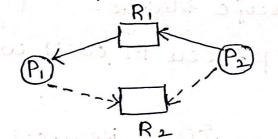
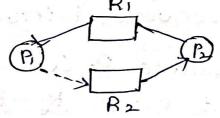
- If we have revource allocation system with only one instance of each revource type, we can use the revource allocation graph discussed previously, for deadlock avoidance
- Along with request and assignment edges it also contain a new type of edge called "claim edge":
- A claim edge Pi→Rj indicates that process
 Pi may request resource Rj at some time
 in future.
- This edge direction is similar to request edge but is represented by a dashed line.



* Resource Allocation Graph.

- When process Pi requests revource Rj, the claims edge is converted into request edge.
- → When Revource Rj is released by Pi, ther assignment edge Rj → Pi is reconverted to claim

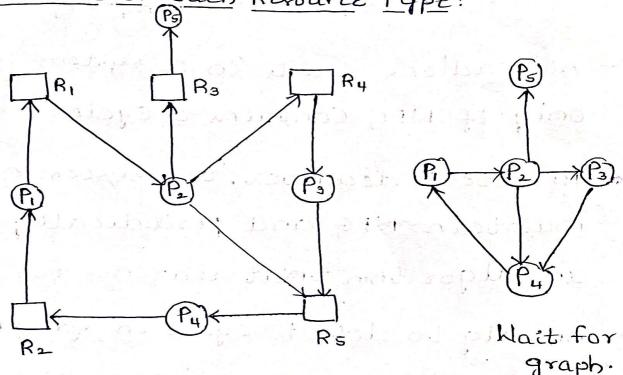
- Now Suppose that Proces Pi requests resource Rj. Then request can be granted only if converting the requesting edge Pi > Rj to an assignment edge Rj > Pi does not result in formation of cycle in graph.
- This can be checked by cycle detection. algorithm.
- This algorithm requires no operations for detecting cycle, where n is number of processes in the system.
- If no cycle esuists, then allocation of resource leaves the system en safe state.
- -If Cycle is found, then allocation leaves the system en an unsafe state.
- -In that case, a process Pr will wait for the request.
- In the above graph of P_Request R2 it cann't be as it forms the cycle.



> Deadlock Detection:

- In deadlock detection, the system may provide:
 - (1) An algorithm that examines the state of the system to determine whether a deadlock has occured.

(2) An algorithm to recover from deadlock. Single Instance of Each Resource Type:



* Resource allocation graph

- If all the Resources has only one instance, then deadlock detection algorithm was variant of RAG called wait for graph.

- He obtain this graph by removing resource nodes and collapsing appropriate edges - In WFG,
 - · an edge from $P_i \rightarrow P_j$ means P_i is waiting for P_j to release a resource that P_i needs
 - · an edge $P_c \rightarrow P_j$ in NFG exiturif

 RAG Contains edges $P_l \rightarrow R_q$ $R_q \rightarrow P_j$ for R_q .
 - A deadlock exists en a system if and only if WFG Contains à Cycle.
- To detect deadlock, the system need to maintain WFG and periodically invoke an algorithm that searches for a cycle.
- An alg to detect cycle in graph require $O(n^2)$ operations, where $n=no\cdot of$ vertices in a graph.
- Note: WFG Scheme is not applicable with Several instances of resource type.

- Algorithm here employs various Data Structus that are similar to those und in "Banker's algorithm".
 - (1) Available vector of length m indicates no of available resources of each type.
- (2) Allocation nxm matrix

indicates no of resource of each type allocated to , process.

(3) Request - nxm matrix

each process

	Allocation Request Available
Po	0-10-010,000000000000000000000000000000
P,	200 202 010
P2	3 0 3 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
P ₃	211100211
Pu.	002 002 526
4. 5/1	< Po, P2, P3, P4, P,7

additional request - Suppose makes Available (001) Request Allocation 0 0 0 010 000 Po 202 200 PI 0 0 1 3 0 3 Pz 1000 29990 Bankla WAY! P3 0 0 2 002 Py < Po,

-Here number of available resources are not sufficient to fulfill requests of other processes: (P1,P2,P3,P4).

- Thus deadlock exists among P1, P2, P3, P4.

(C) Detection-Algorithm Usage:

- When should we invoke detection algorithm
- It depends on a factors
 - (a) How often a deadlock likely to occur?
 - (b) How many processes will be affected by deadlock when happened.

Mote: Invoking deadlock detection alq will incur overhead in Computational time.

Alternative is to invoke/hour or when Cpu

(11+11:20+inn drops < 407.

-> Recovery from deadlock:

- When deadlock detection algorithm determines deadlock there are a powibility to deal with deadlocks.
 - (b) Let sys recover from it automatically.
- There are two options to break the deadlock.
 - (a) Abort one or more processes to break Circular wait
 - (b) To preempt some revources from one or more deadlock processes

(a) Process Termination:

- 2 methods: In both system reclaims all resources allocated to the terminated processes
 - (a) Abort all deadlocked processer.

 This method break deadlock at greater expense.

- Because deadlock have computed longer time and again they have to compute (b) Abort one process at a time until deadlock is eliminated.
- Better option.
- Choring of which process to abort depends on many factors like:
 - (a) What the preority of process is
 - (b) How long it has computed and how much time left for computation.
 - (C) How many and what types of the resources are wed.
- (d) How many more resources are needed.
- (e) Whether the proces is interactive/
- (b) Revource preemption:
- Here 3 levier need to be addressed.
 - (1) Selecting a victim-Which resource and which process to be preempted depends

- on no of revources deadlock proces és holding.
- (2) Rollback: If we preempt a revource what need to be clone with the process.
- We must rollback proces to some safe state.
- In general, it is difficult to determine what a safe state is. So better to total rollback, abort and then restart the process
- (3) Starvation: Resources must not always be preempted from same process
- We must ensure that a process can be rollback for finite number of times