

# PyEpics: Python Epics Channel Access

*Release 3.3.2*

Matthew Newville

Dec 20, 2018



# CONTENTS

|          |  |           |
|----------|--|-----------|
| <b>1</b> | <b>Downloading and Installation</b>  | <b>3</b>  |
| 1.1      | Prerequisites . . . . .  | 3         |
| 1.2      | Downloads and Installation . . . . .   | 3         |
| 1.3      | Getting Started, Setting up the Epics Environment . . . . .  | 4         |
| 1.4      | Testing . . . . .  | 4         |
| 1.5      | Development Version . . . . .  | 4         |
| 1.6      | Getting Help . . . . .   | 4         |
| 1.7      | License . . . . .  | 5         |
| 1.8      | Acknowledgments . . . . .  | 6         |
| <b>2</b> | <b>PyEpics Overview</b>  | <b>7</b>  |
| 2.1      | Quick Start . . . . .  | 8         |
| 2.2      | Functions defined in <code>epics</code> : <code>caget()</code> , <code>caput()</code> , etc. . . . . | 10        |
| 2.3      | Motivation and design concepts . . . . .   | 14        |
| 2.4      | Status and to-do list . . . . .  | 15        |
| <b>3</b> | <b>PV: Epics Process Variables</b>   | <b>17</b> |
| 3.1      | The PV class . . . . .   | 17        |
| 3.2      | String representation for a PV . . . . .   | 23        |
| 3.3      | Automatic Monitoring of a PV . . . . .   | 24        |
| 3.4      | User-supplied Callback functions . . . . .   | 24        |
| 3.5      | User-supplied Connection Callback functions . . . . .  | 26        |
| 3.6      | User-supplied Access Rights Callback functions . . . . .   | 26        |
| 3.7      | Put with wait, put callbacks, and <code>put_complete</code> . . . . .                                | 26        |
| 3.8      | The <code>get_pv()</code> function and <code>_PVcache_</code> cache of PVs . . . . .                 | 27        |
| 3.9      | Examples . . . . .   | 28        |
| <b>4</b> | <b>ca: Low-level Channel Access module</b>   | <b>33</b> |
| 4.1      | General description, difference with C library . . . . .   | 33        |
| 4.2      | Initialization, Finalization, and Life-cycle . . . . .   | 34        |
| 4.3      | Using the CA module . . . . .  | 34        |
| 4.4      | Implementation details . . . . .   | 44        |
| 4.5      | User-supplied Callback functions . . . . .   | 46        |
| 4.6      | Omissions . . . . .  | 47        |
| 4.7      | <code>CAThread</code> class . . . . .  | 48        |
| 4.8      | Examples . . . . .   | 48        |
| <b>5</b> | <b>Working with waveform / array data</b>  | <b>51</b> |
| 5.1      | Arrays without Numpy . . . . .   | 51        |
| 5.2      | Variable Length Arrays: NORD and NELM . . . . .  | 51        |

|           |   |           |
|-----------|---|-----------|
| 5.3       | Character Arrays . . . . .  | 52        |
| 5.4       | Example handling Large Arrays . . . . .                             | 53        |
| <b>6</b>  | <b>Devices: collections of PVs</b>                                  | <b>55</b> |
| 6.1       | Overview . . . . .  | 55        |
| 6.2       | Epics Motor Device . . . . .  | 56        |
| 6.3       | Other Device Examples . . . . .                                     | 60        |
| <b>7</b>  | <b>Alarms: respond when a PV goes out of range</b>                  | <b>65</b> |
| 7.1       | Overview . . . . .  | 65        |
| 7.2       | Alarm Example . . . . .   | 66        |
| <b>8</b>  | <b>Auto-saving: simple save/restore of PVs</b>                      | <b>67</b> |
| 8.1       | AutoSaver class . . . . .   | 68        |
| 8.2       | Supported Data Types . . . . .                                      | 69        |
| <b>9</b>  | <b>wx: wxPython Widgets for Epics</b>                               | <b>71</b> |
| 9.1       | PV-aware Widgets . . . . .  | 71        |
| 9.2       | Decorators and other Utility Functions . . . . .                    | 75        |
| 9.3       | wxMotorPanel Widget . . . . .                                       | 75        |
| 9.4       | OGL Classes . . . . .   | 77        |
| <b>10</b> | <b>Advanced Topic with Python Channel Access</b>                    | <b>79</b> |
| 10.1      | The wait and timeout options for get(), ca.get_complete() . . . . . | 79        |
| 10.2      | Strategies for connecting to a large number of PVs . . . . .        | 80        |
| 10.3      | time.sleep() or epics.poll()? . . . . .                             | 82        |
| 10.4      | Using Python Threads . . . . .                                      | 82        |
| 10.5      | Using Multiprocessing with PyEpics . . . . .                        | 86        |
|           | <b>Python Module Index</b>  | <b>89</b> |
|           | <b>Index</b>  | <b>91</b> |

PyEpics is an interface for the Channel Access (CA) library of the [Epics Control System](#) to the Python Programming language. The pyepics package provides a base `epics` module to python, with methods for reading from and writing to Epics Process Variables (PVs) via the CA protocol. The package includes a thin and fairly complete layer over the low-level Channel Access library in the `ca` module, and higher level abstractions built on top of this basic functionality.

The package includes a very simple interface to CA similar to the Unix command-line tools and EZCA library with functions `epics.caget()`, `epics.caput()`, `epics.cainfo()`, and `epics.camonitor()`. There is also a `pv.PV` class which represents an Epics Process Variable as a full-featured and easy-to-use Python object. Additional modules provide higher-level programming support to CA, including grouping related PVs into a `device.Device`, creating alarms in `alarm.Alarm`, and saving PVs values in the `autosave` module. There is also support for conveniently using epics PVs to wxPython widgets in the `wx` module, and some support for using PyQt widgets in the `qt` module.

---

In addition to the Pyepics library described here, several applications built with pyepics are available at <http://github.com/pyepics/epicsapps/>. See <http://pyepics.github.com/epicsapps/> for further details.

---



## DOWNLOADING AND INSTALLATION

### 1.1 Prerequisites

PyEpics works with Python version 2.7, 3.5, or 3.6. It is supported and regularly used and tested on 64-bit Linux, 64-bit Mac OSX, 64-bit Windows. It should still work on 32-bit Windows, 32-bit Linux, and on Linux with ARM processors, such as raspberry Pi, but these are tested regularly. It appears to work with Python 3.7, but this has tested much. It may also work with older versions of Python (such as 3.4), but these are not tested. For Windows, pyepics has been reported to work with IronPython (Python written with .NET), but this is not routinely tested.

The EPICS Channel Access library Version 3.14 or higher is required for pyepics to actually communicate with Epics variables. Specifically, the shared libraries libca and libCom (*libca.so* and *libCom.so* on Linux, *libca.dylib* and *libCom.dylib* on Mac OSX, or *ca.dll* and *Com.dll* on Windows) from *Epics Base* are required to use this module. Some features, including ‘subarray records’ will only work with version 3.14.12 and higher, and version 3.15 or higher is strongly recommended.

For all supported operating systems (linux-64, linux-32, linux-arm, windows-64, windows-32, and darwin-64), pre-built versions of *libca* (and *libCom*) built with 3.16.2 are provided, and will be installed within the python packages directory and used by default. That means that you do not need to install Epics base libraries or any other packages to use pyepics. For Epics experts who may want to use their own versions the *libca* from Epics base, instructions for how to do this are given below.

The Python [numpy module](#) is highly recommended, though it is not required. If available, it will be used to automatically convert between EPICS waveforms and numpy arrays.

The *autosave* module requires the *pyparsing* package, which is widely available and often installed by default with many Python distributions. The *wx* module requires the *wxPython* package, and the *qt* module requires *PyQt* or *PySide*.

### 1.2 Downloads and Installation

The latest stable version of the pyepics package is 3.3.2. Source code kits and Windows installers can be found at [pyepics PyPI](#), and can be installed with:

```
pip install pyepics
```

If you’re using Anaconda Python, there are a few conda channels for pyepics, including:

```
conda install -c GSECARS pyepics
```

You can also download the source package, unpack it, and install with:

```
python setup.py install
```

## 1.3 Getting Started, Setting up the Epics Environment

As mentioned above, pyepics must be able to find and load the Channel Access dynamic library (*libca.so*, *libca.dylib*, or *ca.dll* depending on the system) at runtime in order to actually work. For the most commonly used operating systems and architectures, modern version of these libraries are provided, and will be installed and used with pyepics. We strongly recommend using these.

If these provided versions of *libca* do not work for you, please let us know. If you need to or wish to use a different version of *libca*, you can set the environmental variable `PYEPICS_LIBCA` to the full path of the dynamic library to use as *libca*, for example:

```
> export PYEPICS_LIBCA=/usr/local/epics/base-3.15.5/lib/linux-x86_64/libca.so
```

Note that *libca* will need to find another Epics CA library *libCom*. This is almost always in the same folder as *libca*, but you may need to make sure that the *libca* you are pointing to can find the required *libCom*. The methods for telling shared libraries (or executable files) how to find other shared libraries varies with system, but you may need to set other environmental variables such as `LD_LIBRARY_PATH` or `DYLIB_LIBRARY_PATH` or use *ldconfig*.

**To find out which CA library will be used by pyepics, use:**

```
>>> import epics
>>> epics.ca.find_libca()
```

which will print out the full path of the CA dynamic library that will be used.

With the Epics library loaded, you will need to be able to connect to Epics Process Variables. Generally, these variables are provided by Epics I/O controllers (IOCs) that are processes running on some device on the network. If you are connecting to PVs provided by IOCs on your local subnet, you should have no trouble. If trying to reach further network, you may need to set the environmental variable `EPICS_CA_ADDR_LIST` to specify which networks to search for PVs.

## 1.4 Testing

Automated and continuous unit-testing is done with the TravisCI (<https://travis-ci.org/pyepics/pyepics>) for Python 2.7, 3.5, and 3.6 using an Epics IOC running in a Docker image. Many tests located in the *tests* folder can also be run using the script *tests/simulator.py* as long as the Epics database in *tests/pydebug.db* is loaded in a local IOC. In addition, tests are regularly run on Mac OSX, and 32-bit and 64-bit Windows.

## 1.5 Development Version

Development of pyepics is done through the [pyepics github repository](#). To get a read-only copy of the latest version, use one of:

```
git clone http://github.com/pyepics/pyepics.git
git clone git@github.com:pyepics/pyepics.git
```

## 1.6 Getting Help

For questions, bug reports, feature request, please consider using the following methods:



1. Send email to the Epics Tech Talk mailing list. You can send mail directly to Matt Newville <[newville@cars.uchicago.edu](mailto:newville@cars.uchicago.edu)>, but the mailing list has many Epics experts reading it, so someone else interested or knowledgeable about the topic might provide an answer. Since the mailing list is archived and the main mailing list for Epics work, a question to the mailing list has a better chance of helping someone else.
2. Create an Issue on <http://github.com/pyepics/pyepics>. Though the github Issues seem to be intended for bug tracking, they are a fine way to catalog various kinds of questions and feature requests.
3. If you are sure you have found a bug in existing code, or have some code you think would be useful to add to pyepics, consider making a Pull Request on <http://github.com/pyepics/pyepics>.

## 1.7 License

The pyepics source code, this documentation, and all material associated with it are distributed under the Epics Open License:

The epics python module was originally written by

Matthew Newville <[newville@cars.uchicago.edu](mailto:newville@cars.uchicago.edu)> CARS, University of Chicago

There have been several contributions from many others, notably Angus Gratton <[angus.gratton@anu.edu.au](mailto:angus.gratton@anu.edu.au)>. See the Acknowledgements section of the documentation for a list of more contributors.

Except where explicitly noted, all files in this distribution are licensed under the Epics Open License.:

---

Copyright 2010 Matthew Newville, The University of Chicago. All rights reserved.

The epics python module is distributed subject to the following license conditions: SOFTWARE LICENSE AGREEMENT Software: epics python module

1. The “Software”, below, refers to the epics python module (in either source code, or binary form and accompanying documentation). Each licensee is addressed as “you” or “Licensee.”
2. The copyright holders shown above and their third-party licensors hereby grant Licensee a royalty-free nonexclusive license, subject to the limitations stated herein and U.S. Government license rights.
3. You may modify and make a copy or copies of the Software for use within your organization, if you meet the following conditions:
  1. Copies in source code must include the copyright notice and this Software License Agreement.
  2. Copies in binary form must include the copyright notice and this Software License Agreement in the documentation and/or other materials provided with the copy.
4. You may modify a copy or copies of the Software or any portion of it, thus forming a work based on the Software, and distribute copies of such work outside your organization, if you meet all of the following conditions:
  1. Copies in source code must include the copyright notice and this Software License Agreement;
  2. Copies in binary form must include the copyright notice and this Software License Agreement in the documentation and/or other materials provided with the copy;
  3. Modified copies and works based on the Software must carry prominent notices stating that you changed specified portions of the Software.

5. Portions of the Software resulted from work developed under a U.S. Government contract and are subject to the following license: the Government is granted for itself and others acting on its behalf a paid-up, nonexclusive, irrevocable worldwide license in this computer software to reproduce, prepare derivative works, and perform publicly and display publicly.

6. WARRANTY DISCLAIMER. THE SOFTWARE IS SUPPLIED “AS IS” WITHOUT WARRANTY OF ANY KIND. THE COPYRIGHT HOLDERS, THEIR THIRD PARTY LICENSORS, THE UNITED STATES, THE UNITED STATES DEPARTMENT OF ENERGY, AND THEIR EMPLOYEES: (1) DISCLAIM ANY WARRANTIES, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, TITLE OR NON-INFRINGEMENT, (2) DO NOT ASSUME ANY LEGAL LIABILITY OR RESPONSIBILITY FOR THE ACCURACY, COMPLETENESS, OR USEFULNESS OF THE SOFTWARE, (3) DO NOT REPRESENT THAT USE OF THE SOFTWARE WOULD NOT INFRINGE PRIVATELY OWNED RIGHTS, (4) DO NOT WARRANT THAT THE SOFTWARE WILL FUNCTION UNINTERRUPTED, THAT IT IS ERROR-FREE OR THAT ANY ERRORS WILL BE CORRECTED.

7. LIMITATION OF LIABILITY. IN NO EVENT WILL THE COPYRIGHT HOLDERS, THEIR THIRD PARTY LICENSORS, THE UNITED STATES, THE UNITED STATES DEPARTMENT OF ENERGY, OR THEIR EMPLOYEES: BE LIABLE FOR ANY INDIRECT, INCIDENTAL, CONSEQUENTIAL, SPECIAL OR PUNITIVE DAMAGES OF ANY KIND OR NATURE, INCLUDING BUT NOT LIMITED TO LOSS OF PROFITS OR LOSS OF DATA, FOR ANY REASON WHATSOEVER, WHETHER SUCH LIABILITY IS ASSERTED ON THE BASIS OF CONTRACT, TORT (INCLUDING NEGLIGENCE OR STRICT LIABILITY), OR OTHERWISE, EVEN IF ANY OF SAID PARTIES HAS BEEN WARNED OF THE POSSIBILITY OF SUCH LOSS OR DAMAGES.

---

In plain English, this says that there is no warranty or guarantee that the code will actually work, but you can do anything you like with this code except a) claim that you wrote it or b) claim that the people who did write it endorse your use of the code. Unless you’re the US government, in which case you can probably do whatever you want.

## 1.8 Acknowledgments

pyepics was originally written and is maintained by Matt Newville <[newville@cars.uchicago.edu](mailto:newville@cars.uchicago.edu)>. Many important contributions to the library have come from Angus Gratton while at the Australian National University, and from Daron Chabot and Ken Lauer. Several other people have provided valuable additions, suggestions, pull requests or bug reports, which has greatly improved the quality of the library: Robbie Clarken, Daniel Allen, Michael Abbott, Thomas Caswell, Alain Peteut, Steven Hartmann, Rokvintar, Georg Brandl, Niklas Claesson, Jon Brinkmann, Marco Cammarata, Craig Haskins, David Vine, Pete Jemian, Andrew Johnson, Janko Kolar, Irina Kosheleva, Tim Mooney, Eric Norum, Mark Rivers, Friedrich Schotte, Mark Vigder, Steve Wasserman, and Glen Wright.

## PYEPICS OVERVIEW

The python *epics* package provides several function, modules, and classes to interact with EPICS Channel Access. The simplest approach uses the functions `caget()`, `caput()`, and `cainfo()` within the top-level *epics* module to get and put values of Epics Process Variables. These functions are similar to the standard command line utilities and the EZCA library interface, and are described in more detail below.

To use the *epics* package, import it with:

```
import epics
```

The main components of this module include

- functions `caget()`, `caput()`, `cainfo()` and others described in more detail below.
- a `ca` module, providing the low-level library as a set of functions, meant to be very close to the C library for Channel Access.
- a `PV` object, representing a Process Variable (PV) and giving a higher-level interface to Epics Channel Access.
- a `Device` object: a collection of related PVs, similar to an Epics Record.
- a `Motor` object: a `Device` that represents an Epics Motor.
- an `Alarm` object, which can be used to set up notifications when a PV's values goes outside an acceptable bounds.
- an `epics.wx` module that provides wxPython classes designed for use with Epics PVs.

If you're looking to write quick scripts or a simple introduction to using Channel Access, the `caget()` and `caput()` functions are probably where you want to start.

If you're building larger scripts and programs, using `PV` objects provided by the *pv* module is recommended. The `PV` class provides a Process Variable (PV) object that has both methods (including `get()` and `put()`) to read and change the PV, and attributes that are kept automatically synchronized with the remote channel. For larger applications where you find yourself working with sets of related PVs, you may find the `Device` class helpful.

The lowest-level CA functionality is exposed in the `ca` module, and companion `dbf` module. While not necessary recommended for most use cases, this module does provide a fairly complete wrapping of the basic EPICS CA library. For people who have used CA from C or other languages, this module should be familiar and seem quite usable, if a little more verbose and C-like than using `PV` objects.

In addition, the *epics* package contains more specialized modules for alarms, Epics motors, and several other *devices* (collections of PVs), and a set of wxPython widget classes for using EPICS PVs with wxPython.

The *epics* package is supported and well-tested on Linux, Mac OS X, and Windows with Python versions 2.7, and 3.5 and above.

## 2.1 Quick Start

Whether you're familiar with Epics Channel Access or not, start here. You'll then be able to use Python's introspection tools and built-in help system, and the rest of this document as a reference and for detailed discussions.

### 2.1.1 Procedural Approach: `caget()`, `caput()`

To get values from PVs, you can use the `caget()` function:

```
>>> from epics import caget, caput, cainfo
>>> m1 = caget('XXX:m1.VAL')
>>> print(m1)
1.2001
```

To set PV values, you can use the `caput()` function:

```
>>> caput('XXX:m1.VAL', 1.90)
>>> print(caget('XXX:m1.VAL'))
1.9000
```

To see more detailed information about a PV, use the `cainfo()` function:

```
>>> cainfo('XXX:m1.VAL')
== XXX:m1.VAL (time_double) ==
  value      = 1.9
  char_value = '1.9000'
  count      = 1
  nelm       = 1
  type       = time_double
  units      = mm
  precision  = 4
  host       = somehost.aps.anl.gov:5064
  access     = read/write
  status     = 0
  severity   = 0
  timestamp  = 1513352940.872 (2017-12-15 09:49:00.87179)
  posixseconds = 1513352940.0
  nanoseconds= 871788105
  upper_ctrl_limit = 50.0
  lower_ctrl_limit = -48.0
  upper_disp_limit = 50.0
  lower_disp_limit = -48.0
  upper_alarm_limit = 0.0
  lower_alarm_limit = 0.0
  upper_warning_limit = 0.0
  lower_warning_limit = 0.0
  PV is internally monitored, with 0 user-defined callbacks:
=====
```

The simplicity and clarity of these functions make them ideal for many cases.

### 2.1.2 Creating and Using PV Objects

If you are repeatedly referencing the same PV, you may find it more convenient to create a PV object and use it in a more object-oriented manner.

```
>>> from epics import PV
>>> pv1 = PV('XXX:m1.VAL')
```

PV objects have several methods and attributes. The most important methods are `get()` and `put()` to receive and send the PV's value, and the `value` attribute which stores the current value. In analogy to the `caget()` and `caput()` examples above, the value of a PV can be fetched either with

```
>>> print(pv1.get())
1.90
```

or

```
>>> print(pv1.value)
1.90
```

To set a PV's value, you can either use

```
>>> pv1.put(1.9)
```

or assign the value attribute

```
>>> pv1.value = 1.9
```

You can see a few of the most important properties of a PV by simply printing it:

```
>>> print(pv1)
<PV 'XXX:m1.VAL', count=1, type=time_double, access=read/write>
```

Even more complete information can be seen by printing the PVs `info` attribute:

```
>>> print(pv1.info)
== XXX:m1.VAL (time_double) ==
value      = 1.9
char_value = '1.9000'
count      = 1
nelm       = 1
type       = time_double
units      = mm
precision  = 4
host       = somehost.aps.anl.gov:5064
access     = read/write
status     = 0
severity   = 0
timestamp  = 1513352940.872 (2017-12-15 09:49:00.87179)
posixseconds = 1513352940.0
nanoseconds= 871788105
upper_ctrl_limit = 50.0
lower_ctrl_limit = -48.0
upper_disp_limit = 50.0
lower_disp_limit = -48.0
upper_alarm_limit = 0.0
lower_alarm_limit = 0.0
upper_warning_limit = 0.0
lower_warning_limit = 0.0
PV is internally monitored, with 0 user-defined callbacks:
=====
```

PV objects have several additional methods related to monitoring changes to the PV values or connection state including user-defined functions to be run when the value changes. There are also attributes associated with a PVs *Control Attributes*, like those shown above in the `info` attribute. Further details are at [PV: Epics Process Variables](#).

## 2.2 Functions defined in `epics`: `caget()`, `caput()`, etc.

As shown above, the simplest interface to EPICS Channel Access is found with the functions `caget()`, `caput()`, and `cainfo()`. There are also functions `camonitor()` and `camonitor_clear()` to setup and clear a simple monitoring of changes to a PV. These functions all take the name of an Epics Process Variable (PV) as the first argument and are similar to the EPICS command line utilities of the same names.

Internally, these functions keeps a cache of connected PV (in this case, using *PV* objects) so that repeated use of a PV name will not actually result in a new connection to the PV – see [The `get\_pv\(\)` function and `\_PVcache` cache of PVs](#) for more details. Thus, though the functionality is simple and straightforward, the performance of using these simple function can be quite good. In addition, there are also functions `caget_many()` and `caput_many()` for getting and putting values for multiple PVs at a time.

### 2.2.1 `caget()`

```
epics.caget(pvname[, as_string=False[, count=None[, as_numpy=True[, timeout=None[,  
                use_monitor=False]]]])
```

retrieves and returns the value of the named PV.

