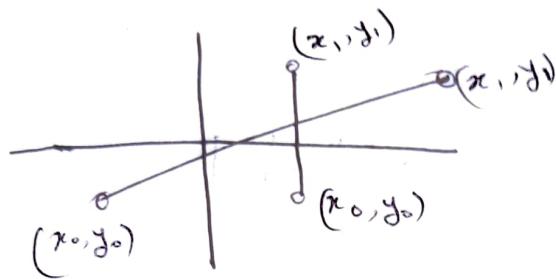


Computer graphics course → Graphical Algorithms
 → Engineering Behind Graphics



$$P_0 \rightarrow P_1$$

$$|v| = \frac{P_1 - P_0}{P_1 - P_0}$$

$$y = mx + c \quad \dots \textcircled{1}$$

$$\begin{aligned} x_1 - x_0 &= dx \\ y_1 - y_0 &= dy \end{aligned}$$

for $(x_0 \text{ to } x_1)$ {

do Pixel(x, y);

$y + = m;$

}

for $(y_0 \text{ to } y_1)$ {

do Pixel(x, y);

$x + = 1/m;$

}

$$m = \frac{dy}{dx}$$

Pto

$$y = mx + c$$

DDA Algorithm (Digital Differential Analyzer)

```
void drawLine( x0, y0, x1, y1 ) {
```

```
    int dx = x1 - x0, dy = y1 - y0;
```

```
    int maxVal = max( |dx|, |dy| );
```

↓

step

```
    dx = dx / step, dy = dy / step;
```

```
    i = 0, x = x0, y = y0;
```

```
    while ( i <= step ) {
```

```
        drawPixel( x, y )
```

```
        x += dx;
```

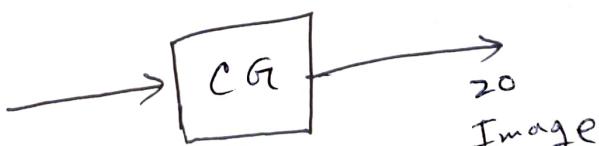
```
        y += dy;
```

```
        i++;
```

}

*

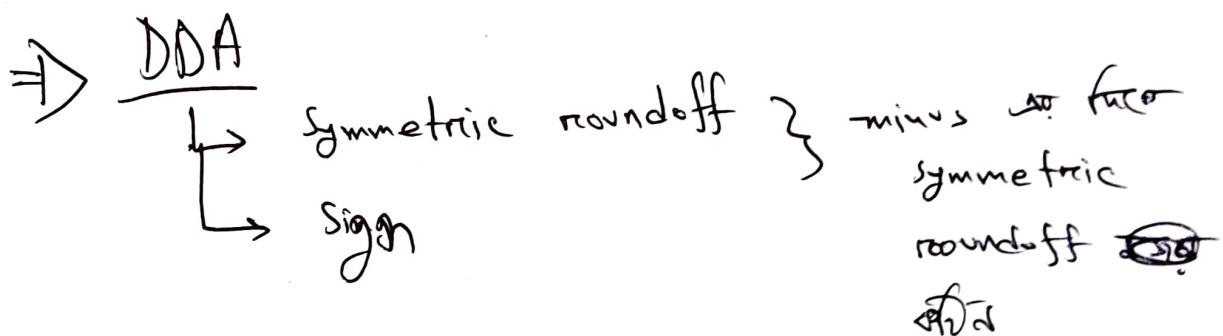
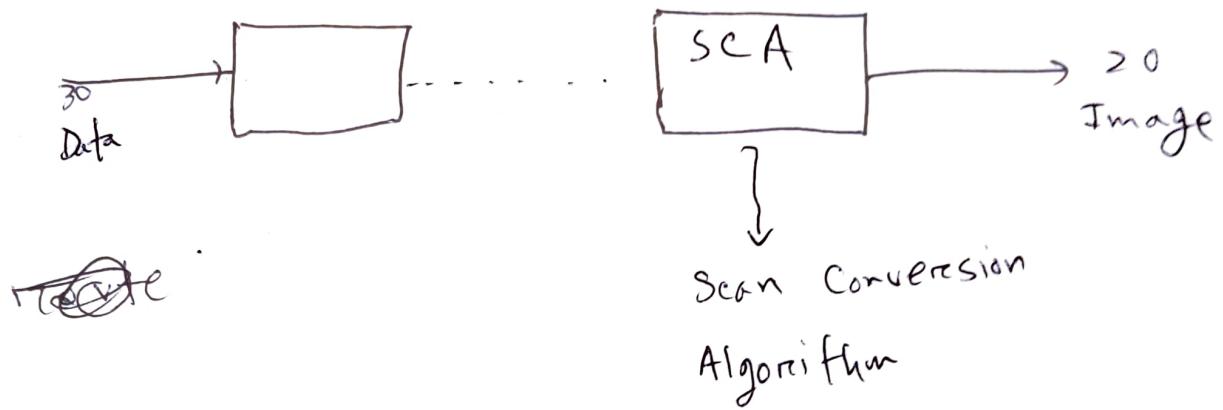
3D
Data



① Model → Geometric

* Rendering Pipeline

- ↳ drawing steps used by machine
- ↳ strictly maintains sequences



- Line Drawing Algorithm (Normal DDA - algo একটি)

↳ drawPixel (x, y) floating-point values

→ drawPixel ($\text{int}(x+0.5), \text{int}(y+0.5)$) করে কোথা ?

↳ $0.5 \geq 0$ এবং $0.5 < 0$ পরিসর, ফল ঘোষণা করুন

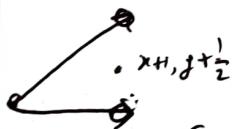


- Mid Point Line-Drawing Algo / Bresenham's Line Drawing Algo.

$$y = mx + c \quad \text{(i)}$$

$$Ax + By + C = 0 \quad \text{(ii)} \Rightarrow A = dy, B = -dx$$

equation (ii) ৰ স্বত্ত্বে Point (x, y) is on the line.



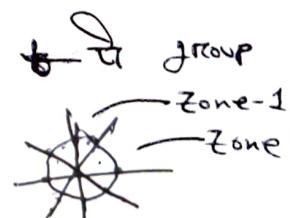
$(x+1, y+\frac{1}{2})$ Point ~~এখন~~ positive/negative কোন জাত

এবং Line কে কোন কোণ নাই,

2nd ^{finding} of this algo → Finding equation (i)'s return value using
"Rate of change"

weakness → Line এর slope ক্ষেত্রে Division করা

এবং অন্য কোন কোণ



অন্য কোণের zone-0 কোণ



$dx \geq dy$.



$$\frac{dy}{dx} \leq 1$$

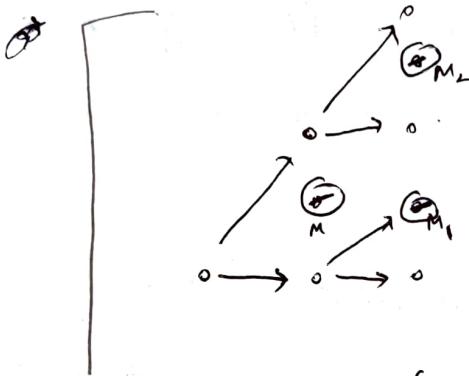
Zone-0 (0),

→ dx, dy sign equal, $dx \geq dy$.

→ Zone-1 (1),

dx, dy sign equal, $dy \geq dx$

$$d_1 = d_2 = d$$



$$f(x, y) = Ax + By + C = 0$$

(from eq-2)

$$f(M) = A(x+1) + B(y+\frac{1}{2}) + C = d$$

$$f(M_1) = A(x+2) + B(y+\frac{1}{2}) + C = d_1$$

$d_1 - d = A$ ($x=1$ increment → "deviation" Δp
change" $\overline{C} = A$)

→ Next Pixel East → \overline{C} across deviation Δp

same \overline{C} across first \overline{C} , so,

$$\Delta E = d_1 - d = A \quad (\text{East } \Delta \text{ deviation}) \quad \text{--- (III)}$$

$$= dy$$

$$\text{likewise, } \Delta NF = d_2 - d = A + B = \frac{dy - dx}{2} < 0 \quad \text{--- (IV)}$$

if $\Delta E \geq 0$ then
 $\Delta NF < 0$.

