Natural User Interfaces

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Review

 A tangible user interface is a user interface in which a person interacts with digital information through the physical environment.

 Multimodal generally refers to an interface that can accept input from two or more combined modes

What is NUI?



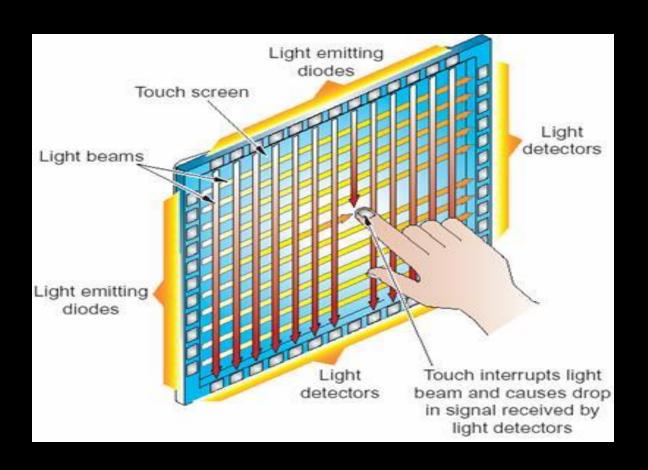
Natural user interface, or NUI, is the common parlance used by designers and developers of computer interfaces to refer to a user interface that is effectively invisible, or becomes invisible with successive learned interactions, to its users. The word natural is used because most computer interfaces use artificial control devices whose operation has to be learned.

NUI – Common Interactions

- Multi-touch
 - Mobile Devices, Table-top interactions
- Gestural Interfaces
- Speech Interfaces
- Physiological Interfaces
 - EEG, PPG, EMG, Sound

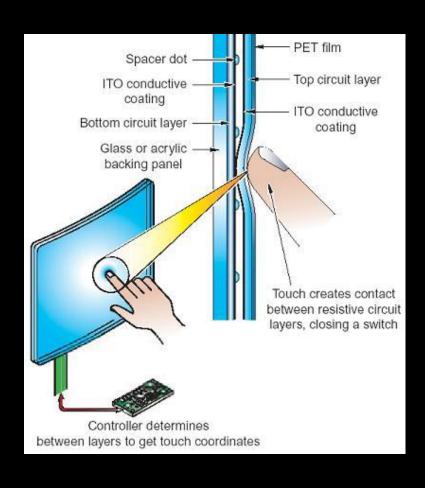
Touch Sensing - 1

Infrared Think laser pointer(s)



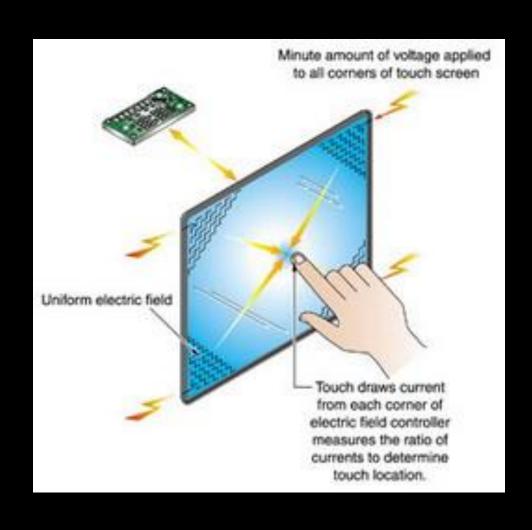
Touch Sensing - 2

Resistive Think Push Down and drag



Touch Sensing - 3

Capacitive Think Electric Impulse



Gesture Interface - Kinect

 Kinect (code name Project Natal) is a "controller-free gaming and entertainment experience" by Microsoft for the Xbox 360 platform