#### Parameters

- **pvname** – name of Epics Process Variable.
- **as\_string** (True/False) – whether to return string representation of the PV value.
- **count** (integer or None) – number of elements to return for array data.
- **as\_numpy** (True/False) – whether to return the Numerical Python representation for array data.
- **timeout** (float or None) – maximum time to wait (in seconds) for value before returning None.
- **use\_monitor** (True/False) – whether to rely on monitor callbacks or explicitly get value now.

The `count` and `as_numpy` options apply only to array or waveform data. The default behavior is to return the full data array and convert to a numpy array if available. The `count` option can be used to explicitly limit the number of array elements returned, and `as_numpy` can turn on or off conversion to a numpy array.

The `timeout` argument sets the maximum time to wait for a value to be fetched over the network. If the timeout is exceeded, `caget()` will return `None`. This might imply that the PV is not actually available, but it might also mean that the data is large or network slow enough that the data just hasn't been received yet, but may show up later.

The `use_monitor` argument sets whether to rely on the monitors from the underlying PV. The default is `False`, so that each `caget()` will explicitly ask the value to be sent instead of relying on the automatic monitoring normally used for persistent PVs. This makes `caget()` act more like command-line tools, and slightly less efficient than creating a PV and getting values with it. If performance is a concern, using monitors is recommended. For more details on making `caget()` more efficient, see [Automatic Monitoring of a PV](#) and [The wait and timeout options for `get\(\)`, `ca.get\_complete\(\)`](#).

The `as_string` argument tells the function to return the **string representation** of the value. The details of the string representation depends on the variable type of the PV. For integer (short or long) and string PVs, the string representation is pretty easy: 0 will become '0', for example. For float and doubles, the internal precision of the PV is used to format the string value. For enum types, the name of the enum state is returned:

```
>>> from epics import caget, caput, cainfo
>>> print(caget('XXX:m1.VAL'))      # A double PV
0.10000000000000001

>>> print(caget('XXX:m1.DESC'))     # A string PV
'Motor 1'

>>> print(caget('XXX:m1.FOFF'))     # An Enum PV
1
```

Adding the `as_string=True` argument always results in string being returned, with the conversion method depending on the data type, for example using the precision field of a double PV to determine how to format the string, or using the names of the enumeration states for an enum PV:

```
>>> print(caget('XXX:m1.VAL', as_string=True))
'0.10000'

>>> print(caget('XXX:m1.FOFF', as_string=True))
'Frozen'
```

For integer or double array data from Epics waveform records, the regular value will be a numpy array (or a python list if numpy is not installed). The string representation will be something like '<array size=128, type=int>' depending on the size and type of the waveform. An array of doubles might be:

```
>>> print(caget('XXX:scan1.P1PA'))  # A Double Waveform
array([-0.08      , -0.078      , -0.076      , ...,
        1.99599814, 1.99799919,  2.         ])

>>> print(caget('XXX:scan1.P1PA', as_string=True))
'<array size=2000, type=time_double>'
```

As an important special case CHAR waveform records will be turned to Python strings when `as_string` is True. This is useful to work around the low limit of the maximum length (40 characters!) of EPICS strings which has inspired the fairly common usage of CHAR waveforms to represent longer strings:

```
>>> epics.caget('MyAD:TIFFF1:FilePath')
array([ 47, 104, 111, 109, 101,  47, 101, 112, 105,  99, 115,  47, 115,
        99, 114,  97, 116,  99, 104,  47,   0], dtype=uint8)
>>> epics.caget('MyAD:TIFFF1:FilePath', as_string=True)
'/home/epics/scratch/'
```

Of course, character waveforms are not always used for long strings, but can also hold byte array data, such as comes from some detectors and devices.

## 2.2.2 caput ()

`epics.caput (pvname, value[, wait=False[, timeout=60]])`  
set the value of the named PV.

### Parameters

- **pvname** – name of Epics Process Variable

- **value** – value to send.
- **wait** (True/False) – whether to wait until the processing has completed.
- **timeout** (*double*) – how long to wait (in seconds) for put to complete before giving up.

**Return type** integer

The optional *wait* argument tells the function to wait until the processing completes. This can be useful for PVs which take significant time to complete, either because it causes a physical device (motor, valve, etc) to move or because it triggers a complex calculation or data processing sequence. The *timeout* argument gives the maximum time to wait, in seconds. The function will return after this (approximate) time even if the *caput()* has not completed.

This function returns 1 on success, and a negative number if the timeout has been exceeded.

```
>>> from epics import caget, caput, cainfo
>>> caput('XXX:m1.VAL', 2.30)
1
>>> caput('XXX:m1.VAL', -2.30, wait=True)
... waits a few seconds ...
1
```

### 2.2.3 cainfo()

`epics.cainfo(pvname[, print_out=True])`

prints (or returns as a string) an informational paragraph about the PV, including Control Settings.

#### Parameters

- **pvname** – name of Epics Process Variable
- **print\_out** – whether to write results to standard output (otherwise the string is returned).

### 2.2.4 camonitor()

`epics.camonitor(pvname[, writer=None[, callback=None]])`

This sets a monitor on the named PV, which will cause *something* to be done each time the value changes. By default the PV name, time, and value will be printed out (to standard output) when the value changes, but the action that actually happens can be customized.

#### Parameters

- **pvname** – name of Epics Process Variable
- **writer** (None or a callable function that takes a string argument.) – where to write results to standard output .
- **callback** (None or callable function) – user-supplied function to receive result

One can specify any function that can take a string as *writer*, such as the `write()` method of an open file that has been open for writing. If left as None, messages of changes will be sent to `sys.stdout.write()`. For more complete control, one can specify a *callback* function to be called on each change event. This callback should take keyword arguments for *pvname*, *value*, and *char\_value*. See [User-supplied Callback functions](#) for information on writing callback functions for *camonitor()*.

```
>>> from epics import camonitor
>>> camonitor('XXX.m1.VAL')
XXX.m1.VAL 2010-08-01 10:34:15.822452 1.3
```

(continues on next page)



(continued from previous page)

```
XXX.m1.VAL 2010-08-01 10:34:16.823233 1.2
XXX.m1.VAL 2010-08-01 10:34:17.823233 1.1
XXX.m1.VAL 2010-08-01 10:34:18.823233 1.0
```

### 2.2.5 camonitor\_clear()

`epics.camonitor_clear(pvname)`  
clears a monitor set on the named PV by `camonitor()`.

**Parameters** `pvname` – name of Epics Process Variable

This simple example monitors a PV with `camonitor()` for while, with changes being saved to a log file. After a while, the monitor is cleared and the log file is inspected:

```
>>> import epics
>>> fh = open('PV1.log', 'w')
>>> epics.camonitor('XXX:DMM1Ch2_calc.VAL', writer=fh.write)
>>> .... wait for changes ...
>>> epics.camonitor_clear('XXX:DMM1Ch2_calc.VAL')
>>> fh.close()
>>> fh = open('PV1.log', 'r')
>>> for i in fh.readlines(): print(i[:-1])
XXX:DMM1Ch2_calc.VAL 2010-03-24 11:56:40.536946 -183.5035
XXX:DMM1Ch2_calc.VAL 2010-03-24 11:56:41.536757 -183.6716
XXX:DMM1Ch2_calc.VAL 2010-03-24 11:56:42.535568 -183.5112
XXX:DMM1Ch2_calc.VAL 2010-03-24 11:56:43.535379 -183.5466
XXX:DMM1Ch2_calc.VAL 2010-03-24 11:56:44.535191 -183.4890
XXX:DMM1Ch2_calc.VAL 2010-03-24 11:56:45.535001 -183.5066
XXX:DMM1Ch2_calc.VAL 2010-03-24 11:56:46.535813 -183.5085
XXX:DMM1Ch2_calc.VAL 2010-03-24 11:56:47.536623 -183.5223
XXX:DMM1Ch2_calc.VAL 2010-03-24 11:56:48.536434 -183.6832
```

### 2.2.6 caget\_many()

`epics.caget_many(pvlist[, as_string=False[, count=None[, as_numpy=True[, timeout=None]]]])`  
get a list of PVs as quickly as possible. Returns a list of values for each PV in the list. Unlike `caget()`, this method does not use automatic monitoring (see *Automatic Monitoring of a PV*).

**Parameters**

- **pvlist** (list or tuple of str) – A list of process variable names.
- **as\_string** (True/False) – whether to return string representation of the PV values.
- **count** (integer or None) – number of elements to return for array data.
- **as\_numpy** (True/False) – whether to return the Numerical Python representation for array data.
- **timeout** (float or None) – maximum time to wait (in seconds) for value before returning None.

For detailed information about the arguments, see the documentation for `caget()`. Also see *Strategies for connecting to a large number of PVs* for more discussion.

### 2.2.7 `caput_many()`

`epics.caput_many(pvlist, values[, wait=False[, connection_timeout=None[, put_timeout=60]]])`  
put values to a list of PVs as quickly as possible. Returns a list of ints for each PV in the list: 1 if the put was successful, -1 if it timed out. Unlike `caput()`, this method does not use automatic monitoring (see [Automatic Monitoring of a PV](#)).

#### Parameters

- **pvlist** (list or tuple of str) – A list of process variable names.
- **values** (list or tuple) – values to put to each PV.
- **wait** – if 'each', `caput_many()` will wait for each PV to process before starting the next. If 'all', `caput_many()` will issue puts for all PVs immediately, then wait for all of them to complete. If any other value, `caput_many()` will not wait for put processing to complete.
- **connection\_timeout** (float or None) – maximum time to wait (in seconds) for a connection to be established to each PV.
- **put\_timeout** (float or None) – maximum time to wait (in seconds) for processing to complete for each PV (if wait is 'each'), or for processing to complete for all PVs (if wait is 'all').

Because connections to channels normally connect very quickly (less than a second), but processing a put may take a significant amount of time (due to a physical device moving, or due to complex calculations or data processing sequences), a separate timeout duration can be specified for connections and processing puts.

## 2.3 Motivation and design concepts

There are other Python wrappings for Epics Channel Access, so it is useful to outline the design goals for PyEpics. The motivations for PyEpics3 included:

- 1) providing both low-level (C-like) and higher-level access (Python objects) to the EPICS Channel Access protocol.
- 2) supporting as many features of Epics 3.14 as possible, including preemptive callbacks and thread support.
- 3) easy support and distribution for Windows and Unix-like systems.
- 4) support for both Python 2 and Python 3.
- 5) using Python's ctypes library.

The idea is to provide both a low-level interface to Epics Channel Access (CA) that closely resembled the C interface to CA, and to build higher level functionality and complex objects on top of that foundation. The Python ctypes library conveniently allows such direct wrapping of a shared libraries, and requires no compiled code for the bridge between Python and the CA library. This makes it very easy to wrap essentially all of CA from Python code, and support multiple platforms. Since ctypes loads a shared object library at runtime, the underlying CA library can be upgraded without having to re-build the Python wrapper. The ctypes interface provides the most reliable thread-safety available, as each call to the underlying C library is automatically made thread-aware without explicit code. Finally, by avoiding the C API altogether, supporting both Python2 and Python3 is greatly simplified.

## 2.4 Status and to-do list

The PyEpics package is actively maintained, but the core library is reasonably stable and ready to use in production code. Features are being added slowly, and testing is integrated into development so that the chance of introducing bugs into existing codes is minimized. The package is targeted and tested to work with Python 2.7 and Python 3 simultaneously.

There are several desired features are left unfinished or could use improvement:

- add more Epics Devices, including low-level epics records and more suport for Area Detectors.
- build and improve applications using PyEpics, especially for common data acquisition needs.
- improve and extend the use of PyQt widgets with PyEpics.

If you are interested in working on any of these or other topics, please contact the authors.



## PV: EPICS PROCESS VARIABLES

The `pv` module provides a higher-level class `pv.PV`, which creates a *PV* object for an EPICS Process Variable. A *PV* object has both methods and attributes for accessing it's properties.

### 3.1 The `PV` class

```
class pv.PV(pvname[, callback=None[, form='time'[, verbose=False[, auto_monitor=None[,  
count=None[, connection_callback=None[, connection_timeout=None[, ac-  
cess_callback=None ]]]]]]]])  
create a PV object for a named Epics Process Variable.
```

#### Parameters

- **pvname** – name of Epics Process Variable
- **callback** (*callable, tuple, list or None*) – user-defined callback function on changes to PV value or state.
- **form** (*string, one of ('native', 'ctrl', or 'time')*) – which epics *data type* to use: the 'native', 'time', or the 'ctrl' (Control) variant.
- **verbose** (True/False) – whether to print out debugging messages
- **auto\_monitor** (None, True, False, or bitmask (see [Automatic Monitoring of a PV](#))) – whether to automatically monitor the PV for changes.
- **count** (*int*) – number of data elements to return by default (see [here](#))
- **connection\_callback** (*callable or None*) – user-defined function called on changes to PV connection status.
- **connection\_timeout** (*float or None*) – time (in seconds) to wait for connection before giving up
- **access\_callback** (*callable or None*) – user-defined function called on changes to PV access rights

Once created, a PV should (barring any network issues) automatically connect and be ready to use.

```
>>> from epics import PV  
>>> p = PV('XX:m1.VAL')  
>>> print p.get()  
>>> print p.count, p.type
```

The *pvname* is required, and is the name of an existing Process Variable.

The *callback* parameter specifies one or more python methods to be called on changes, as discussed in more detail at [User-supplied Callback functions](#)

The *connection\_callback* parameter specifies a python method to be called on changes to the connection status of the PV (that is, when it connects or disconnects). This is discussed in more detail at [User-supplied Connection Callback functions](#)

The *form* parameter specifies which of the three variants ‘native’, ‘ctrl’ (Control) or ‘time’ (the default) to use for the PV. The ‘native’ form returns just the value, the ‘time’ form includes the timestamp from the server the PV lives on, as well as status information. The control form includes several additional fields such as limits to the PV, which can be useful in some cases. Also note that the additional ‘ctrl’ value fields (see the [Table of Control Attributes](#)) can be obtained with `get_ctrlvars()` even for PVs of ‘native’ or ‘time’ form.

The *auto\_monitor* parameter specifies whether the PV should be automatically monitored. See [Automatic Monitoring of a PV](#) for a detailed description of this.

The *verbose* parameter specifies more verbose output on changes, and is intended for debugging purposes.

The *access\_callback* parameter specifies a python method to be called on changes to the access rights of the PV (read/write access changes). This is discussed in more detail [here](#).

### 3.1.1 methods

A PV has several methods for getting and setting its value and defining callbacks to be executed when the PV changes.

```
pv.get([count=None[, as_string=False[, as_numpy=True[, timeout=None[, use_monitor=True[,  
    with_ctrlvars=False]]]]]])  
get and return the current value of the PV
```

#### Parameters

- **count** (integer or None) – maximum number of array elements to return
- **as\_string** (True/False) – whether to return the string representation of the value.
- **as\_numpy** – whether to try to return a numpy array where appropriate.
- **timeout** (float or None) – maximum time to wait for data before returning None.
- **use\_monitor** (True/False) – whether to rely on monitor callbacks or explicitly get value now.

see [String representation for a PV](#) for details on how the string representation is determined.

With the *as\_numpy* option, an array PV (that is, a PV whose value has more than one element) will be returned as a numpy array, provided the numpy module is available. See [Strategies for working with large arrays](#) for a discussion of strategies for how to best deal with very large arrays.

The *use\_monitor* option controls whether the most recent value from the automatic monitoring will be used or whether the value will be explicitly asked for right now. Usually, you can rely on a PVs value being kept up to date, and so the default here is `True`. But, since network traffic is not instantaneous and hard to predict, the value returned with *use\_monitor=True* may be out-of-date.

The *timeout* sets how long (in seconds) to wait for the value to be sent. This only applies with *use\_monitor=False*, or if the PV is not automatically monitored. Otherwise, the most recently received value will be sent immediately.

The *with\_ctrlvars* option requests DBR\_CTRL data, including control limits, precision, and so on, in addition to the value normally returned. This metadata will be available by accessing various attributes such as `lower_ctrl_limit`.

See *Automatic Monitoring of a PV* for more on monitoring PVs and *The wait and timeout options for get()*, *ca.get\_complete()* for more details on what happens when a `pv.get()` times out.

```
pv.get_with_metadata([form=None[, count=None[, as_string=False[, as_numpy=True[, time-
out=None[, use_monitor=True[, with_ctrlvars=False]]]]]])
```

Returns a dictionary of the current value and associated metadata

#### Parameters

- **form** ({'native', 'time', 'ctrl', None}) – EPICS *data type* to request: the 'native', or the 'ctrl' (Control) or 'time' variant. Defaults to the PV instance attribute `form`.
- **count** (integer or None) – maximum number of array elements to return
- **as\_string** (True/False) – whether to return the string representation of the value.
- **as\_numpy** – whether to try to return a numpy array where appropriate.
- **timeout** (float or None) – maximum time to wait for data before returning None.
- **use\_monitor** (True/False) – whether to rely on monitor callbacks or explicitly get value now.

See `PV.get`, above, for further notes on each of these parameters.

Each request to EPICS can optionally contain additional metadata associated with the value. While `PV.get` updates the PV instance with any metadata, `get_with_metadata` will return the requested metadata and value in a dictionary.

The exception is when the PV is set to auto-monitor and the `use_monitor` parameter here is set. This means that both the value and metadata will use the cached values instead of making a new request. Because of this, the metadata and value returned here will be a full dictionary of all known metadata for the PV instance.

```
pv.put(value[, wait=False[, timeout=30.0[, use_complete=False[, callback=None[, callback_data=None
]]]])
```

set the PV value, optionally waiting to return until processing has completed, or setting the `put_complete` to indicate complete-ness.

#### Parameters

- **value** – value to set PV
- **wait** (True/False) – whether to wait for processing to complete (or time-out) before returning.
- **timeout** (*float*) – maximum time to wait for processing to complete before returning anyway.
- **use\_complete** (True/False) – whether to use a built-in callback to set `put_complete`.
- **callback** (None or a valid python function) – user-supplied function to run when processing has completed.
- **callback\_data** – extra data to pass on to a user-supplied callback function.

The `wait` and `callback` arguments, as well as the 'use\_complete' / `put_complete` attribute give a few options for knowing that a `put()` has completed. See *Put with wait, put callbacks, and put\_complete* for more details.

```
pv.get_ctrlvars()
```

returns a dictionary of the **control values** for the PV. This dictionary may have many members, depending on the data type of PV. See the *Table of Control Attributes* for details.

`pv.get_timevars()`

returns a dictionary of the **time values** for the PV, which include *status*, *severity*, and the *timestamp* from the CA server.

`pv.poll([evt=1.e-4[, iot=1.0]])`

poll for changes. This simply calls `epics.ca.poll()`

**Parameters**

- **evt** (*float*) – time to pass to `epics.ca.pend_event()`
- **iot** (*float*) – time to pass to `epics.ca.pend_io()`

`pv.connect([timeout=None])`

this explicitly connects a PV, and returns whether or not it has successfully connected. It is probably not that useful, as connection should happen automatically. See `wait_for_connection()`.

**Parameters** **timeout** (*float*) – maximum connection time, passed to `epics.ca.connect_channel()`

**Return type** True/False

if timeout is None, the PVs connection\_timeout parameter will be used. If that is also None, `episc.ca.DEFAULT_CONNECTION_TIMEOUT` will be used.

`pv.wait_for_connection([timeout=None])`

this waits until a PV is connected, or has timed-out waiting for a connection. Returns whether the connection has occurred.

**Parameters** **timeout** (*float*) – maximum connection time.

**Return type** True/False

if timeout is None, the PVs connection\_timeout parameter will be used. If that is also None, `epics.ca.DEFAULT_CONNECTION_TIMEOUT` will be used.

`pv.disconnect()`

disconnect a PV, clearing all callbacks.

`pv.reconnect()`

reconnect (or try to) a disconnected PV.

`pv.clear_auto_monitor()`

turn off automatic monitoring of a PV. Note that this will suspend all event callbacks on a PV at the CA level by calling `epics.ca.clear_subscription()`, but will not clear the list of PVs callbacks. This means that doing `reconnect()` will resume event processing including any callbacks or the PV.

`pv.add_callback(callback=None[, index=None[, with_ctrlvars=True[, **kw]])`

adds a user-defined callback routine to be run on each change event for this PV. Returns the integer *index* for the callback.

**Parameters**

- **callback** (None or callable) – user-supplied function to run when PV changes.
- **index** (None (integer will be produced) or immutable) – identifying key for this callback
- **with\_ctrlvars** – whether to (try to) make sure that accurate `control` values will be sent to the callback.
- **kw** – additional keyword/value arguments to pass to each execution of the callback.

**Return type** integer



Note that multiple callbacks can be defined, each having its own index (a dictionary key, typically an integer). When a PV changes, all the defined callbacks will be executed. They will be called in order (by sorting the keys of the `callbacks` dictionary)

See also: `callbacks` attribute, *User-supplied Callback functions*

`pv.remove_callback(index=None)`

remove a user-defined callback routine using supplied

**Parameters** `index` (None or integer) – index of user-supplied function, as returned by `add_callback()`, and also to key for this callback in the `callbacks` dictionary.

**Return type** integer

If only one callback is defined an `index="None"`, this will clear the only defined callback.

See also: `callbacks` attribute, *User-supplied Callback functions*

`pv.clear_callbacks()`

remove all user-defined callback routine.

`pv.run_callbacks()`

execute all user-defined callbacks right now, even if the PV has not changed. Useful for debugging!

See also: `callbacks` attribute, *User-supplied Callback functions*

`pv.run_callback(index)`

execute a particular user-defined callback right now, even if the PV has not changed. Useful for debugging!

See also: `callbacks` attribute, *User-supplied Callback functions*

`pv.force_read_access_rights()`

force a read of the access rights for a PV. Normally, a PV will have access rights determined automatically and subscribe to changes in access rights. But sometimes (especially 64-bit Windows), the automatically reported values are wrong. This methods will explicitly read the access rights.

### 3.1.2 attributes

A PV object has many attributes, each associated with some property of the underlying PV: its *value*, *host*, *count*, and so on. For properties that can change, the PV attribute will hold the latest value for the corresponding property. Most attributes are **read-only**, and cannot be assigned to. The exception to this rule is the *value* attribute.

`pv.value`

The current value of the PV.

**Note:** The *value* attribute can be assigned to. When read, the latest value will be returned, even if that means a `get()` needs to be called.

Assigning to *value* is equivalent to setting the value with the `put()` method.

```
>>> from epics import PV
>>> p1 = PV('xxx.VAL')
>>> print p1.value
1.00
>>> p1.value = 2.00
```

`pv.char_value`

The string representation of the string, as described in `get()`.

`pv.status`

The PV status, which will be 1 for a Normal, connected PV.

**pv.type**

string describing data type of PV, such as *double*, *float*, *enum*, *string*, *int*, *long*, *char*, or one of the *ctrl* or *time* variants of these, which will be named *ctrl\_double*, *time\_enum*, and so on. See the [Table of DBR Types](#)

**pv.ftype**

The integer value (from the underlying C library) indicating the PV data type according to [Table of DBR Types](#)

**pv.host**

string of host machine provide this PV.

