



# Convolutional Neural Network

In this notebook, we'll walk through the steps required to train your own convolutional neural network (CNN) on the CIFAR dataset

```
In [2]: import sys
import os

project_root = os.path.abspath(os.path.join(os.getcwd(), '../..'))
if project_root not in sys.path:
    sys.path.insert(0, project_root)

import numpy as np

from tensorflow.keras import layers, models, optimizers, utils, datasets
from notebooks.utils import display
```

## 0. Parameters

```
In [2]: NUM_CLASSES = 10
```

## 1. Prepare the Data

```
In [3]: (x_train, y_train), (x_test, y_test) = datasets.cifar10.load_data()
```

```
In [4]: x_train = x_train.astype("float32") / 255.0
x_test = x_test.astype("float32") / 255.0

y_train = utils.to_categorical(y_train, NUM_CLASSES)
y_test = utils.to_categorical(y_test, NUM_CLASSES)
```

```
In [5]: display(x_train[:10])
print(y_train[:10])
```

```

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```

```

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 [0. 0. 0. 1. 0. 0. 0. 0. 0. 0.]]

```

## 2. Build the model

```

In [6]: input_layer = layers.Input((32, 32, 3))

x = layers.Conv2D(filters=32, kernel_size=3, strides=1, padding="same")(
    input_layer
)
x = layers.BatchNormalization()(x)
x = layers.LeakyReLU()(x)

x = layers.Conv2D(filters=32, kernel_size=3, strides=2, padding="same")(x)
x = layers.BatchNormalization()(x)
x = layers.LeakyReLU()(x)

x = layers.Conv2D(filters=64, kernel_size=3, strides=1, padding="same")(x)
x = layers.BatchNormalization()(x)
x = layers.LeakyReLU()(x)

```

```
x = layers.Conv2D(filters=64, kernel_size=3, strides=2, padding="same")(x)
x = layers.BatchNormalization()(x)
x = layers.LeakyReLU()(x)

x = layers.Flatten()(x)

x = layers.Dense(128)(x)
x = layers.BatchNormalization()(x)
x = layers.LeakyReLU()(x)
x = layers.Dropout(rate=0.5)(x)

x = layers.Dense(NUM_CLASSES)(x)
output_layer = layers.Activation("softmax")(x)

model = models.Model(input_layer, output_layer)

model.summary()
```

**Model: "functional"**



Layer (type)	Output Shape	Par
input_layer (InputLayer)	(None, 32, 32, 3)	
conv2d (Conv2D)	(None, 32, 32, 32)	
batch_normalization (BatchNormalization)	(None, 32, 32, 32)	
leaky_re_lu (LeakyReLU)	(None, 32, 32, 32)	
conv2d_1 (Conv2D)	(None, 16, 16, 32)	9
batch_normalization_1 (BatchNormalization)	(None, 16, 16, 32)	
leaky_re_lu_1 (LeakyReLU)	(None, 16, 16, 32)	
conv2d_2 (Conv2D)	(None, 16, 16, 64)	18
batch_normalization_2 (BatchNormalization)	(None, 16, 16, 64)	
leaky_re_lu_2 (LeakyReLU)	(None, 16, 16, 64)	
conv2d_3 (Conv2D)	(None, 8, 8, 64)	36
batch_normalization_3 (BatchNormalization)	(None, 8, 8, 64)	
leaky_re_lu_3 (LeakyReLU)	(None, 8, 8, 64)	
flatten (Flatten)	(None, 4096)	
dense (Dense)	(None, 128)	524
batch_normalization_4 (BatchNormalization)	(None, 128)	
leaky_re_lu_4 (LeakyReLU)	(None, 128)	
dropout (Dropout)	(None, 128)	
dense_1 (Dense)	(None, 10)	1
activation (Activation)	(None, 10)	

**Total params:** 592,554 (2.26 MB)

**Trainable params:** 591,914 (2.26 MB)

**Non-trainable params:** 640 (2.50 KB)

### 3. Train the model

```
In [7]: opt = optimizers.Adam(learning_rate=0.0005)
        model.compile(
```

