

Program design and analysis



- ⌘ Software components.
- ⌘ Representations of programs.
- ⌘ Assembly and linking.

Design Pattern

:Components of embedded system



- ⌘ Components mainly used for embedded software: the state machine, the circular buffer, queue
- ⌘ State diagram to describe behavior suited for reactive systems
- ⌘ Circular buffer ,queue used for DSP
- ⌘ Sequence diagram to show how classes interact

Different types of Design Pattern



- ⌘ The digital filter is easily described as design pattern
- ⌘ Data structures and their associated actions can be described
- ⌘ Reactive system that reacts to external stimuli

Software state machine



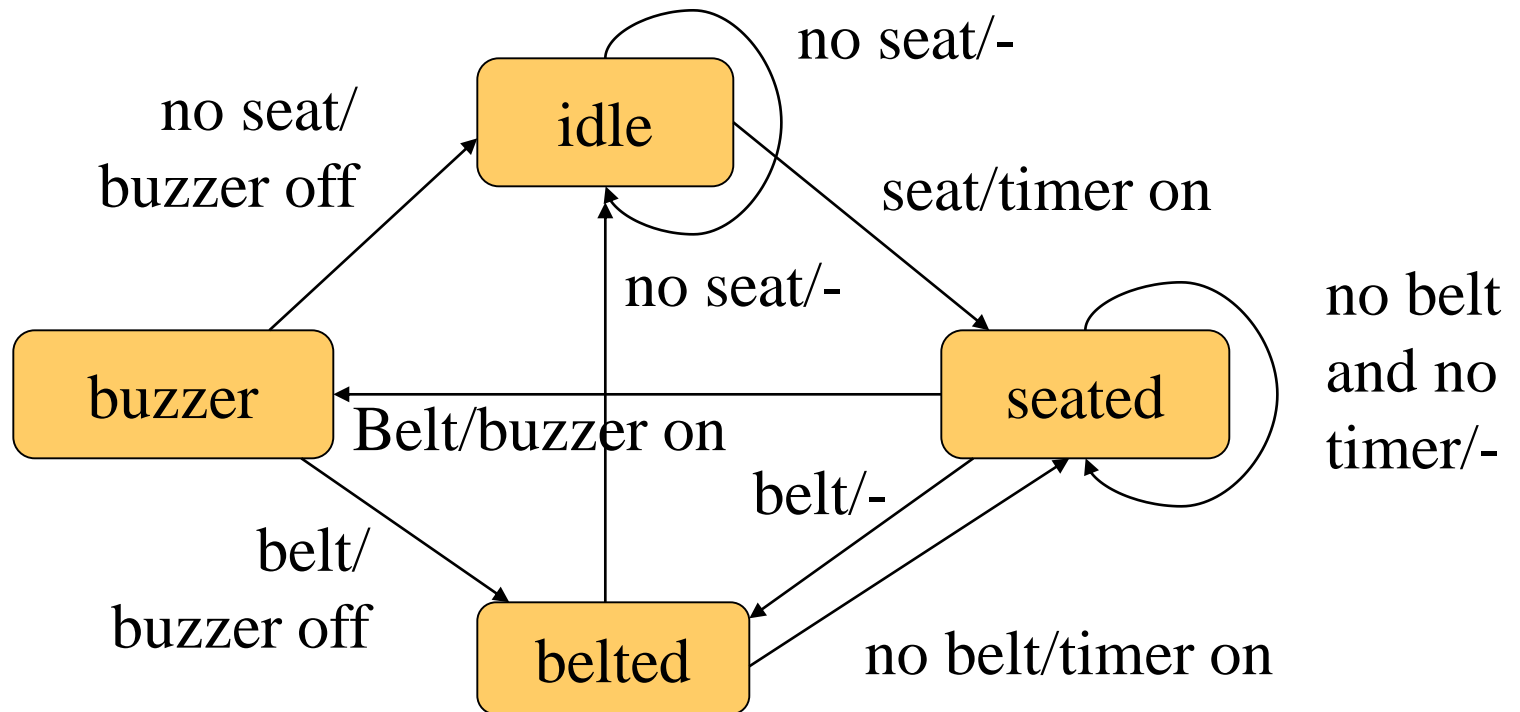
⌘ State machine keeps internal state as a variable, changes state based on inputs.

⌘ Uses:

- ☑ control-dominated code;

- ☑ reactive systems.

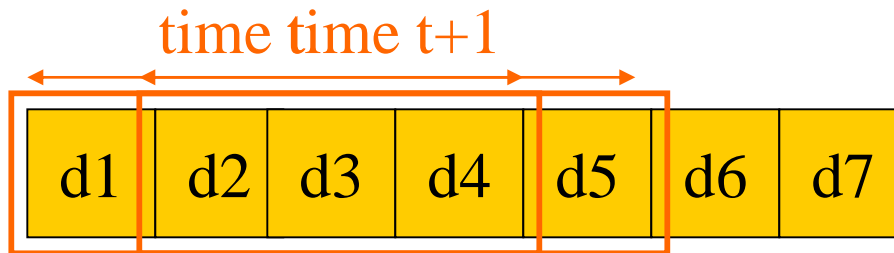
State machine example (Seat belt controller)



Signal processing and circular buffer

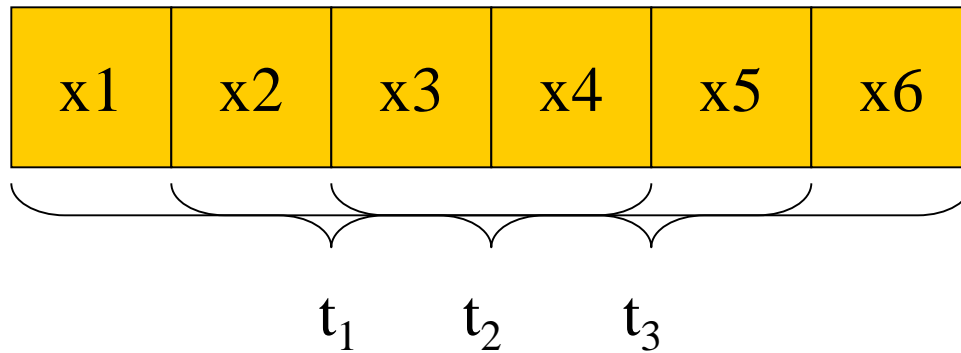
⌘ Commonly used in signal processing:

- ☑ new data constantly arrives;
- ☑ each datum has a limited lifetime.

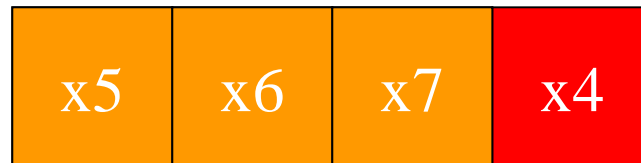


⌘ Use a circular buffer to hold the data stream.

Circular buffer



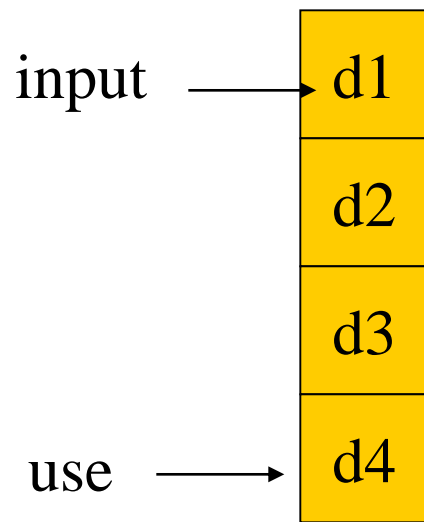
Data stream



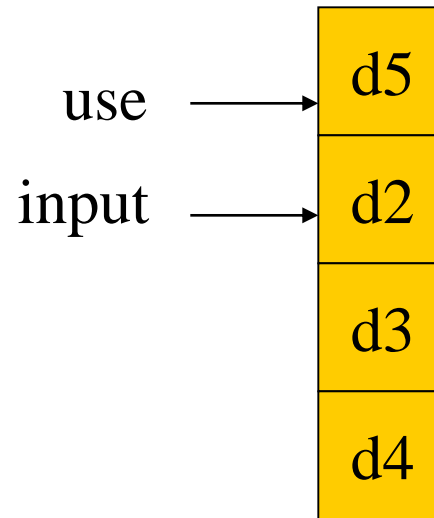
Circular buffer

Circular buffers

⌘ Indexes locate currently used data,
current input data:



time t_1



time $t_1 + 1$

Queues



⌘ Elastic buffer: holds data that arrives irregularly.