**pv.count**

number of data elements in a PV. 1 except for waveform PVs, where it gives the number of elements in the waveform. For recent versions of Epics Base (3.14.11 and later?), this gives the *.NORD* field, which gives the number of elements last put into the PV and which may be less than the maximum number allowed (see *nelm* below).

**pv.nelm**

number of data elements in a PV. 1 except for waveform PVs where it gives the maximum number of elements in the waveform. For recent versions of Epics Base (3.14.11 and later?), this gives the *.NELM* parameter. See also the *count* attribute above.

**pv.read\_access**

Boolean (True/False) for whether PV is readable

**pv.write\_access**

Boolean (True/False) for whether PV is writable

**pv.access**

string describing read/write access. One of 'read/write', 'read-only', 'write-only', 'no access'.

**pv.severity**

severity value of PV. Usually 0 for PVs that are not in an alarm condition.

**pv.timestamp**

floating point timestamp (relative to the POSIX time origin, not the EPICS time origin) of the last event seen for this PV. Note that this will contain the timestamp from the Epics server if the PV object was created with the *form='time'* option. Otherwise, the timestamp will be set to time according to the client, indicating when the data arrive from the server.

**pv.posixseconds**

Integer number of seconds (relative to the POSIX time origin, not the EPICS time origin) of the last event seen for this PV. This will be set only if the PV object was created with the *form='time'* option, and will reflect the timestamp from the server. Otherwise, this value will be 0 which can be used to signal that the *timestamp* attribute is from the client.

**pv.nanoseconds**

Integer number of nanoseconds for the last event seen for this PV. This will be set only if the PV object was created with the *form='time'* option, and will give higher time resolution than the *timestamp* attribute.

**pv.precision**

number of decimal places of precision to use for float and double PVs

**pv.units**

string of engineering units for PV

**pv.enum\_strs**

a list of strings for the enumeration states of this PV (for enum PVs)

**pv.info**

a string paragraph (ie, including newlines) showing much of the information about the PV.

**pv.upper\_disp\_limit**

```
pv.lower_disp_limit
pv.upper_alarm_limit
pv.lower_alarm_limit
pv.lower_warning_limit
pv.upper_warning_limit
pv.upper_ctrl_limit
pv.lower_ctrl_limit
```

These are all the various kinds of limits for a PV.

```
pv.put_complete
```

a Boolean (True/False) value for whether the most recent `put()` has completed.

```
pv.callbacks
```

a dictionary of currently defined callbacks, to be run on changes to the PV. This dictionary has integer keys (generally in increasing order of when they were defined) which sets which order for executing the callbacks. The values of this dictionary are tuples of (*callback*, *keyword\_arguments*).

**Note:** The `callbacks` attribute can be assigned to or manipulated directly. This is not recommended. Use the methods `add_callback()`, `remove_callback()`, and `clear_callbacks()` instead of altering this dictionary directly.

```
pv.connection_callbacks
```

a simple list of connection callbacks: functions to be run when the connection status of the PV changes. See *User-supplied Connection Callback functions* for more details.

```
pv.access_callbacks
```

an list of access callbacks: functions to be run when the access rights of the PV changes. See *User-supplied Access Rights Callback functions* for more details.

## 3.2 String representation for a PV

The string representation for a PV, as returned either with the *as\_string* argument to `epics.ca.get()` or from the *char\_value* attribute (they are equivalent) needs some further explanation.

The value of the string representation (hereafter, the *char\_value*), will depend on the native type and count of a PV. *Table of String Representations*

Table of String Representations: How raw data *value* is mapped to *char\_value* for different native data types.

| <i>data types</i> | <i>count</i> | <i>char_value</i>                   |
|-------------------|--------------|-------------------------------------|
| string            | 1            | = value                             |
| char              | 1            | = value                             |
| short             | 1            | = str(value)                        |
| long              | 1            | = str(value)                        |
| enum              | 1            | = enum_str[value]                   |
| double            | 1            | = ("%%.%if" % (precision)) % value  |
| float             | 1            | = ("%%.%if" % (precision)) % value  |
| char              | > 1          | = long string from bytes in array   |
| all others        | > 1          | = <array size=*count*, type=*type*> |

For double/float values with large exponents, the formatting will be (“%%.%%ig” % (precision)) % value. For character waveforms (char data with count > 1), the `char_value` will be set according to:

```
>>> firstnull = val.index(0)
>>> if firstnull == -1: firstnull= len(val)
>>> char_value = ''.join([chr(i) for i in val[:firstnull]).rstrip()
```

### 3.3 Automatic Monitoring of a PV

When creating a PV, the `auto_monitor` parameter specifies whether the PV should be automatically monitored or not. Automatic monitoring means that an internal callback will be registered for changes. Any callbacks defined by the user will be called by this internal callback when changes occur.

For most scalar-value PVs, this automatic monitoring is desirable, as the PV will see all changes (and run callbacks) without any additional interaction from the user. The PV’s value will always be up-to-date and no unnecessary network traffic is needed.

Possible values for `auto_monitor` are:

**False** For some PVs, especially those that change much more rapidly than you care about or those that contain large arrays as values, `auto_monitoring` can add network traffic that you don’t need. For these, you may wish to create your PVs with `auto_monitor=False`. When you do this, you will need to make calls to `get()` to explicitly get the latest value.

**None** The default value for `auto_monitor` is `None`, and is set to `True` if the element count for the PV is smaller than `epics.ca.AUTOMONITOR_MAXLENGTH` (default of 65536). To suppress monitoring of PVs with fewer array values, you will have to explicitly turn `auto_monitor` to `False`. For waveform arrays with more elements, automatic monitoring will not be done unless you explicitly set `auto_monitor=True`, or to an explicit mask. See *Strategies for working with large arrays* for more details.

**True** When `auto_monitor` is set to `True`, the value will be monitored using the default subscription mask set at `epics.ca.DEFAULT_SUBSCRIPTION_MASK`.

This mask determines which kinds of changes cause the PV to update. By default, the subscription updates when the PV value changes by more than the monitor deadband, or when the PV alarm status changes. This behavior is the same as the default in EPICS’ `camonitor` tool.

**Mask** It is also possible to request an explicit type of CA subscription by setting `auto_monitor` to a numeric subscription mask made up of `dbr.DBE_ALARM`, `dbr.DBE_LOG` and/or `dbr.DBE_VALUE`. This mask will be passed directly to `epics.ca.create_subscription()`. An example would be:

```
pv1 = PV('AAA', auto_monitor=dbr.DBE_VALUE)
pv2 = PV('BBB', auto_monitor=dbr.DBE_VALUE|dbr.DBE_ALARM)
pv3 = PV('CCC', auto_monitor=dbr.DBE_VALUE|dbr.DBE_ALARM|dbr.DBE_LOG)
```

which will generate callbacks for `pv1` only when the value of ‘AAA’ changes, while `pv2` will receive callbacks if the value or alarm state of ‘BBB’ changes, and `pv3` will receive callbacks for all changes to ‘CCC’. Note that these `dbr.DBE_****` constants are ORed together as a bitmask.

### 3.4 User-supplied Callback functions

This section describes user-defined functions that are called when the value of a PV changes. These callback functions are useful as they allow you to be notified of changes without having to continually ask for a PVs current value. Much of this information is similar to that in *User-supplied Callback functions* for the `ca` module, though there are some important enhancements to callbacks on `PV` objects.

You can define more than one callback function per PV to be run on value changes. These functions can be specified when creating a PV, with the *callback* argument which can take either a single callback function or a list or tuple of callback functions. After a PV has been created, you can add callback functions with *add\_callback()*, remove them with *remove\_callback()*, and explicitly run them with *run\_callback()*. Each callback has an internal unique *index* (a small integer number) that can be used for specifying which one to add, remove, and run.

When defining a callback function to be run on changes to a PV, it is important to know two things:

- 1) how your function will be called.
- 2) what is permissible to do inside your callback function.

Callback functions will be called with several keyword arguments. You should be prepared to have them passed to your function, and should always include *\*\*kw* to catch all arguments. Your callback will be sent the following keyword parameters:

- *pvname*: the name of the pv
- *value*: the latest value
- *char\_value*: string representation of value
- *count*: the number of data elements
- *ftype*: the numerical CA type indicating the data type
- *type*: the python type for the data
- *status*: the status of the PV (1 for OK)
- *precision*: number of decimal places of precision for floating point values
- *units*: string for PV units
- *severity*: PV severity
- *timestamp*: timestamp from CA server.
- *read\_access*: read access (True/False)
- *write\_access*: write access (True/False)
- *access*: string description of read- and write-access
- *host*: host machine and CA port serving PV
- *enum\_strs*: the list of enumeration strings
- *upper\_disp\_limit*: upper display limit
- *lower\_disp\_limit*: lower display limit
- *upper\_alarm\_limit*: upper alarm limit
- *lower\_alarm\_limit*: lower alarm limit
- *upper\_warning\_limit*: upper warning limit
- *lower\_warning\_limit*: lower warning limit
- *upper\_ctrl\_limit*: upper control limit
- *lower\_ctrl\_limit*: lower control limit
- *chid*: integer channel ID
- ***cb\_info*: (index, self) tuple containing callback ID and the PV object**

Some of these may not be directly applicable to all PV data types, and some values may be `None` if the control parameters have not yet been fetched with `get_ctrlvars()`.

It is important to keep in mind that the callback function will be run *inside* a CA function, and cannot reliably make any other CA calls. It is helpful to think “this all happens inside of a `pend_event()` call”, and in an epics thread that may or may not be the main thread of your program. It is advisable to keep the callback functions short and not resource-intensive. Consider strategies which use the callback only to record that a change has occurred and then act on that change later – perhaps in a separate thread, perhaps after `pend_event()` has completed.

The `cb_info` parameter supplied to the callback needs special attention, as it is the only non-Epics information passed. The `cb_info` parameter will be a tuple containing `(index, self)` where `index` is the key for the `callbacks` dictionary for the PV and `self` is PV object. A principle use of this tuple is to **remove the current callback** if an error happens, as for example in GUI code if the widget that the callback is meant to update disappears.

### 3.5 User-supplied Connection Callback functions

A *connection* callback is a user-defined function that is called when the connection status of a PV changes – that is, when a PV initially connects, disconnects or reconnects due to the process serving the PV going away, or loss of network connection. A connection callback can be specified when a PV is created, or can be added by appending to the `connection_callbacks` list. If there is more than one connection callback defined, they will all be run when the connection state changes.

A connection callback should be prepared to receive the following keyword arguments:

- `pvname`: the name of the pv
- `conn`: the connection status

where `conn` will be either `True` or `False`, specifying whether the PV is now connected. A simple example is given below.

### 3.6 User-supplied Access Rights Callback functions

An *access rights* callback is a user-defined function that is called when the access rights - read/write permissions - of a PV undergo changes. The callback will be invoked upon successful initialization and at all events that change a PV's access rights, including disconnection and reconnection events. An *access rights* callback can be specified when a PV is created, or can be added by appending to the `access_callbacks` list of the PV object. If there are multiple access rights callbacks defined for a PV, they will all be run on access rights events.

### 3.7 Put with wait, put callbacks, and put\_complete

Some EPICS records take a significant amount of time to fully process, and sometimes you want to wait until the processing completes before going on. There are a few ways to accomplish this. First, one can simply wait until the processing is done:

```
import epics
p = epics.PV('XXX')
p.put(1.0, wait=True)
print 'Done'
```

This will hang until the processing of the PV completes (motor moving, etc) before printing ‘Done’. You can also specify a maximum time to wait – a *timeout* (in seconds):

```
p.put(1.0, wait=True, timeout=30)
```

which will wait up to 30 seconds. For the pedantic, this timeout should not be used as an accurate clock – the actual wait time may be slightly longer.

A second method is to use the ‘use\_complete’ option and watch for the `put_complete` attribute to become `True` after a `put()`. This is somewhat more flexible than using `wait=True` as above, because you can more carefully control how often you look for a `put()` to complete, and what to do in the interim. A simple example would be:

```
p.put(1.0, use_complete=True)
waiting = True
while waiting:
    time.sleep(0.001)
    waiting = not p.put_complete
```

An additional advantage of this approach is that you can easily wait for multiple PVs to complete with python’s built-in `all` function, as with:

```
pvgroup = (epics.PV('XXX'), epics.PV('YYY'), epics.PV('ZZZ'))
newvals = (1.0, 2.0, 3.0)
for pv, val in zip(pvgroup, newvals):
    pv.put(val, use_complete=True)

waiting = True
while waiting:
    time.sleep(0.001)
    waiting = not all([pv.put_complete for pv in pvgroup])
print 'All puts are done!'
```

For maximum flexibility, one can all define a *put callback*, a function to be run when the `put()` has completed. This function requires a `pvname` keyword argument, but will receive no others, unless you pass in data with the `callback_data` argument (which should be dict-like) to `put()`. A simple example would be:

```
pv = epics.PV('XXX')
def onPutComplete(pvname=None, **kws):
    print 'Put done for %s' % pvname

pv.put(1.0, callback=onPutComplete)
```

## 3.8 The `get_pv()` function and `_PVcache_` cache of PVs

As mentioned in the previous chapter, a cache of PVs is maintained for each process using pyepics. When using `epics.caget()`, `epics.caput()` and so forth, or when creating a `PV` directly, the corresponding PV is kept in a global cache, held in `pv._PVcache_`.

The function `get_pv()` will retrieve the named PV from this cache, or create a new `PV` if one is not found. In long-running or complex processes, it is not unusual to access a particular PV many times, perhaps calling a function that creates a PV but only keeping that PV object for the life of the function. Using `get_pv()` instead of creating a `PV` can improve performance (the PV is already connected) and is highly recommended.

```
pv.get_pv(pvname[, form='time'[, connect=False[, timeout=5[, context=None[, **kws ]]]]])
```

retrieves a PV from `_PVcache` or creates and returns a new PV.

### Parameters

- **pvname** – name of Epics Process Variable

- **form** (*string, one of ('native', 'ctrl', or 'time')*) – which epics *data type* to use: the ‘native’, or the ‘ctrl’ (Control) or ‘time’ variant.
- **connect** (True/False) – whether to wait for the PV to connect.
- **timeout** (float or None) – maximum time to wait (in seconds) for value before returning None.
- **context** (integer or None (default)) – integer threading context.

Additional keywords are passed directly to *PV*.

`pv._PVcache_`

A cache of *PV* objects for the process.

## 3.9 Examples

Some simple examples using PVs follow.

### 3.9.1 Basic Use

The simplest approach is to simply create a PV and use its *value* attribute:

```
>>> from epics import PV
>>> p1 = PV('xxx.VAL')
>>> print p1.value
1.00
>>> p1.value = 2.00
```

The *print p1.value* line automatically fetches the current PV value. The *p1.value = 2.00* line does a *put ()* to set the value, causing any necessary processing over the network.

The above example is equivalent to

```
>>> from epics import PV
>>> p1 = PV('xxx.VAL')
>>> print p1.get()
1.00
>>> p1.put(value = 2.00)
```

To get a string representation of the value, you can use either

```
>>> print p1.get(as_string=True)
'1.000'
```

or, equivalently

```
>>> print p1.char_value
'1.000'
```

### 3.9.2 Requests including Metadata

It is also possible to get the metadata associated with a single Channel Access request using *get\_with\_metadata()*:



```

>>> from epics import PV
>>> p1 = PV('xxx.VAL', form='time')

>>> print(p1.get())
1.00

>>> p1.get_with_metadata()
{'status': 0,
 'severity': 0,
 'timestamp': 1543429156.811018,
 'posixseconds': 1543429156.0,
 'nanoseconds': 811018603,
 'value': 1.0}

>>> print(p1.get_with_metadata(form='ctrl'))
{'upper_disp_limit': 100.0,
 'lower_disp_limit': -100.0,
 'upper_alarm_limit': 0.0,
 'upper_warning_limit': 0.0,
 'lower_warning_limit': 0.0,
 'lower_alarm_limit': 0.0,
 'upper_ctrl_limit': 100.0,
 'lower_ctrl_limit': -100.0,
 'precision': 3,
 'units': 'deg',
 'status': 0,
 'severity': 0,
 'value': 1.0}

```

### 3.9.3 Example of using info and more properties examples

A PV has many attributes. This can be seen from its *info* paragraph:

```

>>> import epics
>>> p = epics.PV('13IDA:m3')
>>> print p.info
== 13IDA:m3 (native_double) ==
  value      = 0.2
  char_value = '0.200'
  count      = 1
  type       = double
  units      = mm
  precision  = 3
  host       = ioc13ida.cars.aps.anl.gov:5064
  access     = read/write
  status     = 0
  severity   = 0
  timestamp  = 1274809682.967 (2010-05-25 12:48:02.967364)
  upper_ctrl_limit = 5.49393415451
  lower_ctrl_limit = -14.5060658455
  upper_disp_limit = 5.49393415451
  lower_disp_limit = -14.5060658455
  upper_alarm_limit = 0.0
  lower_alarm_limit = 0.0
  upper_warning_limit = 0.0
  lower_warning_limit = 0.0

```

(continues on next page)

(continued from previous page)

```
PV is internally monitored, with 0 user-defined callbacks:
=====
```

The individual attributes can also be accessed as below. Many of these (the *control attributes*, see *Table of Control Attributes*) will not be filled in until either the *info* attribute is accessed or until `get_ctrlvars()` is called.

```
>>> print p.type
double
>>> print p.units, p.precision, p.lower_disp_limit
mm 3 -14.5060658455
```

### 3.9.4 Getting a string value

It is not uncommon to want a string representation of a PVs value, for example to show in a display window or to write to some report. For string PVs and integer PVs, this is a simple task. For floating point values, there is ambiguity how many significant digits to show. EPICS PVs all have a *precision* field, which sets how many digits after the decimal place should be described. In addition, for ENUM PVs, it would be desire able to get at the name of the ENUM state, not just its integer value.

To get the string representation of a PVs value, use either the *char\_value* attribute or the *as\_string=True* argument to `get()`

### 3.9.5 Example of put ()

To put a new value to a variable, either of these two approaches can be used:

```
>>> import epics
>>> p = epics.PV('XXX')
>>> p.put(1.0)
```

Or (equivalently):

```
>>> import epics
>>> p = epics.PV('XXX')
>>> p.value = 1.0
```

The *value* attribute is the only attribute that can be set.

### 3.9.6 Example of simple callback

It is often useful to get a notification of when a PV changes. In general, it would be inconvenient (and possibly inefficient) to have to continually ask if a PVs value has changed. Instead, it is better to set a *callback* function: a function to be run when the value has changed.

A simple example of this would be:

```
import epics
import time
def onChanges(pvname=None, value=None, char_value=None, **kw):
    print 'PV Changed! ', pvname, char_value, time.ctime()
```

(continues on next page)

(continued from previous page)

```

mypv = epics.PV(pvname)
mypv.add_callback(onChanges)

print 'Now wait for changes'

t0 = time.time()
while time.time() - t0 < 60.0:
    time.sleep(1.e-3)
print 'Done.'

```

This first defines a *callback function* called *onChanges()* and then simply waits for changes to happen. Note that the callback function should take keyword arguments, and generally use *\*\*kw* to catch all arguments. See [User-supplied Callback functions](#) for more details.

### 3.9.7 Example of connection callback

A connection callback:

```

#
# example of using a connection callback that will be called
# for any change in connection status

import epics
import time
import sys
from pvnames import motor1

write = sys.stdout.write
def onConnectionChange(pvname=None, conn= None, **kws):
    write('PV connection status changed: %s %s\n' % (pvname, repr(conn)))
    sys.stdout.flush()

def onValueChange(pvname=None, value=None, host=None, **kws):
    write('PV value changed: %s (%s) %s\n' % (pvname, host, repr(value)))
    sys.stdout.flush()
mypv = epics.PV(motor1,
                connection_callback= onConnectionChange,
                callback= onValueChange)

mypv.get()

write('Now waiting, watching values and connection changes:\n')
t0 = time.time()
while time.time()-t0 < 300:
    time.sleep(0.01)

```

### 3.9.8 Example of an access rights callback

Associating an access rights callback with a PV:

```

import epics
import time

```

(continues on next page)

(continued from previous page)

```
def access_rights_callback(read_access, write_access, pv=None):
    print "%s - read=%s, write=%s" % (pv.pvname, read_access, write_access)

# should immediately see the message upon connection
apv = epics.PV('pvname', access_callback=access_rights_callback)

try:
    start = time.time()
    while (time.time() - start) < 30:
        time.sleep(0.25)
except KeyboardInterrupt:
    pass
```

## CA: LOW-LEVEL CHANNEL ACCESS MODULE

The `ca` module provides a low-level wrapping of the EPICS Channel Access (CA) library, using ctypes. Most users of the `epics` module will not need to be concerned with most of the details here, and will instead use the simple procedural interface (`epics.caget()`, `epics.caput()` and so on), or use the `epics.PV` class to create and use epics PV objects.

### 4.1 General description, difference with C library

The `ca` module provides a fairly complete mapping of the C interface to the CA library while also providing a pleasant Python experience. It is expected that anyone using this module is somewhat familiar with Channel Access and knows where to consult the [Channel Access Reference Documentation](#). Here, we focus on the differences with the C interface, and assume a general understanding of what the functions are meant to do.

#### 4.1.1 Name Mangling

As a general rule, a CA function named `ca_XXX` in the C library will have the equivalent function called `XXX` in the `ca` module. This is because the intention is that one will import the `ca` module with

```
>>> from epics import ca
```

so that the Python function `ca.XXX()` will correspond to the C function `ca_XXX`. That is, the CA library called its functions `ca_XXX` because C does not have namespaces. Python does have namespaces, and so they are used.

Similar name *un-mangling* also happens with the DBR prefixes for constants, held here in the `dbr` module. Thus, the C constant `DBR_STRING` becomes `dbr.STRING` in Python.

#### 4.1.2 Other Changes and Omissions

Several functions in the C version of the CA library are not implemented in the Python module. Most of these unimplemented functions are currently seen as unnecessary for Python, though some of these could be added without much trouble if needed. See [Omissions](#) for further details.

In addition, while the CA library supports several DBR types in C, not all of these are supported in Python. Only native types and their `DBR_TIME` and `DBR_CTRL` variants are supported here. The `DBR_STS` and `DBR_GR` variants are not, as they are subsets of the `DBR_CTRL` type, and space optimization is not something you'll be striving for with Python. Several `dbr_XXX` functions are also not supported, as they appear to be needed only to be able to dynamically allocate memory, which is not necessary in Python.

## 4.2 Initialization, Finalization, and Life-cycle

The Channel Access library must be initialized before it can be used. There are 3 main reasons for this need:

1. CA requires a context model (preemptive callbacks or non-preemptive callbacks) to be specified before any actual calls can be made.
2. the ctypes interface requires that the shared library be loaded before it is used.
3. ctypes also requires that references to the library and callback functions be kept for the life-cycle of CA-using part of a program (or else they will be garbage collected).

