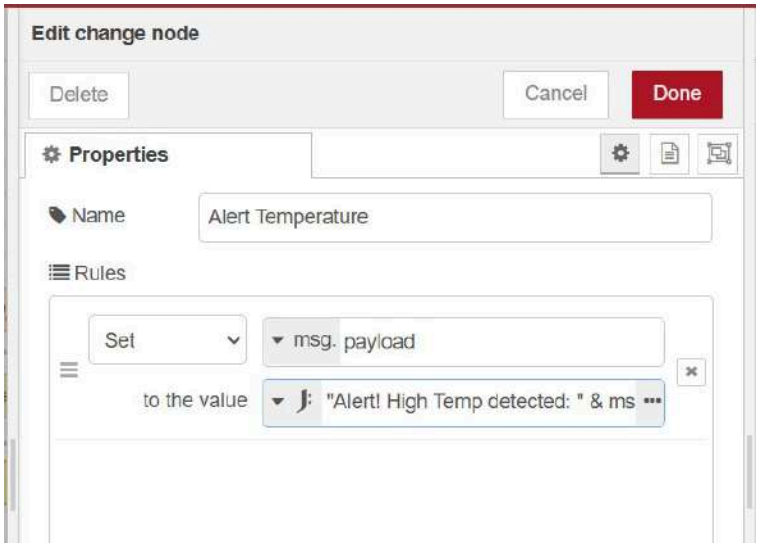
80 deg C.

Switch node: Will check the temperature values and log based on the set threshold

values (here 50 deg C).

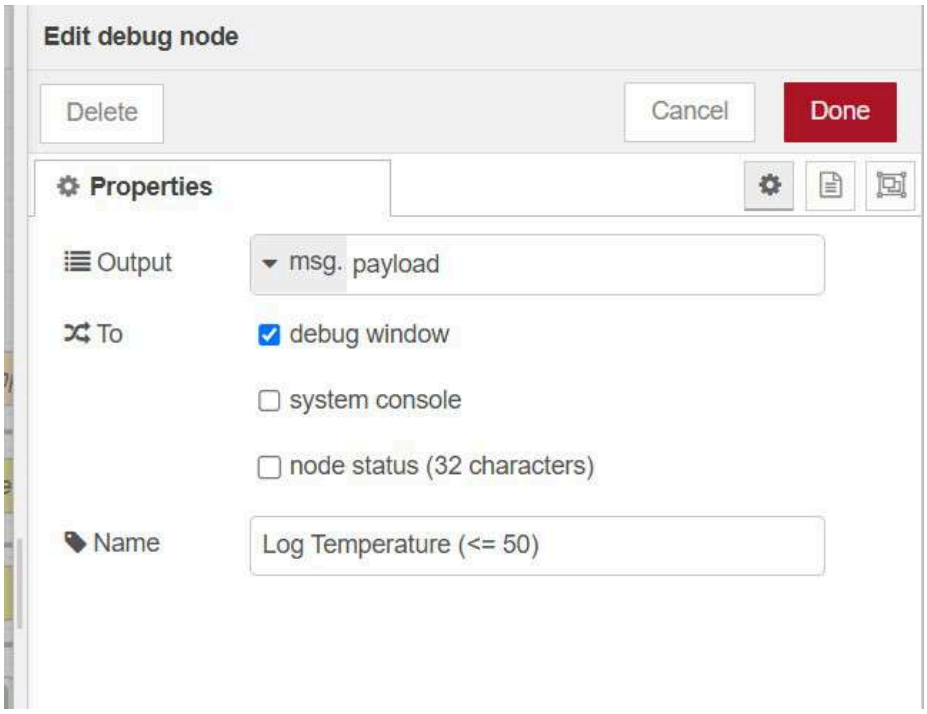


Change node: Sets msg.payload = "Alert! High Temp detected."

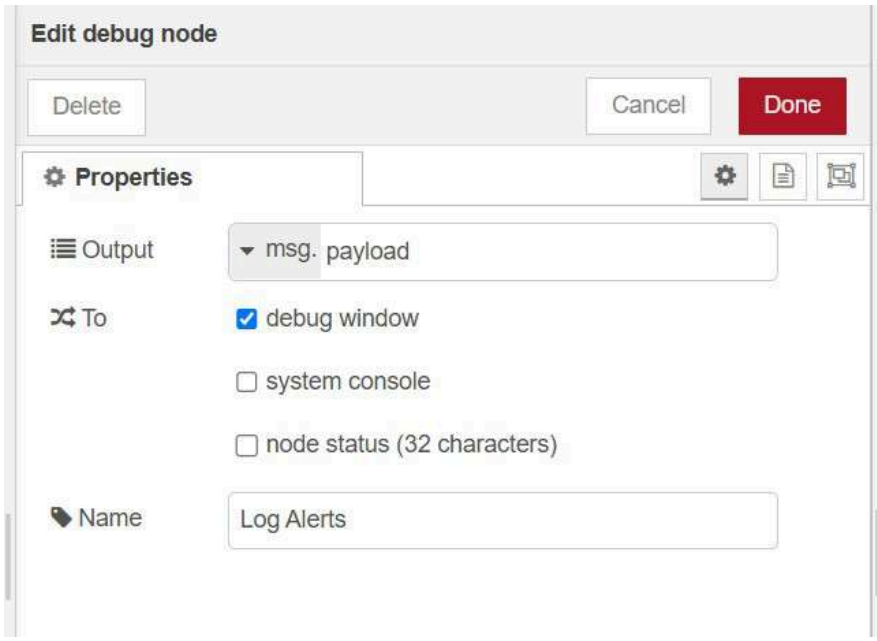


Debug Node:

Log Temperature: If temperature is <= 50 deg C.