Models of programs



⌘ Source code is not a good representation for programs:

- ☐ clumsy;

- ☐ leaves much information implicit.

⌘ Compilers derive intermediate representations to manipulate and optimize the program.

Data flow graph

- ⌘ **DFG**: data flow graph.
- ⌘ Does not represent control.
- ⌘ Models basic block: code with no entry or exit.
- ⌘ Describes the minimal ordering requirements on operations.
- ⌘ Round nodes-denote operators
- ⌘ Square node-represent values

Single assignment form



$x = a + b;$

$y = c - d;$

$z = x * y;$

$y = b + d;$

original basic block

$x = a + b;$

$y = c - d;$

$z = x * y;$

$y1 = b + d;$

single assignment form

Data flow graph

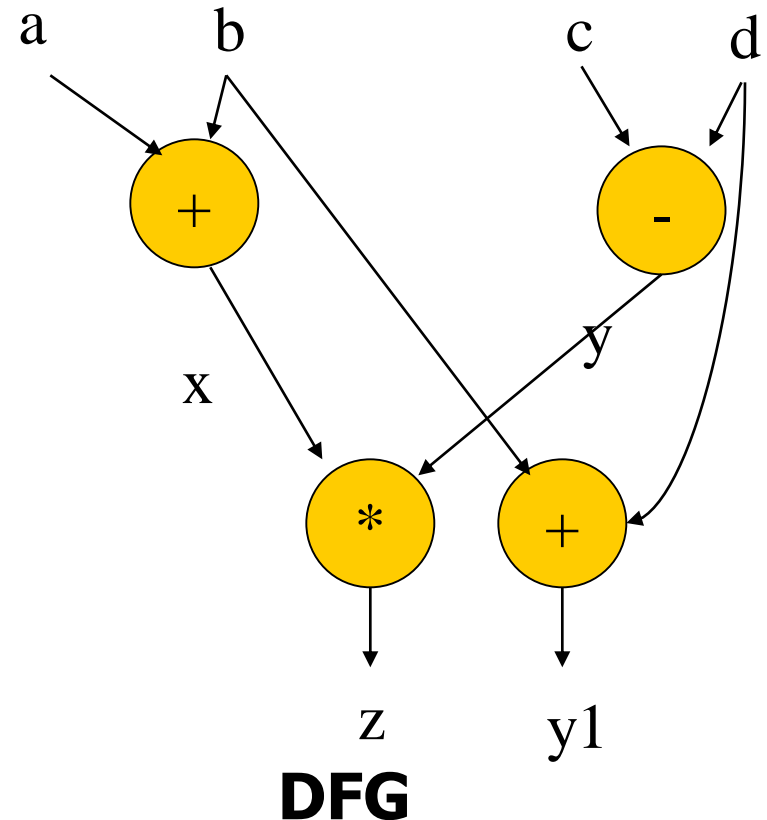
$x = a + b;$

$y = c - d;$

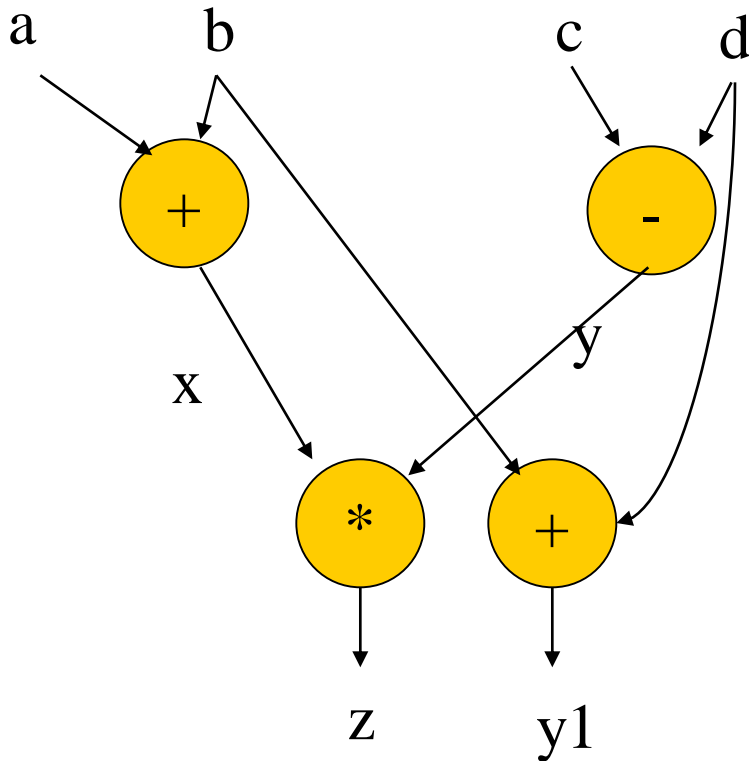
$z = x * y;$

$y1 = b + d;$

single assignment form



DFGs and partial orders



Partial order:

⌘ $a+b, c-d; b+d \ x*y$

Can do pairs of operations in any order.

Control-data flow graph

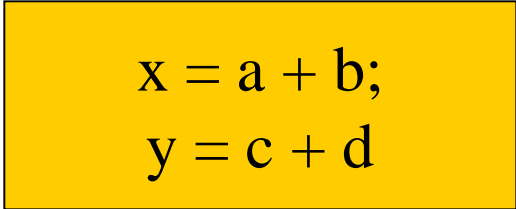


- ⌘ **CDFG**: represents control and data.
- ⌘ Uses data flow graphs as components.
- ⌘ Two types of nodes:
 - ☐ Decision node;
 - ☐ data flow node.

Data flow node



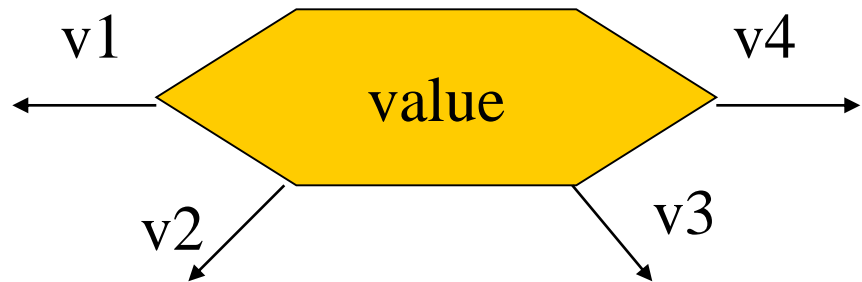
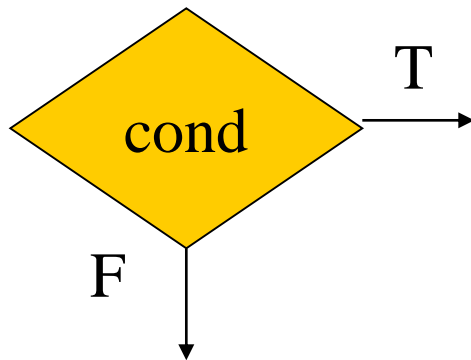
Encapsulates a data flow graph:



```
x = a + b;  
y = c + d
```

Write operations in basic block form for simplicity.

