## ESS201: C++ Programming

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## Tasks:

 Rewrite struct vector3d from Lab01 to a class interface with (private) data members (float \_x, \_y, \_z), in a single C++ file.

```
struct vector3d {
   float x, y, z; // data
}

class vector3d {
   private:
   float _x, _y, _z; // data
};
```

- The constructor must take in three float values. Additionally, the class must have a default constructor, destructor, copy constructor, public members get\_x(), get\_y(), get\_z() to access the private data members, and public member functions set\_x, set\_y, set\_z to modify the private data members.
- The class member changes to (set 1):

  vector3d& add(vector3d b)

  vector3d& subtract(vector3d b)

  float& dot(vector3d b)

  vector3d& cross(vector3d b)

  float& norm()

  as opposed to the functions using struct (set 2):

  vector3d add(vector3d a, vector3d b)

  vector3d subtract(vector3d a, vector3d b)

  float dot(vector3d a, vector3d b)

  vector3d cross(vector3d a, vector3d b)

  float norm(vector3d a)

Set 1 can be assumed to be public members. One can assume that the vector3d a in all functions in set 2 are subsumed as the object itself in set 1. e.g. for a slight variant from the required member function:

```
float dot(vector3d a, vector3d b) {
   return (a.x*b.x+a.y*b.y+a.z*b.z) ;
becomes:
float dot(vector3d b) {
   return (_x*b.get_x()+_y*b.get_y() + _z*b.get_z()) ;
```

 The scalar-vector multiplication function, which is public, has to be overloaded: vector3d scalar\_product(float a);
 vector3d scalar\_product(int a);

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iriena sta::c	ostream& ope	rator<<(sto	d::ostream	&os, vect	or3d &v)	;

<sup>&</sup>lt;sup>1</sup>Note: the vectors to be inputted and outputted are formatted with its three components separated by a single space.

- Input: should take in 4 lines of input at commandline prompt, i.e. first two lines for vectors, next one for float scalar, and the last one for int scalar. e.g.
  - 3 3.4 5 2.1 4.2 4.1 0.5 3
- Output: should be in 8 lines, i.e. for addition of two input vectors; then for subtraction; then for scalar-vector multiplication of the float scalar value with the first vector; then for scalar-vector multiplication of the integer scalar value with the second vector; fifth line is for dot product of the two vectors; next one for the cross product; and the last two lines giving the L2 norm of each of the two vectors. e.g. output for the afore-mentioned input is:
  - 5.1 7.6 9.1 0.9 -0.8 0.9 1.5 1.7 2.5 6.3 12.6 12.3 41.08 -7.06 -1.8 5.46 6.74981 6.23378