→ Finding first value of dinit

$$= A(x_0+1) + B(y_0+\frac{1}{2}) + C \quad (\text{First point is } x_0, y_0)$$

we know, $Ax_0 + By_0 + C = 0$

so,

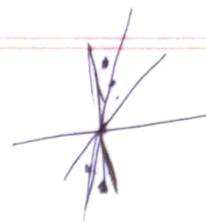
$$A + \frac{B}{2} = dinit$$

Init derivatives of zone-0

① ~~Derive~~ Derive initial derivation

as,

$$A = \frac{dy}{dx}, \quad B = -\frac{dx}{dy}, \quad \text{dinit} = \frac{dy}{dx} - \frac{dx}{2} \quad \text{--- } \textcircled{v}$$



void drawLine 0 (int x_0 , int y_0 , int x_1 , int y_1) {

$$\text{int } dx = x_1 - x_0, \quad dy = y_1 - y_0$$

$\frac{dy}{dx}$
to avoid fraction

}

$$\text{int } \Delta E = 2 * dy, \quad \Delta NE = 2 (dy - dx);$$

$$\text{int } d = 2 * dy - dx;$$

$$\text{int } x = x_0, \quad y = y_0$$

drawPixel (x_0, y_0)

dinit >

'sign'

while ($x < x_1$) {

if ($d < 0$) { //AE

$$d += \Delta E$$

$x++$

}



else { //NE

$$d += \Delta NE$$

$x++, y++$

}

drawPixel (x, y);

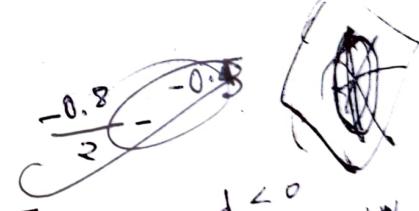
}

}

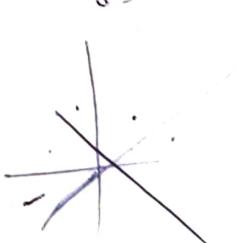
"for" loop Line (-20, 30) ~~0000~~ (10, 50) (5 25(1/4),



"for" simulation ~~0000~~



$$\begin{aligned} &\frac{-1}{2} + 0.4 \\ &-0.5 + 0.4 \\ &= 0.1 \end{aligned}$$



10

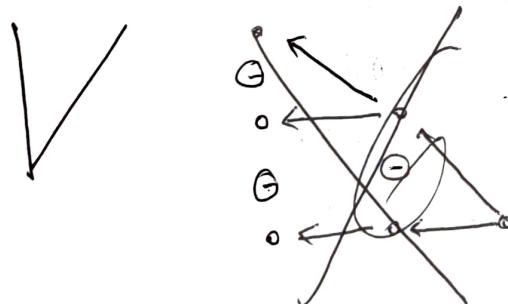
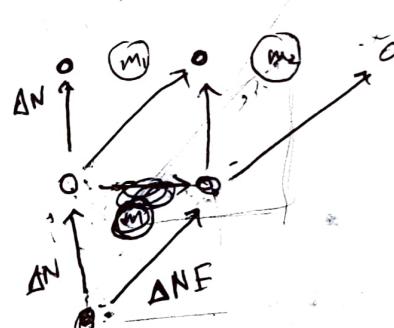
$$dx = 30, dy = 20, \frac{dy - dx}{d_{init}} = 5$$

so, $d = d_{init} \times 2 = 10$

<u>x</u>	<u>y</u>	<u>d</u>	<u>$\Delta E / \Delta NE$</u>
-20	30	10	<u>$40, 20 (\Delta NE)$</u>
<i>new</i> \rightarrow -19	31	-10 $\downarrow 10 + (-20)$	ΔE
\leftarrow -18	31	30 $30 + -20 = 10$	ΔNE
-17	32	-10	ΔE
-16	33	30	ΔNE
-15	33	30	ΔNE
-14	34	10	ΔNE

$\Delta E = 10$
 $\Delta NE = 20$
 $\Delta NE = 10$

Zone - 1



ΔE
 ΔNE
 ΔN
 M_1, M_2, M_3
 x, y

$$f(m) = A(x + \frac{1}{2}) + B(y + 1) + c = d$$

$$f(m_1) = A(x + \frac{1}{2}) + B(y + 2) + c = d_1$$

$$f(m_2) = A(x + \frac{3}{2}) + B(y + 2) + c = d_2$$

$\Delta N = d_1 - d = B$,
 $\epsilon - dx$

$$\Delta NE = d_2 - d_1 = dy - dx$$

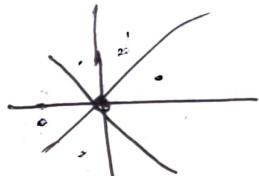
$$d_{init} = \frac{A}{2} + B = \frac{dy}{2} - \frac{dx}{2}$$

$y = 1, \kappa = 0.25$ δ_{TO} , $d_{\text{init}} > 0$ so,

+ve ΔN ΔN

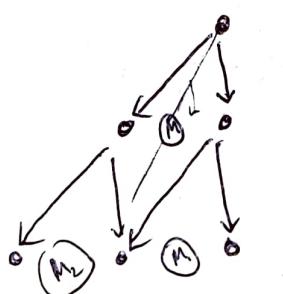
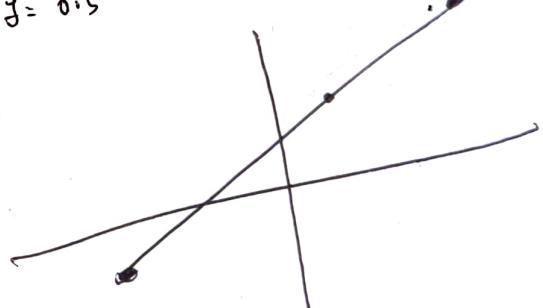
$d_{\text{init}} \leq 0$ तैन, ΔN

Assignment
→ SWNT प्रारंभ Randomly \rightarrow $\frac{\partial}{\partial t}$ zone derivation वर्ते तरीका
first, लोगों के अपने दिन, (Monday)



$$\kappa = -1$$

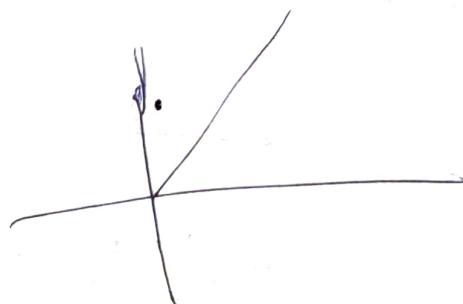
$$y = 0.5$$



$$\delta < 0$$

$d_{\text{init}} \leq 0 :$ SW

$d_{\text{init}} \geq 0 :$ W

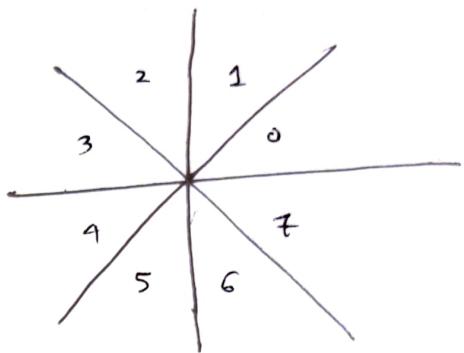


Slope-independent Line:

Algorithm - (1)

① Determine slope

② Run Accordingly



or algorithm(2) -

① Determine slope

② Convert slope into a specific one

③ Draw

↳ b) Draw in

original but process

in zone-0

a) say for ZONE

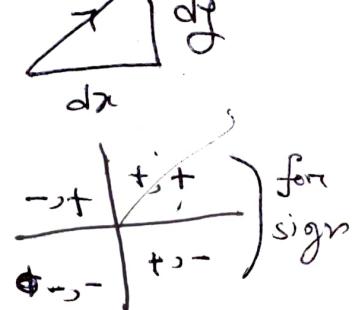
zone-0

→ Both algo has same complexity, but algo-2 (2)

Code optimized (less size code)

From (x_0, y_0) (x_1, y_1) → Zone Determination

(2nd) Zone-0 (2)

 $dx, dy > 0, dx \geq dy$ 

→ code 2. Here if $|dx, dy|$ sign (RSSD),

Inner if \oplus zero absolute value compare
then

else, else if $|dx| > |dy|$, to GTS

0, 3, 4, 7 consider

Inner if \ominus sign consider.

for 0 (Inner)
case same
 $\times \times \rightarrow$



void drawLine (int x_0 , int y_0 , int x_1 , int y_1) {

// Determine Zone, then call drawLine0,
drawLine1

int $dx = x_1 - x_0$, $dy = y_1 - y_0$;

or something
else

[zone = determineZone (dx, dy)]