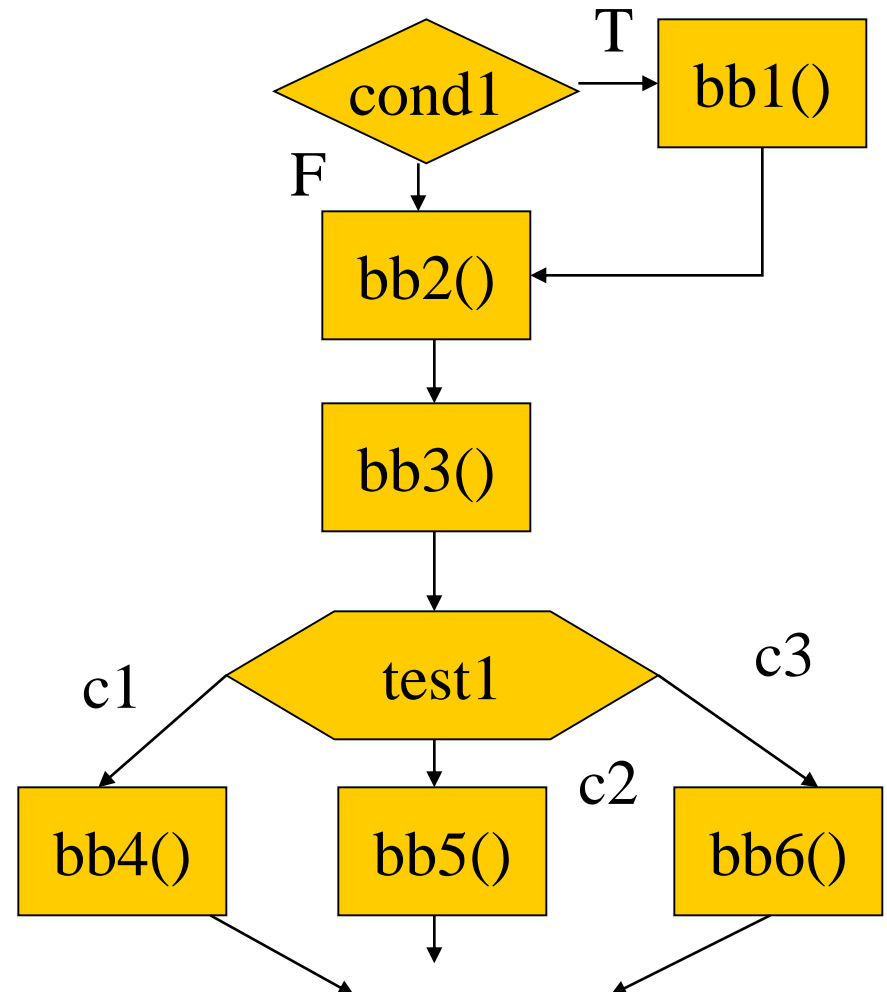
Control



Equivalent forms

CDFG example

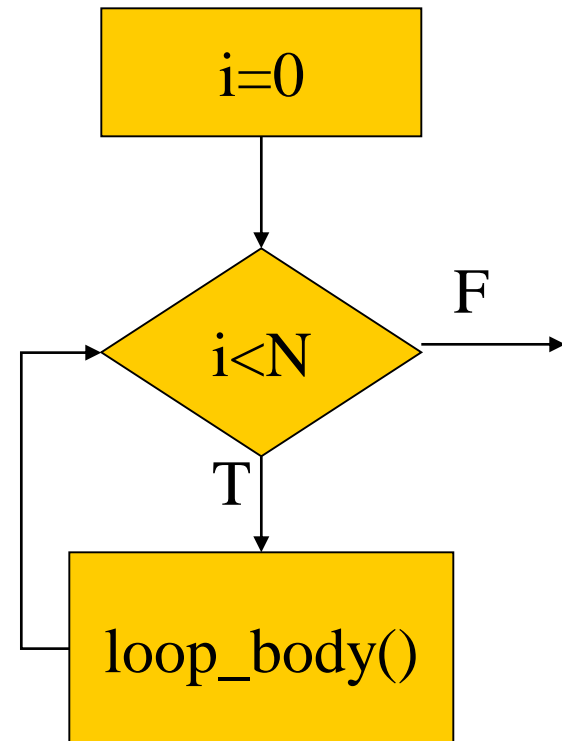
```
if (cond1) bb1();  
    else bb2();  
bb3();  
switch (test1) {  
    case c1: bb4(); break;  
    case c2: bb5(); break;  
    case c3: bb6(); break;  
}
```



for loop

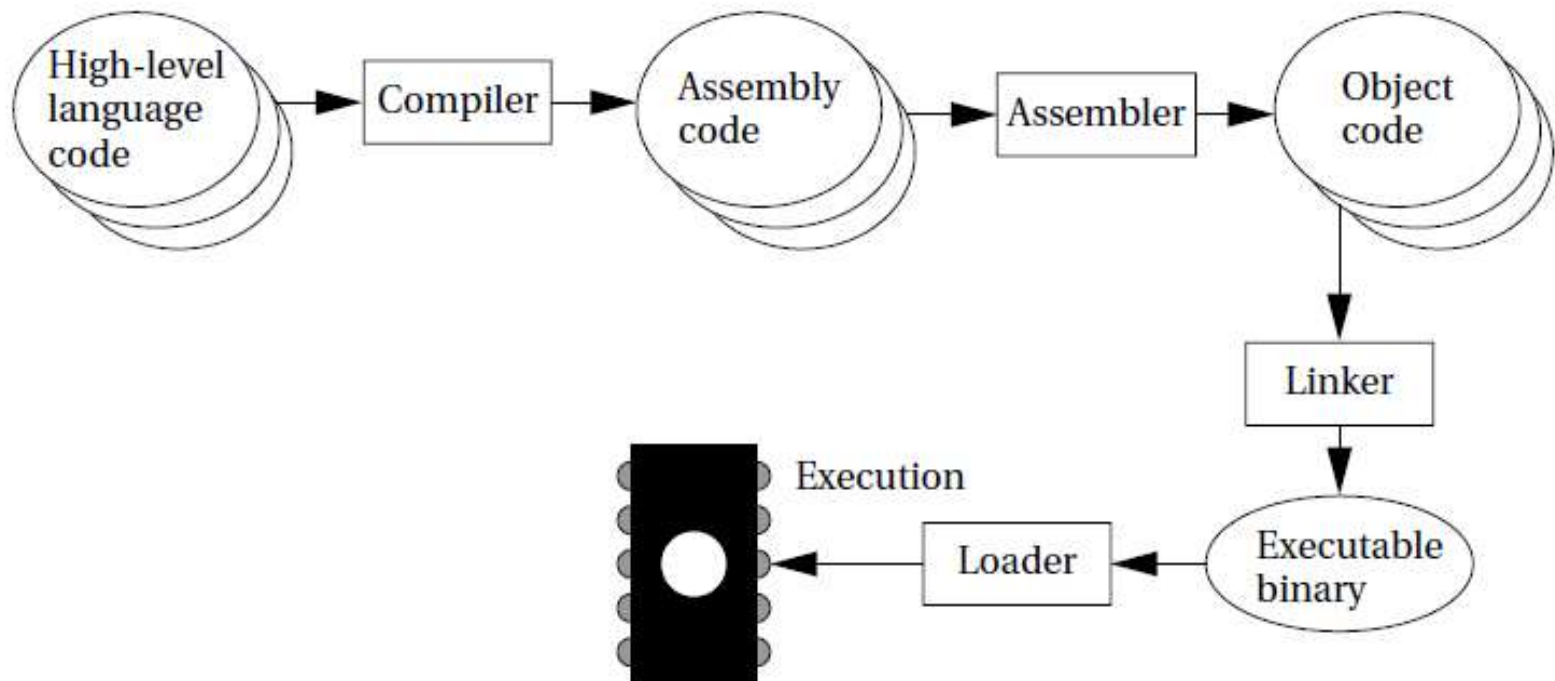
```
for (i=0; i<N; i++)  
    loop_body();  
for loop
```

```
i=0;  
while (i<N) {  
    loop_body(); i++; }  
equivalent
```



Assembly and linking

⌘ Last steps in compilation:



Multiple-module programs



- ⌘ Programs may be composed from several files.
- ⌘ Addresses become more specific during processing:
 - 📁 **relative addresses** are measured relative to the start of a module;
 - 📁 **absolute addresses** are measured relative to the start of the CPU address space.