As far as is possible, the `ca` module hides the details of the CA lifecycle from the user, so that it is not necessary to worry about explicitly initializing a Channel Access session. Instead, the library is initialized as soon as it is needed, and intervention is really only required to change default settings. The `ca` module also handles finalizing the CA session, so that core-dumps and warning messages do not happen due to CA still being ‘alive’ as a program ends.

Because some users may wish to customize the initialization and finalization process, the detailed steps will be described here. These initialization and finalization tasks are handled in the following way:

- The `libca` variable in the `ca` module holds a permanent, global reference to the CA shared object library (DLL).
- the function `initialize_libca()` is called to initialize libca. This function takes no arguments, but does use the global Boolean `PREEMPTIVE_CALLBACK` (default value of `True`) to control whether preemptive callbacks are used.
- the function `finalize_libca()` is used to finalize libca. Normally, this function is registered to be called when a program ends with `atexit.register()`. Note that this only gets called on a graceful shutdown. If the program crashes (for a non-CA related reason, for example), this finalization may not be done, and connections to Epics Variables may not be closed completely on the Channel Access server.

### `epics.ca.PREEMPTIVE_CALLBACK`

sets whether preemptive callbacks will be used. The default value is `True`. If you wish to run without preemptive callbacks this variable *MUST* be set before any other use of the CA library. With preemptive callbacks enabled, EPICS communication will not require client code to continually poll for changes. With preemptive callback disables, you will need to frequently poll epics with `pend_io()` and `func:pend_event`.

### `epics.ca.DEFAULT_CONNECTION_TIMEOUT`

sets the default *timeout* value (in seconds) for `connect_channel()`. The default value is `2.0`

### `epics.ca.AUTOMONITOR_MAXLENGTH`

sets the default array length (ie, how many elements an array has) above which automatic conversion to numpy arrays *and* automatic monitoring for PV variables is suppressed. The default value is `65536`. To be clear: waveforms with fewer elements than this value will be automatically monitored changes, and will be converted to numpy arrays (if numpy is installed). Larger waveforms will not be automatically monitored.

*Working with waveform / array data* and *Strategies for working with large arrays* for more details.

## 4.3 Using the CA module

Many general-purpose CA functions that deal with general communication and threading contexts are very close to the C library:

### `epics.ca.initialize_libca()`

Initialize the Channel Access library.

This loads the shared object library (DLL) to establish Channel Access Connection. The value of `PREEMPTIVE_CALLBACK` sets the pre-emptive callback model.

This must be called prior to any actual use of the CA library, but will be called automatically by the the `withCA()` decorator, so you should not need to call this directly from most real programs.

### Returns

`libca` [object] ca library object, used for all subsequent ca calls

### See also:

`withCA` decorator to ensure CA is initialized

### Notes

This function must be called prior to any real CA calls.

`epics.ca.finalize_libca()`  
shutdown channel access:

run `clear_channel()` for all chids in `_cache`, then calls `flush_io()` and `poll()` a few times.

### Parameters

`maxtime` [float] maximum time (in seconds) to wait for `flush_io()` and `poll()` to complete.

`epics.ca.pend_io(timeout=1.0)`  
polls CA for i/o.

`epics.ca.pend_event(timeout=1.e-5)`  
polls CA for events

`epics.ca.poll(evt=1.e-5[, iot=1.0])`  
a convenience function which is equivalent to: `pend_event(evt) pend_io(iot)`

`epics.ca.create_context()`  
Create a new context, using the value of `PREEMPTIVE_CALLBACK` to set the context type. Note that both `context_create` and `create_context` (which is more consistent with the Verb\_Object of the rest of the CA library) are supported.

### Parameters

`ctx` [int] 0 – No preemptive callbacks, 1 – use preemptive callbacks, None – use value of `PREEMPTIVE_CALLBACK`

`epics.ca.destroy_context()`  
destroy current context

`epics.ca.current_context()`  
return the current context

`epics.ca.attach_context(context)`  
attach to the supplied context

`epics.ca.detach_context()`  
detach context

`epics.ca.use_initial_context()`  
Attaches to the context created when `libca` is initialized. Using this function is recommended when writing threaded programs that using CA.

### See also:

*Using Python Threads*

```
epics.ca.client_status(context, level)
    print (to stderr) information about Channel Access status, including status for each channel, and search and
    connection statistics.

epics.ca.version()
    Print Channel Access version string. Currently, this should report '4.13'

epics.ca.message(status)
    Print a message corresponding to a Channel Access status return value.

epics.ca.flush_io()
    flush i/o

epics.ca.replace_printf_handler(fcn=None)
    replace the normal printf() output handler with the supplied function (defaults to sys.stderr.write())
```

**Warning:** `replace_printf_handler()` appears to not actually work.

We think this is due to a real limitation of Python's `ctypes` module not supporting the mapping of C `va_list` function arguments to Python. If you are interested in this or have ideas of how to fix it, please let us know.

### 4.3.1 Creating and Connecting to Channels

The basic channel object is the Channel ID or `chid`. With the CA library (and `ca` module), one creates and acts on the `chid` values. These are simply `ctypes.c_long` (C long integers) that hold the memory address of the C representation of the channel, but it is probably a good idea to treat these as object instances.

```
epics.ca.create_channel(pvname, connect=False, callback=None, auto_cb=True)
    create a Channel for a given pvname

    creates a channel, returning the Channel ID chid used by other functions to identify this channel.
```

**Parameters**

**pvname** [string] the name of the PV for which a channel should be created.

**connect** [bool] whether to (try to) connect to PV as soon as possible.

**auto\_cb** [bool] whether to automatically use an internal connection callback.

**callback** [callable or None] user-defined Python function to be called when the connection state changes.

**Returns**

**chid** [ctypes.c\_long] channel ID.

**Notes**

1. The user-defined connection callback function should be prepared to accept keyword arguments of

| keyword       | meaning                      |
|---------------|------------------------------|
| <i>pvname</i> | name of PV                   |
| <i>chid</i>   | Channel ID                   |
| <i>conn</i>   | whether channel is connected |



2. If `auto_cb` is `True`, an internal connection callback is used so that you should not need to explicitly connect to a channel, unless you are having difficulty with dropped connections.
3. If the channel is already connected for the PV name, the callback will be called immediately.

`epics.ca.connect_channel(chid, timeout=None, verbose=False)`  
 connect to a channel, waiting up to timeout for a channel to connect. It returns the connection state, `True` or `False`.

This is usually not needed, as implicit connection will be done when needed in most cases.

#### Parameters

**chid** [ctypes.c\_long] Channel ID  
**timeout** [float] maximum time to wait for connection.  
**verbose** [bool] whether to print out debugging information

#### Returns

**connection\_state** [bool] that is, whether the Channel is connected

#### Notes

1. If `timeout` is `None`, the value of `DEFAULT_CONNECTION_TIMEOUT` is used (defaults to 2.0 seconds).
2. Normally, channels will connect in milliseconds, and the connection callback will succeed on the first attempt.
3. For un-connected Channels (that are nevertheless queried), the 'ts' (timestamp of last connection attempt) and 'failures' (number of failed connection attempts) from the `_cache` will be used to prevent spending too much time waiting for a connection that may never happen.

Many other functions require a valid Channel ID, but not necessarily a connected Channel. These functions are essentially identical to the CA library versions, and include:

`epics.ca.name(chid)`  
 return PV name for channel name

`epics.ca.host_name(chid)`  
 return host name and port serving Channel

`epics.ca.element_count(chid)`  
 return number of elements in Channel's data. 1 for most Channels, > 1 for waveform Channels

`epics.ca.replace_access_rights_event(chid, callback=None)`

`epics.ca.read_access(chid)`  
 return *read access* for a Channel: 1 for `True`, 0 for `False`.

`epics.ca.write_access(chid)`  
 return *write access* for a channel: 1 for `True`, 0 for `False`.

`epics.ca.field_type(chid)`  
 return the integer DBR field type.

See the *ftype* column from [Table of DBR Types](#).

`epics.ca.clear_channel(chid)`  
 clear the channel

`epics.ca.state(chid)`  
 return state (that is, attachment state) for channel

A few additional pythonic functions have been added:

`epics.ca.isConnected(chid)`

return whether channel is connected: `dbr.CS_CONN==state(chid)`

This is `True` for a connected channel, `False` for an unconnected channel.

`epics.ca.access(chid)`

returns a string describing read/write access: one of *no access*, *read-only*, *write-only*, or *read/write*

`epics.ca.promote_type(chid[, use_time=False[, use_ctrl=False ]])`

promotes the native field type of a `chid` to its `TIME` or `CTRL` variant. Returns the integer corresponding to the promoted field value.

See [Table of DBR Types](#).

`epics.ca._cache`

The `ca` module keeps a global cache of Channels that holds connection status and a bit of internal information for all known PVs. This cache is not intended for general use.

`epics.ca.show_cache(print_out=True)`

print out a listing of PVs in the current session to standard output. Use the `print_out=False` option to be returned the listing instead of having it printed out.

`epics.ca.clear_cache()`

Clears global caches of Epics CA connections, and fully detaches from the CA context. This is important when doing multiprocessing (and is done internally by `CAProcess`), but can be useful to fully reset a Channel Access session.

## 4.3.2 Interacting with Connected Channels

Once a `chid` is created and connected there are several ways to communicating with it. These are primarily encapsulated in the functions `get()`, `put()`, and `create_subscription()`, with a few additional functions for retrieving specific information.

These functions are where this python module differs the most from the underlying CA library, and this is mostly due to the underlying CA function requiring the user to supply `DBR TYPE` and count as well as `chid` and allocated space for the data. In python none of these is needed, and keyword arguments can be used to specify such options.

`epics.ca.get(chid, ftype=None, count=None, as_string=False, as_numpy=True, wait=True, timeout=None)`

return the current value for a Channel. Note that there is not a separate form for array data.

### Parameters

**chid** [ctypes.c\_long] Channel ID

**ftype** [int] field type to use (native type is default)

**count** [int] maximum element count to return (full data returned by default)

**as\_string** [bool] whether to return the string representation of the value. See notes below.

**as\_numpy** [bool] whether to return the Numerical Python representation for array / waveform data.

**wait** [bool] whether to wait for the data to be received, or return immediately.

**timeout** [float] maximum time to wait for data before returning `None`.

### Returns

**data** [object] Normally, the value of the data. Will return `None` if the channel is not connected, `wait=False` was used, or the data transfer timed out.

## Notes

1. Returning `None` indicates an *incomplete get*
2. The `as_string` option is not as complete as the `as_string` argument for `PV.get()`. For Enum types, the name of the Enum state will be returned. For waveforms of type CHAR, the string representation will be returned. For other waveforms (with `count > 1`), a string like `<array count=3, type=1>` will be returned.
3. The `as_numpy` option will convert waveform data to be returned as a numpy array. This is only applied if numpy can be imported.
4. The `wait` option controls whether to wait for the data to be received over the network and actually return the value, or to return immediately after asking for it to be sent. If `wait=False` (that is, immediate return), the `get` operation is said to be *incomplete*. The data will be still be received (unless the channel is disconnected) eventually but stored internally, and can be read later with `get_complete()`. Using `wait=False` can be useful in some circumstances.
5. The `timeout` option sets the maximum time to wait for the data to be received over the network before returning `None`. Such a timeout could imply that the channel is disconnected or that the data size is larger or network slower than normal. In that case, the `get` operation is said to be *incomplete*, and the data may become available later with `get_complete()`.

See [Table of DBR Types](#) for a listing of values of `ftype`,

See [Strategies for working with large arrays](#) for a discussion of strategies for how to best deal with very large arrays.

See [Strategies for connecting to a large number of PVs](#) for a discussion of when using `wait=False` can give a large performance boost.

See [The wait and timeout options for get\(\), ca.get\\_complete\(\)](#) for further discussion of the `wait` and `timeout` options and the associated `get_complete()` function.

`epics.ca.get_with_metadata(chid, ftype=None, count=None, as_string=False, as_numpy=True, wait=True, timeout=None)`  
Return the current value along with metadata for a Channel

### Parameters

- chid** [ctypes.c\_long] Channel ID
- ftype** [int] field type to use (native type is default)
- count** [int] maximum element count to return (full data returned by default)
- as\_string** [bool] whether to return the string representation of the value. See notes.
- as\_numpy** [bool] whether to return the Numerical Python representation for array / waveform data.
- wait** [bool] whether to wait for the data to be received, or return immediately.
- timeout** [float] maximum time to wait for data before returning `None`.

### Returns

- data** [dict or None] The dictionary of data, guaranteed to at least have the 'value' key. Depending on `ftype`, other keys may also be present:

```
{'precision', 'units', 'status', 'severity', 'enum_strs', 'status',  
'severity', 'timestamp', 'posixseconds', 'nanoseconds',  
'upper_disp_limit', 'lower_disp_limit', 'upper_alarm_limit',  
'upper_warning_limit', 'lower_warning_limit', 'lower_alarm_limit',  
'upper_ctrl_limit', 'lower_ctrl_limit'}
```

Returns `None` if the channel is not connected, `wait=False` was used, or the data transfer timed out.

**See also:**

**See** `func:get` for additional usage notes.

`epics.ca.get_complete(chid, ftype=None, count=None, as_string=False, as_numpy=True, timeout=None)`  
returns the current value for a Channel, completing an earlier incomplete `get()` that returned `None`, either because `wait=False` was used or because the data transfer did not complete before the timeout passed.

#### Parameters

**chid** [ctypes.c\_long] Channel ID

**ftype** [int] field type to use (native type is default)

**count** [int] maximum element count to return (full data returned by default)

**as\_string** [bool] whether to return the string representation of the value.

**as\_numpy** [bool] whether to return the Numerical Python representation for array / waveform data.

**timeout** [float] maximum time to wait for data before returning `None`.

#### Returns

**data** [object] This function will return `None` if the previous `get()` actually completed, or if this data transfer also times out.

#### Notes

1. The default timeout is dependent on the element count:: `default_timeout = 1.0 + log10(count)` (in seconds)
2. Consult the doc for `get()` for more information.

See *The wait and timeout options for get(), ca.get\_complete()* for further discussion.

`epics.ca.get_complete_with_metadata(chid, ftype=None, count=None, as_string=False, as_numpy=True, timeout=None)`

Returns the current value and associated metadata for a Channel

This completes an earlier incomplete `get()` that returned `None`, either because `wait=False` was used or because the data transfer did not complete before the timeout passed.

#### Parameters

**chid** [ctypes.c\_long] Channel ID

**ftype** [int] field type to use (native type is default)

**count** [int] maximum element count to return (full data returned by default)

**as\_string** [bool] whether to return the string representation of the value.

**as\_numpy** [bool] whether to return the Numerical Python representation for array / waveform data.

**timeout** [float] maximum time to wait for data before returning `None`.

### Returns

**data** [dict or None] This function will return `None` if the previous `get()` actually completed, or if this data transfer also times out.

**See also:**

**See** `func: get_complete` for additional usage notes.

`epics.ca.put(chid, value, wait=False, timeout=30, callback=None, callback_data=None)`  
sets the Channel to a value, with options to either wait (block) for the processing to complete, or to execute a supplied callback function when the process has completed.

### Parameters

**chid** [ctypes.c\_long] Channel ID

**wait** [bool] whether to wait for processing to complete (or time-out) before returning.

**timeout** [float] maximum time to wait for processing to complete before returning anyway.

**callback** [None or callable] user-supplied function to run when processing has completed.

**callback\_data** [object] extra data to pass on to a user-supplied callback function.

### Returns

**status** [int] 1 for success, -1 on time-out

### Notes

1. Specifying a callback will override setting `wait=True`.
2. A put-callback function will be called with keyword arguments `pvname=pvname`, `data=callback_data`

See *User-supplied Callback functions* for more on this *put callback*,

`epics.ca.create_subscription(chid, use_time=False, use_ctrl=False, mask=None, callback=None)`  
create a *subscription to changes*. Sets up a user-supplied callback function to be called on any changes to the channel.

### Parameters

**chid** [ctypes.c\_long] channel ID

**use\_time** [bool] whether to use the TIME variant for the PV type

**use\_ctrl** [bool] whether to use the CTRL variant for the PV type

**ftype** [integer or None] ftype to use, overriding native type, `use_time` or `use_ctrl` if `None`, the native type is looked up, which requires a connected channel.

**mask** [integer or None] bitmask combination of `dbr.DBE_ALARM`, `dbr.DBE_LOG`, and `dbr.DBE_VALUE`, to control which changes result in a callback. If `None`, defaults to `DEFAULT_SUBSCRIPTION_MASK`.

**callback** [None or callable] user-supplied callback function to be called on changes

**timeout** [None or int] connection timeout used for unconnected channels.

### Returns

**(callback\_ref, user\_arg\_ref, event\_id)** The returned tuple contains *callback\_ref* an *user\_arg\_ref* which are references that should be kept for as long as the subscription lives (otherwise they may be garbage collected, causing no end of trouble). *event\_id* is the id for the event (useful for clearing a subscription).

### Notes

Keep the returned tuple in named variable!! if the return argument gets garbage collected, a coredump will occur.

If the channel is not connected, the ftype must be specified for a successful subscription.

See *User-supplied Callback functions* for more on writing the user-supplied callback,

**Warning:** *event\_id* is the id for the event (useful for clearing a subscription). You **must** keep the returned tuple in active variables, either as a global variable or as data in an encompassing class. If you do *not* keep this data, the return value will be garbage collected, the C-level reference to the callback will disappear, and you will see coredumps.

On Linux, a message like:

```
python: Objects/funcobject.c:451: func_dealloc: Assertion 'g->gc.gc_refs != (-2) ' failed.
Abort (core dumped)
```

is a hint that you have *not* kept this data.

### `epics.ca.DEFAULT_SUBSCRIPTION_MASK`

This value is the default subscription type used when calling `create_subscription()` with *mask=None*. It is also used by default when creating a PV object with `auto_monitor` is set to `True`.

The initial default value is `dbr.DBE_ALARM|dbr.DBE_VALUE` (i.e. update on alarm changes or value changes which exceeds the monitor deadband.) The other possible flag in the bitmask is `dbr.DBE_LOG` for archive-deadband changes.

If this value is changed, it will change the default for all subsequent calls to `create_subscription()`, but it will not change any existing subscriptions.

`epics.ca.clear_subscription(event_id)`  
cancel subscription given its *event\_id*

Several other functions are provided:

`epics.ca.get_timestamp(chid)`  
return the timestamp of a Channel – the time of last update.

`epics.ca.get_severity(chid)`  
return the severity of a Channel.

`epics.ca.get_precision(chid)`  
return the precision of a Channel. For Channels with native type other than `FLOAT` or `DOUBLE`, this will be 0

`epics.ca.get_enum_strings(chid)`  
return list of names for `ENUM` states of a Channel. Returns `None` for non-`ENUM` Channels

`epics.ca.get_ctrlvars(chid)`  
return the CTRL fields for a Channel.

Depending on the native type, the keys may include *status*, *severity*, *precision*, *units*, *enum\_strs\**, *upper\_disp\_limit*, *lower\_disp\_limit*, *upper\_alarm\_limit\**, *lower\_alarm\_limit*, *upper\_warning\_limit\**, *lower\_warning\_limit*, *upper\_ctrl\_limit*, *lower\_ctrl\_limit*

### Notes

*enum\_strs* will be a list of strings for the names of ENUM states.

See [Table of Control Attributes](#)

Table of Control Attributes

| <i>attribute</i>    | <i>data types</i>           |
|---------------------|-----------------------------|
| status              |                             |
| severity            |                             |
| precision           | 0 for all but double, float |
| units               |                             |
| enum_strs           | enum only                   |
| upper_disp_limit    |                             |
| lower_disp_limit    |                             |
| upper_alarm_limit   |                             |
| lower_alarm_limit   |                             |
| upper_warning_limit |                             |
| lower_warning_limit |                             |
| upper_ctrl_limit    |                             |
| lower_ctrl_limit    |                             |

Note that *enum\_strs* will be a tuple of strings for the names of ENUM states.

`epics.ca.get_timevars(chid)`  
returns a dictionary of TIME fields for a Channel. This will contain keys of *status*, *severity*, and *timestamp*.

### 4.3.3 Synchronous Groups

**Warning:** Synchronous groups are simulated in pyepics, but are not recommended, and probably don't really make sense for usage within pyepics and using asynchronous i/o anyway.

Synchronous Groups can be used to ensure that a set of Channel Access calls all happen together, as if in a *transaction*. Synchronous Groups should be avoided in pyepics, and are not well tested. They probably make little sense in the context of asynchronous I/O. The documentation here is given for historical purposes.

The idea is to first create a synchronous group, then add a series of `sg_put()` and `sg_get()` which do not happen immediately, and finally block while all the channel access communication is done for the group as a unit. It is important to *not* issue `pend_io()` during the building of a synchronous group, as this will cause pending `sg_put()` and `sg_get()` to execute.

`epics.ca.sg_create()`  
create synchronous group. Returns a *group id*, *gid*, which is used to identify this group and to be passed to all other synchronous group commands.

`epics.ca.sg_delete(gid)`  
delete a synchronous group

`epics.ca.sg_block(gid[, timeout=10.0])`  
block for a synchronous group to complete processing

`epics.ca.sg_get(gid, chid[, ftype=None[, as_string=False[, as_numpy=True]]])`  
synchronous-group get of the current value for a Channel. same options as `get()`

This function will not immediately return the value, of course, but the address of the underlying data.

After the `sg_block()` has completed, you must use `_unpack()` to convert this data address to the actual value(s).

### Examples

```
>>> chid = epics.ca.create_channel(PV_Name)
>>> epics.ca.connect_channel(chid1)
>>> sg = epics.ca.sg_create()
>>> data = epics.ca.sg_get(sg, chid)
>>> epics.ca.sg_block(sg)
>>> print epics.ca._unpack(data, chid=chid)
```

`epics.ca.sg_put(gid, chid, value)`  
perform a *put* within a synchronous group.

This *put* cannot wait for completion or for a callback to complete.

`epics.ca.sg_test(gid)`  
test whether a synchronous group has completed.

`epics.ca.sg_reset(gid)`  
resets a synchronous group

## 4.4 Implementation details

The details given here should mostly be of interest to those looking at the implementation of the *ca* module, those interested in the internals, or those looking to translate lower-level C or Python code to this module.

### 4.4.1 DBR data types

Table of DBR Types



| CA type     | integer ftype | Python ctypes type |
|-------------|---------------|--------------------|
| string      | 0             | string             |
| int         | 1             | integer            |
| short       | 1             | integer            |
| float       | 2             | double             |
| enum        | 3             | integer            |
| char        | 4             | byte               |
| long        | 5             | integer            |
| double      | 6             | double             |
| time_string | 14            |                    |
| time_int    | 15            |                    |
| time_short  | 15            |                    |
| time_float  | 16            |                    |
| time_enum   | 17            |                    |
| time_char   | 18            |                    |
| time_long   | 19            |                    |
| time_double | 20            |                    |
| ctrl_string | 28            |                    |
| ctrl_int    | 29            |                    |
| ctrl_short  | 29            |                    |
| ctrl_float  | 30            |                    |
| ctrl_enum   | 31            |                    |
| ctrl_char   | 32            |                    |
| ctrl_long   | 33            |                    |
| ctrl_double | 34            |                    |

#### 4.4.2 PySEVCHK and ChannelAccessException: checking CA return codes

##### **exception** `epics.ca.ChannelAccessException`

This exception is raised when the `ca` module experiences unexpected behavior and must raise an exception

`epics.ca.PySEVCHK(func_name, status[, expected=dbr.ECA_NORMAL])`

This checks the return *status* returned from a `libca.ca_***` and raises a `ChannelAccessException` if the value does not match the *expected* value (which is normally `dbr.ECA_NORMAL`).