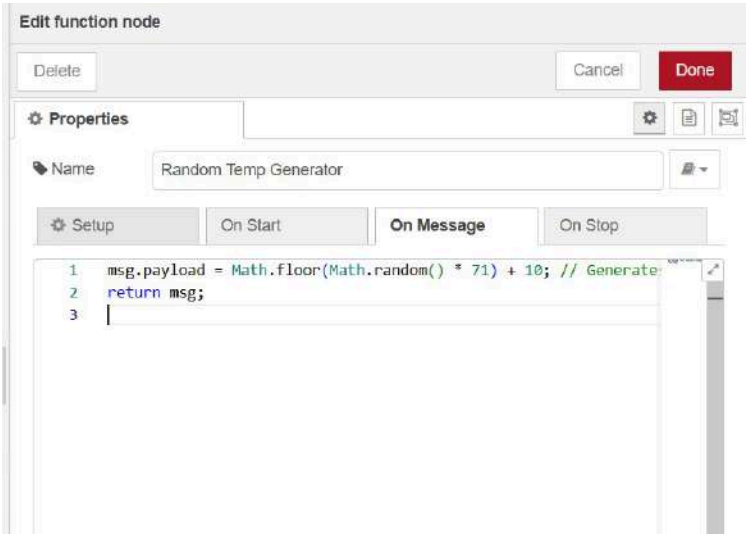


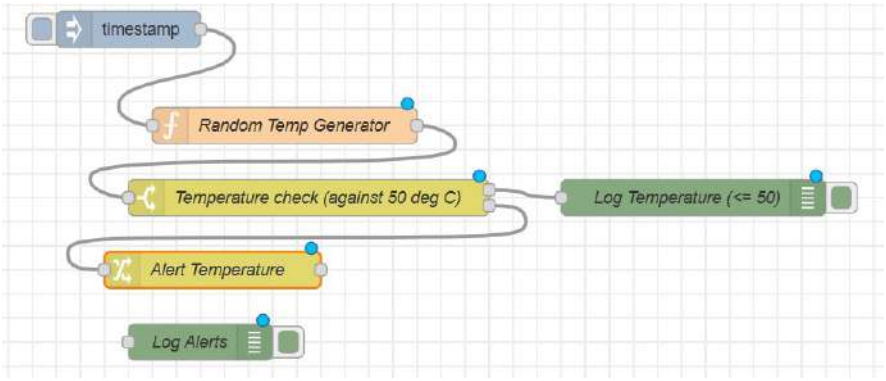
Alert: If Temperature is >50 degC.



Code for Random Temp Generator function

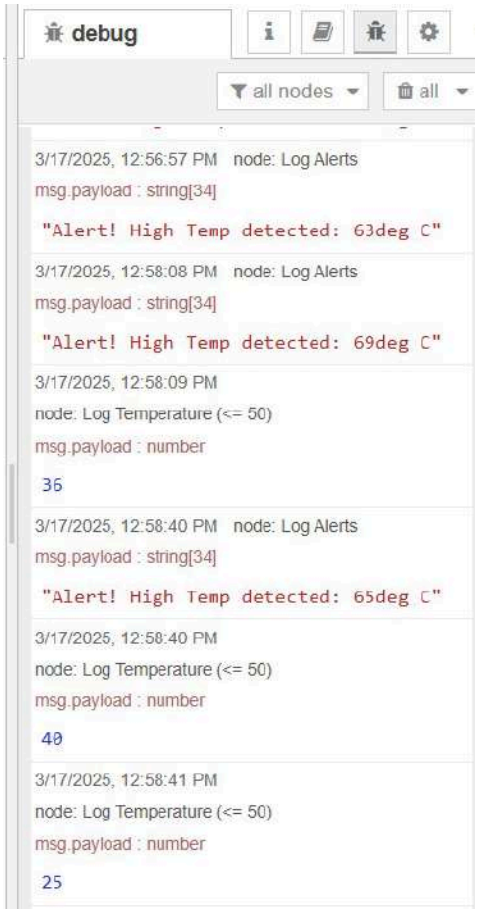
```
msg.payload = Math.floor(Math.random() * 71) + 10; // Generates temp
between 10°C - 80°C

return msg;
```





4. Deploy and inject the timestamp node. Output will be visible in the debug mode.

Output


debug
all nodes
all
3/17/2025, 12:56:57 PM node: Log Alerts
msg.payload : string[34]
"Alert! High Temp detected: 63deg C"
3/17/2025, 12:58:08 PM node: Log Alerts
msg.payload : string[34]
"Alert! High Temp detected: 69deg C"
3/17/2025, 12:58:09 PM
node: Log Temperature (<= 50)
msg.payload : number
36
3/17/2025, 12:58:40 PM node: Log Alerts
msg.payload : string[34]
"Alert! High Temp detected: 65deg C"
3/17/2025, 12:58:40 PM
node: Log Temperature (<= 50)
msg.payload : number
40
3/17/2025, 12:58:41 PM
node: Log Temperature (<= 50)
msg.payload : number
25