Assemblers



⌘ Major tasks:

- ☑ generate binary for symbolic instructions;
- ☑ translate labels into addresses;
- ☑ handle pseudo-ops (data, etc.).

⌘ Generally one-to-one translation.

⌘ Assembly labels:

```
                ORG 100  
label1    ADR r4,c
```

Symbol table



	ADD r0,r1,r2	xx	0x8
xx	ADD r3,r4,r5	yy	0x10
	CMP r0,r3		
yy	SUB r5,r6,r7		

assembly code

symbol table

Symbol table generation



- ⌘ Use program location counter (**PLC**) to determine address of each location.
- ⌘ Scan program, keeping count of PLC.
- ⌘ Addresses are generated at assembly time, not execution time.

Symbol table example

PLC=0x7	LD r0,r1,r2	xx	0x8
PLC=0x7	LD r3,r4,r5	yy	0x10
PLC=0x7	MP r0,r3		
PLC=0x7	yy → SUB r5,r6,r7		

Two-pass assembly



⌘ Pass 1:

- ☑ generate symbol table

⌘ Pass 2:

- ☑ generate binary instructions

Relative address generation



- ⌘ Some label values may not be known at assembly time.
- ⌘ Labels within the module may be kept in relative form.
- ⌘ Must keep track of external labels---can't generate full binary for instructions that use external labels.

Pseudo-operations



⌘ Pseudo-ops do not generate instructions:

- ☒ **ORG** sets program location.

- ☒ **EQU** generates symbol table entry without advancing PLC.

- ☒ **Data statements** define data blocks.

Linking



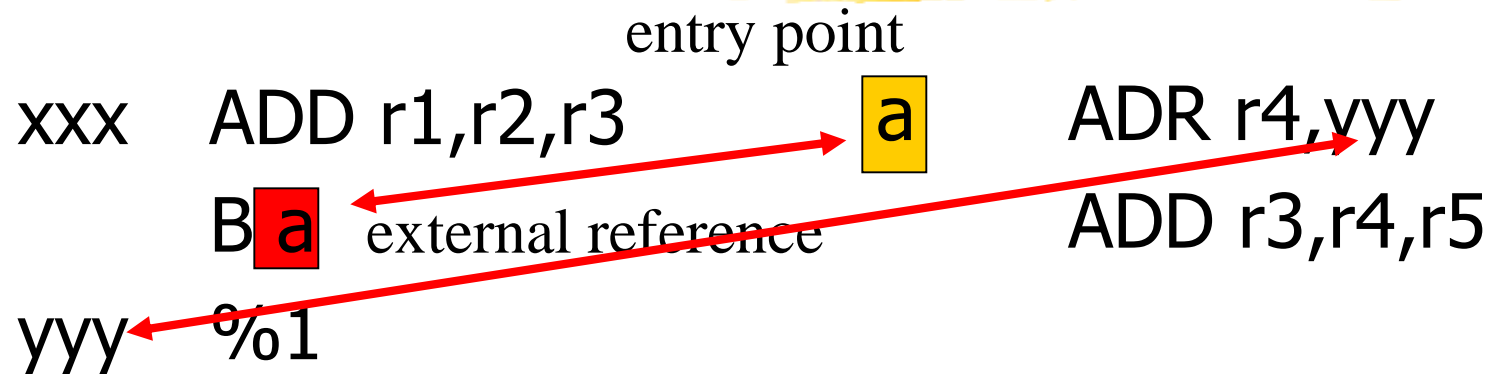
⌘ Combines several object modules into a single executable module.

⌘ Jobs:

- ☑ put modules in order;

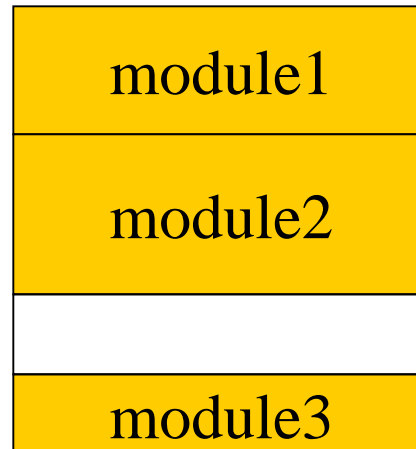
- ☑ resolve labels across modules.

Externals and entry points



Module ordering

- ⌘ Code modules must be placed in absolute positions in the memory space.
- ⌘ **Load map** or linker flags control the order of modules.



Dynamic linking



⌘ Some operating systems link modules dynamically at run time:

- ☑ shares one copy of library among all executing programs;
- ☑ allows programs to be updated with new versions of libraries.

Program design and analysis



- ⌘ Compilation flow.
- ⌘ Basic statement translation.
- ⌘ Basic optimizations.
- ⌘ Interpreters and just-in-time compilers.

Compilation



⌘ Compilation strategy (Wirth):

☑ compilation = translation + optimization

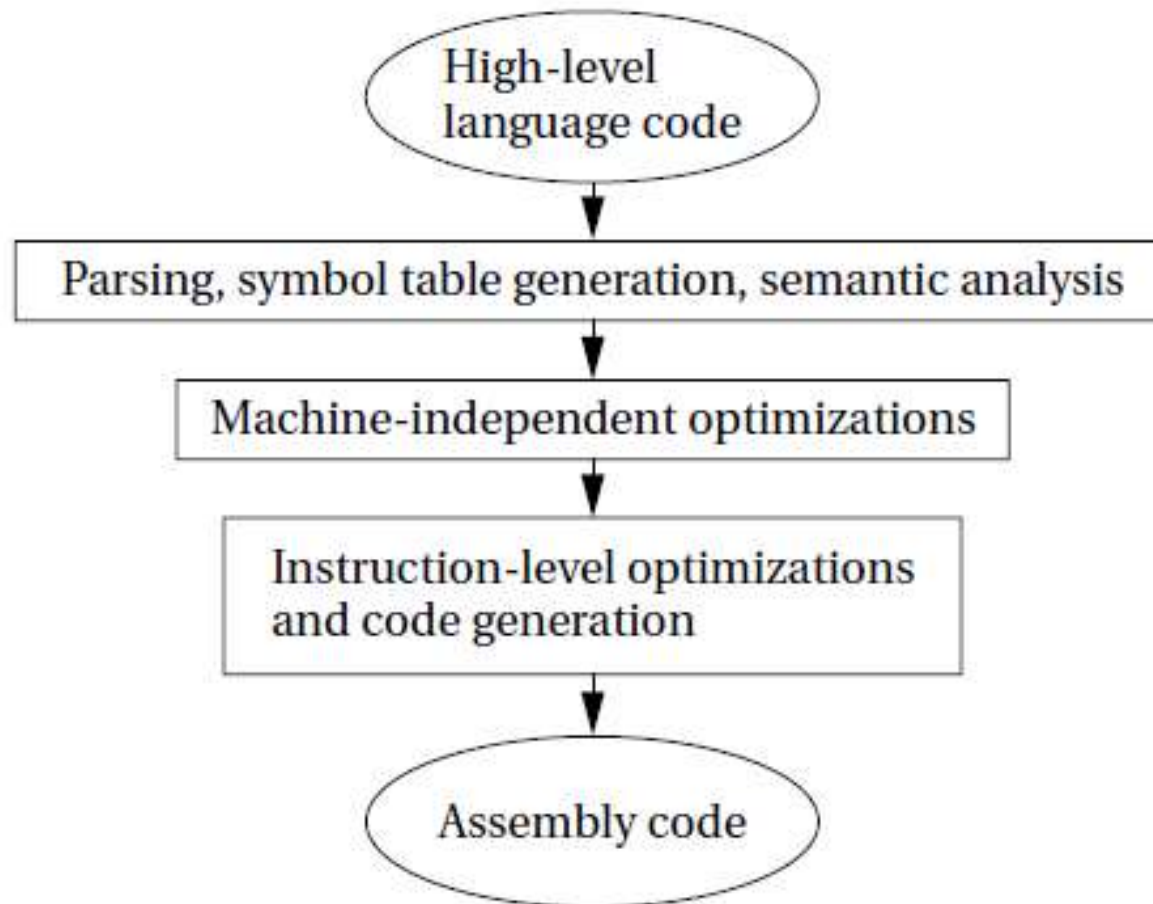
⌘ Compiler determines quality of code:

☑ use of CPU resources;

☑ memory access scheduling;

☑ code size.