↳ zone go \oplus , depend on call
drawLine

int determineZone (int dx , int dy) {

if ($|dx| \geq |dy|$) { // 0, 7, 3, 9 zones

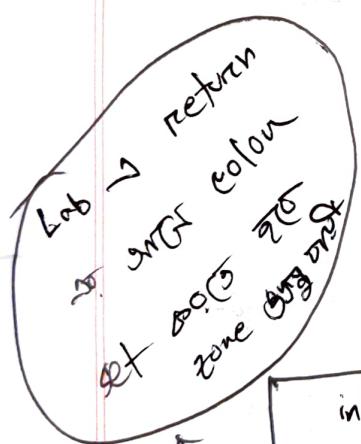
if ($dx \geq 0 \& dy \geq 0$) return 0;

elif ($dx \geq 0 \& dy \leq 0$) return 7;

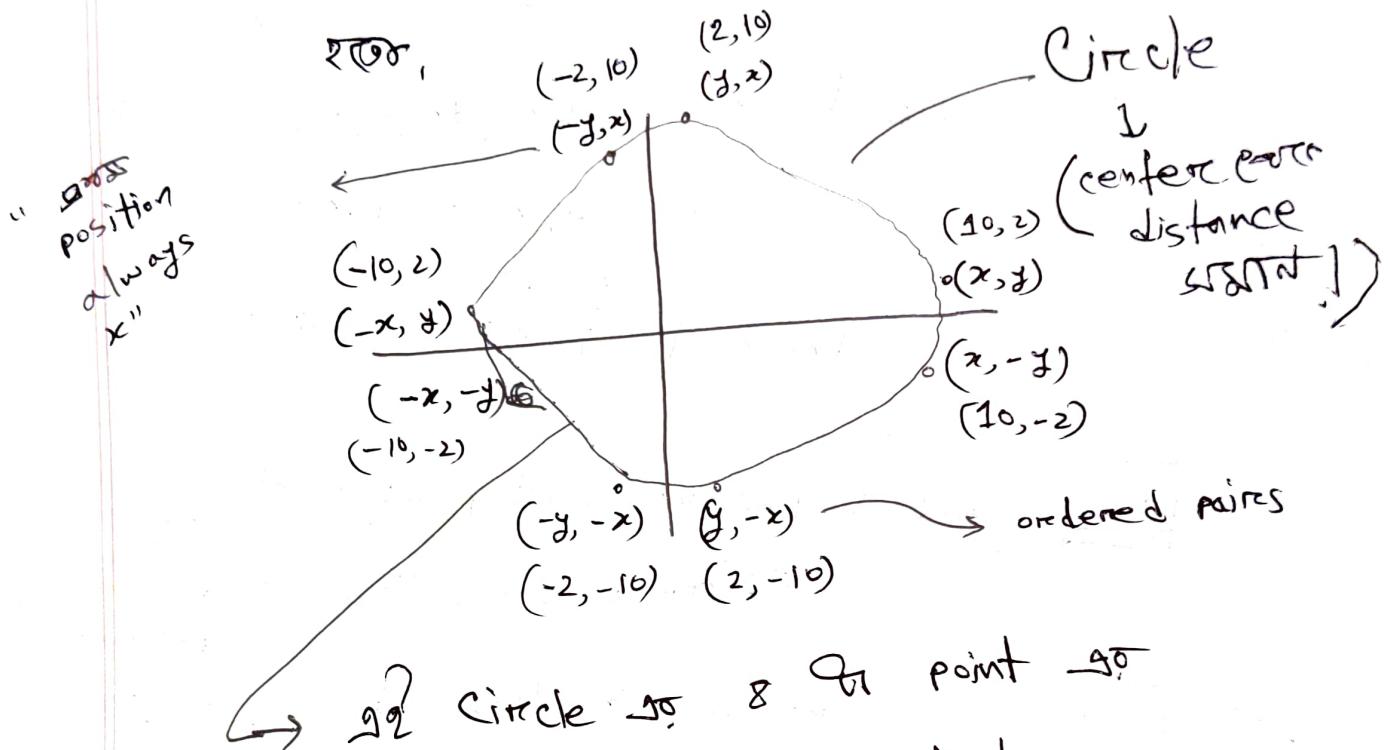
elif ($dx \leq 0 \& dy \leq 0$) return 4;

else return 3;

} else → same with // 1, 6, 2, 5 ...



→ अब Initial Oxy का endpoint, center important, तो यह उसके Zone-0, Zone-4 तक



सेटों Relation is called

8-way Symmetry

↪ we can use this to take
all to a specific zone

example

$(-10, -2)$

↪ $(10, 2)$ [extra minus
first sign
only]

→ 0, 1, 3, 4 तक sign change
पर्याप्त है

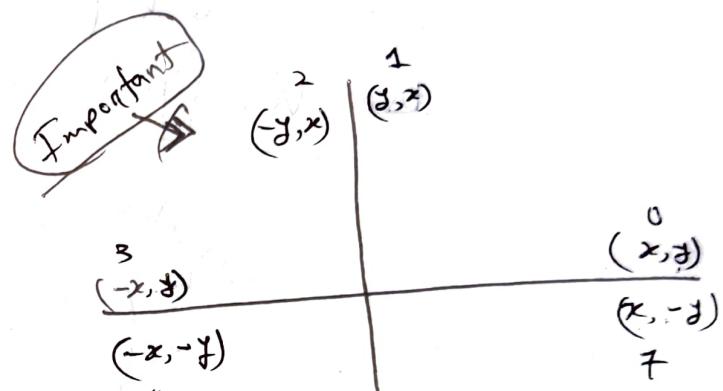
~~Zone~~ Zone ~~Zone~~ $(1, 2) \leftrightarrow (-2, 10)$

$\rightarrow 1, 2, 5, 6 \rightarrow$ 3x3 matrix rule

* We need a table for zone-0 to zone-all

and another " " zone-all to zone-0

Zone	Any to 0
1	$(x, y) \rightarrow (y, x)$
2	$(x, y) \rightarrow (y, -x)$
3	$(x, y) \rightarrow (-x, y)$
4	$(x, y) \rightarrow (-x, -y)$
5	$(x, y) \rightarrow (-y, -x)$
6	$(x, y) \rightarrow (-y, x)$
7	$(x, y) \rightarrow (x, -y)$



for 0, 3, 4, 7

↳ natural

for 1, 2, 5, 6

↳ x, y swap
but not minus

First \rightarrow
coordinate

0, 3, 4, 7

Then
1, 2, 5, 6

* Zone Determination \rightarrow algo

zone-0 \rightarrow without any change

zone-i \rightarrow i \rightarrow 3x3 mapping (i to 0)
From Table

Example for zone-3 \rightarrow call $(-x_0, y_0, -x_1, y_1)$

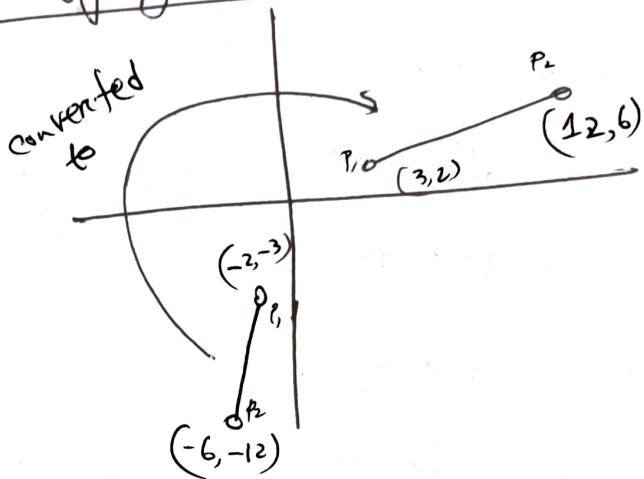
For, ~~Zone~~ ~~Mapping~~

$$Z_0 \Rightarrow d_L(x_0, y_0, x_1, y_1)$$

$$Z_1 \Rightarrow d_L(y_0, x_0, y_1, x_1) \dots$$

$$Z_5 \Rightarrow d_L(-y_0, -x_0, -y_1, -x_1)$$

~~For~~ Verifying with Example



→ Direct zone-0 case back ~~for~~ ~~for~~
by another Argument ~~so~~ draw line

→ (So five arguments
 $(x_0, y_0, x_1, y_1, \text{zone})$)

Zone	Mapping
0	$(x, y) \rightarrow (x, y)$
1	$(x, y) \rightarrow (y, x)$
2	$(x, y) \rightarrow (-y, x)$
3	$(x, y) \rightarrow (x, -y)$
4	$(x, y) \rightarrow (-x, -y)$
5	$(x, y) \rightarrow (-x, y)$
6	$(x, y) \rightarrow (y, -x)$

→ ~~another~~ figure ~~for~~

→ ~~another~~ 6 case
any 5 back to
3rd another
table

Code void drawline0 (int x0... int zone) {

// same algo for line draw

// enter drawPixel (x,y,zone) \Rightarrow

drawPixel(x,y,zone);
}

→ unlike 2 inputs
before, 3 here

void drawPixel (int x, int y, int zone) {

switch (zone) {

case 0: glVertex2i (x,y);

case 1: glVertex2i (y,x);

case 7: ...

