

```
#include "FreeRTOS.h"
```

```
#include "task.h"
```

```
#include "queue.h"
```

```
#include "semphr.h"
```

```
#include "portmacro.h"
```

```
#include <stdio.h>
```

```
#define FIRE_ALARM_PRIORITY    3
```

```
#define SECURITY_BREACH_PRIORITY 2
```

```
#define LOW_BATTERY_PRIORITY   1
```

```
#define FIRE_ALARM_PIN        0
```

```
#define SECURITY_BREACH_PIN    1
```

```
#define BATTERY_VOLTAGE_PIN    2
```

```
volatile BaseType_t fire_alarm_triggered = pdFALSE;
```

```
volatile BaseType_t security_breach_triggered = pdFALSE;
```

```
volatile BaseType_t low_battery_triggered = pdFALSE;
```

```
void fire_alarm_ISR(void) {
```

```
    fire_alarm_triggered = pdTRUE;
```

```
}
```

```
void security_breach_ISR(void) {
```

```
    security_breach_triggered = pdTRUE;
```

```
}
```

```
void battery_check_ISR(void) {  
    if (/* Check battery level */) {  
        low_battery_triggered = pdTRUE;  
    }  
}
```

```
void fire_alarm_task(void *pvParameters) {  
    for(;;) {  
        if (fire_alarm_triggered) {  
            printf("Fire Alarm Triggered! Activating emergency response...\n");  
            fire_alarm_triggered = pdFALSE;  
        }  
        vTaskDelay(10);  
    }  
}
```

```
void security_breach_task(void *pvParameters) {  
    for(;;) {  
        if (security_breach_triggered) {  
            printf("Security Breach Detected! Triggering alarm...\n");  
            security_breach_triggered = pdFALSE;  
        }  
        vTaskDelay(10);  
    }  
}
```

```
}
```

```
void low_battery_task(void *pvParameters) {  
    for(;;) {  
        if (low_battery_triggered) {  
            printf("Low Battery Detected! Please charge the system.\n");  
            low_battery_triggered = pdFALSE;  
        }  
        vTaskDelay(10);  
    }  
}
```

```
void init_hardware(void) {  
    // Configure pins for external interrupts  
    configure_external_interrupt(FIRE_ALARM_PIN, fire_alarm_ISR);  
    configure_external_interrupt(SEcurity_BREACH_PIN, security_breach_ISR);  
    configure_timer_interrupt(battery_check_ISR);  
}
```

```
void configure_external_interrupt(int pin, void (*ISR_handler)(void)) {  
    // Configure external interrupt  
}
```

```
void configure_timer_interrupt(void (*ISR_handler)(void)) {  
    // Configure timer interrupt for periodic battery check  
}
```

```
int main(void) {  
    init_hardware();  
  
    xTaskCreate(fire_alarm_task, "FireAlarm", 100, NULL, FIRE_ALARM_PRIORITY, NULL);  
    xTaskCreate(security_breach_task, "SecurityBreach", 100, NULL,  
SECURITY_BREACH_PRIORITY, NULL);  
    xTaskCreate(low_battery_task, "LowBattery", 100, NULL, LOW_BATTERY_PRIORITY, NULL);  
  
    vTaskStartScheduler();  
  
    while(1);  
}
```