Basic compilation phases



Statement translation and optimization

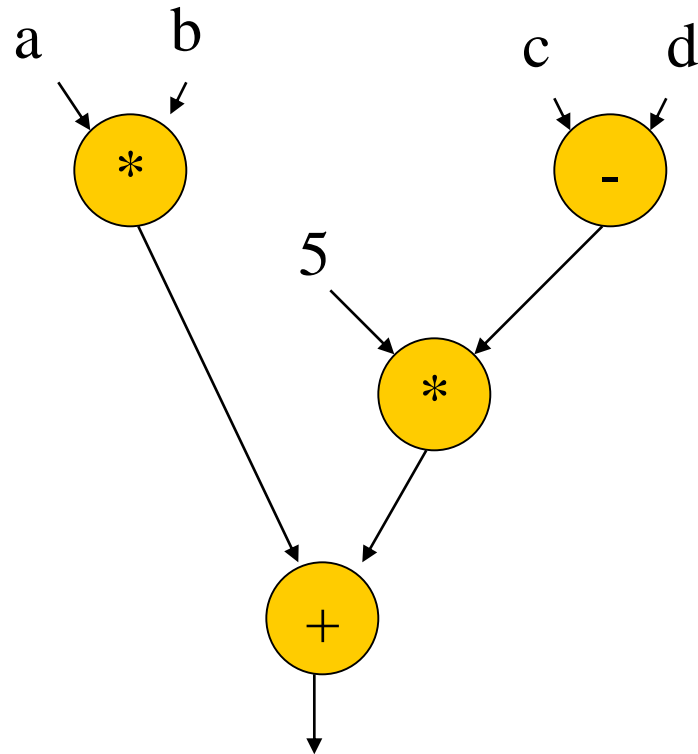


- ⌘ Source code is translated into intermediate form such as CDFG.
- ⌘ CDFG is transformed/optimized.
- ⌘ CDFG is translated into instructions with optimization decisions.
- ⌘ Instructions are further optimized.

Arithmetic expressions

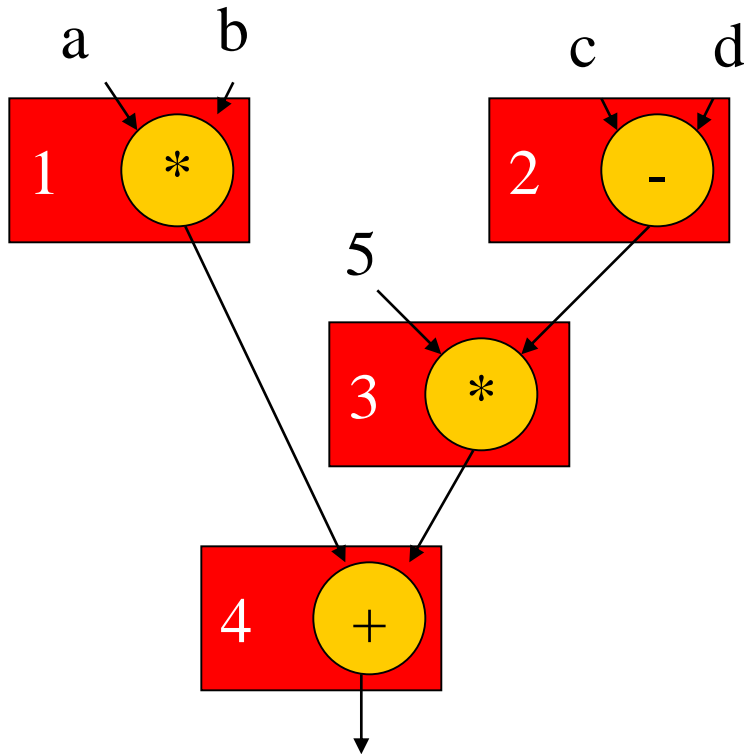
$a*b + 5*(c-d)$

expression



DFG

Arithmetic expressions, cont'd.



DFG

```
ADR r4,a
MOV r1,[r4]
ADR r4,b
MOV r2,[r4]
ADD r3,r1,r2
ADR r4,c
MOV r1,[r4]
ADR r4,d
MOV r5,[r4]
SUB r6,r4,r5
MUL r7,r6,#5
ADD r8,r7,r3
```

code

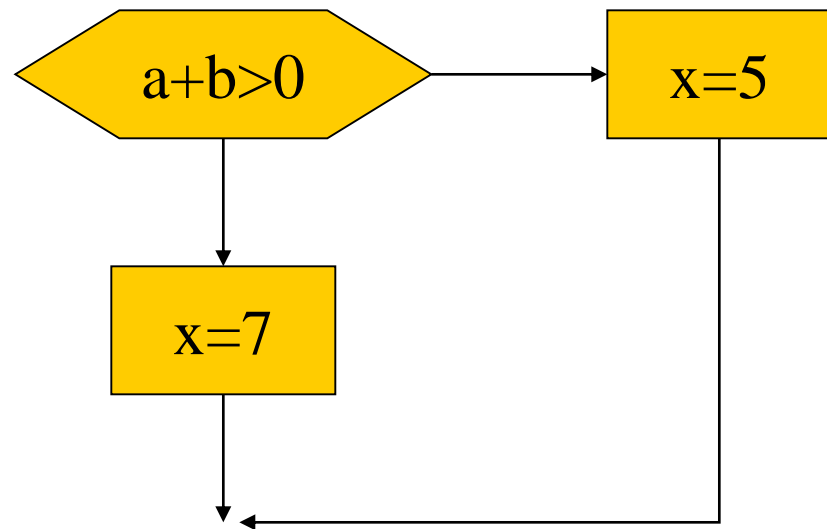
Control code generation

if ($a+b > 0$)

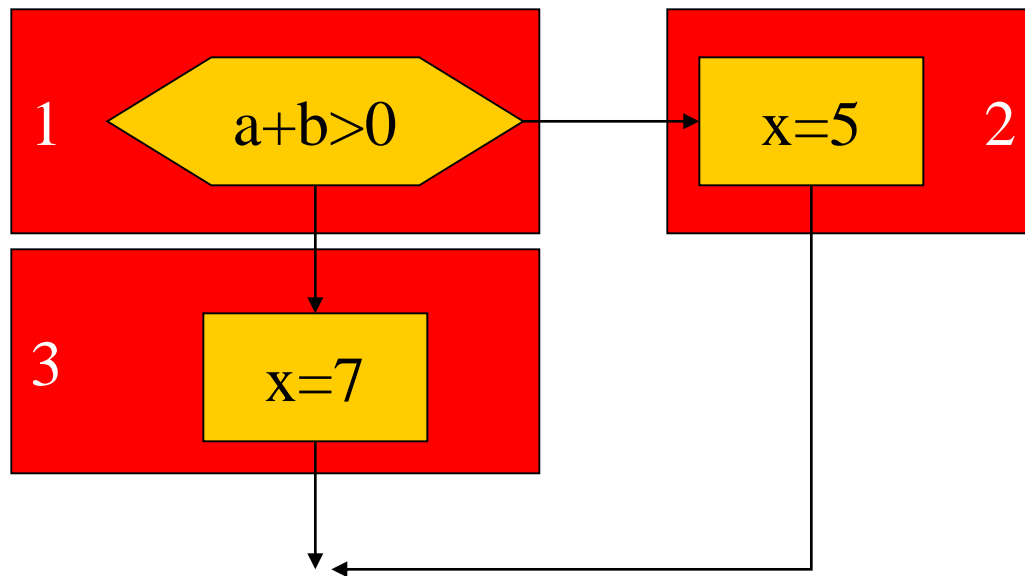
$x = 5;$

else

$x = 7;$



Control code generation, cont'd.



```
ADR r5,a
LDR r1,[r5]
ADR r5,b
LDR r2,b
ADD r3,r1,r2
BLE label3
LDR r3,#5
ADR r5,x
STR r3,[r5]
B stmtent
LDR r3,#7
ADR r5,x
STR r3,[r5]
stmtent ...
```