}

}

⇒ Comparison between Algo-1 and Algo-2

[LAB \rightarrow Σ Δ $\rho(\sigma)$ $\text{MEM}(\sigma)$ $T(\sigma)$]

"ମୁଖ୍ୟ ଅଧ୍ୟୋତ୍ସାହିତ କେନ୍ଦ୍ରାଳୀତା",

ଆଜିର କ୍ଷେତ୍ର ଯେତି" - S.R

18.1.23

Lect-4, Wednesday

Circle Drawing Algorithm

$$(x-a)^2 + (y-b)^2 = r^2 \dots\dots (i)$$

$$x^2 + y^2 - r^2 = 0 \dots\dots (ii)$$

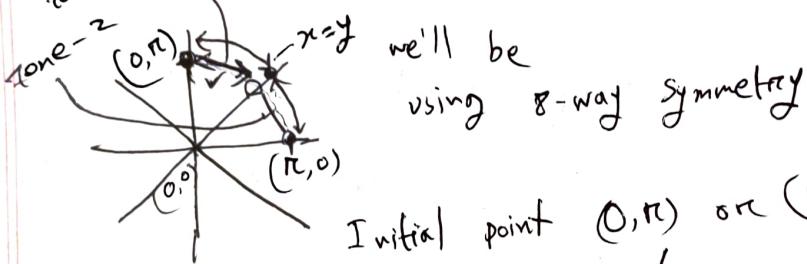
(Processing of a,b
in function
27,

so this equation
is used for
processing

* Circles first derivative isn't

constant \rightarrow so rate of change (tangent) will

continuously change \rightarrow use del constant π unlike
line's



Initial point $(0, r)$ or $(r, 0)$

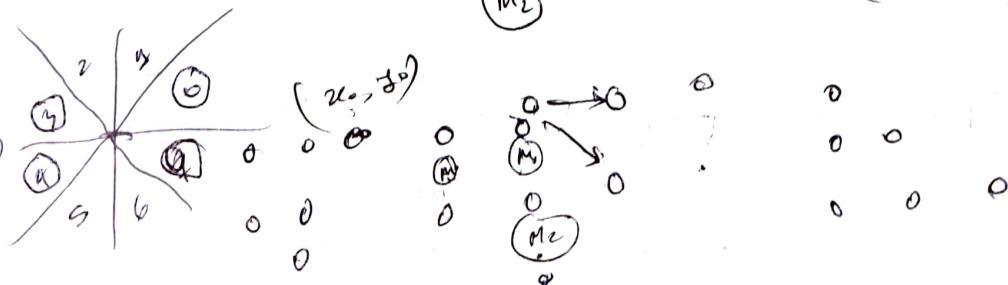
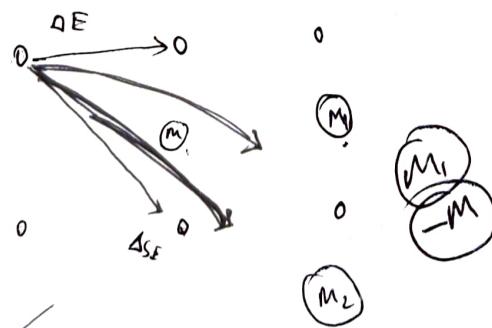
zone $\rightarrow 0, 7, 3, 4 \rightarrow$ loop controller $x \leftarrow$
 $1, 2, 5, 6 \rightarrow$ loop controller $y \leftarrow$

if initial is (x_0, y_0)

$$M = (x_0 + 1, y_0 - \frac{1}{2})$$

$$M_1 = (x_0 + 2, y_0 - \frac{1}{2})$$

$$M_2 = (x_0 + 2, y_0 - \frac{3}{2})$$



-2.3



-4

$$4 + \frac{1}{4} = \frac{17}{4}$$

$$\frac{17}{4}$$

$\frac{1}{2} \times \pi - 2 \times \frac{\pi}{4}$
6

$$f(x_0, y_0) = x_0^2 + y_0^2 - r^2 = 0$$

Now, $f(x_0 + \frac{1}{2}, y_0 - \frac{1}{2}) = x_0^2 + 4x_0 + 4 + y_0^2 - y_0 + \frac{1}{4} - r^2 = d_1$

$$d_{\Delta E} = d_1 - d = 4x_0 - y_0 + \frac{47}{4}$$

$M_1 \rightarrow f(x_0 + 2, y - \frac{1}{2}) = d_2$

$$\boxed{\Delta E = d_2 - d = 2x + 3} \quad (i)$$

$M_2 \rightarrow f(x_0 + 2, y - \frac{3}{2}) = d_3$

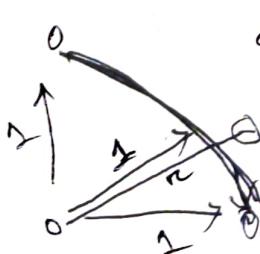
$$\boxed{\Delta S E = d_3 - d = 2x + 3 + 2y + 2 = 2x - 2y + 5} \quad (ii)$$

Here, For zone-7, initial point is $(0, r)$

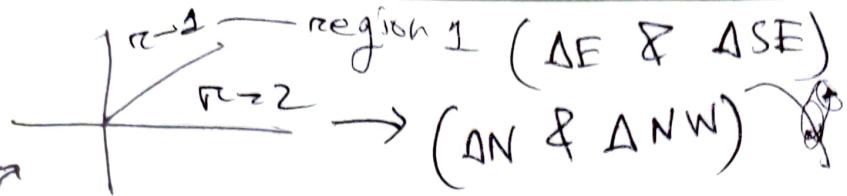
so, first midpoint = $(0+1, r - \frac{1}{2}) = (1, r - \frac{1}{2})$

$$f(1, r - \frac{1}{2}) = 1 + \frac{1}{4} - \pi = \frac{5}{4} - \pi = d_{\text{init}}$$

so, we got d_{init} by
putting in the first
midpoint value



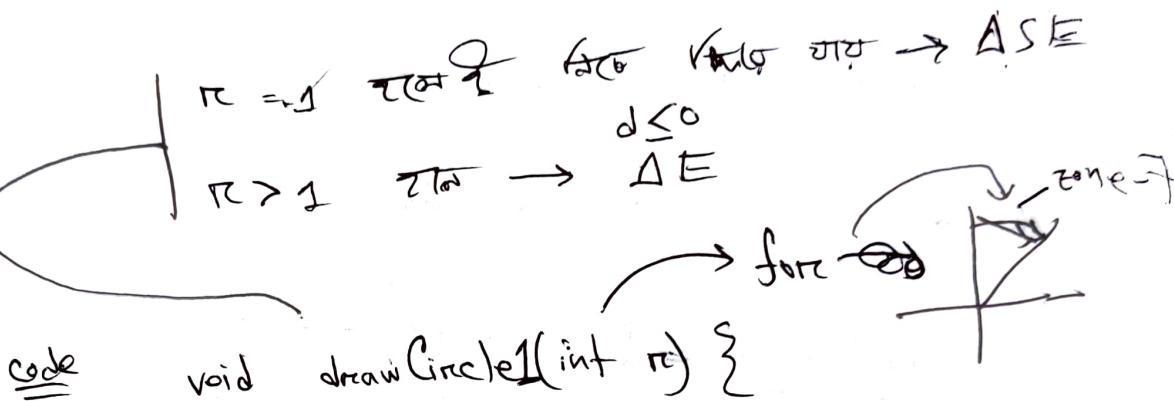
$$x^2 + y^2 - r^2 = 0 \rightarrow \text{positive } \theta? \\ \text{negative?}$$



$\Rightarrow r=1$ तो $r > 1 \Rightarrow$ 3.5 Circle में वृत्त

दोनों दिशों के लिए यहाँ

$$d \geq 0$$



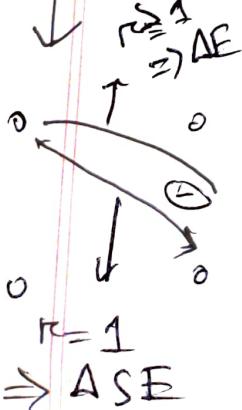
int $x=0, y=r;$
 int $d = 5 - 4 \times r;$
 loop controller → draw8way(x, y);
 loop controller → while($x \leq y$) {
 loop controller → if ($d < 0$) { // AE
 loop controller → } else { // ASE
 loop controller → }

