$$C = \frac{1}{2n} \sum_{i=1}^{n} || y_i - a_i^{\perp} ||^2 \approx \frac{1}{2m} \sum_{i=1}^{m} || y_i - a_i^{\perp} ||^2$$
For Mini Batch

Let. Pj. be a parameter of jth newton in 1th layer.

$$\frac{\partial c}{\partial p_{j}^{k}} = \frac{1}{2m} \sum_{i=1}^{m} \frac{\partial}{\partial p_{j}^{k}} || y_{i} - a_{i}^{k} ||^{2}$$

Now, we do derivative for every data point in Mini Batch. So, we can obsorp the summation, index i when calculating derivative for a single data point. We also ignore the constant $\frac{1}{2m}$.

So, we get,
$$\frac{\partial}{\partial P_{j}^{L}} \parallel \psi - \alpha^{L} \parallel^{2} = \frac{\partial \delta}{\partial P_{j}^{L}}$$

$$(8 = C \text{ if } m = 1)$$

Now,
$$\frac{\partial g}{\partial p_{j}^{l}} = \frac{\partial}{\partial z_{j}^{l}} \frac{\partial}{\partial p_{j}^{l}} = \frac{\partial}{\partial z_{j}^{l}} \frac{\partial}{\partial p_{j}^{l}} - (*)$$
where,
$$\frac{\partial}{\partial p_{j}^{l}} = \frac{\partial}{\partial z_{j}^{l}} \frac{\partial}{\partial p_{j}^{l}} = \frac{\partial}{\partial z_{j}^{l}} \frac{\partial}{\partial p_{j}^{l}} - (*)$$

$$Z_{j}^{l} = \frac{\partial S_{j}^{l}}{\partial Z_{j}^{l}}$$

$$Z_{j}^{l} = w_{j1} a_{1}^{l-1} + w_{j2} a_{2}^{l-1} + w_{j3} a_{3}^{l-1} + \cdots$$

$$+ w_{j} N_{l-1} a_{N_{l-1}}^{l-1} + b_{j}^{l}$$

We calculate δ_j^{l} for l=1, then using that calculate δ_t^{l-1} , so on .

FOR
$$l = L$$

$$\int_{J}^{L} = \frac{\partial Q}{\partial z_{j}^{L}} = \frac{\partial Q}{\partial a_{j}^{L}} \cdot \frac{\partial a_{j}^{L}}{\partial z_{j}^{L}}$$

$$= \frac{\partial}{\partial a_{j}^{L}} \parallel \frac{y_{j}^{L}}{z_{j}^{L}} - \frac{\partial}{\partial z_{j}^{L}} \cdot \frac{\partial}{\partial z_{j}^{L$$

For any layer
$$l$$
,

$$S_{j}^{l} = \frac{\partial 8}{\partial Z_{j}^{l}}$$

$$= \sum_{t=1}^{N_{l}+1} \frac{\partial 8}{\partial Z_{t}^{l+1}} \frac{\partial Z_{t}^{l+1}}{\partial Z_{j}^{l}}$$

$$= \sum_{t=1}^{N_{l}+1} \frac{\partial l}{\partial Z_{t}^{l+1}} \frac{\partial Z_{t}^{l+1}}{\partial Z_{j}^{l}}$$

$$= \sum_{t=1}^{N_{l}+1} \frac{\lambda + 1}{\lambda + 1} \frac{\lambda}{\lambda} + b_{t}^{l+1}$$

$$= \sum_{s=1}^{N_{l}} \frac{\lambda + 1}{\lambda + 1} \frac{\lambda}{\lambda} + b_{t}^{l+1}$$

$$= \sum_{s=1}^{N_{l}} \frac{\lambda + 1}{\lambda + 1} \frac{\lambda}{\lambda} + b_{t}^{l+1}$$

$$= \sum_{s=1}^{N_{l}} \frac{\lambda + 1}{\lambda + 1} \frac{\lambda}{\lambda} + b_{t}^{l+1}$$

:
$$\frac{\partial z_{t}^{l+1}}{\partial z_{j}^{l}} = \omega_{tj}^{l+1} \sigma'(z_{j}^{l})$$

: From $(* *)$ $\delta_{j}^{l} = \sum_{t=1}^{N_{l+1}} \delta_{t}^{l+1} \omega_{tj}^{l+1} \sigma'(z_{j}^{l}) \rightarrow$

$$S^{\lambda} = ((W^{\lambda+1})^{T} \delta^{\lambda+1}) \circ \delta'(Z^{\lambda}) - (2)$$

Now, from (*)
$$\frac{\partial Q}{\partial p_{j}^{l}} = \delta_{j}^{l} \cdot \frac{\partial z_{j}^{l}}{\partial p_{j}^{l}}$$

$$= \delta_{j}^{l} \cdot \frac{\partial}{\partial p_{j}^{l}} \left(w_{j_{1}} a_{1}^{l-1} + w_{j_{2}} a_{2}^{l-1} + w_{j_{3}} a_{3}^{l-1} + \cdots + w_{j_{l}} a_{2}^{l-1} + w_{j_{1}} a_{2}^{l-1} + w_{j$$

If,
$$p_{j}^{l} = b_{j}^{l}$$

then, $\frac{\partial g}{\partial b_{j}^{l}} = \delta_{j}^{l} - (3)$
If, $p_{j}^{l} = \omega_{j}^{l}$
then, $\frac{\partial g}{\partial \omega_{j}^{l}} = a_{r}^{l-1} - (4)$

In my code Back backpropagation function

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adds

implements only (1) - (4), update function adds

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the durivatives and divide the sum by Mini Batch

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size.