Procedure linkage



⌘ Need code to:

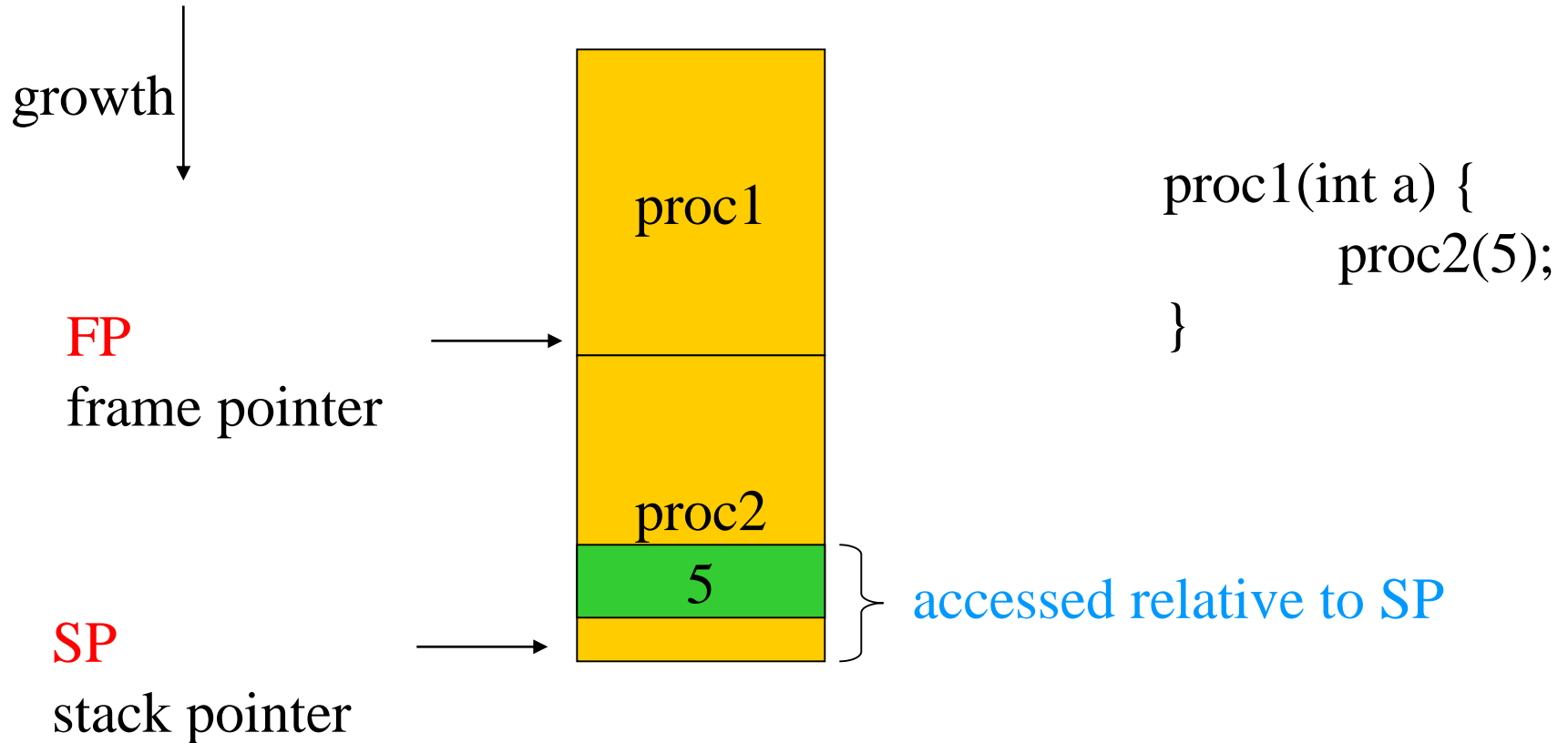
- ☑ call and return;

- ☑ pass parameters and results.

⌘ Parameters and returns are passed on stack.

- ☑ Procedures with few parameters may use registers.

Procedure stacks



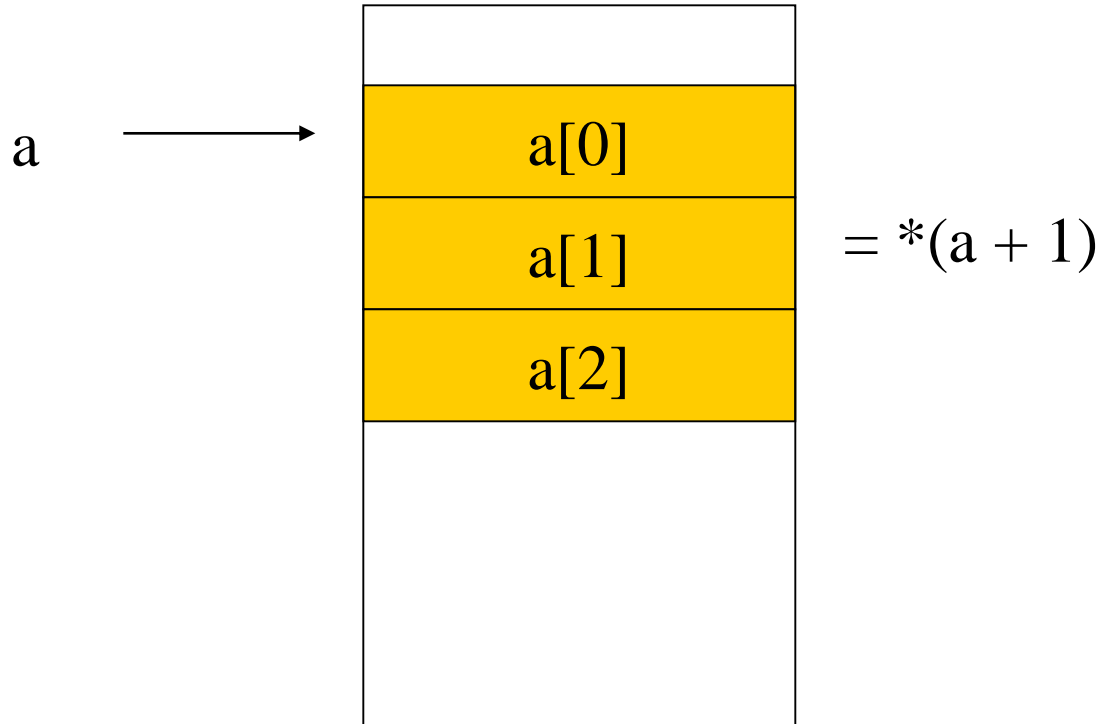
Data structures



- ⌘ Different types of data structures use different data layouts.
- ⌘ Some offsets into data structure can be computed at compile time, others must be computed at run time.