Position matters
 (def errors $\propto \theta(d)$)

$$d+ = (2x+3) \times 4;$$

$$x++;$$

} else { // ASE
 $d+ = (2x-2y+5) \times 4;$
 $x++; y--;$
 draw8way(x, y);





Circle 1 is Region 1 of same

Simulation: Draw a circle for $r=8$ and center is $(0,0)$

<u>x</u>	<u>y</u>	<u>d</u>	<u>$\Delta E / \Delta SE$</u>
0	8	-27	$\Delta E (+12)$
1	8	-15	$\Delta E (+20)$
2	8	5	$\Delta SE (-7)$
3	7	-23	$\Delta E (+36)$
4	7	-34	$\Delta SE (-1)$
5	6	13	$\Delta SE (-4)$
6	5	9	$\Delta SE ()$

$x = y$ ~~at~~, so ~~at~~

at loop ~~at~~ \star

at termination point

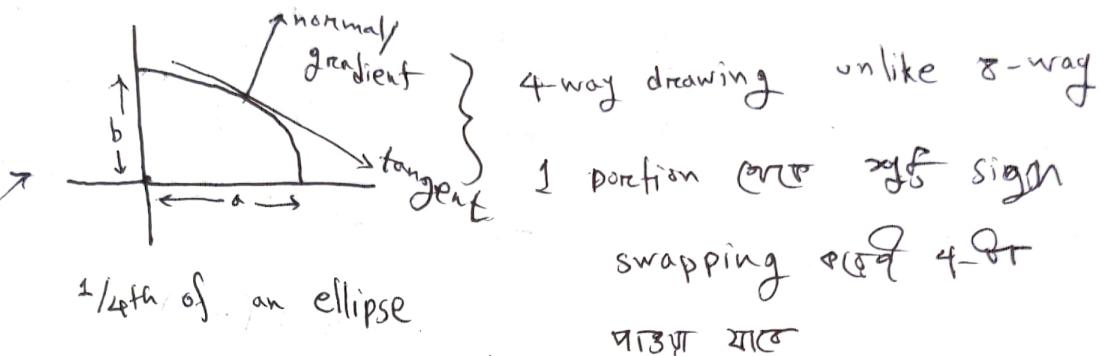
at floating point.

\Rightarrow Region - 2 go ~~to~~ init, AN, ΔNN

out ~~at~~ $\star\star\star$



Ellipse Drawing → Double radius (a, b)

Eq

$$\left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2 = 1 \quad \dots \dots \dots \text{(i)}$$

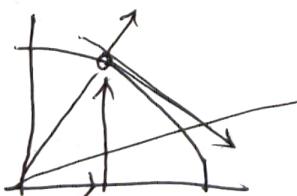
$$b^2x^2 + a^2y^2 - a^2b^2 = 0 \quad \dots \dots \dots \text{(ii)}$$

deviation \Rightarrow implicit form (पाँच याते)

type equation लाइ

→ notice normal/gradient and tangent vectors

- Consider (for understanding) a circle tangent -

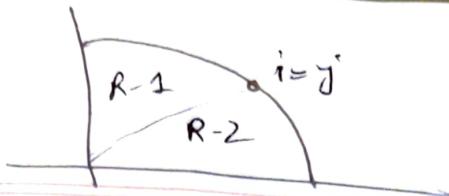


for circle at point (x, y)

grad is (x, y) as well

Reasoning ज्ञानात
Ellipse → termination to कर्तव्य विषय की दृ
जटि करता है तो इसका ग्रेड एवं
जटि करता है तो इसका ग्रेड एवं
 $x = y, (i = j)$

AS



→ grad vector \vec{w} এর সমীক্ষা $j > i$ ক্ষেত্রে $i > j$,
এবং সমীক্ষা কোণ পাই $j = i$.

Region-1 $\rightarrow j > i$

Region-2 $\rightarrow i > j$

- Consider for circle, $x^2 + y^2 = r^2$

x, y, i, j values
main $\left[\begin{array}{l} 2 \text{ rad} \rightarrow \\ 2x \vec{i} + 2y \vec{j} = 0 \end{array} \right] / 2xdx + 2y dy = 0$

- For ellipse, $b^2 x^2 + a^2 y^2 - a^2 b^2 = 0$ so,

$$\text{grad}(x, y) = 2b^2 \vec{x} + (2a^2 \vec{y}) \quad \text{magnitude of } x \text{ component}$$

$$2b^2 x, y \text{ comp} \rightarrow 2a^2 y$$

start point

$$\rightarrow (0, b) \quad \text{সূচিত } 2a^2 y \text{ (y comp)} > 2b^2 x \text{ (x comp)}$$

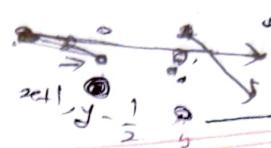
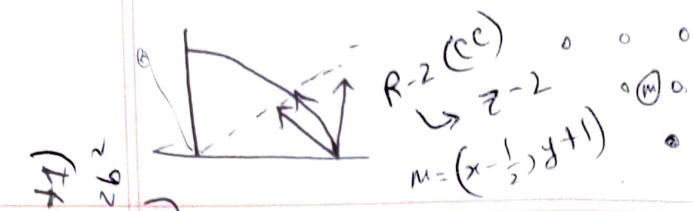
গুরুত্ব $R-1 \rightarrow$

For
new
point,

- Region-1 \rightarrow Zone-7
- Region-2 \rightarrow Zone-6



Region-1 \rightarrow x স্টেট ক্ষেত্র \rightarrow loop controller x
Region-2 \rightarrow y স্টেট ক্ষেত্র \rightarrow loop controller y



Derivation for R-1

As Region-1 = Zone-7,

$$M = (x+1, y - \frac{1}{2})$$

$$M_1 = (x+2, y - \frac{1}{2})$$

$$M_2 = (x+2, y - \frac{3}{2})$$

$$\begin{aligned} d_1 - d &= \Delta E = b^2(x+2)^2 + a^2(y - \frac{1}{2})^2 \\ &\quad - b^2(x+1)^2 - a^2(y - \frac{1}{2})^2 \\ &= b^2(2x+3) \end{aligned}$$

$$\begin{aligned} d_2 - d &= \Delta SF = b^2(x+2)^2 + a^2(y - \frac{3}{2})^2 \\ &\quad - b^2(x+1)^2 - a^2(y - \frac{1}{2})^2 \\ &= b^2(2x+3) + a^2(2y+2) \end{aligned}$$

$$d_{\text{init}} = b^2 + a^2(y - \frac{1}{2})^2 - a^2 b^2$$

$$\begin{aligned} \downarrow \\ \text{at } (0+3, b - \frac{1}{2}) &= b^2 + a^2(b^2 - b + \frac{1}{4}) - a^2 b^2 \\ &= b^2 + a^2 b^2 - a^2 b + \frac{a^2}{4} - a^2 b^2 \end{aligned}$$

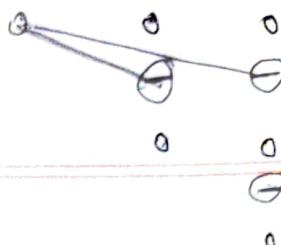
$$\boxed{d_{\text{init}} = b^2 - a^2 b + \frac{a^2}{4}}$$

Think,
if

$$a = b = 1 \text{ then } d > 0$$

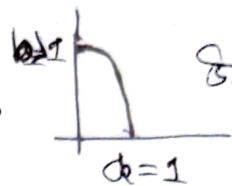
$$a = 2, b = 1 \text{ then } d < 0$$

$$\text{ellipse grad}(x,y) = 2b^2x + 2a^2y$$



• center is at origin if d positive,

$$\textcircled{i} \quad a=1, b>1 \rightarrow$$



vertical ellipse

$$\textcircled{ii} \quad a=1, b=1 \rightarrow \text{circle}$$

d negative \Rightarrow ΔE

d positive \Rightarrow ΔSE

Code
(for region 1)

void drawEllipse1(int a, int b) {

 int x=0, y=b; // initial point of R-1

 int d = 4(b²-a²b)+a²; // multiplied by 4 to remove fraction

 draw4way(x, y); // all 4 part of ellipse drawn

 while($b^2(x+1) < a^2(y-\frac{1}{2})$) {

 if($d < 0$) {

 d += 4b²(2x+3)

 x++

 } else {

 d += 4b²(2x+3)

 x++, y--

}

 draw4way(x, y);

 } ... // Rest code.

we can multiply
 b^2 ,
 a^2 ,
 $2ab$,
 $2a^2b$

or
 b^2 ,
 a^2 ,
 $2ab$,
 $2a^2b$

remember
to multiply
by 4



→ Region-2 वा दिन रहना, Region-1 वा

last point पर्याप्त.