The message from the exception will include the *func\_name* (name of the Python function) and the CA message from `message()`.

`epics.ca.withSEVCHK(fcn)`

decorator to raise a `ChannelAccessException` if the wrapped `ca` function does not return `status = dbr.ECA_NORMAL`. This handles the common case of running `PySEVCHK()` for a function whose return value is from a corresponding `libca` function and whose return value should be `dbr.ECA_NORMAL`.

#### 4.4.3 Function Decorators

In addition to `withSEVCHK()`, several other decorator functions are used heavily inside of `ca.py` or are available for your convenience.

`epics.ca.withCA(fcn)`

decorator to ensure that `libca` and a context are created prior to function calls to the channel access library. This is intended for functions that need CA started to work, such as `create_channel()`.

Note that CA functions that take a Channel ID (*chid*) as an argument are NOT wrapped by this: to get a *chid*, the library must have been initialized already.

`epics.ca.withCHID (fcn)`

decorator to ensure that first argument to a function is a Channel ID, *chid*. The test performed is very weak, as any ctypes long or python int will pass, but it is useful enough to catch most accidental errors before they would cause a crash of the CA library.

`epics.ca.withConnectedCHID (fcn)`

decorator to ensure that the first argument of a function is a fully connected Channel ID, *chid*. This test is (intended to be) robust, and will try to make sure a *chid* is actually connected before calling the decorated function.

`epics.ca.withInitialContext (fcn)`

decorator to ensure that the wrapped function uses the initial threading context created at initialization of CA

See *Using Python Threads* for further discussion.

## 4.4.4 Unpacking Data from Callbacks

Throughout the implementation, there are several places where data returned by the underlying CA library needs to be converted to Python data. This is encapsulated in the `_unpack()` function. In general, you will not have to run this code, but there is one exception: when using `sg_get()`, the values returned will have to be unpacked with this function.

`epics.ca._unpack (chid, data[, count=None[, ftype=None[, as_numpy=None ]]])`

unpacks raw data for a Channel ID *chid* returned by libca functions including `ca_get_array_callback` or subscription callback, and returns the corresponding Python data

Normally, users are not expected to need to access this function, but it will be necessary why using `sg_get()`.

### Parameters

**chid** [ctypes.c\_long or None] channel ID (if not None, used for determining count and ftype)

**data** [object] raw data as returned by internal libca functions.

**count** [integer] number of elements to fetch (defaults to element count of *chid* or 1)

**ftype** [integer] data type of channel (defaults to native type of *chid*)

**as\_numpy** [bool] whether to convert to numpy array.

## 4.5 User-supplied Callback functions

User-supplied callback functions can be provided for `put()`, `replace_access_rights_event()`, and `create_subscription()`. Note that callbacks for *PV* objects are slightly different: see *User-supplied Callback functions* in the *pv* module for details.

When defining a callback function to be run either when a `put()` completes or on changes to the Channel, as set from `create_subscription()`, or when read/write permissions change from `replace_access_rights_event()`, it is important to know two things:

- 1) how your function will be called.
- 2) what is permissible to do inside your callback function.

Callbacks will be called with keyword arguments for `put()` and for `create_subscription()`. You should be prepared to have them passed to your function. Use `**kw` unless you are very sure of what will be sent. For the case of `replace_access_rights_event()`, only positional arguments will be passed.

For callbacks sent when a `put()` completes, your function will be passed these:

- `pvnname`: the name of the pv
- `data`: the user-supplied `callback_data` (defaulting to `None`).

For subscription callbacks, your function will be called with keyword/value pairs that will include:

- `pvnname`: the name of the pv
- `value`: the latest value
- `count`: the number of data elements
- `ftype`: the numerical CA type indicating the data type
- `status`: the status of the PV (1 for OK)
- `chid`: the integer address for the channel ID.

For access rights event callbacks, your function will be passed:

- `read_access`: boolean indicating read access status
- `write_access`: boolean indicating write access status

Depending on the data type, and whether the CTRL or TIME variant was used, the callback function may also include some of these as keyword arguments:

- `enum_strs`: the list of enumeration strings
- `precision`: number of decimal places of precision.
- `units`: string for PV units
- `severity`: PV severity
- `timestamp`: timestamp from CA server.
- `posixseconds`: integer seconds since POSIX epoch of timestamp from CA server.
- `nanoseconds`: integer nanoseconds of timestamp from CA server.

Note that a the user-supplied callback will be run *inside* a CA function, and cannot reliably make any other CA calls. It is helpful to think “this all happens inside of a `pend_event()` call”, and in an epics thread that may or may not be the main thread of your program. It is advisable to keep the callback functions short and not resource-intensive. Consider strategies which use the callback only to record that a change has occurred and then act on that change later – perhaps in a separate thread, perhaps after `pend_event()` has completed.

## 4.6 Omissions

Several parts of the CA library are not implemented in the Python module. These are currently seen as unneeded (with notes where appropriate for alternatives), though they could be added on request.

`epics.ca.ca_add_exception_event()`

*Not implemented*: Python exceptions are raised where appropriate and can be used in user code.

`epics.ca.ca_add_fd_registration()`

*Not implemented*

`epics.ca.ca_client_status()`

*Not implemented*

`epics.ca.ca_set_puser()`

*Not implemented*: it is easy to pass user-defined data to callbacks as needed.

`epics.ca.ca_puser()`

*Not implemented*: it is easy to pass user-defined data to callbacks as needed.

`epics.ca.ca_SEVCHK()`

*Not implemented*: the Python function `PySEVCHK()` is approximately the same.

`epics.ca.ca_signal()`

*Not implemented*: the Python function `PySEVCHK()` is approximately the same.

`epics.ca.ca_test_event()`

*Not implemented*: this appears to be a function for debugging events. These are easy enough to simulate by directly calling Python callback functions.

`epics.ca.ca_dump_dbr()`

*Not implemented*

In addition, not all *DBR* types in the CA C library are supported.

Only native types and their `DBR_TIME` and `DBR_CTRL` variants are supported: `DBR_STS` and `DBR_GR` variants are not. Several `dbr_XXX` functions are also not supported, as they are needed only to dynamically allocate memory.

## 4.7 CATHread class

**class** `epics.ca.CATHread`(*group=None*[, *target=None*[, *name=None*[, *args=()*[, *kwargs={}*]]]])

create a CA-aware subclass of a standard Python `threading.Thread`. See the standard library documentation for further information on how to use Thread objects.

A *CATHread* simply runs `use_initial_context()` prior to running each target function, so that `use_initial_context()` does not have to be explicitly put inside the target function.

The See *Using Python Threads* for further discussion.

## 4.8 Examples

Here are some example sessions using the `ca` module.

### 4.8.1 Create, Connect, Get Value of Channel

Note here that several things have been simplified compare to using CA in C: initialization and creating a main-thread context are handled, and connection of channels is handled in the background:

```
from epics import ca
chid = ca.create_channel('XXX:m1.VAL')
count = ca.element_count(chid)
ftype = ca.field_type(chid)
print "Channel ", chid, count, ftype
value = ca.get()
print value
```

### 4.8.2 Put, waiting for completion

Here we set a PVs value, waiting for it to complete:

```
from epics import ca
chid = ca.create_channel('XXX:m1.VAL')
ca.put(chid, 1.0, wait=True)
```

The `put()` method will wait to return until the processing is complete.

### 4.8.3 Define a callback to Subscribe to Changes

Here, we *subscribe to changes* for a PV, which is to say we define a callback function to be called whenever the PV value changes. In the case below, the function to be called will simply write the latest value out to standard output:

```
from epics import ca
import time
import sys

# define a callback function. Note that this should
# expect certain keyword arguments, including 'pvname' and 'value'
def onChanges(pvname=None, value=None, **kw):
    fmt = 'New Value: %s value=%s, kw=%s\n'
    sys.stdout.write(fmt % (pvname, str(value), repr(kw)))
    sys.stdout.flush()

# create the channel
mypv = 'XXX.VAL'
chid = ca.create_channel(mypv)

# subscribe to events giving a callback function
eventID = ca.create_subscription(chid, callback=onChanges)

# now we simply wait for changes
t0 = time.time()
while time.time()-t0 < 10.0:
    time.sleep(0.001)
```

It is **vital** that the return value from `create_subscription()` is kept in a variable so that it cannot be garbage collected. Failure to keep this value will cause trouble, including almost immediate segmentation faults (on Windows) or seemingly inexplicable crashes later (on linux).

### 4.8.4 Define a connection callback

Here, we define a connection callback – a function to be called when the connection status of the PV changes. Note that this will be called on initial connection:

```
import epics
import time

def onConnectionChange(pvname=None, conn=None, chid=None):
    print 'ca connection status changed: ', pvname, conn, chid

# create channel, provide connection callback
motor1 = '13IDC:m1'
```

(continues on next page)

(continued from previous page)

```
chid = epics.ca.create_channel(motor1, callback=onConnectionChange)

print 'Now waiting, watching values and connection changes:'
t0 = time.time()
while time.time()-t0 < 30:
    time.sleep(0.001)
```

This will run the supplied callback soon after the channel has been created, when a successful connection has been made. Note that the callback should be prepared to accept keyword arguments of *pvname*, *chid*, and *conn* for the PV name, channel ID, and connection state (True or False).

### 4.8.5 Define an access rights change event callback

The following example demonstrates the addition of a function to be called when the access rights of a channel changes. Note this will be called immediately after successful installation:

```
import epics
import time

def on_access_rights_change(read_access, write_access):
    print 'read access = %s, write access = %s' % (read_access, write_access)

# create a channel and attach the above function for access rights events
chid = epics.ca.create_channel('pv_name')
# a message should be printed immediately following this registration
epics.ca.replace_access_rights_event(chid, callback=on_access_rights_change)

# Affecting the channel's access rights, (for example, by enabling/disabling
# CA Security rules), should produce additional console messages
try:
    while True:
        time.sleep(0.25)
except KeyboardInterrupt:
    pass
```

## WORKING WITH WAVEFORM / ARRAY DATA

Though most EPICS Process Variables hold single values, PVs can hold array data from EPICS waveform records. These are always data of a homogenous data type, and have a fixed maximum element count (defined when the waveform is created from the host EPICS process). Epics waveforms are most naturally mapped to Arrays from the `numpy` module, and this is strongly encouraged.

### 5.1 Arrays without Numpy

If you have `numpy` installed, and use the default `as_numpy=True` in `epics.ca.get()`, `pv.get()` or `epics.caget()`, you will get a `numpy` array for the value of a waveform PV. If you do *not* have `numpy` installed, or explicitly use `as_numpy=False` in a get request, you will get the raw C-like array reference from the Python `ctypes` module. These objects are not normally meant for casual use, but are not too difficult to work with either. They can be easily converted to a simple Python list with something like:

```
>>> import epics
>>> epics.ca.HAS_NUMPY = False # turn numpy off for session
>>> p = epics.PV('XX:scan1.P1PA')
>>> p.get()
<epics.dbr.c_double_Array_500 object at 0x853980c>
>>> ldat = list(p.get())
```

Note that this conversion to a list can be very slow for large arrays.

### 5.2 Variable Length Arrays: NORD and NELM

While the maximum length of an array is fixed, the length of data you get back from a monitor, `epics.ca.get()`, `pv.get()`, or `epics.caget()` may be shorter than the maximum length, reflecting the most recent data put to that PV. That is, if some process puts a smaller array to a PV than its maximum length, monitors on that PV may receive only the changed data. For example:

```
>>> import epics
>>> p = epics.PV('Py:double2k')
>>> print p
<PV 'Py:double2k', count=2048/2048, type=double, access=read/write>
>>> import numpy
>>> p.put(numpy.arange(10)/5.0)
>>> print p.get()
array([ 0. ,  0.2,  0.4,  0.6,  0.8,  1. ,  1.2,  1.4,  1.6,  1.8])
```

To be clear, the `pv.put()` above could be done in a separate process – the `pv.get()` is not using a value cached from the `pv.put()`.

This feature was introduced in Epics CA 3.14.12.1, and may not work for data from IOCs running extremely old versions of Epics base.

## 5.3 Character Arrays

As noted in other sections, character waveforms can be used to hold strings longer than 40 characters, which is otherwise a fundamental limit for native Epics strings. Character waveforms shorter than `epics.ca.AUTOMONITOR_MAXLENGTH` can be turned into strings with an optional `as_string=True` to `epics.ca.get()`, `pv.get()`, or `epics.caget()`. If you've defined a Epics waveform record as:

```
record(waveform, "$ (P):filename") {
    field(DTYP, "Soft Channel")
    field(DESC, "file name")
    field(NELM, "128")
    field(FTVL, "CHAR")
}
```

Then you can use this record with:

```
>>> import epics
>>> pvname = 'PREFIX:filename.VAL'
>>> pv = epics.PV(pvname)
>>> print pv.info
....
>>> plain_val = pv.get()
>>> print plain_val
array([ 84,  58,  92, 120,  97, 115,  95, 117, 115, 101, 114,  92,  77,
        97, 114,  99, 104,  50,  48,  49,  48,  92,  70,  97, 115, 116,
        77,  97, 112])
>>> char_val = pv.get(as_string=True)
>>> print char_val
'T:\\xas_user\\March2010\\FastMap'
```

This example uses `pv.get()` but `epics.ca.get()` is essentially equivalent, as its `as_string` parameter works exactly the same way.

Note that Epics character waveforms as defined as above are really arrays of bytes. The conversion to a string assumes the ASCII character set. Unicode is not directly supported. If you are storing non-ASCII data, you would have to convert the raw array data yourself, perhaps like this (for Python3):

```
>>> arr_data = pv.get()
>>> arr_bytes = bytes(list(arr_data))
>>> arr_string = str(arr_bytes, 'LATIN-1')
```

### 5.3.1 Strategies for working with large arrays

EPICS Channels / Process Variables usually have values that can be stored with a small number of bytes. This means that their storage and transfer speeds over real networks is not a significant concern. However, some Process Variables can store much larger amounts of data (say, several megabytes) which means that some of the assumptions about dealing with Channels / PVs may need reconsideration.



When using PVs with large array sizes (here, I'll assert that *large* means more than a few thousand elements), it is necessary to make sure that the environmental variable `EPICS_CA_MAX_ARRAY_BYTES` is suitably set. Unfortunately, this represents a pretty crude approach to memory management within Epics for handling array data as it is used not only sets how large an array the client can accept, but how much memory will be allocated on the server. In addition, this value must be set prior to using the CA library – it cannot be altered during the running of a CA program.

Normally, the default value for `EPICS_CA_MAX_ARRAY_BYTES` is 16384 (16k, and it turns out that you cannot set it smaller than this value!). As Python is used for clients, generally running on workstations or servers with sufficient memory, this default value is changed to  $2 \times 24$ , or 16Mb) when `epics.ca` is initialized. If the environmental variable `EPICS_CA_MAX_ARRAY_BYTES` has not already been set.

The other main issue for PVs holding large arrays is whether they should be automatically monitored. For PVs holding scalar data or small arrays, any penalty for automatically monitoring these variables (that is, causing network traffic every time a PV changes) is a small price to pay for being assured that the latest value is always available. As arrays get larger (as for data streams from Area Detectors), it is less obvious that automatic monitoring is desirable.

The Python `epics.ca` module defines a variable `epics.ca.AUTOMONITOR_MAXLENGTH` which controls whether array PVs are automatically monitored. The default value for this variable is 65536, but can be changed at run-time. Arrays with fewer elements than `epics.ca.AUTOMONITOR_MAXLENGTH` will be automatically monitored, unless explicitly set, and arrays larger than `epics.ca.AUTOMONITOR_MAXLENGTH` will not be automatically monitored unless explicitly set. Auto-monitoring of PVs can be explicitly set with

```
>>> pv2 = epics.PV('ScalerPV', auto_monitor=True)
>>> pv1 = epics.PV('LargeArrayPV', auto_monitor=False)
```

## 5.4 Example handling Large Arrays

Here is an example reading data from an EPICS `areaDetector`, as if it were an image from a digital camera. This uses the common third-party library called *Python Imaging Library* or *pillow* for much of the image processing. This library can be installed with `pip install pillow` or `conda install pillow`:

```
>>> import epics
>>> import Image
>>> pvname = '13IDCPS1:image1:ArrayData'
>>> img_pv = epics.PV(pvname)
>>>
>>> raw_image = img_pv.get()
>>> im_mode = 'RGB'
>>> im_size = (1360, 1024)
>>> img = Image.frombuffer(im_mode, im_size, raw_image,
>>>                        'raw', im_mode, 0, 1)
>>> img.show()
```

The result looks like this (taken with a Prosilica GigE camera):



A more complete application for reading and displaying image from Epics Area Detectors is included at <http://github.com/pyepics/epicsapps/>.

## DEVICES: COLLECTIONS OF PVS

### 6.1 Overview

The `device` module provides a simple interface to a collection of PVs. Here an epics `device.Device` is an object holding a set of PVs, all sharing a prefix, but having many *attributes*. Many PVs will have names made up of *prefix+attribute*, with a common prefix for several related PVs. This almost describes an Epics Record, but as it is concerned only with PV names, the mapping to an Epics Record is not exact. On the other hand, the concept of a *device* is more flexible than a predefined Epics Record as it can actually hold PVs from several different records.:

```
motor1 = epics.Device('XXX:motor1.', attrs=('VAL', 'RBV', 'DESC', 'RVAL',
                                           'LVIO', 'HLS', 'LLS'))

motor1.put('VAL', 1)
print 'Motor %s = %f' % ( motor1.get('DESC'), motor1.get('RBV'))

motor1.VAL = 0
print 'Motor %s = %f' % ( motor1.DES, motor1.RBV )
```

While useful on its own like this, the real point of a *device* is as a base class, to be inherited and extended. In fact, there is a more sophisticated Motor device described below at [Epics Motor Device](#)

```
class device.Device (prefix=None[, delim="[, attrs=None ]])
```

The attribute PVs are built as needed and held in an internal buffer `self._pvs`. This class is kept intentionally simple so that it may be subclassed.

To pre-load attribute names on initialization, provide a list or tuple of attributes with the *attr* option.

Note that *prefix* is actually optional. When left off, this class can be used as an arbitrary container of PVs, or to turn any subclass into an epics Device.

In general, PV names will be mapped as `prefix+delim+attr`. See [add\\_pv\(\)](#) for details of how to override this.

```
device.PV (attr[, connect=True[, **kw]])
```

returns the *PV* object for a device attribute. The connect argument and any other keyword arguments are passed to `epics.PV()`.

```
device.put (attr, value[, wait=False[, timeout=10.0 ]])
```

put an attribute value, optionally wait for completion or up to a supplied timeout value

```
device.get (attr[, as_string=False ])
```

get an attribute value, option `as_string` returns a string representation

```
device.add_callback (attr, callback)
```

add a callback function to an attribute PV, so that the callback function will be run when the attribute's value changes

`device.add_pv(pvname[, attr=None[, **kw]])`

adds an explicitly names `epics.PV()` to the device even though it may violate the normal naming rules (in which `attr` is mapped to `epics.PV(prefix+delim+attr)`. That is, one can say:

```
import epics
m1 = epics.Device('XXX:m1', delim='.')
m1.add_pv('XXX:m2.VAL', attr='other')
print m1.VAL      # print value of XXX:m1.VAL
print m1.other    # prints value of XXX:m2.VAL
```

`device.save_state()`

return a dictionary of all current values – the “current state”.

`device.restore_state(state)`

restores a saved state, as saved with `save_state()`

`device.write_state(fname[, state=None])`

write a saved state to a file. If no state is provide, the current state is written.

`device.read_state(fname[, restore=False])`

reads a state from a file, as written with `write_state()`, and returns it. If “restore” is `True`, the read state will be restored.

`device._pvs`

a dictionary of PVs making up the device.

## 6.2 Epics Motor Device

The Epics Motor record has over 100 fields associated with it. Of course, it is often preferable to think of 1 Motor with many attributes than 100 or so separate PVs. Many of the fields of the Motor record are interrelated and influence other settings, including limits on the range of motion which need to be respected, and which may send notifications when they are violated. Thus, there is a fair amount of functionality for a Motor. Typically, the user just wants to move the motor by setting its drive position, but a fully enabled Motor should allow the use to change and read many of the Motor parameters.

The `Motor` class helps the user create and use Epics motors. A simple example use would be:

```
import epics
m1 = epics.Motor('XXX:m1')

print 'Motor: ', m1.DESC , ' Currently at ', m1.RBV

m1.tweak_val = 0.10
m1.move(0.0, dial=True, wait=True)

for i in range(10):
    m1.tweak(direction='forward', wait=True)
    time.sleep(1.0)
    print 'Motor: ', m1.DESC , ' Currently at ', m1.RBV
```

Which will step the motor through a set of positions. You’ll notice a few features for Motor:

1. Motors can use English-name aliases for attributes for fields of the motor record. Thus ‘VAL’ can be spelled ‘drive’ and ‘DESC’ can be ‘description’. The *Table of Motor Attributes* give the list of names that can be used.
2. The methods for setting positions can use the User, Dial, or Step coordinate system, and can wait for completion.

## 6.2.1 The `epics.Motor` class

**class** `motor.Motor` (*pvname*[, *timeout*=30. ])  
create a `Motor` object for a named Epics Process Variable.

### Parameters

- **pvname** (*string*) – prefix name (no ‘.VAL’ needed!) of Epics Process Variable for a `Motor`
- **timeout** (*float*) – time (in seconds) to wait before giving up trying to connect.

Once created, a `Motor` should be ready to use.

```
>>> from epics import Motor
>>> m = Motor('XX:m1')
>>> print m.drive, m.description, m.slew_speed
1.030 Fine X 5.0
>>> print m.get('device_type', as_string=True)
'asynMotor'
```

A `Motor` has very many fields. Only a few of them are created on initialization – the rest are retrieved as needed. The motor fields can be retrieved either with an attribute or with the `get()` method. A full list of `Motor` attributes and their aliases for the motor record is given in [Table of Motor Attributes](#).