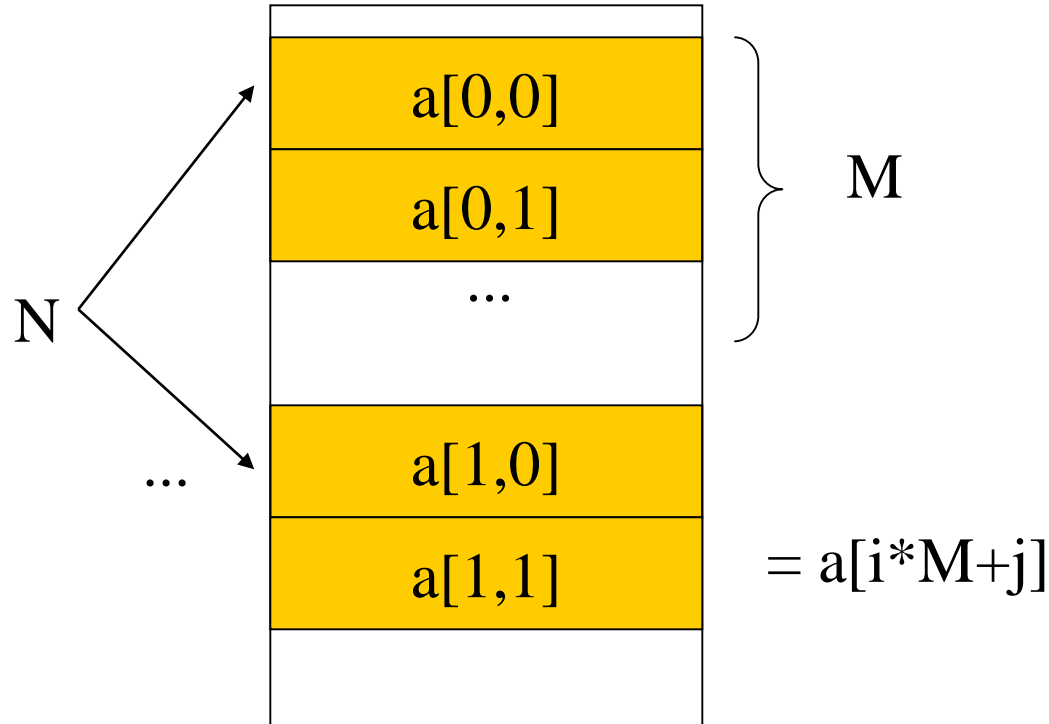
One-dimensional arrays

⌘ C array name points to 0th element:



Two-dimensional arrays

⌘ Column-major layout:

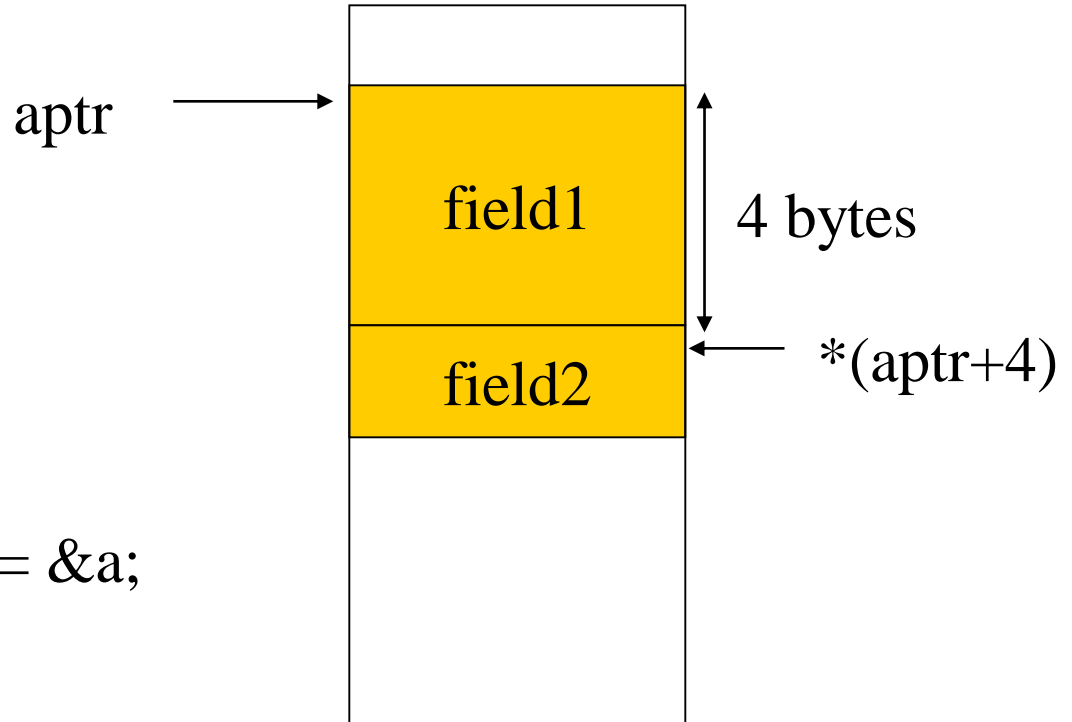


Structures

⌘ Fields within structures are static offsets:

```
struct {  
    int field1;  
    char field2;  
} mystruct;
```

```
struct mystruct a, *aptr = &a;
```



Expression simplification

⌘ Constant folding:

$$\boxed{\wedge} 8+1 = 9$$

⌘ Algebraic:

$$\boxed{\wedge} a*b + a*c = a*(b+c)$$

⌘ Strength reduction:

$$\boxed{\wedge} a*2 = a<<1$$

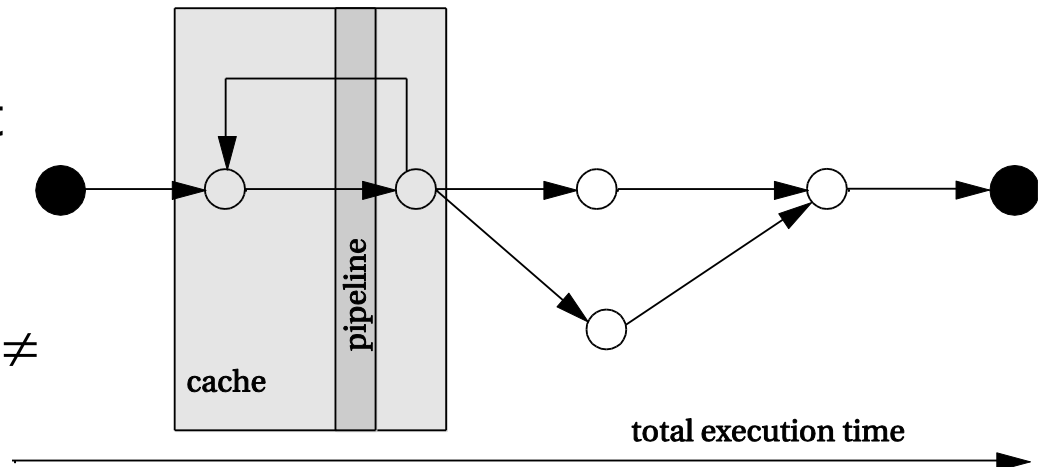
Program design and analysis



- ⌘ Program-level performance analysis.
- ⌘ Optimizing for:
 - ☑ Execution time.
 - ☑ Energy/power.
 - ☑ Program size.
- ⌘ Program validation and testing.

Program-level performance analysis

- ⌘ Need to understand performance in detail:
 - ☒ Real-time behavior, not just typical.
 - ☒ On complex platforms.
- ⌘ Program performance \neq CPU performance:
 - ☒ Pipeline, cache are windows into program.
 - ☒ We must analyze the entire program.



Complexities of program performance



⌘ Varies with input data:

☑ Different-length paths.

⌘ Cache effects.

⌘ Instruction-level performance variations:

☑ Pipeline interlocks.

☑ Fetch times.

How to measure program performance



- ⌘ Simulate execution of the CPU.

 - ☑ Makes CPU state visible.

- ⌘ Measure on real CPU using timer.

 - ☑ Requires modifying the program to control the timer.

- ⌘ Measure on real CPU using logic analyzer.

 - ☑ Requires events visible on the pins.

Program performance metrics



⌘ Average-case execution time.

☑ Typically used in application programming.

⌘ Worst-case execution time.

☑ A component in deadline satisfaction.

⌘ Best-case execution time.

☑ Task-level interactions can cause best-case program behavior to result in worst-case system behavior.

Elements of program performance



⌘ Basic program execution time formula:

☒ execution time = program path + instruction timing

⌘ Solving these problems independently helps simplify analysis.

☒ Easier to separate on simpler CPUs.

⌘ Accurate performance analysis requires:

☒ Assembly/binary code.

☒ Execution platform.