Region-2 वा उन्हें Zone-6.

जहाँ $x_0, y_0, f(x_0)$,

$$f\left(x_0 + \frac{1}{2}\right) f(y_0 - 1) \} \quad f \text{ एक समत}$$

दिन प्राप्त वर्ग,

Termination criteria in R-2

is simply $y > 0$.

Region-2 @ ΔS & ΔSE वर्ग

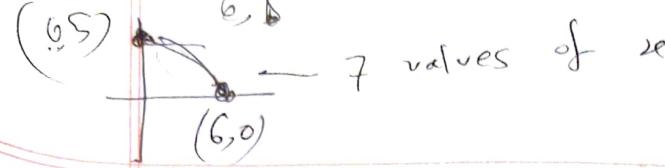
परे derive करते हैं,

$$M = \left(x + \frac{1}{2}, y - 1\right)$$

$$M_1 = \left(x + \frac{1}{2}, y - 2\right)$$

$$M_2 = \left(x + \frac{3}{2}, y - 2\right)$$

so, find ΔS and ΔSE

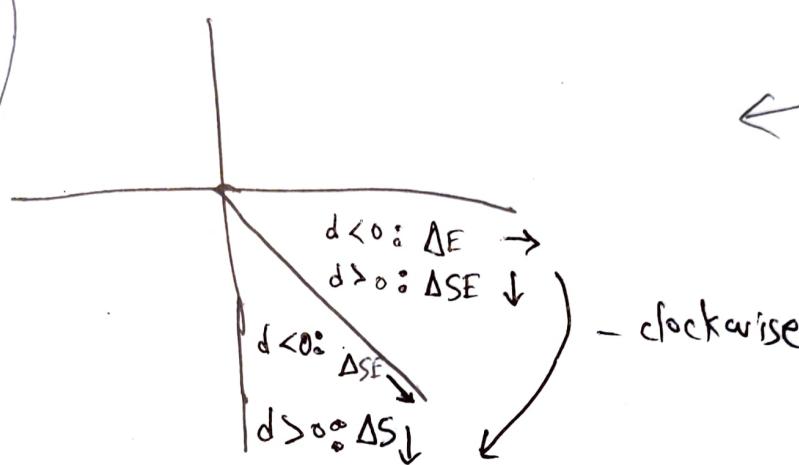


region-2 (0) d negative-positive:

$$\Delta SE \quad d < 0 \quad \text{उल} \quad \Delta SE$$

$$d > 0 \quad \text{उल} \quad \Delta S$$

region-1
→ याकूब
clockwise,
जेमेज



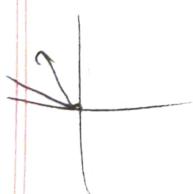
o Program → यह शुरू हो d का लिया,

पर्फेस लॉप → x, y, d, $\Delta E / \Delta SE$

R-1 में d का d-value

R-2 में d का d-value
Repeat for n, y, d, $\Delta SE / \Delta E$

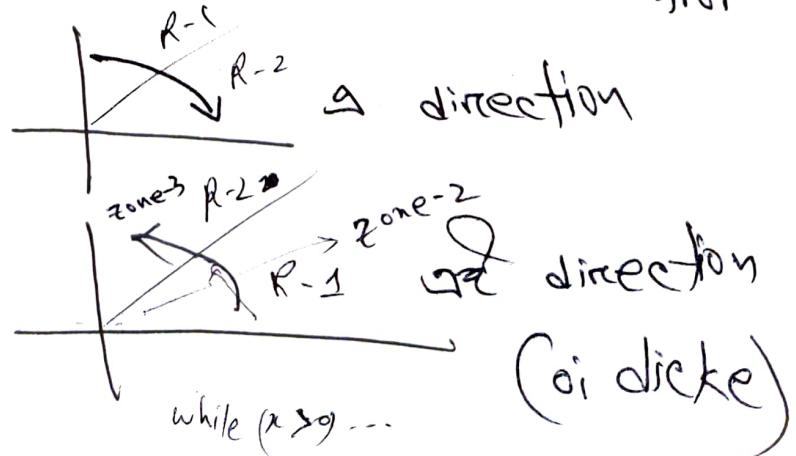
Do for (6,5) → 7 की वाले गिरजे



forwards



forwards





(0, 0) →
~~(0, 0)~~ (-2, 5)

Questions

loop controllers — code (WZ)

circle 8-way

Equation
of a
Line :

$$\frac{x}{7} + \frac{y}{5} = 1$$

Draw the following line using
line drawing algo.

so, range will be

$$(0,5) \text{ to } (7,0)$$

$$(x=0) \quad (y=0)$$

→ Make range yourself if not
given

range, $y = 3$ to 10 ~~5 to 10~~

~~x~~ ~~5 to 10~~ point ~~10~~

~~10~~,

① Find the zone

$$y = mx + c; \quad m = -\frac{1}{7}$$

But if you multiply equation by

5 to keep ~~y~~ up sign 1,

$$\frac{5x}{7} + y = 5 \Rightarrow y = 5 - \frac{5x}{7} \quad m = \frac{-5}{7}$$

$$m = \frac{dy}{dx} = \frac{-5}{7}$$

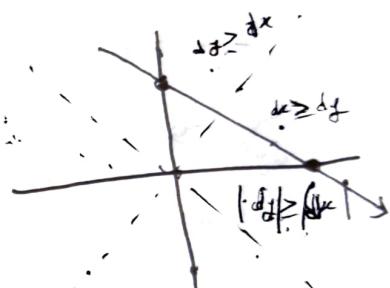
$$dx \leq dy$$

and ~~dx~~

either dy or dx

neg, so zone-3 or 7

→ ~~start~~ so, 7



PDA is floating point algo.



(ii)

Compare the pixel coordinates from Midpoint and DDA algorithm.

(iii). For zone-7, find ΔE , ΔSE and dinit.

$$\text{Eq. } Ax + By + C = d$$
$$A = dy, \quad B = -dx$$

$$By = -Ax + (d - C)$$

$$y = -\frac{A}{B} + \frac{(d - C)}{B}$$



$$d_1 - d = f(x+2, y - \frac{1}{2}) - f(x+1, y - \frac{1}{2})$$
$$= A = \Delta E = dy$$

$$d_2 - d = f(x+2, y - \frac{3}{2}) - f(x+1, y - \frac{3}{2})$$

$$= A - B = dy + dx = \Delta SE$$

$$\text{dinit} = A - \frac{B}{2} = dy + \frac{dx}{2}$$

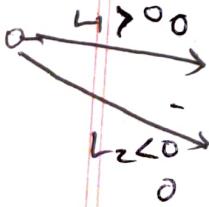
(6, 5) to (7, 0)

$$dy = -5, \quad dx = 7 \quad \text{dinit} = -\frac{3}{2}$$

$$\text{dinit}_{\text{act}} = 2 \times \left(dy + \frac{dx}{2} \right) = -10 + 7$$
$$= -3$$

$$\Delta E = \Delta E_{\text{act}} \times 2 = -10$$

$$\Delta SE = \Delta SE_{\text{act}} \times 2 = 4$$



$$\text{dinit at } (1, -0.25) = 2 \times \left(\frac{1}{4} + \frac{1}{2} \right) > 0$$

positive \Rightarrow ΔE

neg \Rightarrow ΔSE

Simulation

<u>x</u>	<u>y</u>	<u>d</u>	<u>$\Delta F / \Delta S$</u>
0	5	-3	ΔS
1	4	1	ΔF
2	4	-9	ΔS
3	3	-5	ΔS
4	3	-1	ΔS
5	1	3	ΔF
6	1	-7	ΔS
7	0	-3	ΔS