Table of Aliases for attributes for the `epics.Motor` class, and the corresponding attribute name of the `Motor Record` field.

| alias           | Motor Record field | alias           | Motor Record field |
|-----------------|--------------------|-----------------|--------------------|
| disabled        | _able.VAL          | moving          | MOVN               |
| acceleration    | ACCL               | resolution      | MRES               |
| back_accel      | BACC               | motor_status    | MSTA               |
| backlash        | BDST               | offset          | OFF                |
| back_speed      | BVEL               | output_mode     | OMSL               |
| card            | CARD               | output          | OUT                |
| dial_high_limit | DHLM               | prop_gain       | PCOF               |
| direction       | DIR                | precision       | PREC               |
| dial_low_limit  | DLLM               | readback        | RBV                |
| settle_time     | DLY                | retry_max       | RTRY               |
| done_moving     | DMOV               | retry_count     | RCNT               |
| dial_readback   | DRBV               | retry_deadband  | RDBD               |
| description     | DESC               | dial_difference | RDIF               |
| dial_drive      | DVAL               | raw_encoder_pos | REP                |
| units           | EGU                | raw_high_limit  | RHLS               |
| encoder_step    | ERES               | raw_low_limit   | RLLS               |
| freeze_offset   | FOFF               | relative_value  | RLV                |
| move_fraction   | FRAC               | raw_motor_pos   | RMP                |
| hi_severity     | HHSV               | raw_readback    | RRBV               |
| hi_alarm        | HIGH               | readback_res    | RRES               |
| hihi_alarm      | HIHI               | raw_drive       | RVAL               |
| high_limit      | HLM                | dial_speed      | RVEL               |
| high_limit_set  | HLS                | s_speed         | S                  |
| hw_limit        | HLSV               | s_back_speed    | SBAK               |
| home_forward    | HOMF               | s_base_speed    | SBAS               |
| home_reverse    | HOMR               | s_max_speed     | SMAX               |

Continued on next page

Table 1 – continued from previous page

| <b>alias</b>    | <i>Motor Record field</i> | <b>alias</b>  | <i>Motor Record field</i> |
|-----------------|---------------------------|---------------|---------------------------|
| high_op_range   | HOPR                      | set           | SET                       |
| high_severity   | HSV                       | stop_go       | SPMG                      |
| integral_gain   | ICOF                      | s_revolutions | SREV                      |
| jog_accel       | JAR                       | stop          | STOP                      |
| jog_forward     | JOGF                      | t_direction   | TDIR                      |
| jog_reverse     | JOGR                      | tweak_forward | TWF                       |
| jog_speed       | JVEL                      | tweak_reverse | TWR                       |
| last_dial_val   | LDVL                      | tweak_val     | TWV                       |
| low_limit       | LLM                       | use_encoder   | UEIP                      |
| low_limit_set   | LLS                       | u_revolutions | UREV                      |
| lo_severity     | LLSV                      | use_rdbl      | URIP                      |
| lolo_alarm      | LOLO                      | drive         | VAL                       |
| low_op_range    | LOPR                      | base_speed    | VBAS                      |
| low_alarm       | LOW                       | slew_speed    | VELO                      |
| last_rel_val    | LRLV                      | version       | VERS                      |
| last_dial_drive | LRVL                      | max_speed     | VMAX                      |
| last_SPMG       | LSPG                      | use_home      | ATHM                      |
| low_severity    | LSV                       | deriv_gain    | DCOF                      |

## 6.2.2 methods for `epics.Motor`

`motor.get(attr[, as_string=False])`  
sets a field attribute for the motor.

### Parameters

- **attr** (*string* (from table above)) – attribute name
- **as\_string** (*True/False*) – whether to return string value.

Note that `get()` can return the string value, while fetching the attribute cannot do so:

```
>>> m = epics.Motor('XXX:m1')
>>> print m.device_type
0
>>> print m.get('device_type', as_string=True)
'asynMotor'
```

`motor.put(attr, value[, wait=False[, timeout=30]])`  
sets a field attribute for the motor.

### Parameters

- **attr** (*string* (from table above)) – attribute name
- **value** – value for attribute
- **wait** (*True/False*) – whether to wait for completion.
- **timeout** (*float*) – time (in seconds) to wait before giving up trying to connect.

`motor.check_limits()`  
checks whether the current motor position is causing a motor limit violation, and raises a `MotorLimitException` if it is.

returns `None` if there is no limit violation.

`motor.within_limits (value[, limits='user'] )`  
checks whether a target value **would be** a limit violation.

#### Parameters

- **value** – target value
- **limits** (*string*) – one of 'user', 'dial', or 'raw' for which limits to consider

**Return type** True/False

`motor.move (val=None[, relative=None[, wait=False[, timeout=300.0[, dial=False[, raw=False[, ignore_limits=False[, confirm_move=False ]]]]]]])`  
moves motor to specified drive position.

#### Parameters

- **val** – value to move to (float) [Must be provided]
- **relative** – move relative to current position (T/F) [F]
- **wait** – whether to wait for move to complete (T/F) [F]
- **timeout** – max time for move to complete (in seconds) [300]
- **dial** – use dial coordinates (T/F) [F]
- **raw** – use raw coordinates (T/F) [F]
- **ignore\_limits** – try move without regard to limits (T/F) [F]
- **confirm\_move** – try to confirm that move has begun (when wait=False) (T/F) [F]

**Return type** integer

Returns an integer value, according the table below. Note that a return value of 0 with *wait=False* does not really guarantee a successful move, just that a move request was issued. If you're interested in checking that a requested move really did start without waiting for the move to complete, you may want to use the *confirm\_move=True* option.

Table of return values from *move()*.

| return value | meaning  |
|--------------|--|
| -13          | invalid value (cannot convert to float). Move not attempted. |
| -12          | target value outside soft limits. Move not attempted.        |
| -11          | drive PV is not connected: Move not attempted.               |
| -8           | move started, but timed-out.                                 |
| -7           | move started, timed-out, but appears done.                   |
| -5           | move started, unexpected return value from <i>put()</i>      |
| -4           | move-with-wait finished, soft limit violation seen.          |
| -3           | move-with-wait finished, hard limit violation seen.          |
| 0            | move-with-wait finish OK.                                    |
| 0            | move-without-wait executed, not confirmed.                   |
| 1            | move-without-wait executed, move confirmed.                  |
| 3            | move-without-wait finished, hard limit violation seen.       |
| 4            | move-without-wait finished, soft limit violation seen.       |

`motor.tweak (direction='forward'[, wait=False[, timeout=300. ] ] )`  
move the motor by the current *tweak value*

#### Parameters



- **direction** (*string*: 'forward' (default) or 'reverse') – direction of motion
- **wait** (*True/False*) – whether to wait for completion
- **timeout** (*float*) – max time for move to complete (in seconds) [default=300]

`motor.get_position(readback=False[, dial=False[, raw=False ]])`

Returns the motor position in user, dial or raw coordinates.

#### Parameters

- **readback** – whether to return the readback position in the desired coordinate system. The default is to return the drive position of the motor.
- **dial** – whether to return the position in dial coordinates. The default is user coordinates.
- **raw** – whether to return the raw position. The default is user coordinates.

The “raw” and “dial” keywords are mutually exclusive. The “readback” keyword can be used in user, dial or raw coordinates.

`motor.set_position(position[ dial=False[, raw=False ]])`

set (that is, redefine) the current position to supplied value.

#### Parameters

- **position** – The new motor position
- **dial** – whether to set in dial coordinates. The default is user coordinates.
- **raw** – whether to set in raw coordinates. The default is user coordinates.

The ‘raw’ and ‘dial’ keywords are mutually exclusive.

`motor.get_pv(attr)`

returns the *PV* for the corresponding attribute.

`motor.set_callback(attr='drive'[, callback=None[, kw=None ]])`

sets a callback on the *PV* for a particular attribute.

`motor.clear_callback(attr='drive')`

clears a callback on the *PV* for a particular attribute.

`motor.show_info()`

prints out a table of attributes and their current values.

## 6.3 Other Device Examples

An epics Device provides a general way to group together a set of *PVs*. The examples below show how to build on this generality, and may inspire you to build your own device classes.

### 6.3.1 A basic Device without a prefix

Here, we define a very simple device that does not even define a prefix. This is not much more than a collection of *PVs*. Since there is no prefix given, all *PVs* in the device must be *fully qualified*. Note that there is no requirement to share a common prefix in such a collection of *PVs*:



```

from epics import Device
dev = Device()
p1 = dev.PV('13IDC:m1.VAL')
p2 = dev.PV('13IDC:m2.VAL')
dev.put('13IDC:m1.VAL', 2.8)
dev.put('13IDC:m2.VAL', 3.0)
print dev.PV('13IDC:m3.DIR').get(as_string=True)

```

Note that this device cannot use the attributes based on field names.

This may not look very interesting – why not just use a bunch of PVs? If you consider *Device* to be a starting point for building more complicated objects by subclassing *Device* and adding specialized methods, then it can start to get interesting.

### 6.3.2 Epics ai record as Device

For a slightly more useful and typical example, the pyepics distribution includes a Device for an Epics ai (analog input record). The full implementation of this device is:

```

#!/usr/bin/env python
"""Epics analog input record"""
from .. import Device

class ai(Device):
    "Simple analog input device"

    attrs = ('VAL', 'EGU', 'HOPR', 'LOPR', 'PREC', 'NAME', 'DESC',
             'DTYP', 'INP', 'LINR', 'RVAL', 'ROFF', 'EGUF', 'EGUL',
             'AOFF', 'ASLO', 'ESLO', 'EOFF', 'SMOO', 'HIHI', 'LOLO',
             'HIGH', 'LOW', 'HHSV', 'LLSV', 'HSV', 'LSV', 'HYST')

    def __init__(self, prefix, **kwargs):
        if prefix.endswith('.'):
            prefix = prefix[:-1]
        Device.__init__(self, prefix, delim='.', attrs=self.attrs, **kwargs)

```

The code simply pre-defines the fields that are the *suffixes* of an Epics ai input record, and subclasses *Device* with these fields to create the corresponding PVs. For most record suffixes, these will be available as attributes of the Device object. For example, the *ai* class above can be used simply and cleanly as:

```

from epics.devices import ai
This_ai = ai('XXX.PRES')
print 'Value: ', This_ai.VAL
print 'Units: ', This_ai.EGU

```

Of course, you can also use the *get()*, *put()* methods above for a basic Device:

```

This_ai.put('DESC', 'My Pump')

```

Several of the other standard Epics records can easily be exposed as Devices in this way, and the pyepics distribution includes such simple wrappings for the Epics ao, bi, and bo records, as well as several more complex records from synApps.

### 6.3.3 Epics Scaler Record as Device

For a slightly more complicated example: an incomplete, but very useful mapping of the Scaler Record from synApps, including methods for changing modes, and reading and writing data.

```
#!/usr/bin/env python
"""Epics Scaler"""
from .. import Device, poll

class Scaler(Device):
    """
    Simple implementation of SynApps Scaler Record.
    """
    attrs = ('CNT', 'CONT', 'TP', 'T', 'VAL')
    attr_kws = {'calc_enable': '%s_calcEnable.VAL'}
    chan_attrs = ('NM%i', 'S%i')
    calc_attrs = {'calc%i': '%s_calc%i.VAL', 'expr%i': '%s_calc%i.CALC'}
    _nonpvs = ('_prefix', '_pvs', '_delim', '_nchan', '_chans')

    def __init__(self, prefix, nchan=8):
        self._nchan = nchan
        self._chans = range(1, nchan+1)

        attrs = list(self.attrs)
        for i in self._chans:
            for att in self.chan_attrs:
                attrs.append(att % i)

        Device.__init__(self, prefix, delim='.', attrs=attrs)

        for key, val in self.attr_kws.items():
            self.add_pv(val % prefix, attr= key)

        for i in self._chans:
            for key, val in self.calc_attrs.items():
                self.add_pv(val % (prefix, i), attr = key % i)
        self._mutable = False

    def AutoCountMode(self):
        "set to autocount mode"
        self.put('CONT', 1)

    def OneShotMode(self):
        "set to one shot mode"
        self.put('CONT', 0)

    def CountTime(self, ctime):
        "set count time"
        self.put('TP', ctime)

    def Count(self, ctime=None, wait=False):
        "set count, with optional counttime"
        if ctime is not None:
            self.CountTime(ctime)
        self.put('CNT', 1, wait=wait)
        poll()

    def EnableCalcs(self):
```

(continues on next page)

(continued from previous page)

```

    " enable calculations"
    self.put('calc_enable', 1)

    def setCalc(self, i, calc):
        "set the calculation for scaler i"
        attr = 'expr%i' % i
        self.put(attr, calc)

    def getNames(self):
        "get all names"
        return [self.get('NM%i' % i) for i in self._chans]

    def Read(self, use_calc=False):
        "read all values"
        attr = 'S%i'
        if use_calc:
            attr = 'calc%i'
        return [self.get(attr % i) for i in self._chans]

```

Note that we can then create a scaler object from its base PV prefix, and use methods like `Count()` and `Read()` without directly invoking epics calls:

```

s1 = Scaler('XXX:scaler1')
s1.setCalc(2, '(B-2000*A/10000000.)')
s1.enableCalcs()
s1.OneShotMode()
s1.Count(t=5.0, wait=True)
print 'Names: ', s1.getNames()
print 'Raw values: ', s1.Read(use_calc=False)
print 'Calc values: ', s1.Read(use_calc=True)

```

### 6.3.4 Other Devices included in PyEpics

Several other Epics Records have been exposed as Devices, and included in PyEpics distribution. These vary some in how complete and feature-rich they are, and are definitely skewed toward data collection at synchrotron beamlines. A table of current Devices are listed in the *Table of Included Epics Devices* table below. For further details, consult the source code for these modules.

Table of Epics Devices Included in the PyEpics distribution. For those described as “pretty basic”, there are generally only PV suffixes to attributes mapped. Many of the others include one or more methods for specific use of that Device.

| module         | class            | description                                    |
|----------------|------------------|--|
| ad_base        | AD_Camera        | areaDetector Camera, pretty basic              |
| ad_fileplugin  | AD_FilePlugin    | areaDetector File Plugin, many methods         |
| ad_image       | AD_ImagePlugin   | areaDetector Image, with ArrayData attribute   |
| ad_overlay     | AD_OverlayPlugin | areaDetector Overlay, pretty basic             |
| ad_perkinelmer | AD_PerkinElmer   | PerkinElmer(xrd1600) detector, several methods |
| ai             | ai               | analog input, pretty basic (as above)          |
| ao             | ao               | analog output, pretty basic                    |
| bi             | bi               | binary input, pretty basic                     |
| bo             | bo               | binary output, pretty basic                    |
| mca            | MCA              | epics DXP record, pretty basic                 |
| mca            | DXP              | epics MCA record, get_rois()/get_calib()       |
| mca            | MultiXMAP        | Multiple XIA XMaps, several methods            |
| scaler         | Scaler           | epics Scaler record, many methods              |
| scan           | Scan             | epics SScan record, some methods               |
| srs570         | SRS570           | SRS570 Amplifier                               |
| struck         | Struck           | SIS Multichannel Scaler, many methods          |
| transform      | Transform        | epics userTransform record                     |
| xspress3       | Xspress3         | Quantum Electronics Xspress3 Multi-MCA         |

## ALARMS: RESPOND WHEN A PV GOES OUT OF RANGE

### 7.1 Overview

The `alarm` module provides an `Alarm` object to specify an alarm condition and what to do when that condition is met.

```
class alarm.Alarm(pvname[, comparison=None[, trip_point=None[, callback=None[, alert_delay=10]]]])
```

creates an alarm object.

**param pvname** name of Epics PV (string)

**param comparison** operation used to compare PV value to trip\_point.

**type comparison** string or callable. Built in comparisons are listed in *Table of Alarm Operators*.

**param trip\_point** value that will trigger the alarm

**param callback** user-defined callback function to be run when the PVs value meets the alarm condition

**type callback** callable or None

**param alert\_delay** time (in seconds) to wait before executing another alarm callback.

The alarm works by checking the value of the PV each time it changes. If the new value is outside the acceptable range (violates the trip point), then the user-supplied callback function is run. This callback could be set to send a message or to take some other course of action.

The comparison supplied can either be a string as listed in *Table of Alarm Operators* or a custom callable function which takes the two values (PV.value, trip\_point) and returns `True` or `False` based on those values.

Table of built-in Operators for Alarms:

| <i>operator</i> | Python operator     |
|-----------------|---------------------|
| 'eq', '=='      | <code>__eq__</code> |
| 'ne', '!='      | <code>__ne__</code> |
| 'le', '<='      | <code>__le__</code> |
| 'lt', '<'       | <code>__lt__</code> |
| 'ge', '>='      | <code>__ge__</code> |
| 'gt', '>'       | <code>__gt__</code> |

The `alert_delay` prevents the alarm callback from being called too many times. For PVs with floating point values, the value may fluctuate around the trip\_point for a while. If the value violates the trip\_point, then momentarily goes back to an acceptable value, and back again to a violating value, it may not be desirable to send repeated, identical

messages. To prevent this situation, the alarm callback will be called when the alarm condition is met **and** the callback was not called within the time specified by `alert_delay`.

## 7.2 Alarm Example

An epics Alarm is very easy to use. Here is an alarm set to print a message when a PV's value reaches a certain value:

```
from epics import Alarm, poll

def alertMe(pvname=None, char_value=None, **kw):
    print "Soup's on!  %s = %s" % (pvname, char_value)

my_alarm = Alarm(pvname = 'WaterTemperature.VAL',
                 comparison = '>',
                 callback = alertMe,
                 trip_point = 100.0,
                 alert_delay = 600)

while True:
    poll()
```

## AUTO-SAVING: SIMPLE SAVE/RESTORE OF PVS

The `autosave` module provides simple save/restore functionality for PVs, with the functions `save_pvs()` and `restore_pvs()`, and an `AutoSaver` class. These are similar to the autosave module from synApps for IOCs in that they use a compatible *request file* which describes the PVs to save, and a compatible *save file* which holds the saved values. Of course, the reading and writing is done here via Channel Access, and need not be related to an single IOC.

Use of this module requires the `pyparsing` package to be installed. This is a fairly common third-party python package, included in many package managers, or installed with tools such as *easy\_install* or *pip*, or downloaded from [PyPI](#)

Request and Save file formats are designed to be compatible with synApps autosave. Notably, the *file* command with macro substitutions are supported, so that one can have a Request like:

```
# My.req
file "SimpleMotor.req", P=IOC:, Q=m1
```

with a **SimpleMotor.req** file of:

```
# SimpleMotor.req
$(P)$(Q).VAL
$(P)$(Q).DIR
$(P)$(Q).FOFF
```

which can then be used for many instances of a SimpleMotor. There is, however, no automated mechanism for finding request files. You will need to include these in the working directory or specify absolute paths.

With such a file, simply using:

```
import epics.autosave
epics.autosave.save_pvs("My.req", "my_values.sav")
```

will save the current values for the PVs to the file **my\_values.sav**. At a later time, these values can be restored with:

```
import epics.autosave
epics.autosave.restore_pvs("my_values.sav")
```

The saved file will be of nearly identical format as that of the autosave mechanism, and the `restore_pvs()` function can read and restore values using save files from autosave. Note, however, that the purpose here is quite different from that of the standard autosave module (which is designed to save vales so that PVs can be **initialized** at IOC startup). Using the functions here will really do a `caput()` to the saved values.

`autosave.save_pvs(request_file, save_file)`  
saves current value of PVs listed in *request\_file* to the *save\_file*

### Parameters

- **request\_file** – name of Request file to read PVs to save.

- **save\_file** – name of file to save values to write values to

As discussed above, the **request\_file** follows the conventions of the autosave module from synApps.

`autosave.restore_pvs(save_file)`

reads values from *save\_file* and restores them for the corresponding PVs

**Parameters** **save\_file** – name of file to save values to read data from.

Note that `restore_pvs()` will restore all the values it can, skipping over any values that it cannot restore.

## 8.1 AutoSaver class

The *AutoSaver* class provides a convenient way to repeatedly save PVs listed in a request file without having to re-connect all of the PVs. The *AutoSaver* retains the PV connections, and provides a simple `save()` method to save the current PV values to a file. By default, that file will be named from the request file and the current time. This allows you to do something like this:

```
#!/usr/bin/env python
# save PVs from a request file once per minute
import time
from epics.autosave import AutoSaver
my_saver = AutoSaver("My.req")

# save all PVs every minute for a day
t0 = time.time()
while True:
    if time.localtime().tm_sec < 5:
        my_saver.save()
        time.sleep(30 - time.localtime().tm_sec)
    if time.time() - t0 > 86400.0:
        break
    time.sleep(0.5)
```

This will save PVs to files with names like *My\_2017Oct02\_141800.sav*

**class** `autosave.AutoSaver(request_file)`  
create an Automatic Saver based on a request file.

**Parameters** **request\_file** – name of request file

*AutoSaver* has two methods: `read_request_file()` to read a request file, and `save()` to save the results.

`autosave.read_request_file(request_file)`

read and parse request file, begin making PV connections

**Parameters** **request\_file** – name of request file

`autosave.save(save_file=None, verbose=False)`

read current PV values, write save file.

**Parameters**

- **save\_file** – name of save file or *None*. If *None*, the name of the request file and timestamp (to seconds) will be used to build a file name. Note that there is no check for overwriting files.
- **verbose** – whether to print results to the screen [default *False*]



## 8.2 Supported Data Types

All scalar PV values can be saved and restored with the *autosave* routines. There is some support for waveform (array) data. For example, character waveforms containing long strings can be saved and restored. In addition, numerical arrays in waveform can be saved and restored. For array data, the results may not be fully compatible with the autosave module.

### 8.2.1 Examples

A simple example using the autosave module:

```
import epics.autosave
# save values
epics.autosave.save_pvs("my_request_file.req",
                        "/tmp/my_recent_save.sav")

# wait 30 seconds
time.sleep(30)

# restore those values back
epics.autosave.restore_pvs("/tmp/my_recent_save.sav")
```



## WX: WXPYTHON WIDGETS FOR EPICS

The `wx` module of `epics` (that is, `epics.wx`) provides a set of wxPython classes for epics PVs. Most of these are derived from wxPython widgets, with special support added for epics PVs, especially regarding when to automatically update the widget based on a changing value for a PV.

Some examples of code that uses pyepics and wxPython are included in the `scripts` folder of the pyepics source distribution kit. In addition, there are some full-fledged applications using Epics and wxPython at [pyepics applications](#).

### 9.1 PV-aware Widgets

Several basic wxPython widgets have been extended so as to connect the widget with a corresponding *PV*. For example, setting the text value of a `PVTextCtrl` will forward that value to the epics *PV*, and if the *PV* is changed by externally, the value displayed in the widget will be automatically updated.

#### 9.1.1 PVMixin

```
class wx.PVMixin ([pv=None[, pvname=None]])
```

This is a mixin class for wx Controls with epics PVs: This connects to PV, and manages connection and callback events for the PV. It provides the following basic methods used by most of the PV<->widget classes below.

```
wx.SetPV (pv=None)
```

set the PV corresponding to the widget.

```
wx.Update (value=None)
```

set the widgets value from the PV's value. If value="None", the current value for the PV is used.

```
wx.GetValue (as_string=True)
```

return the PVs value.

```
wx.OnEpicsConnect ()
```

PV connection event handler.

```
wx.OnPVChange (value)
```

PV monitor (subscription) event handler. Must be overwritten for each widget type.

```
wx.GetEnumStrings ()
```

return enumeration strings for the PV

#### 9.1.2 PVCtrlMixin

```
class wx.PVCtrlMixin (parent, pv=None, font=None, fg=None, bg=None, **kw)
```

This is a mixin class for wx Controls with epics PVs: This subclasses PVCtrlMixin and adds colour translations PV, and manages callback events for the PV.