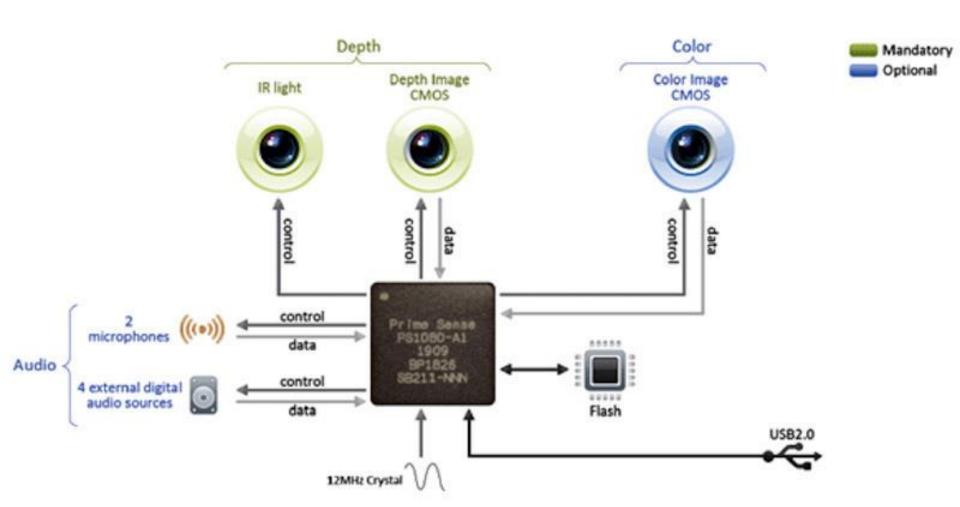


- Launched on 11/4/2010 in North America at USD \$150 MSRP.
- Sold 10M+ units world wide.
- Open source drivers for Linux, Mac, PC appeared a few days after the launch date

How Does It Work?

- The Kinect hardware is a combination of
 - An RGB camera,
 - A depth sensor
 - A multi-array microphone



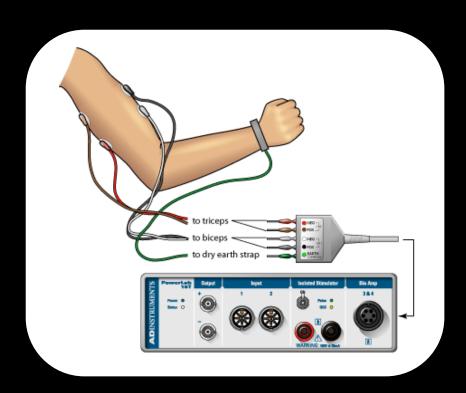


Kinect and PrimeSense



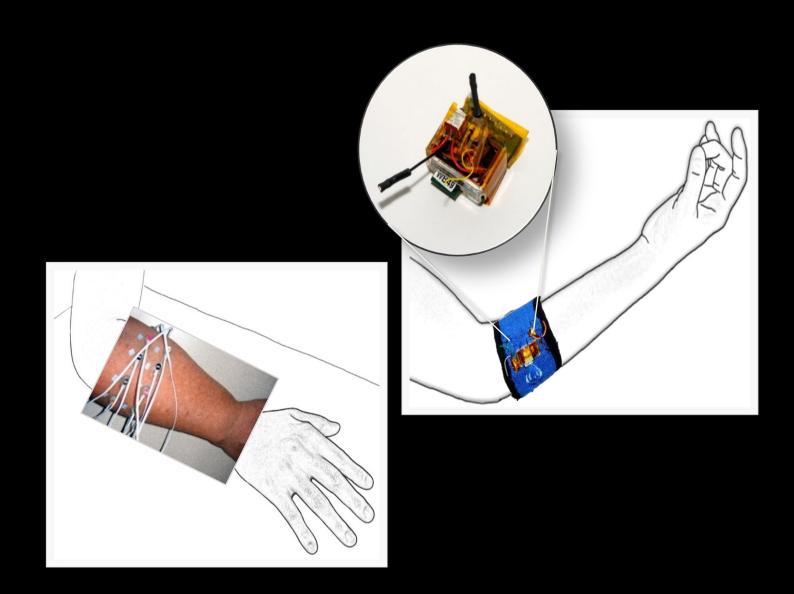
Physiological Interfaces

- Electroencephalogram (EEG)
- Sound (ScratchInput, Skinput)

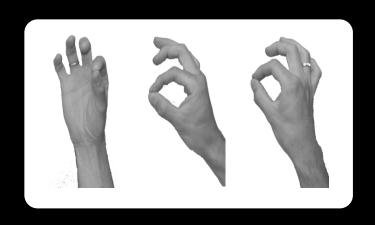




Muscle Sensing for Finger Gestures

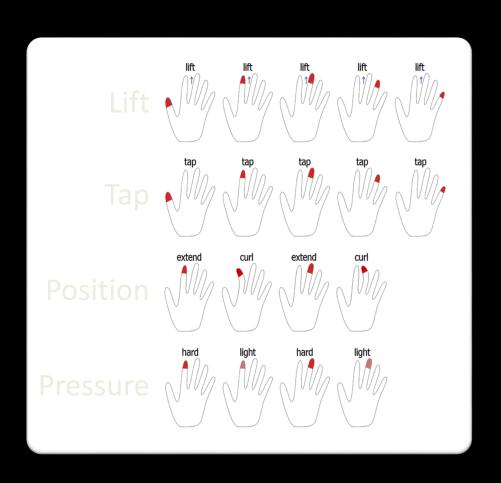


Gestures in Free Space





Gestures on Surfaces (e.g. table)



