



Convolutional Neural Network

In this notebook, we'll walk through the steps required to train your own convolutional neural network (CNN) on the CIFAR dataset

```
In [2]: import sys
import os

project_root = os.path.abspath(os.path.join(os.getcwd(), '../..'))
if project_root not in sys.path:
    sys.path.insert(0, project_root)

import numpy as np

from tensorflow.keras import layers, models, optimizers, utils, datasets
from notebooks.utils import display
```

0. Parameters

```
In [2]: NUM_CLASSES = 10
```

1. Prepare the Data

```
In [3]: (x_train, y_train), (x_test, y_test) = datasets.cifar10.load_data()
```

```
In [4]: x_train = x_train.astype("float32") / 255.0
x_test = x_test.astype("float32") / 255.0

y_train = utils.to_categorical(y_train, NUM_CLASSES)
y_test = utils.to_categorical(y_test, NUM_CLASSES)
```

```
In [5]: display(x_train[:10])
print(y_train[:10])
```

```
array([[[[0.23137255, 0.24313726, 0.24705882],  
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        ...,  
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        [0.3254902 , 0.20784314, 0.13333334]],
```

```
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```

```
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```

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[0. 0. 0. 1. 0. 0. 0. 0. 0. 0.]]
```

2. Build the model

```
In [6]: input_layer = layers.Input((32, 32, 3))  
  
x = layers.Conv2D(filters=32, kernel_size=3, strides=1, padding="same")(input_layer)  
x = layers.BatchNormalization()(x)  
x = layers.LeakyReLU()(x)  
  
x = layers.Conv2D(filters=32, kernel_size=3, strides=2, padding="same")(x)  
x = layers.BatchNormalization()(x)  
x = layers.LeakyReLU()(x)  
  
x = layers.Conv2D(filters=64, kernel_size=3, strides=1, padding="same")(x)  
x = layers.BatchNormalization()(x)
```

```
x = layers.LeakyReLU()(x)

x = layers.Conv2D(filters=64, kernel_size=3, strides=2, padding="same")(x)
x = layers.BatchNormalization()(x)
x = layers.LeakyReLU()(x)

x = layers.Flatten()(x)

x = layers.Dense(128)(x)
x = layers.BatchNormalization()(x)
x = layers.LeakyReLU()(x)
x = layers.Dropout(rate=0.5)(x)

x = layers.Dense(NUM_CLASSES)(x)
output_layer = layers.Activation("softmax")(x)

model = models.Model(input_layer, output_layer)

model.summary()
```

Model: "functional"

Layer (type)	Output Shape	Param #
input_layer (InputLayer)	(None, 32, 32, 3)	0
conv2d (Conv2D)	(None, 32, 32, 32)	896
batch_normalization (BatchNormalization)	(None, 32, 32, 32)	128
leaky_re_lu (LeakyReLU)	(None, 32, 32, 32)	0
conv2d_1 (Conv2D)	(None, 16, 16, 32)	9,248
batch_normalization_1 (BatchNormalization)	(None, 16, 16, 32)	128
leaky_re_lu_1 (LeakyReLU)	(None, 16, 16, 32)	0
conv2d_2 (Conv2D)	(None, 16, 16, 64)	18,496
batch_normalization_2 (BatchNormalization)	(None, 16, 16, 64)	256
leaky_re_lu_2 (LeakyReLU)	(None, 16, 16, 64)	0
conv2d_3 (Conv2D)	(None, 8, 8, 64)	36,928
batch_normalization_3 (BatchNormalization)	(None, 8, 8, 64)	256
leaky_re_lu_3 (LeakyReLU)	(None, 8, 8, 64)	0
flatten (Flatten)	(None, 4096)	0
dense (Dense)	(None, 128)	524,416
batch_normalization_4 (BatchNormalization)	(None, 128)	512
leaky_re_lu_4 (LeakyReLU)	(None, 128)	0
dropout (Dropout)	(None, 128)	0
dense_1 (Dense)	(None, 10)	1,290

activation (Activation)	(None, 10)	0
-------------------------	------------	---

Total params: 592,554 (2.26 MB)

Trainable params: 591,914 (2.26 MB)

Non-trainable params: 640 (2.50 KB)

3. Train the model

```
In [7]: opt = optimizers.Adam(learning_rate=0.0005)
model.compile(
    loss="categorical_crossentropy", optimizer=opt, metrics=["accuracy"])
)
```