#### Parameters

- **parent** – wx parent widget
- **pv** – epics.PV
- **font** – wx.Font for display
- **fg** – foreground colour
- **bg** – background colour

A class that inherits from this class **must** provide a method called `_SetValue`, which will set the contents of the corresponding widget when the PV's value changes.

In general, the widgets will automatically update when the PV changes. Where appropriate, setting the value with the widget will set the PV value.

### 9.1.3 PVText

```
class wx.PVText (parent, pv=None, font=None, fg=None, bg=None, minor_alarm="DARKRED",  
                 major_alarm="RED", invalid_alarm="ORANGERED", auto_units=False, units="",  
                 **kw)
```

derived from wx.StaticText and PVCtrlMixin, this is a StaticText widget whose value is set to the string representation of the value for the corresponding PV.

By default, the text colour will be overridden when the PV enters an alarm state. These colours can be modified (or disabled by being set to `None`) as part of the constructor.

“units” specifies a unit suffix (like ‘ A ’ or ‘ mm ’) to put after the text value whenever it is displayed.

Alternatively, “auto\_units” means the control will automatically display the “EGU” units value from the PV, whenever it updates. If this value is set, “units” is ignored. A space is inserted between the value and the unit.

### 9.1.4 PVTextCtrl

```
class wx.PVTextCtrl (parent, pv=None, font=None, fg=None, bg=None, dirty_timeout=2500, **kw)
```

derived from wx.TextCtrl and PVCtrlMixin, this is a TextCtrl widget whose value is set to the string representation of the value for the corresponding PV.

Setting the value (hitting Return or Enter) or changing focus away from the widget will set the PV value immediately. Otherwise, the widget will wait for ‘dirty\_timeout’ milliseconds after the last keypress and then set the PV value to whatever is written in the field.

### 9.1.5 PVFloatCtrl

```
class wx.PVFloatCtrl (parent, pv=None, font=None, fg=None, bg=None, **kw)
```

A special variation of a wx.TextCtrl that allows only floating point numbers, as associated with a double, float, or integer PV. Trying to type in a non-numerical value will be ignored. Furthermore, if a PV's limits can be determined, they will be used to limit the allowed range of input values. For a value that is within limits, the value will be *put* to the PV on return. Out-of-limit values will be highlighted in a different color.

### 9.1.6 PVBitmap

**class** wx.PVBitmap (*parent, pv=None, bitmaps={}, defaultBitmap=None*)

A Static Bitmap where the image is based on PV value.

If the bitmaps dictionary is set, it should be set as PV.Value(Bitmap) where particular bitmaps will be shown if the PV takes those certain values.

If you need to do any more complex or dynamic drawing, you may want to look at the OGL PV controls.

### 9.1.7 PVCheckBox

**class** wx.PVCheckBox (*self, parent, pv=None, on\_value=1, off\_value=0, \*\*kw*)

Checkbox based on a binary PV value, both reads/writes the PV on changes. on\_value and off\_value are the specific values that are mapped to the checkbox.

There are multiple options for translating PV values to checkbox settings (from least to most complex):

- Use a PV with values 0 and 1
- Use a PV with values that convert via Python's own bool(x)
- Set on\_value and off\_value in the constructor
- Use SetTranslations() to set a dictionary for converting various PV values to booleans.

### 9.1.8 PVFloatSpin

**class** wx.PVFloatSpin (*parent, pv=None, deadTime=500, min\_val=None, max\_val=None, increment=1.0, digits=-1, \*\*kw*)

A FloatSpin is a floating point spin control with buttons to increase and decrease the value by a particular increment. Arrow keys and page up/down can also be used (the latter changes the value by 10x the increment.)

PVFloatSpin is a special derivation that assigns a PV to the FloatSpin control. deadTime is the delay (in milliseconds) between when the user finishes typing a value and when the PV is set to it (to prevent half-typed numeric values being set.)

### 9.1.9 PVButton

**PVButton** (*parent, pv=None, pushValue=1, disablePV=None, disableValue=1, \*\*kw*)

A wx.Button linked to a PV. When the button is pressed, 'pushValue' is written to the PV (useful for momentary PVs with HIGH= set.) Setting disablePV and disableValue will automatically cause the button to disable when that PV has a certain value.

### 9.1.10 PVRadioButton

**class** wx.PVRadioButton (*parent, pv=None, pvValue=None, \*\*kw*)

A PVRadioButton is a radio button associated with a particular PV and one particular value.

Suggested for use in a group where all radio buttons are PVRadioButtons, and they all have a discrete value set.

### 9.1.11 PVComboBox

**class** wx.PVComboBox (*parent, pv=None, \*\*kw*)

A ComboBox linked to a PV. Both reads/writes the combo value on changes.

### 9.1.12 PVEnumComboBox

**class** wx.PVEnumComboBox (*parent, pv=None, \*\*kw*)

A ComboBox linked to an “enum” type PV (such as bi,bo,mbbi,mbbo.) The ComboBox is automatically populated with a non-editable list of the PV enum values, allowing the user to select them from the drop-down.

Both reads/writes the combo value on changes.

### 9.1.13 PVEnumButtons

**class** wx.PVEnumButtons (*parent, pv=None, font=None, fg=None, bg=None, \*\*kw*)

This will create a wx.Panel of buttons (a button bar), 1 for each enumeration state of an enum PV. The set of buttons will correspond to the current state of the PV

### 9.1.14 PVEnumChoice

**class** wx.PVEnumChoice (*parent, pv=None, font=None, fg=None, bg=None, \*\*kw*)

This will create a dropdown list (a wx.Choice) with a list of enumeration states for an enum PV.

### 9.1.15 PVAlarm

**class** wx.PVAlarm (*parent, pv=None, font=None, fg=None, bg=None, trip\_point=None, \*\*kw*)

This will create a pop-up message (wx.MessageDialog) that is shown when the corresponding PV trips the alarm level.

### 9.1.16 PVCollapsiblePane

**class** wx.PVCollapsiblePane (*parent, pv=None, minor\_alarm="DARKRED", major\_alarm="RED",  
invalid\_alarm="ORANGERED", \*\*kw*)

This is equivalent to wx.CollapsiblePane, except the label shown on the pane’s “expansion button” comes from a PV.

The additional keyword arguments can be any of the other constructor arguments supported by wx.CollapsiblePane.

By default, the foreground colour of the pane button will be overridden when the PV enters an alarm state. On GTK, this means the colour of the triangular drop-down button but not the label text. These colours can be modified (or disabled by being set to None) as part of the constructor.

Supports the .SetTranslation() method, whose argument is a dictionary mapping PV values to display labels. If the PV value is not found in the dictionary, it will displayed verbatim as the label.

## 9.2 Decorators and other Utility Functions

`wx.DelayedEpicsCallback()`

decorator to wrap an Epics callback in a `wx.CallAfter`, so that the `wx` and `epics ca` threads do not clash. This also checks for dead `wxPython` objects (say, from a closed window), and remove callbacks to them.

`wx.EpicsFunction()`

decorator to wrap function in a `wx.CallAfter()` so that Epics calls can be made in a separate thread, and asynchronously.

This decorator should be used for all code that mix calls to `wx` and `epics`

`wx.finalize_epics()`

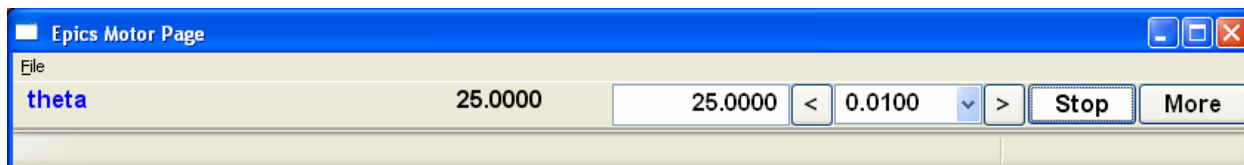
This function will finalize `epics`, and close all Channel Access communication, by calling `epics.ca.finalize_libca()`. This may be useful when closing an application, as in a method bound to `wx.EVT_CLOSE` event from a top-level application window. Be careful to **not** call this function when closing a Window if your application is not closing, and if you are still doing any Channel Access work in the other windows.

## 9.3 wxMotorPanel Widget

A dedicated `wx` Widget for Epics Motors is included in the `wx` module that provides an easy-to-use Motor panel that is similar to the normal MEDM window, but with a few niceties from the more sophisticated `wx` toolkit. This widget can be used simply as:

```
import wx
from epics.wx import MotorPanel
....
mymotor = MotorPanel(parent, 'XXX:m1')
```

A sample panel looks like this



Which shows from right to left: the motor description, an information message (blank most of the time), the readback value, the drive value, arrows to tweak the motor, and a drop-down combobox for tweak values, a “Stop” button and a “More” button. The panel has the following features:

- All controls are “live” and will respond to changes from other source.
- The values for the tweak values in the ComboBox are automatically generated from the precision and travel range of the motor.
- The entry box for the drive value will *only* accept numeric input, and will only set the drive value when hitting Enter or Return.
- The drive value will change to Red text on a Yellow background when the value in the box violates the motors (user) limits. If Enter or Return when the the displayed value violates the limit, the motor will not be moved, but the displayed value will be changed to the closest limit value.
- Pressing the “Stop” button will stop the motor (with the `.SPMG` field), and set the Info field to “Stopped”. The button label will change to “Go”, and the motor will not move until this button is pressed.

Finally, the “More” button will bring up a more complete form of Motor parameters that looks like:

**Motor Details: 13XRM:m3 | theta**

13XRM:m3: (asynMotor)

Label:  units:

---

**Drive**

|            | User  | Dial                                    | Raw  |                                      |
|------------|---|---|--|--------------------------------------|
| High Limit | <input type="text" value="1500.0000"/>  | <input type="text" value="1500.0000"/>  |  | <input type="button" value="Stop"/>  |
| Readback   | <input type="text" value="25.0000"/>  | <input type="text" value="25.0000"/>    | <input type="text" value="50000"/>   | <input type="button" value="Pause"/> |
| Move       | <input type="text" value="25.0000"/>  | <input type="text" value="25.0000"/>    | <input type="text" value="50000"/>   | <input type="button" value="Move"/>  |
| Low Limit  | <input type="text" value="-1500.0000"/>   | <input type="text" value="-1500.0000"/> |  | <input type="button" value="Go"/>    |
| Tweak      | <input type="button" value="←"/> <input type="text" value="0.0100"/> <input type="button" value="→"/> |   | <input type="button" value="Enable"/> <input type="button" value="Disable"/> |                                      |

---

**Calibration**

Mode:   Freeze Offset:

Direction:   Offset Value:

---

**Dynamics**

|                    | Normal                               | Backlash                            |
|--------------------|--------------------------------------|-------------------------------------|
| Max Speed          | <input type="text" value="20.0000"/> |                                     |
| Speed              | <input type="text" value="20.0000"/> | <input type="text" value="1.0000"/> |
| Base Speed         | <input type="text" value="1.0000"/>  |                                     |
| Accel (s)          | <input type="text" value="0.5000"/>  | <input type="text" value="0.2000"/> |
| Backslash Distance |                                      | <input type="text" value="0.0000"/> |
| Move Fraction      |                                      | <input type="text" value="1.0000"/> |

---

**Resolution**

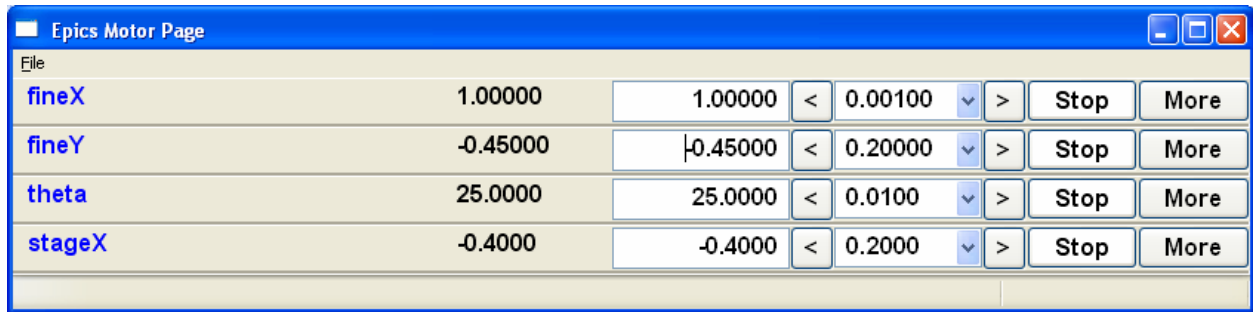
|             |                                     |             |                                     |
|-------------|-------------------------------------|-------------|-------------------------------------|
| Motor Res   | <input type="text" value="0.0005"/> | Encoder Res | <input type="text" value="0.0005"/> |
| Steps / Rev | <input type="text" value="2000"/>   | Units / Rev | <input type="text" value="1.0000"/> |
| Precision   | <input type="text" value="4"/>      |             |                                     |

Many such MotorPanels can be put in a vertical stack, as generated from the ‘wx\_motor.py’ script in the scripts folder of the source distribution as:



```
~>python wx_motor.py XXX:m1 XXX:m2 XXX:m3 XXX:m4
```

will look like this:



## 9.4 OGL Classes

OGL is a graphics drawing library shipped with wxPython. Is it built around the concept of “shapes” which are added to “canvases” and can be moved, scrolled, zoomed, animated, etc.

There is a PVShapeMixin class which allows PV callback functionality to be added to any OGL Shape class, and there are also PVRectangle and PVCircle subclasses already created.

A recommended way to use these OGL classes is to make a static bitmap background for your display, place it in an OGL Canvas and then add an overlay of shapes which appear/disappear/resize/change colour based on the PV values.

### 9.4.1 PVShapeMixin

**class** `wx.PVShapeMixin` (*self*, *pv=None*, *pvname=None*)

Similar to PVMixin, this mixin should be added to any ogl.Shape subclass that needs PV callback support.

The main method is PVChanged(*self*, *raw\_value*), which should be overridden in the subclass to provide specific processing based on the changed value.

There are also some built-in pieces of functionality. These are enough to do simple show/hide or change colour shape functionality, without needing to write specific code.

SetBrushTranslations(*translations*) allows setting a dict of PV Value -> wx.Brush mappings, which can be used to automatically repaint the shape foreground (fill) when the PV changes.

SetPenTranslations(*translations*) similar to brush translations, but the values are wx.Pen instances that are used to repaint the shape outline when the PV changes.

SetShownTranslations(*translations*) sets a dictionary of PV Value -> bool values which are used to show/hide the shape depending on the PV value, as it changes.

### 9.4.2 PVRectangle

**class** `wx.PVRectangle` (*self*, *w*, *h*, *pv=None*, *pvname=None*)

A PVCtrlMixin for the Rectangle shape class.

### 9.4.3 PVCircle

```
class wx.PVCircle(self, diameter, pv=None, pvname=None)
```

A PVCtrlMixin for the Circle shape class.

## ADVANCED TOPIC WITH PYTHON CHANNEL ACCESS

This chapter contains a variety of “usage notes” and implementation details that may help in getting the best performance from the pyepics module.

### 10.1 The wait and timeout options for `get()`, `ca.get_complete()`

The `get` functions, `epics.caget()`, `pv.get()` and `epics.ca.get()` all ask for data to be transferred over the network. For large data arrays or slow networks, this can take a noticeable amount of time. For PVs that have been disconnected, the `get` call will fail to return a value at all. For this reason, these functions all take a `timeout` keyword option. The lowest level `epics.ca.get()` also has a `wait` option, and a companion function `epics.ca.get_complete()`. This section describes the details of these.

If you’re using `epics.caget()` or `pv.get()` you can supply a timeout value. If the value returned is `None`, then either the PV has truly disconnected or the timeout passed before receiving the value. If the `get` is incomplete, in that the PV is connected but the data has simply not been received yet, a subsequent `epics.caget()` or `pv.get()` will eventually complete and receive the value. That is, if a PV for a large waveform record reports that it is connected, but a `pv.get()` returns `None`, simply trying again later will probably work:

```
>>> p = epics.PV('LargeWaveform')
>>> val = p.get()
>>> val
>>> time.sleep(10)
>>> val = p.get()
```

At the lowest level (which `pv.get()` and `epics.caget()` use), `epics.ca.get()` issues a get-request with an internal callback function. That is, it calls the CA library function `libca.ca_array_get_callback()` with a pre-defined callback function. With `wait=True` (the default), `epics.ca.get()` then waits up to the timeout or until the CA library calls the specified callback function. If the callback has been called, the value can then be converted and returned.

If the callback is not called in time or if `wait=False` is used but the PV is connected, the callback will be called eventually, and simply waiting (or using `epics.ca.pend_event()` if `epics.ca.PREEMPTIVE_CALLBACK` is `False`) may be sufficient for the data to arrive. Under this condition, you can call `epics.ca.get_complete()`, which will NOT issue a new request for data to be sent, but wait (for up to a timeout time) for the previous get request to complete.

`epics.ca.get_complete()` will return `None` if the timeout is exceeded or if there is not an “incomplete get” that it can wait to complete. Thus, you should use the return value from `epics.ca.get_complete()` with care.

Note that `pv.get()` (and so `epics.caget()`) will normally rely on the PV value to be filled in automatically by monitor callbacks. If monitor callbacks are disabled (as is done for large arrays and can be turned off) or if the monitor hasn’t been called yet, `pv.get()` will check whether it should call `epics.ca.get()` or `epics.ca.get_complete()`.

If not specified, the timeout for `epics.ca.get_complete()` (and all other get functions) will be set to:

```
timeout = 0.5 + log10(count)
```

Again, that's the maximum time that will be waited, and if the data is received faster than that, the `get` will return as soon as it can.

## 10.2 Strategies for connecting to a large number of PVs

Occasionally, you may find that you need to quickly connect to a large number of PVs, say to write values to disk. The most straightforward way to do this, say:

```
import epics

pvnamelist = read_list_pvs()
pv_vals = {}
for name in pvnamelist:
    pv = epics.PV(name)
    pv_vals[name] = pv.get()
```

or even just:

```
values = [epics.caget(name) for name in pvnamelist]
```

does incur some performance penalty. To minimize the penalty, we need to understand its cause.

Creating a *PV* object (using any of `pv.PV`, or `pv.get_pv()`, or `epics.caget()`) will automatically use connection and event callbacks in an attempt to keep the *PV* alive and up-to-date during the session. Normally, this is an advantage, as you don't need to explicitly deal with many aspects of Channel Access. But creating a *PV* does request some network traffic, and the *PV* will not be “fully connected” and ready to do a `PV.get()` until all the connection and event callbacks are established. In fact, `PV.get()` will not run until those connections are all established. This takes very close to 30 milliseconds for each *PV*. That is, for 1000 *PVs*, the above approach will take about 30 seconds.

The simplest remedy is to allow all those connections to happen in parallel and in the background by first creating all the *PVs* and then getting their values. That would look like:

```
# improve time to get multiple PVs: Method 1
import epics

pvnamelist = read_list_pvs()
pvs = [epics.PV(name) for name in pvnamelist]
values = [p.get() for p in pvs]
```

Though it doesn't look that different, this improves performance by a factor of 100, so that getting 1000 *PV* values will take around 0.4 seconds.

Can it be improved further? The answer is Yes, but at a price. For the discussion here, we'll can the original version “Method 0” and the method of creating all the *PVs* then getting their values “Method 1”. With both of these approaches, the script has fully connected *PV* objects for all *PVs* named, so that subsequent use of these *PVs* will be very efficient.

But this can be made even faster by turning off any connection or event callbacks, avoiding *PV* objects altogether, and using the `epics.ca` interface. This has been encapsulated into `epics.caget_many()` which can be used as:

```
# get multiple PVs as fast as possible: Method 2
import epics
```

(continues on next page)

(continued from previous page)

```
pvnamelist = read_list_pvs()
values = epics.caget_many(pvlist)
```

In tests using 1000 PVs that were all really connected, Method 2 will take about 0.25 seconds, compared to 0.4 seconds for Method 1 and 30 seconds for Method 0. To understand what `epics.caget_many()` is doing, a more complete version of this looks like this:

```
# epics.caget_many made explicit: Method 3
from epics import ca

pvnamelist = read_list_pvs()

pvdata = {}
pvchids = []
# create, don't connect or create callbacks
for name in pvnamelist:
    chid = ca.create_channel(name, connect=False, auto_cb=False) # note 1
    pvchids.append(chid)

# connect
for chid in pvchids:
    ca.connect_channel(chid)

# request get, but do not wait for result
ca.poll()
for chid in pvchids:
    ca.get(chid, wait=False) # note 2

# now wait for get() to complete
ca.poll()
for chid in pvchids:
    val = ca.get_complete(data[0])
    pvdata[ca.name(chid)] = val
```

The code here probably needs detailed explanation. As mentioned above, it uses the `ca` level, not `PV` objects. Second, the call to `epics.ca.create_channel()` (Note 1) uses `connect=False` and `auto_cb=False` which mean to not wait for a connection before returning, and to not automatically assign a connection callback. Normally, these are not what you want, as you want a connected channel and to be informed if the connection state changes, but we're aiming for maximum speed here. We then use `epics.ca.connect_channel()` to connect all the channels. Next (Note 2), we tell the CA library to request the data for the channel without waiting around to receive it. The main point of not having `epics.ca.get()` wait for the data for each channel as we go is that each data transfer takes time. Instead we request data to be sent in a separate thread for all channels without waiting. Then we do wait by calling `epics.ca.poll()` once and only once, (not `len(pvnamelist)` times!). Finally, we use the `epics.ca.get_complete()` method to convert the data that has now been received by the companion thread to a python value.

Method 2 and 3 have essentially the same runtime, which is somewhat faster than Method 1, and much faster than Method 0. Which method you should use depends on use case. In fact, the test shown here only gets the PV values once. If you're writing a script to get 1000 PVs, write them to disk, and exit, then Method 2 (`epics.caget_many()`) may be exactly what you want. But if your script will get 1000 PVs and stay alive doing other work, or even if it runs a loop to get 1000 PVs and write them to disk once a minute, then Method 1 will actually be faster. That is doing `epics.caget_many()` in a loop, as with:

```
# caget_many() 10 times
import epics
import time
```

(continues on next page)

(continued from previous page)

```

pvnamelist = read_list_pvs()
for i in range(10):
    values = epics.ca.get_many(pvlist)
    time.sleep(0.01)

```

will take around considerably *longer* than creating the PVs once and getting their values in a loop with:

```

# pv.get() 10 times
import epics
import time
pvnamelist = read_list_pvs()
pvs = [epics.PV(name) for name in pvnamelist]
for i in range(10):
    values = [p.get() for p in pvs]
    time.sleep(0.01)

```

In tests with 1000 PVs, looping with `epics.ca.get_many()` took about 1.5 seconds, while the version looping over `PV.get()` took about 0.5 seconds.

