

Examples :-

① Input as $\rightarrow 000111111$

Result : Accepted.

② Input as $\rightarrow 00001111$

Result : Not Accepted.

★ Convert PDA to CFG

$$\delta(q_0, b, z_0) = \{(q_0, zz_0)\}$$

$$\delta(q_0, \epsilon, z_0) = \{(q_0, \epsilon)\}$$

$$\delta(q_0, a, z) = \{(q_0, zz)\}$$

$$\delta(q_0, a, z) = \{(q_1, z)\}$$

$$\delta(q_1, b, z) = \{(q_1, \epsilon)\}$$

$$\delta(q_1, a, z_0) = \{(q_0, z_0)\}$$

$$\begin{aligned} \rightarrow V &= [qz, q'], q, q' \in Q, z \in F \\ V &= \{(q_0 z_0 q_0), (q_0 z_0 q_1), (q_0 z q_0), (q_0 z q_1), (q_1 z_0 q_0), (q_1 z_0 q_1), (q_1 z q_0), \\ &\quad (q_1 z q_1)\} \end{aligned}$$

$$S \rightarrow [q_0 z_0 q] \quad \forall q \in Q$$

$$S \rightarrow [q_0 z_0 q_0] / [q_0 z_0 q_1]$$

$$T = \Sigma = \{a, b\}, \quad \Gamma = \{a, b\}$$

$$1) \delta(q_0, b, z_0) = (q_0, z z_0)$$

$$\begin{aligned} \rightarrow \text{Push} &= [q_0, z_0, q_0] \rightarrow b [q_0, z q_0] [q_0, z_0, q_0] \\ [q_0, z_0, q_0] &\rightarrow b [q_0, z q_1] [q_1, z_0, q_0] \\ [q_0, z_0, q_1] &\rightarrow b [q_0, z q_0] [q_0, z_0, q_1] \\ [q_0, z_0, q_1] &\rightarrow b [q_0, z q_1] [q_1, z_0, q_1] \end{aligned}$$

$$2) \delta(q_0, \epsilon, z_0) = (q_0, \epsilon)$$

$$\rightarrow \text{POP} : [q_0, z_0, q_0] \rightarrow \epsilon$$

$$3) \delta(q_0, b, z) = (q_0, z, z)$$

$$\begin{aligned} \rightarrow \text{Push} : [q_0, z q_0] &\rightarrow b [q_0, z q_0] [q_0, z q_0] \\ [q_0, z q_0] &\rightarrow b [q_0, z q_1] [q_1, z q_0] \\ [q_0, z q_1] &\rightarrow b [q_0, z q_0] [q_0, z q_1] \\ [q_0, z q_1] &\rightarrow b [q_0, z q_1] [q_1, z q_1] \end{aligned}$$

$$4) \delta(q_0, a, z) = (q_1, z)$$

$$\begin{aligned} \left[\begin{array}{l} \text{No-operation} \\ \text{read} \end{array} \right] : [q_0, z q_0] &\rightarrow a [q_1, z q_0] \\ [q_0, z q_1] &\rightarrow a [q_1, z q_1] \end{aligned}$$

$$5) \delta(q_1, b, z) = (q_1, \epsilon)$$

$$\text{Pop} : [q_1, z q_1] \rightarrow b$$

$$6) \delta(q_1, a, z_0) = (q_0, z_0)$$

$$\left[\begin{array}{l} \text{No-operation} \\ \text{Read} \end{array} \right] \begin{array}{l} [q_1, z_0, q_0] \rightarrow a[q_0, z_0, q_0] \\ [q_1, z_0, q_1] \rightarrow a[q_0, z_0, q_1] \end{array}$$

$$G = (V, T, P, S)$$

$$V = \{(q_0, z_0, q_0), (q_0, z_0, q_1), (q_0, z_1, q_0), (q_0, z_1, q_1), (q_1, z_0, q_0), (q_1, z_0, q_1), (q_1, z_1, q_0), (q_1, z_1, q_1)\}$$

$$T = \{a, b\}$$

$$S \rightarrow [q_0, z_0, q_0] / [q_0, z_0, q_1]$$

$$[q_0, z_0, q_0] \rightarrow b[q_0, z_1, q_0][q_0, z_0, q_0]$$

$$[q_0, z_0, q_0] \rightarrow b[q_0, z_1, q_0][q_1, z_0, q_0]$$

$$[q_0, z_0, q_1] \rightarrow b[q_0, z_1, q_0][q_0, z_0, q_1]$$

$$[q_0, z_0, q_1] \rightarrow b[q_0, z_1, q_1][q_1, z_0, q_1]$$

$$[q_0, z_1, q_0] \rightarrow \epsilon$$

$$[q_0, z_1, q_0] \rightarrow a[q_1, z_1, q_0]$$

$$[q_0, z_1, q_1] \rightarrow a[q_1, z_1, q_1]$$

$$[q_0, z_1, q_1] \rightarrow b$$