Instruction timing



- ⌘ Not all instructions take the same amount of time.
 - ☒ Multi-cycle instructions.
 - ☒ Fetches.
- ⌘ Execution times of instructions are not independent.
 - ☒ Pipeline interlocks.
 - ☒ Cache effects.
- ⌘ Execution times may vary with operand value.
 - ☒ Floating-point operations.
 - ☒ Some multi-cycle integer operations.

Trace-driven measurement



⌘ Trace-driven:

- ☑ Instrument the program.

- ☑ Save information about the path.

⌘ Requires modifying the program.

⌘ Trace files are large.

⌘ Widely used for cache analysis.

Performance optimization motivation



- ⌘ Embedded systems must often meet deadlines.
 - ☐ Faster may not be fast enough.
- ⌘ Need to be able to analyze execution time.
 - ☐ Worst-case, not typical.
- ⌘ Need techniques for reliably improving execution time.

Programs and performance analysis



⌘ Best results come from analyzing optimized instructions, not high-level language code:

- ☑ non-obvious translations of HLL statements into instructions;
- ☑ code may move;
- ☑ cache effects are hard to predict.

Physical measurement



- ⌘ In-circuit emulator allows tracing.
 - ☑ Affects execution timing.
- ⌘ Logic analyzer can measure behavior at pins.
 - ☑ Address bus can be analyzed to look for events.
 - ☑ Code can be modified to make events visible.
- ⌘ Particularly important for real-world input streams.

CPU simulation



- ⌘ Some simulators are less accurate.
- ⌘ Cycle-accurate simulator provides accurate clock-cycle timing.
 - ☑ Simulator models CPU internals.
 - ☑ Simulator writer must know how CPU works.

Performance optimization hints



- ⌘ Use registers efficiently.
- ⌘ Use page mode memory accesses.
- ⌘ Analyze cache behavior:
 - ☑ instruction conflicts can be handled by rewriting code, rescheduling;
 - ☑ conflicting scalar data can easily be moved;
 - ☑ conflicting array data can be moved, padded.

Optimizing for energy



⌘ First-order optimization:

☑ high performance = low energy.

⌘ Not many instructions trade speed for energy.

Optimizing for energy, cont'd.



- ⌘ Use registers efficiently.
- ⌘ Identify and eliminate cache conflicts.
- ⌘ Moderate loop unrolling eliminates some loop overhead instructions.
- ⌘ Eliminate pipeline stalls.
- ⌘ Inlining procedures may help: reduces linkage, but may increase cache thrashing.

Efficient loops



⌘ General rules:

- ☑ Don't use function calls.
- ☑ Keep loop body small to enable local repeat (only forward branches).
- ☑ Use unsigned integer for loop counter.
- ☑ Use \leq to test loop counter.
- ☑ Make use of compiler---global optimization, software pipelining.

Energy/power optimization



⌘ **Energy**: ability to do work.

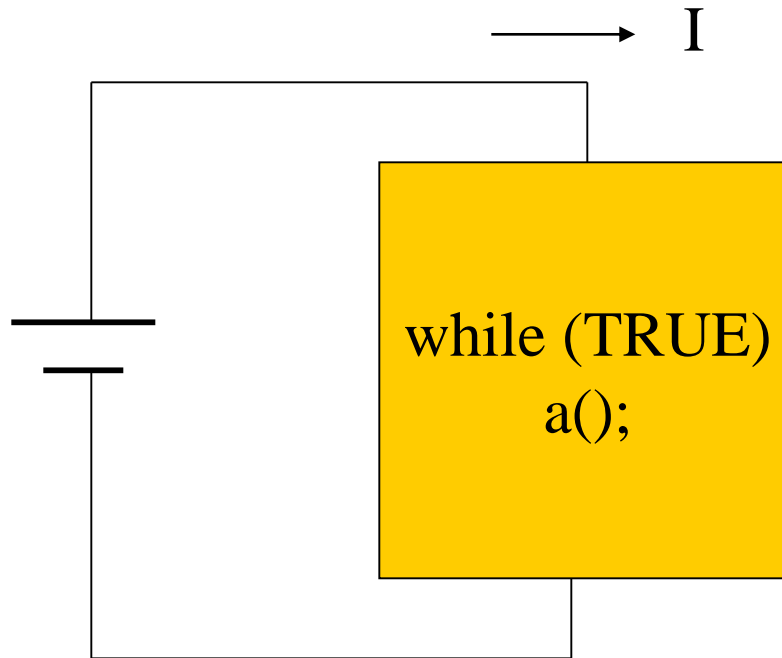
☑ Most important in battery-powered systems.

⌘ **Power**: energy per unit time.

☑ Important even in wall-plug systems---power becomes heat.

Measuring energy consumption

⌘ Execute a small loop, measure current:



Sources of energy consumption



⌘ Relative energy per operation (Catthoor et al):

- ☒ memory transfer: 33
- ☒ external I/O: 10
- ☒ SRAM write: 9
- ☒ SRAM read: 4.4
- ☒ multiply: 3.6
- ☒ add: 1

Cache behavior is important



- ⌘ Energy consumption has a sweet spot as cache size changes:
 - ⏏ **cache too small**: program thrashes, burning energy on external memory accesses;
 - ⏏ **cache too large**: cache itself burns too much power.

Data size minimization



- ⌘ Reuse constants, variables, data buffers in different parts of code.
 - ☑ Requires careful verification of correctness.
- ⌘ Generate data using instructions.

Reducing code size



- ⌘ Avoid function inlining.
- ⌘ Choose CPU with compact instructions.
- ⌘ Use specialized instructions where possible.

Program validation and testing

⌘ But does it work?

⌘ Concentrate here on functional verification.

⌘ Major testing strategies:

☑ Black box doesn't look at the source code.

(Generate tests without looking at the internal structure of the program)

☑ Clear box (white box) does look at the source code (Generate tests based on the program).

Clear-box testing



⌘ Examine the source code to determine whether it works:

- ☑ Can you actually exercise a path?

- ☑ Do you get the value you expect along a path?

⌘ Testing procedure:

- ☑ **Controllability**: provide program with inputs.

- ☑ Execute.

- ☑ **Observability**: examine outputs.

Execution path

- ⌘ The most fundamental concept in clear-box testing is the path of execution through a program
- ⌘ Is it possible to execute every complete path in an arbitrary program? The answer is no, because the program may contain a while loop that is not guaranteed to terminate
- ⌘ simple measure, **Cyclomatic complexity** [McC76], allows us to measure the control complexity of a program.
- ⌘ A simple condition testing strategy is known as **branch testing** [Mye79].
- ⌘ This strategy requires the true and false branches of a conditional and every simple condition in the conditional's expression to be tested at least once.
- ⌘ Another testing strategy known as **data flow testing** makes use of **def-use analysis** (short for definition-use analysis). It selects paths that have some relationship to the program's function.
- ⌘ The terms def and use come from compilers, which use def-use analysis for optimization [Aho06]. A variable's value is **defined** when an assignment is made to the variable; it is **used** when it appears on the right side of an assignment (sometimes called a **C-use** for computation use) or in a conditional expression (sometimes called **P-use** for predicate use). A **def-use pair** is a definition of a variable's value and a use of that value.

Black-box testing



- ⌘ Complements clear-box testing.
 - ☑ May require a large number of tests.
- ⌘ Tests software in different ways.

Black-box test vectors



⌘ Random tests.

- ⌘ Random values are generated with a given distribution. The expected values are computed independently of the system, and then the test inputs are applied. A large number of tests must be applied for the results to be statistically significant, but the tests are easy to generate.

⌘ Regression tests.

- ☑ Tests of previous versions, bugs, etc.
- ☑ May be clear-box tests of previous versions.

How much testing is enough?



- ⌘ Exhaustive testing is impractical.
- ⌘ One important measure of test quality---bugs escaping into field.
- ⌘ Good organizations can test software to give very low field bug report rates.
- ⌘ Error injection measures test quality:
 - ☑ Add known bugs.
 - ☑ Run your tests.
 - ☑ Determine % injected bugs that are caught.