To be clear, it is **connecting** to Epics PVs that is expensive, not the retrieving of data from connected PVs. You can lower the connection expense by not retaining the connection or creating monitors on the PVs, but if you are going to re-use the PVs, that savings will be lost quickly. In short, use Method 1 over `epics.ca.get_many()` unless you've benchmarked your use-case and have demonstrated that `epics.ca.get_many()` is better for your needs.

## 10.3 time.sleep() or epics.poll()?

In order for a program to communicate with Epics devices, it needs to allow some time for this communication to happen. With `epics.ca.PREEMPTIVE_CALLBACK` set to `True`, this communication will be handled in a thread separate from the main Python thread. This means that CA events can happen at any time, and `epics.ca.pend_event()` does not need to be called to explicitly allow for event processing.

Still, some time must be released from the main Python thread on occasion in order for events to be processed. The simplest way to do this is with `time.sleep()`, so that an event loop can simply be:

```

>>> while True:
>>>     time.sleep(0.001)

```

Unfortunately, the `time.sleep()` method is not a very high-resolution clock, with typical resolutions of 1 to 10 ms, depending on the system. Thus, even though events will be asynchronously generated and epics with pre-emptive callbacks does not *require* `epics.ca.pend_event()` or `epics.ca.poll()` to be run, better performance may be achieved with an event loop of:

```

>>> while True:
>>>     epics.poll(evt=1.e-5, iot=0.1)

```

as the loop will be run more often than using `time.sleep()`.

## 10.4 Using Python Threads

An important feature of the PyEpics package is that it can be used with Python threads, as Epics 3.14 supports threads for client code. Even in the best of cases, working with threads can be somewhat tricky and lead to unexpected behavior, and the Channel Access library adds a small level of complication for using CA with Python threads. The

result is that some precautions may be in order when using PyEpics and threads. This section discusses the strategies for using threads with PyEpics.

First, to use threads with Channel Access, you must have `epics.ca.PREEMPTIVE_CALLBACK = True`. This is the default value, but if `epics.ca.PREEMPTIVE_CALLBACK` has been set to `False`, threading will not work.

Second, if you are using PV objects and not making heavy use of the `epics.ca` module (that is, not making and passing around chids), then the complications below are mostly hidden from you. If you're writing threaded code, it's probably a good idea to read this just to understand what the issues are.

### 10.4.1 Channel Access Contexts

The Channel Access library uses a concept of *contexts* for its own thread model, with contexts holding sets of threads as well as Channels and Process Variables. For non-threaded work, a process will use a single context that is initialized prior doing any real CA work (done in `epics.ca.initialize_libca()`). In a threaded application, each new thread begins with a new, uninitialized context that must be initialized or replaced. Thus each new python thread that will interact with CA must either explicitly create its own context with `epics.ca.create_context()` (and then, being a good citizen, destroy this context as the thread ends with `epics.ca.destroy_context()` or attach to an existing context.

The generally recommended approach is to use a single CA context throughout an entire process and have each thread attach to the first context created (probably from the main thread). This avoids many potential pitfalls (and crashes), and can be done fairly simply. It is the default mode when using PV objects.

The most explicit use of contexts is to put `epics.ca.create_context()` at the start of each function call as a thread target, and `epics.ca.destroy_context()` at the end of each thread. This will cause all the activity in that thread to be done in its own context. This works, but means more care is needed, and so is not the recommended.

The best way to attach to the initially created context is to call `epics.ca.use_initial_context()` before any other CA calls in each function that will be called by `Thread.run()`. Equivalently, you can add a `withInitialContext()` decorator to the function. Creating a PV object will implicitly do this for you, as long as it is your first CA action in the function. Each time you do a `PV.get()` or `PV.put()` (or a few other methods), it will also check that the initial context is being used.

Of course, this approach requires CA to be initialized already. Doing that *in the main thread* is highly recommended. If it happens in a child thread, that thread must exist for all CA work, so either the life of the process or with great care for processes that do only some CA calls. If you are writing a threaded application in which the first real CA calls are inside a child thread, it is recommended that you initialize CA in the main thread,

As a convenience, the `CAThread` in the `epics.ca` module is a very thin wrapper around the standard `threading.Thread` which adding a call of `epics.ca.use_initial_context()` just before your threaded function is run. This allows your target functions to not explicitly set the context, but still ensures that the initial context is used in all functions.

### 10.4.2 How to work with CA and Threads

Summarizing the discussion above, to use threads you must use run in `PREEMPTIVE_CALLBACK` mode. Furthermore, it is recommended that you use a single context, and that you initialize CA in the main program thread so that your single CA context belongs to the main thread. Using PV objects exclusively makes this easy, but it can also be accomplished relatively easily using the lower-level `ca` interface. The options for using threads (in approximate order of reliability) are then:

1. use PV objects for threading work. This ensures you're working in a single CA context.
2. use `CAThread` instead of `Thread` for threads that will use CA calls.

3. put `epics.ca.use_initial_context()` at the top of all functions that might be a Thread target function, or decorate them with `withInitialContext()` decorator, `@withInitialContext`.
4. use `epics.ca.create_context()` at the top of all functions that are inside a new thread, and be sure to put `epics.ca.destroy_context()` at the end of the function.
5. ignore this advise and hope for the best. If you're not creating new PVs and only reading values of PVs created in the main thread inside a child thread, you may not see a problems, at least not until you try to do something fancier.

### 10.4.3 Thread Examples

This is a simplified version of test code using Python threads. It is based on code originally from Friedrich Schotte, NIH, and included as `thread_test.py` in the `tests` directory of the source distribution.

In this example, we define a `run_test` procedure which will create PVs from a supplied list, and monitor these PVs, printing out the values when they change. Two threads are created and run concurrently, with overlapping PV lists, though one thread is run for a shorter time than the other.

```
"""This script tests using EPICS CA and Python threads together
Based on code from Friedrich Schotte, NIH, modified by Matt Newville
19-Apr-2010
"""
import time
from sys import stdout
from threading import Thread
import epics
from epics.ca import CAThread

from pvnames import updating_pvlist
pvlist_a = updating_pvlist[:-1]
pvlist_b = updating_pvlist[1:]

def run_test(runtime=1, pvnames=None, run_name='thread c'):
    msg = '-> thread "%s" will run for %.3f sec, monitoring %s\n'
    stdout.write(msg % (run_name, runtime, pvnames))
    def onChanges(pvname=None, value=None, char_value=None, **kw):
        stdout.write('  %s = %s (%s)\n' % (pvname, char_value, run_name))
        stdout.flush()

    # epics.ca.use_initial_context() # epics.ca.create_context()
    start_time = time.time()
    pvs = [epics.PV(pvn, callback=onChanges) for pvn in pvnames]

    while time.time()-start_time < runtime:
        time.sleep(0.1)

    [p.clear_callbacks() for p in pvs]
    stdout.write('Completed Thread %s\n' % (run_name))

stdout.write("First, create a PV in the main thread:\n")
p = epics.PV(updating_pvlist[0])

stdout.write("Run 2 Background Threads simultaneously:\n")
th1 = CAThread(target=run_test, args=(3, pvlist_a, 'A'))
th1.start()
```

(continues on next page)



(continued from previous page)

```

th2 = CATHread(target=run_test,args=(6, pvlist_b, 'B'))
th2.start()

th2.join()
th1.join()
stdout.write('Done\n')

```

In light of the long discussion above, a few remarks are in order: This code uses the standard Thread library and explicitly calls `epics.ca.use_initial_context()` prior to any CA calls in the target function. Also note that the `run_test()` function is first called from the main thread, so that the initial CA context does belong to the main thread. Finally, the `epics.ca.use_initial_context()` call in `run_test()` above could be replaced with `epics.ca.create_context()`, and run OK.

The output from this will look like:

```

First, create a PV in the main thread:
Run 2 Background Threads simultaneously:
-> thread "A" will run for 3.000 sec, monitoring ['Py:ao1', 'Py:ai1', 'Py:long1']
-> thread "B" will run for 6.000 sec, monitoring ['Py:ai1', 'Py:long1', 'Py:ao2']
Py:ao1 = 8.3948 (A)
Py:ai1 = 3.14 (B)
Py:ai1 = 3.14 (A)
Py:ao1 = 0.7404 (A)
Py:ai1 = 4.07 (B)
Py:ai1 = 4.07 (A)
Py:long1 = 3 (B)
Py:long1 = 3 (A)
Py:ao1 = 13.0861 (A)
Py:ai1 = 8.49 (B)
Py:ai1 = 8.49 (A)
Py:ao2 = 30 (B)
Completed Thread A
Py:ai1 = 9.42 (B)
Py:ao2 = 30 (B)
Py:long1 = 4 (B)
Py:ai1 = 3.35 (B)
Py:ao2 = 31 (B)
Py:ai1 = 4.27 (B)
Py:ao2 = 31 (B)
Py:long1 = 5 (B)
Py:ai1 = 8.20 (B)
Py:ao2 = 31 (B)
Completed Thread B
Done

```

Note that while both threads A and B are running, a callback for the PV `Py:ai1` is generated in each thread.

Note also that the callbacks for the PVs created in each thread are **explicitly cleared** with:

```
[p.clear_callbacks() for p in pvs]
```

Without this, the callbacks for thread A will persist even after the thread has completed!

## 10.5 Using Multiprocessing with PyEpics

An alternative to Python threads that has some very interesting and important features is to use multiple *processes*, as with the standard Python multiprocessing module. While using multiple processes has some advantages over threads, it also has important implications for use with PyEpics. The basic issue is that multiple processes need to be fully separate, and do not share global state. For epics Channel Access, this means that all those things like established communication channels, callbacks, and Channel Access **context** cannot easily be share between processes.

The solution is to use a *CAProcess*, which acts just like multiprocessing.Process, but knows how to separate contexts between processes. This means that you will have to create PV objects for each process (even if they point to the same PV).

**class CAProcess** (*group=None, target=None, name=None, args=(), kwargs={}*)  
 a subclass of multiprocessing.Process that clears the global Channel Access context before running you target function in its own process.

**class CAPool** (*processes=None, initializer=None, initargs=(), maxtasksperchild=None*)  
 a subclass of multiprocessing.pool.Pool, creating a Pool of *CAProcess* instances.

A simple example of using multiprocessing successfully is given:

```
from __future__ import print_function
import epics
import time
import multiprocessing as mp
import threading

import pvnames
PVN1 = pvnames.double_pv # 'Py:ao2'
PVN2 = pvnames.double_pv2 # 'Py:ao3'

def subprocess(*args):
    print('==subprocess==', args)
    mypvs = [epics.PV(pvname) for pvname in args]

    for i in range(10):
        time.sleep(0.750)
        out = [(p.pvname, p.get(as_string=True)) for p in mypvs]
        out = ', '.join(["%s=%s" % o for o in out])
        print('==sub (%d): %s' % (i, out))

def main_process():
    def monitor(pvname=None, char_value=None, **kwargs):
        print('--main:monitor %s=%s' % (pvname, char_value))

    print('--main:')
    pv1 = epics.PV(PVN1)
    print('--main:init %s=%s' % (PVN1, pv1.get()))
    pv1.add_callback(callback=monitor)

    try:
        procl = epics.CAProcess(target=subprocess,
                                args=(PVN1, PVN2))
        procl.start()
        procl.join()
    except KeyboardInterrupt:
        print('--main: killing subprocess')
        procl.terminate()
```

(continues on next page)

(continued from previous page)

```
print('--main: subprocess complete')
time.sleep(0.9)
print('--main:final %s=%s' % (PVN1, pv1.get()))

if __name__ == '__main__':
    main_process()
```

here, the main process and the subprocess can each interact with the same PV, though they need to create a separate connection (here, using PV) in each process.

Note that different *CAPProcess* instances can communicate via standard `multiprocessing.Queue`. At this writing, no testing has been done on using multiprocessing Managers.



## PYTHON MODULE INDEX

### a

alarm, [65](#)  
autosave, [67](#)

### d

device, [55](#)

### e

epics, [10](#)  
epics.ca, [33](#)

### m

motor, [56](#)

### p

pv, [17](#)

### w

wx, [71](#)



## Symbols

`_PVcache` (in module *pv*), 28  
`_cache` (in module *epics.ca*), 38  
`_pvs` (in module *device*), 56  
`_unpack` () (in module *epics.ca*), 46

## A

`access` (in module *pv*), 22  
`access` () (in module *epics.ca*), 38  
`access_callbacks` (in module *pv*), 23  
`add_callback` () (in module *device*), 55  
`add_callback` () (in module *pv*), 20  
`add_pv` () (in module *device*), 55  
`Alarm` (class in *alarm*), 65  
`alarm` (module), 65  
`attach_context` () (in module *epics.ca*), 35  
`AUTOMONITOR_MAXLENGTH` (in module *epics.ca*), 34  
`autosave` (module), 67  
`AutoSaver` (class in *autosave*), 68

## C

`ca_add_exception_event` () (in module *epics.ca*), 47  
`ca_add_fd_registration` () (in module *epics.ca*), 47  
`ca_client_status` () (in module *epics.ca*), 47  
`ca_dump_dbr` () (in module *epics.ca*), 48  
`ca_puser` () (in module *epics.ca*), 48  
`ca_set_puser` () (in module *epics.ca*), 48  
`ca_SEVCHK` () (in module *epics.ca*), 48  
`ca_signal` () (in module *epics.ca*), 48  
`ca_test_event` () (in module *epics.ca*), 48  
`caget` () (in module *epics*), 10  
`caget_many` () (in module *epics*), 13  
`cainfo` () (in module *epics*), 12  
`callbacks` (in module *pv*), 23  
`camonitor` () (in module *epics*), 12  
`camonitor_clear` () (in module *epics*), 13  
`CAPool` (built-in class), 86  
`CAProcess` (built-in class), 86  
`caput` () (in module *epics*), 11  
`caput_many` () (in module *epics*), 14

`CAThread` (class in *epics.ca*), 48  
`ChannelAccessException`, 45  
`char_value` (in module *pv*), 21  
`check_limits` () (in module *motor*), 58  
`clear_auto_monitor` () (in module *pv*), 20  
`clear_cache` () (in module *epics.ca*), 38  
`clear_callback` () (in module *motor*), 60  
`clear_callbacks` () (in module *pv*), 21  
`clear_channel` () (in module *epics.ca*), 37  
`clear_subscription` () (in module *epics.ca*), 42  
`client_status` () (in module *epics.ca*), 36  
`connect` () (in module *pv*), 20  
`connect_channel` () (in module *epics.ca*), 37  
`connection_callbacks` (in module *pv*), 23  
`count` (in module *pv*), 22  
`create_channel` () (in module *epics.ca*), 36  
`create_context` () (in module *epics.ca*), 35  
`create_subscription` () (in module *epics.ca*), 41  
`current_context` () (in module *epics.ca*), 35

## D

`DEFAULT_CONNECTION_TIMEOUT` (in module *epics.ca*), 34  
`DEFAULT_SUBSCRIPTION_MASK` (in module *epics.ca*), 42  
`DelayedEpicsCallback` () (in module *wx*), 75  
`destroy_context` () (in module *epics.ca*), 35  
`detach_context` () (in module *epics.ca*), 35  
`Device` (class in *device*), 55  
`device` (module), 55  
`disconnect` () (in module *pv*), 20

## E

`element_count` () (in module *epics.ca*), 37  
`enum_strs` (in module *pv*), 22  
`epics` (module), 10  
`epics.ca` (module), 33  
`EpicsFunction` () (in module *wx*), 75

## F

`field_type` () (in module *epics.ca*), 37  
`finalize_epics` () (in module *wx*), 75

`finalize_libca()` (in module *epics.ca*), 35  
`flush_io()` (in module *epics.ca*), 36  
`force_read_access_rights()` (in module *pv*), 21  
`ftype` (in module *pv*), 22

## G

`get()` (in module *device*), 55  
`get()` (in module *epics.ca*), 38  
`get()` (in module *motor*), 58  
`get()` (in module *pv*), 18  
`get_complete()` (in module *epics.ca*), 40  
`get_complete_with_metadata()` (in module *epics.ca*), 40  
`get_ctrlvars()` (in module *epics.ca*), 42  
`get_ctrlvars()` (in module *pv*), 19  
`get_enum_strings()` (in module *epics.ca*), 42  
`get_position()` (in module *motor*), 60  
`get_precision()` (in module *epics.ca*), 42  
`get_pv()` (in module *motor*), 60  
`get_pv()` (in module *pv*), 27  
`get_severity()` (in module *epics.ca*), 42  
`get_timestamp()` (in module *epics.ca*), 42  
`get_timevars()` (in module *epics.ca*), 43  
`get_timevars()` (in module *pv*), 19  
`get_with_metadata()` (in module *epics.ca*), 39  
`get_with_metadata()` (in module *pv*), 19  
`GetEnumStrings()` (in module *wx*), 71  
`GetValue()` (in module *wx*), 71

## H

`host` (in module *pv*), 22  
`host_name()` (in module *epics.ca*), 37

## I

`info` (in module *pv*), 22  
`initialize_libca()` (in module *epics.ca*), 34  
`isConnected()` (in module *epics.ca*), 38

## L

`lower_alarm_limit` (in module *pv*), 23  
`lower_ctrl_limit` (in module *pv*), 23  
`lower_disp_limit` (in module *pv*), 22  
`lower_warning_limit` (in module *pv*), 23

## M

`message()` (in module *epics.ca*), 36  
`Motor` (class in *motor*), 57  
`motor` (module), 56  
`move()` (in module *motor*), 59  
`Multiprocessing`, 85

## N

`name()` (in module *epics.ca*), 37

`nanoseconds` (in module *pv*), 22  
`nelm` (in module *pv*), 22

## O

`OnEpicsConnect()` (in module *wx*), 71  
`OnPVChange()` (in module *wx*), 71

## P

`pend_event()` (in module *epics.ca*), 35  
`pend_io()` (in module *epics.ca*), 35  
`poll()` (in module *epics.ca*), 35  
`poll()` (in module *pv*), 20  
`posixseconds` (in module *pv*), 22  
`precision` (in module *pv*), 22  
`PREEMPTIVE_CALLBACK` (in module *epics.ca*), 34  
`promote_type()` (in module *epics.ca*), 38  
`put()` (in module *device*), 55  
`put()` (in module *epics.ca*), 41  
`put()` (in module *motor*), 58  
`put()` (in module *pv*), 19  
`put_complete` (in module *pv*), 23  
`PV` (class in *pv*), 17  
`pv` (module), 17  
`PV()` (in module *device*), 55  
`PVAlarm` (class in *wx*), 74  
`PVBitmap` (class in *wx*), 73  
`PVCheckBox` (class in *wx*), 73  
`PVCircle` (class in *wx*), 78  
`PVCollapsiblePane` (class in *wx*), 74  
`PVComboBox` (class in *wx*), 74  
`PVCtrlMixin` (class in *wx*), 71  
`PVEnumButtons` (class in *wx*), 74  
`PVEnumChoice` (class in *wx*), 74  
`PVEnumComboBox` (class in *wx*), 74  
`PVFloatCtrl` (class in *wx*), 72  
`PVFloatSpin` (class in *wx*), 73  
`PVMixin` (class in *wx*), 71  
`PVRadioButton` (class in *wx*), 73  
`PVRectangle` (class in *wx*), 77  
`PVShapeMixin` (class in *wx*), 77  
`PVText` (class in *wx*), 72  
`PVTextCtrl` (class in *wx*), 72  
`PySEVCHK()` (in module *epics.ca*), 45

## R

`read_access` (in module *pv*), 22  
`read_access()` (in module *epics.ca*), 37  
`read_request_file()` (in module *autosave*), 68  
`read_state()` (in module *device*), 56  
`reconnect()` (in module *pv*), 20  
`remove_callback()` (in module *pv*), 21  
`replace_access_rights_event()` (in module *epics.ca*), 37



[replace\\_printf\\_handler\(\)](#) (in module *epics.ca*), 36  
[restore\\_pvs\(\)](#) (in module *autosave*), 68  
[restore\\_state\(\)](#) (in module *device*), 56  
[run\\_callback\(\)](#) (in module *pv*), 21  
[run\\_callbacks\(\)](#) (in module *pv*), 21  
[withSEVCHK\(\)](#) (in module *epics.ca*), 45  
[write\\_access\(\)](#) (in module *pv*), 22  
[write\\_access\(\)](#) (in module *epics.ca*), 37  
[write\\_state\(\)](#) (in module *device*), 56  
[wx](#) (module), 71

## S

[save\(\)](#) (in module *autosave*), 68  
[save\\_pvs\(\)](#) (in module *autosave*), 67  
[save\\_state\(\)](#) (in module *device*), 56  
[set\\_callback\(\)](#) (in module *motor*), 60  
[set\\_position\(\)](#) (in module *motor*), 60  
[SetPV\(\)](#) (in module *wx*), 71  
[severity](#) (in module *pv*), 22  
[sg\\_block\(\)](#) (in module *epics.ca*), 44  
[sg\\_create\(\)](#) (in module *epics.ca*), 43  
[sg\\_delete\(\)](#) (in module *epics.ca*), 43  
[sg\\_get\(\)](#) (in module *epics.ca*), 44  
[sg\\_put\(\)](#) (in module *epics.ca*), 44  
[sg\\_reset\(\)](#) (in module *epics.ca*), 44  
[sg\\_test\(\)](#) (in module *epics.ca*), 44  
[show\\_cache\(\)](#) (in module *epics.ca*), 38  
[show\\_info\(\)](#) (in module *motor*), 60  
[state\(\)](#) (in module *epics.ca*), 37  
[status](#) (in module *pv*), 21

## T

[Threads](#), 82  
[timestamp](#) (in module *pv*), 22  
[tweak\(\)](#) (in module *motor*), 59  
[type](#) (in module *pv*), 21

## U

[units](#) (in module *pv*), 22  
[Update\(\)](#) (in module *wx*), 71  
[upper\\_alarm\\_limit](#) (in module *pv*), 23  
[upper\\_ctrl\\_limit](#) (in module *pv*), 23  
[upper\\_disp\\_limit](#) (in module *pv*), 22  
[upper\\_warning\\_limit](#) (in module *pv*), 23  
[use\\_initial\\_context\(\)](#) (in module *epics.ca*), 35

## V

[value](#) (in module *pv*), 21  
[version\(\)](#) (in module *epics.ca*), 36

## W

[wait\\_for\\_connection\(\)](#) (in module *pv*), 20  
[withCA\(\)](#) (in module *epics.ca*), 45  
[withCHID\(\)](#) (in module *epics.ca*), 46  
[withConnectedCHID\(\)](#) (in module *epics.ca*), 46  
[within\\_limits\(\)](#) (in module *motor*), 58  
[withInitialContext\(\)](#) (in module *epics.ca*), 46