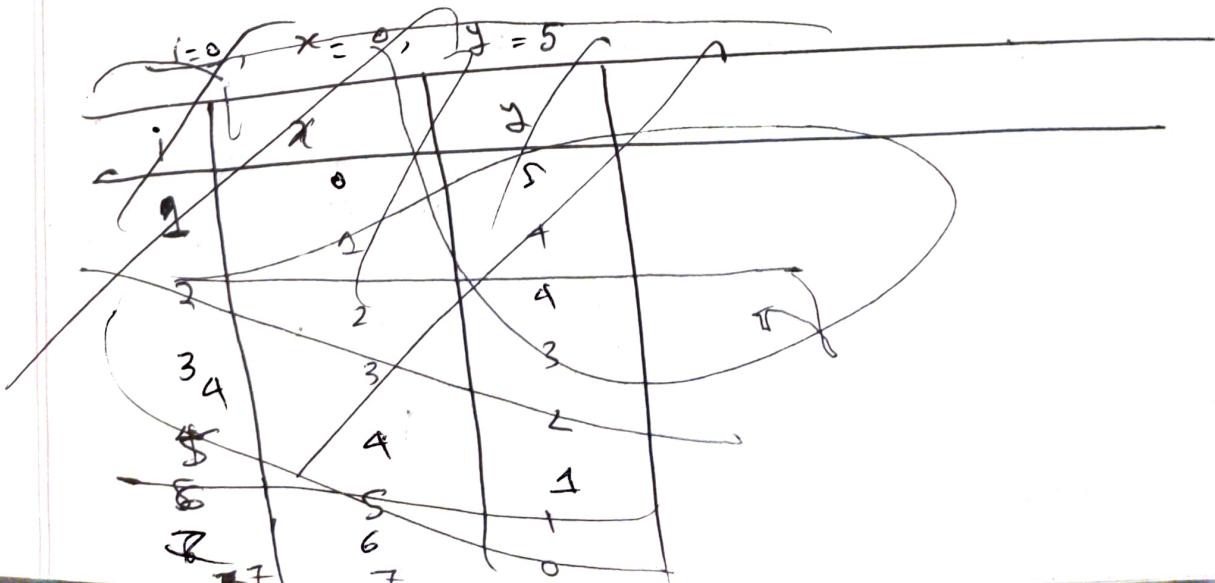
⇒ Now we do DDA and Compare.

DDA Simulation

$$dx = 7, \quad dy = -5, \quad \text{STEP} = \max(|dx|, |dy|) = 7$$

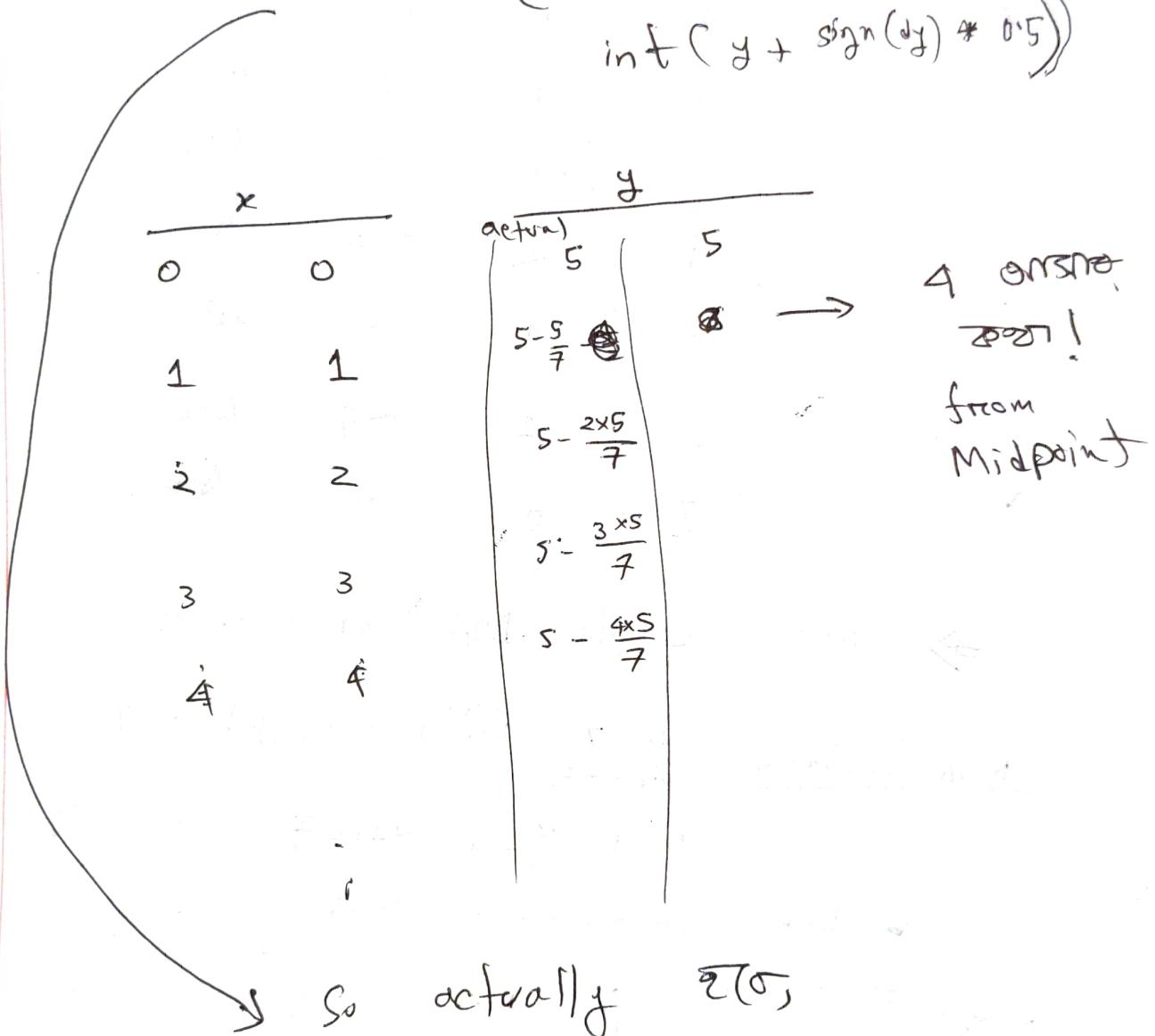
$$dx_{act} = \frac{7}{7} = 1, \quad dy_{act} = \frac{-5}{7} \quad dy_{act} = -\frac{5}{7}$$

loop controller $\rightarrow x$ (max)



⇒ Symmetric roundoff

drawPixel ($\text{int}(x + \text{sign}(\Delta x) * 0.5)$,
 $\text{int}(y + \text{sign}(\Delta y) * 0.5)$)



So actually $\bar{x}(5)$

drawPixel ($\text{int}(x + \text{sign}(\cancel{x_{curr}}) * 0.5)$,
 $\text{int}(y + \text{sign}(\cancel{y_{curr}}) * 0.5)$)

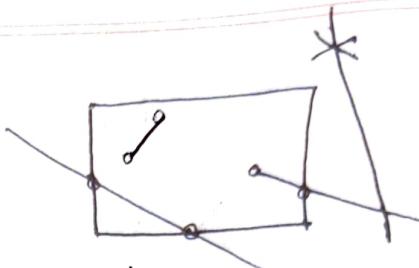
dynamically x or y go sign $\cancel{20}$

ପ୍ରଥମ ଫିଲ୍ଡ $\pi/4$ + 0.5 ଏ - 0.5 $\pi/4$.

\Rightarrow ଦେଇଲା କହେନ୍ତି କି sign(dx) sign(dy) କଟକ,

ଅନ୍ୟାନ୍ୟ sign(x) sign(y) କଟ.

Line Clipping Algorithm



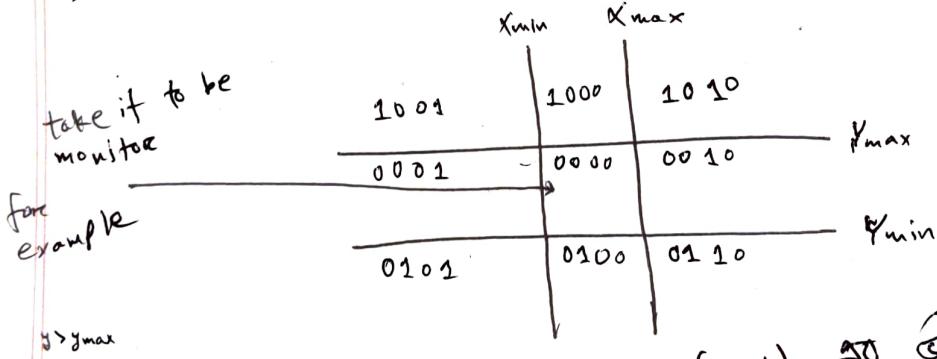
Cohen-Sutherland LCA:

→ Two separate ~~iterations~~ discovery

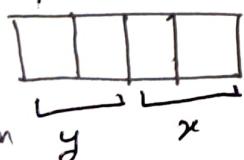
→ Left Line to right endpoint to

Binary code (0000) → using the code, deciding whether it'll be drawn

→ for both 2D and 3D



if (0000) point to (x, y) to 2000 false out



4-bit code 2000 out 2111 - Region Outpt

(x, y) position
 x, y inter-changeable

if $y > y_{\text{max}} \rightarrow 10$

in-between $y_{\text{min}} \rightarrow 00$

else $y < y_{\text{min}} \rightarrow 01$

y_{min}

same for x_s .