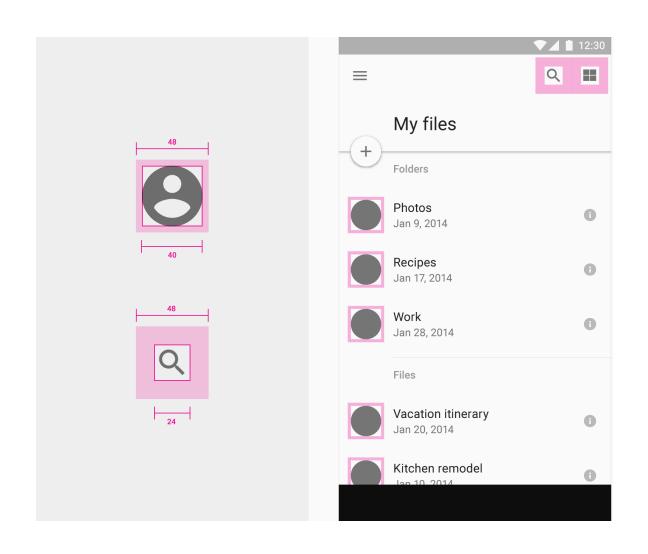
Touch Interaction

What is the Appropriate Target Size?

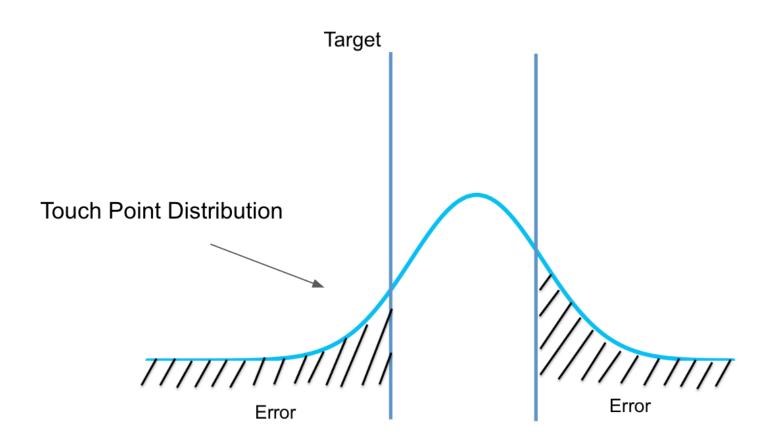


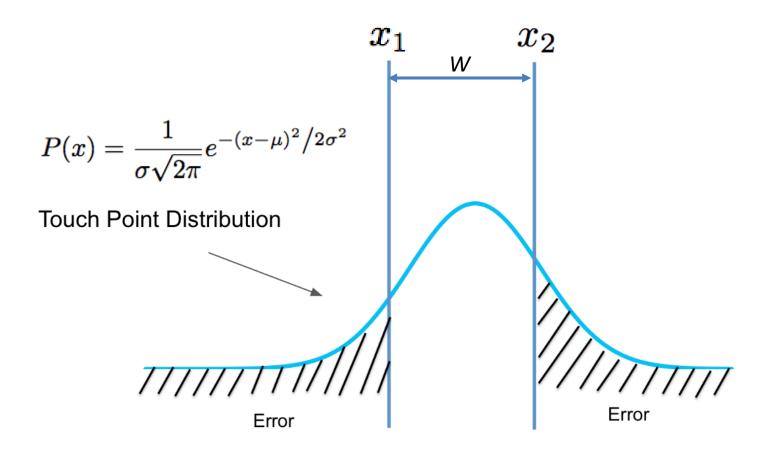


Target Size Suggested by Android



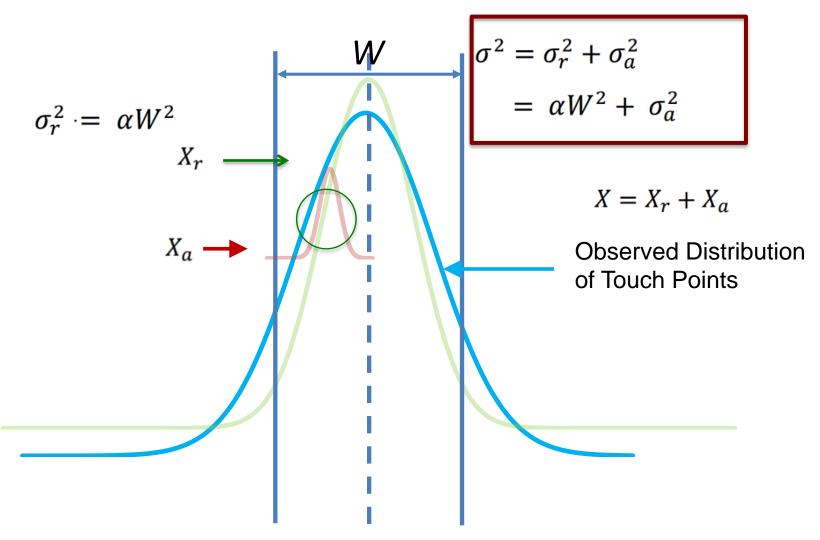
Target Acquisition





$$P(x_1 \leqslant X \leqslant x_2) = \int_{x_1}^{x_2} P(x) dx = \frac{1}{2} \left[\operatorname{erf} \left(\frac{x_2 - \mu}{\sigma \sqrt{2}} \right) - \operatorname{erf} \left(\frac{x_1 - \mu}{\sigma \sqrt{2}} \right) \right]$$