```
loss="categorical_crossentropy", optimizer=opt, metrics=["accuracy"]
)
```

```
In [8]: model.fit(
        x_train,
        y_train,
        batch_size=32,
        epochs=10,
        shuffle=True,
        validation_data=(x_test, y_test),
    )
```

```
Epoch 1/10
1563/1563 ————— 22s 14ms/step — accuracy: 0.4491 — loss: 1.57
17 — val_accuracy: 0.5734 — val_loss: 1.1989
Epoch 2/10
1563/1563 ————— 22s 14ms/step — accuracy: 0.5885 — loss: 1.16
19 — val_accuracy: 0.6432 — val_loss: 1.0085
Epoch 3/10
1563/1563 ————— 22s 14ms/step — accuracy: 0.6507 — loss: 1.00
18 — val_accuracy: 0.6388 — val_loss: 1.0335
Epoch 4/10
1563/1563 ————— 21s 14ms/step — accuracy: 0.6812 — loss: 0.91
23 — val_accuracy: 0.6693 — val_loss: 0.9263
Epoch 5/10
1563/1563 ————— 22s 14ms/step — accuracy: 0.7072 — loss: 0.84
32 — val_accuracy: 0.6922 — val_loss: 0.8831
Epoch 6/10
1563/1563 ————— 22s 14ms/step — accuracy: 0.7188 — loss: 0.80
36 — val_accuracy: 0.6488 — val_loss: 1.0208
Epoch 7/10
1563/1563 ————— 21s 13ms/step — accuracy: 0.7362 — loss: 0.75
46 — val_accuracy: 0.7145 — val_loss: 0.8231
Epoch 8/10
1563/1563 ————— 21s 13ms/step — accuracy: 0.7497 — loss: 0.71
74 — val_accuracy: 0.7202 — val_loss: 0.8095
Epoch 9/10
1563/1563 ————— 22s 14ms/step — accuracy: 0.7615 — loss: 0.68
45 — val_accuracy: 0.7223 — val_loss: 0.8001
Epoch 10/10
1563/1563 ————— 22s 14ms/step — accuracy: 0.7730 — loss: 0.65
26 — val_accuracy: 0.7277 — val_loss: 0.7982
```

```
Out[8]: <keras.src.callbacks.history.History at 0x14f0ea680>
```

## 4. Evaluation

```
In [9]: model.evaluate(x_test, y_test, batch_size=1000)
```

```
10/10 ————— 1s 57ms/step — accuracy: 0.7277 — loss: 0.7982
```

```
Out[9]: [0.7981552481651306, 0.7276999950408936]
```

```
In [10]: CLASSES = np.array(
        [
            "airplane",
```

```

        "automobile",
        "bird",
        "cat",
        "deer",
        "dog",
        "frog",
        "horse",
        "ship",
        "truck",
    ]
)

preds = model.predict(x_test)
preds_single = CLASSES[np.argmax(preds, axis=-1)]
actual_single = CLASSES[np.argmax(y_test, axis=-1)]

```

313/313 ————— 1s 3ms/step

```

In [11]: import matplotlib.pyplot as plt

n_to_show = 10
indices = np.random.choice(range(len(x_test)), n_to_show)

fig = plt.figure(figsize=(15, 3))
fig.subplots_adjust(hspace=0.4, wspace=0.4)

for i, idx in enumerate(indices):
    img = x_test[idx]
    ax = fig.add_subplot(1, n_to_show, i + 1)
    ax.axis("off")
    ax.text(
        0.5,
        -0.35,
        "pred = " + str(preds_single[idx]),
        fontsize=10,
        ha="center",
        transform=ax.transAxes,
    )
    ax.text(
        0.5,
        -0.7,
        "act = " + str(actual_single[idx]),
        fontsize=10,
        ha="center",
        transform=ax.transAxes,
    )
    ax.imshow(img)

```



pred = truck  
act = truck



pred = automobile  
act = automobile



pred = ship  
act = ship



pred = dog  
act = dog



pred = ship  
act = ship



pred = dog  
act = dog



pred = ship  
act = ship



pred = cat  
act = cat



pred = frog  
act = horse



pred = automobile  
act = automobile

In [ ]: