```
#include <xc.h>
#define XTAL FREQ 20000000
#pragma config FOSC = HS
                            // Oscillator Selection bits (HS oscillator)
                              // Watchdog Timer Enable bit (WDT disabled)
#pragma config WDTE = OFF
#pragma config PWRTE = OFF
                              // Power-up Timer Enable bit (PWRT disabled)
#pragma config BOREN = ON
                              // Brown-out Reset Enable bit (BOR enabled)
#pragma config LVP = ON
                            // Low-Voltage (Single-Supply) In-Circuit Serial Programming
Enable bit (RB3/PGM pin has PGM function; low-voltage programming enabled)
#pragma config CPD = OFF
                            // Data EEPROM Memory Code Protection bit (Data EEPROM
code protection off)
#pragma config WRT = OFF
                             // Flash Program Memory Write Enable bits (Write protection
off; all program memory may be written to by EECON control)
#pragma config CP = ON
                           // Flash Program Memory Code Protection bit (All program
memory code-protected)
// #pragma config statements should precede project file includes.
// Use project enums instead of #define for ON and OFF.
#define DOOR SENSOR PIN PORTAbits.RAO
#define LIGHT CONTROL PIN PORTBbits.RB0
#define DOOR LED PIN PORTBbits.RB1
#define ROOF SWITCH PIN PORTBbits.RB1
void initSystem();
void initI2C();
void controlLighting();
```

```
void updateLEDStatus();
void transmitDoorStatus(unsigned char doorStatus);
void delay_ms(unsigned int ms);
void main() {
  unsigned char doorStatus = 0;
 initSystem();
 initI2C();
  while(1) {
    doorStatus = (DOOR_SENSOR_PIN == 0) ? 0 : 1;
    controlLighting();
    updateLEDStatus();
    transmitDoorStatus(doorStatus);
    __delay_ms(100);
  }
}
void initSystem() {
  TRISA = 0x01;
 TRISB = 0x00;
```

```
ANSEL = 0x00;
  LATB = 0x00;
}
void initI2C() {
  SSP1STAT = 0x80;
  SSP1CON1 = 0x28;
  TRISCbits.TRISC3 = 1;
  TRISCbits.TRISC4 = 1;
}
void controlLighting() {
  if (DOOR SENSOR PIN == 0 && ROOF SWITCH PIN == 1) {
    PORTBbits.RB0 = 1; // Set RB0 (Turn on light)
 } else {
    PORTBbits.RB0 = 0; // Clear RB0 (Turn off light)
 }
}
void updateLEDStatus() {
 if (DOOR_SENSOR_PIN == 0) {
    PORTBbits.RB1 = 1; // Set RB1 (Turn on LED)
  } else {
    PORTBbits.RB1 = 0; // Clear RB1 (Turn off LED)
  }
}
```

```
void transmitDoorStatus(unsigned char doorStatus) {
    SSP1BUF = doorStatus;
    while (SSP1STATbits.BF);
}

void delay_ms(unsigned int ms) {
    while(ms--) {
        __delay_ms(1);
    }
}
```