```
In [8]: model.fit(
    x_train,
    y_train,
    batch_size=32,
    epochs=10,
    shuffle=True,
    validation_data=(x_test, y_test),
)
```

```
Epoch 1/10
1563/1563 22s 14ms/step - accuracy: 0.4491 - loss: 1.5717 - val_accuracy: 0.5734 - val_loss: 1.1989
Epoch 2/10
1563/1563 22s 14ms/step - accuracy: 0.5885 - loss: 1.1619 - val_accuracy: 0.6432 - val_loss: 1.0085
Epoch 3/10
1563/1563 22s 14ms/step - accuracy: 0.6507 - loss: 1.0018 - val_accuracy: 0.6388 - val_loss: 1.0335
Epoch 4/10
1563/1563 21s 14ms/step - accuracy: 0.6812 - loss: 0.9123 - val_accuracy: 0.6693 - val_loss: 0.9263
Epoch 5/10
1563/1563 22s 14ms/step - accuracy: 0.7072 - loss: 0.8432 - val_accuracy: 0.6922 - val_loss: 0.8831
Epoch 6/10
1563/1563 22s 14ms/step - accuracy: 0.7188 - loss: 0.8036 - val_accuracy: 0.6488 - val_loss: 1.0208
Epoch 7/10
1563/1563 21s 13ms/step - accuracy: 0.7362 - loss: 0.7546 - val_accuracy: 0.7145 - val_loss: 0.8231
Epoch 8/10
1563/1563 21s 13ms/step - accuracy: 0.7497 - loss: 0.7174 - val_accuracy: 0.7202 - val_loss: 0.8095
Epoch 9/10
1563/1563 22s 14ms/step - accuracy: 0.7615 - loss: 0.6845 - val_accuracy: 0.7223 - val_loss: 0.8001
Epoch 10/10
1563/1563 22s 14ms/step - accuracy: 0.7730 - loss: 0.6526 - val_accuracy: 0.7277 - val_loss: 0.7982
```

Out[8]: <keras.src.callbacks.history.History at 0x14f0ea680>

4. Evaluation

In [9]: `model.evaluate(x_test, y_test, batch_size=1000)`

```
10/10 1s 57ms/step - accuracy: 0.7277 - loss: 0.7982
```

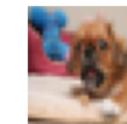
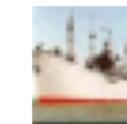
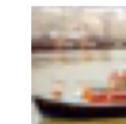
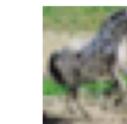
Out[9]: [0.7981552481651306, 0.7276999950408936]

```
In [10]: CLASSES = np.array(  
    [  
        "airplane",  
        "automobile",  
        "bird",  
        "cat",  
        "deer",  
        "dog",  
        "frog",  
        "horse",  
        "ship",  
        "truck",  
    ]  
)  
  
preds = model.predict(x_test)  
preds_single = CLASSES[np.argmax(preds, axis=-1)]  
actual_single = CLASSES[np.argmax(y_test, axis=-1)]
```

313/313 ━━━━━━ 1s 3ms/step

```
In [11]: import matplotlib.pyplot as plt  
  
n_to_show = 10  
indices = np.random.choice(range(len(x_test)), n_to_show)  
  
fig = plt.figure(figsize=(15, 3))  
fig.subplots_adjust(hspace=0.4, wspace=0.4)  
  
for i, idx in enumerate(indices):  
    img = x_test[idx]  
    ax = fig.add_subplot(1, n_to_show, i + 1)  
    ax.axis("off")  
    ax.text(  
        0.5,  
        -0.35,  
        "pred = " + str(preds_single[idx]),  
        fontsize=10,  
        ha="center",  
        transform=ax.transAxes,  
    )  
    ax.text(  
        0.5,
```

```
    0.5,  
    -0.7,  
    "act = " + str(actual_single[idx]),  
    fontsize=10,  
    ha="center",  
    transform=ax.transAxes,  
)  
ax.imshow(img)
```

pred = truck
act = truckpred = automobile
act = automobilepred = ship
act = shippred = dog
act = dogpred = ship
act = shippred = dog
act = dogpred = ship
act = shippred = cat
act = catpred = frog
act = horsepred = automobile
act = automobile

In []: