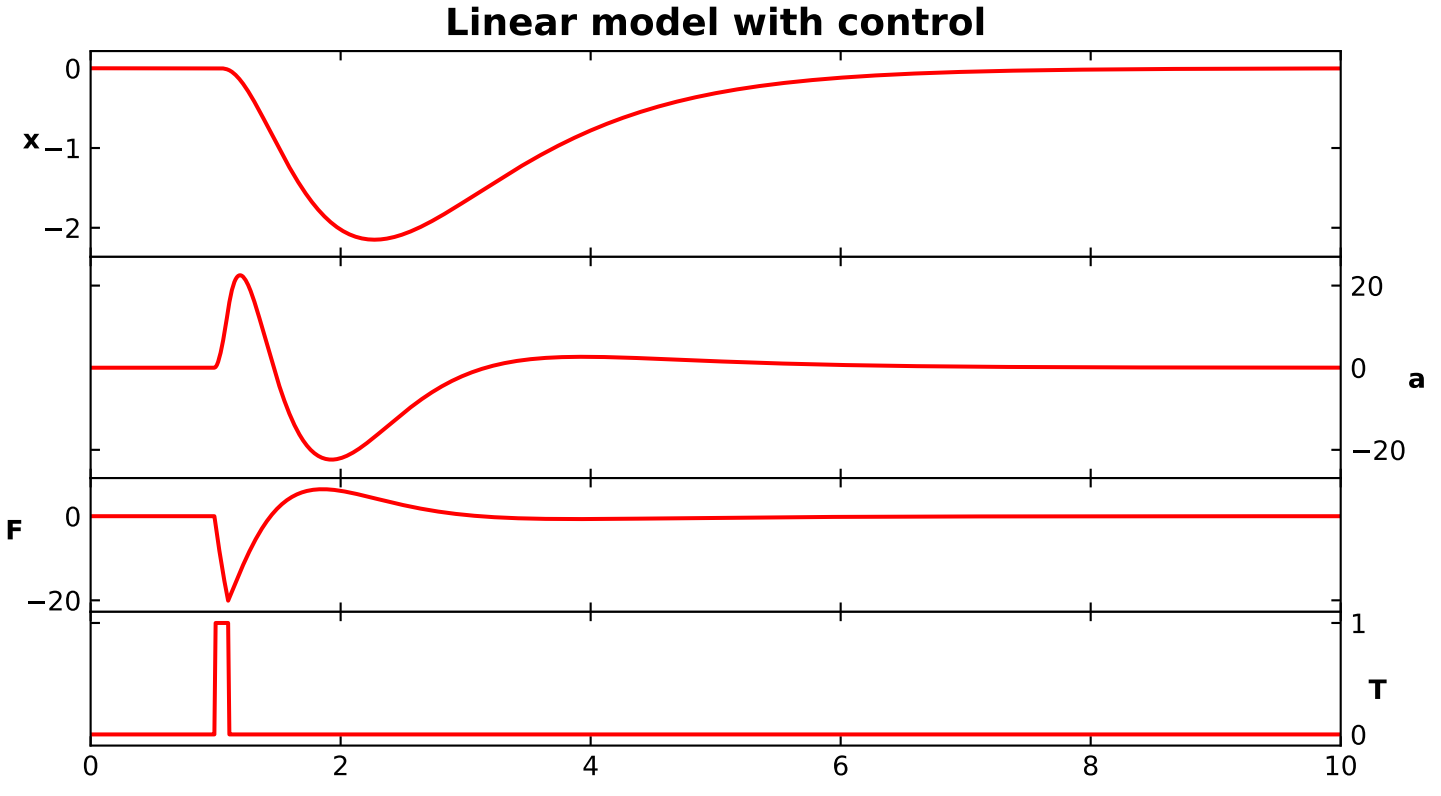
Linear model with control
x
F
a
T
0
−1
−2
20
−20
1
0
2
4
6
8
10