$$= \operatorname{erf} \left(\frac{W}{2\sqrt{2}\sigma} \right)$$

Dual Gaussian Distribution Model

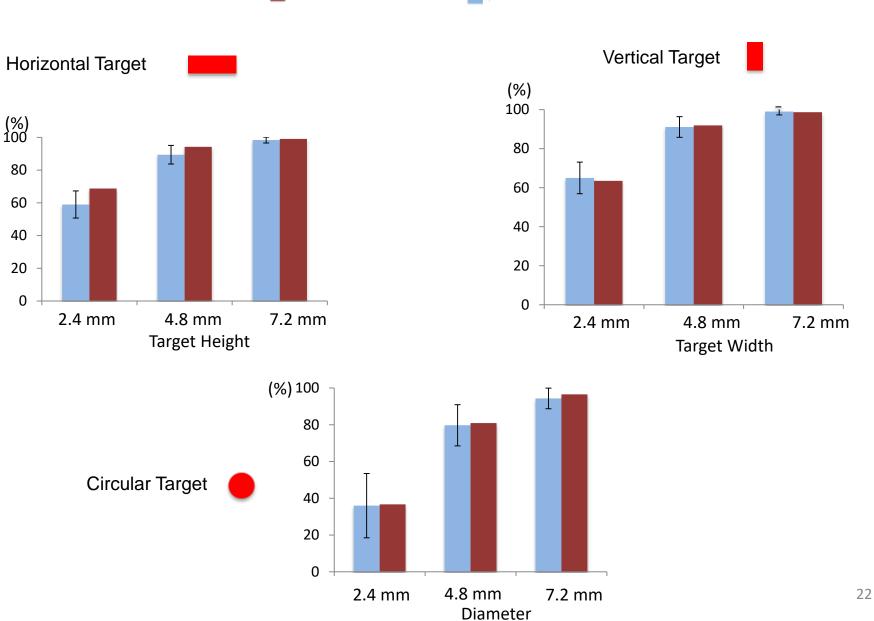


[Bi, Li, Zhai. FFitts Law: Modeling Finger Touch with Fitts' Law. CHI2013]

[Bi, Zhai. Bayesian Touch. UIST2013]

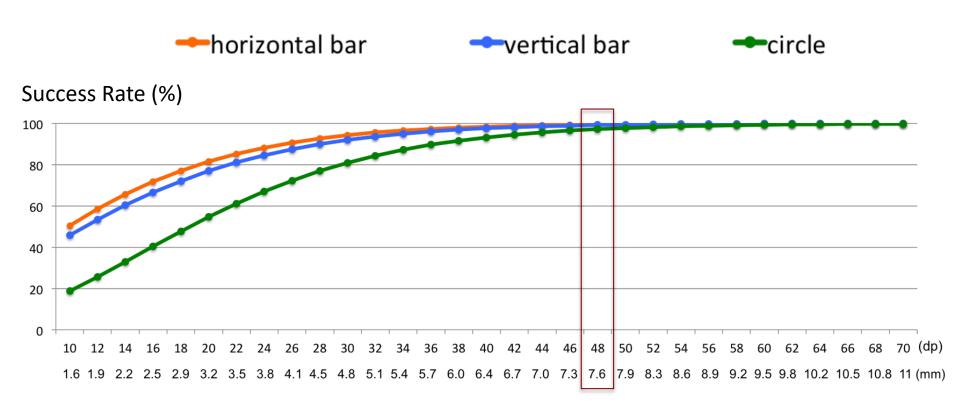
Evaluation

Predicted vs. Observed Success Rates



Application 1

Predicted Success Rate per Target Size



Target Width/Height/Diameter

[Bi, Zhai. Predicting Finger-Touch Accuracy Based on the Dual Gaussian Distribution Model. UIST2016]