→ 9 combinations (instead of 2^4)

Because → none has more than 2 ones.

Octal
value

\rightarrow int $y_{max} = 100$, $y_{min} = -100$, $x_{max} = 150$, $x_{min} = -150$

↑ ↑ 0010 0001
1000 0100

code int TOP = 8, BOTTOM = 4, RIGHT = 2, LEFT = 1;
int makeCode (int x, int y) {

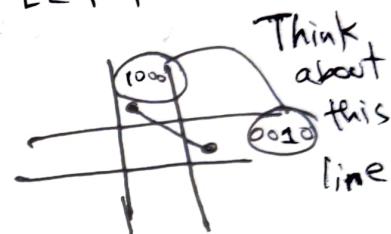
int code = 0;

(Boundary points
are also
taken as
is used)

if ($y > y_{max}$) code += TOP
else if ($y < y_{min}$) code += BOTTOM
if ($x > x_{max}$) code += RIGHT
else if ($x < x_{min}$) code += LEFT

Return code;

}



\Rightarrow Second discovery,

test point z^0

* \rightarrow Trivially accepted: OR is zero

\rightarrow Trivially rejected: AND is !zero

else \rightarrow test and clipping

\hookrightarrow go one or zero \leftarrow

until trivially accepted or

rejected

\rightarrow "In 3D what for z^0 ?"

6 bit
region
Output

\rightarrow near user = +7

32 \leftarrow far user = -7

16 \leftarrow 6 bit z^0 accepted rejected same

But \rightarrow 4-loop maximum
for 2D, 3D \leftarrow INT GRTR

Work by

104

205

100

- At a glance we can trivially accepted/rejected.
- Clipping → Algo error called Z^+ ,
clipping \hookrightarrow accepted Z^+ draws Z^+ .

// code

```
void CohenSutherland (int x0, int y0, int x1, int y1){  
    int code0, code1, code, x, y;  
    code0 = makeCode (x0, y0); code1 = makeCode (x1, y1);  
    while (1) {  
        if ((code0 | code1) == 0) { // Accepted  
            drawLine (x0, y0, x1, y1);  
            break;  
        }  
        else if (code0 & code1) { // Rejected  
            break;  
        }  
    }  
}
```

else

Pto

$$\frac{y+100 - 200}{400} = \frac{x+300 - 700}{-700}$$

partial & safety
1 ans

else { // partial

if (code == 0) code = code 0
else code = code 1

safety
measure

if (code & TOP) { // above ymax

$$y = y_{max};$$

$$x = x_0 + (y_{max} - y_0) \times (x_1 - x_0) / (y_1 - y_0);$$

else if (code & BOTTOM) {

$$y = y_{min};$$

$$x = x_0 + (y_{min} - y_0) \times (x_1 - x_0) / (y_1 - y_0);$$

} else if (code & RIGHT) {

$$x = x_{max};$$

$$y = y_0 + (x_{max} - x_0) \times (y_1 - y_0) / (x_1 - x_0);$$

}

else {

$$x = x_{min};$$

$$y = y_0 + (x_{min} - x_0) \times (y_1 - y_0) / (x_1 - x_0);$$

As (x_0, y_0)

\Rightarrow for
clip

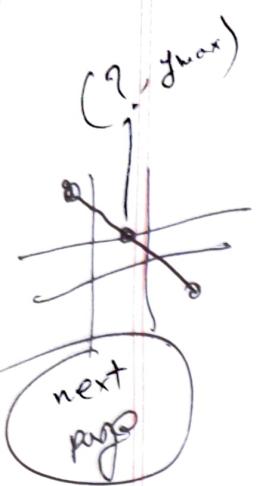
clip

} if (code == code 0) { $x_0 = x, y_0 = y;$
 $code0 = makeCode(x_0, y_0)$

else { $x_1 = x, y_1 = y, code1 = makeCode(x_1, y_1)$

} // else part.

} // while loop



Parametric Equation of a line

$$x_t = x_0 + t(x_1 - x_0)$$

$$y_t = y_0 + t(y_1 - y_0)$$

y corr t \Rightarrow exp x Δ const.

$$x_t = x_0 + \frac{y_t - y_0}{y_1 - y_0} (x_1 - x_0)$$

$$\text{so, } x_t = x_0 + \frac{y_{\max} - y_0}{y_1 - y_0} (x_1 - x_0)$$

→ Quiz!?

⇒ Parametric Line-Clipping Algorithm

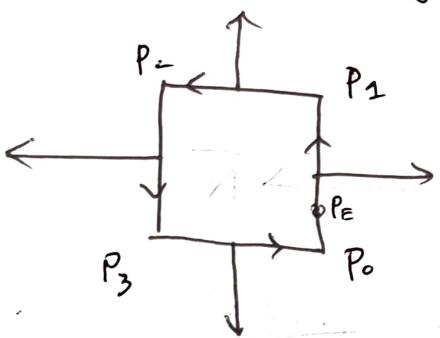
→ Polygon has more than two points

→ Boundary direction of a polygon that each

side go normal line or gradient vectors

→ On-face and off-face of a surface

→ On face zero切线, tangents are
always anti-clockwise.



it's a $P_0 P_1 P_2 P_3$ polygon
(anti-clockwise)

Let, P_E be any point

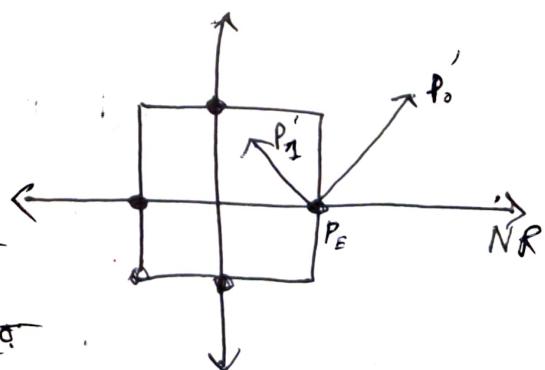
How do we know mathematically if a point is
inside the polygon?

$$(P'_0 - P_E) \cdot NR > 0 \rightarrow \text{inside}$$

$$< 0 \rightarrow \text{outside}$$

$$= 0 \rightarrow \text{on line}$$

$(P'_1 - P_E) \cdot NR > 0$ since leaving, < 0 since entering



*

\Rightarrow Entering t_E and Leaving t_L

मात्र t पर, ~~जबकि~~ entering, ~~जबकि~~ leaving

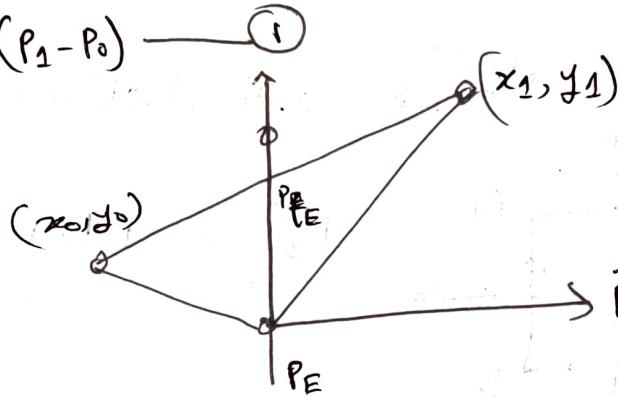
$\Rightarrow (x_0, y_0)$ इसके लिए t के सभी स्थितियाँ

जैसे t छला t_E ,

(x_1, y_1) इसके लिए t के अन्य स्थितियाँ

जैसे t छला t_L .

$$P(t) = P_0 + t(P_1 - P_0) \quad \text{--- (i)}$$



$$(P_{t_E} - P_E) \cdot N = 0 \quad \text{--- (ii)}$$

From (i) and (ii) $\Rightarrow (P_0 + t_E(P_1 - P_0) - P_E) \cdot N = 0$

$$\Rightarrow (P_0 - P_E) \cdot N + t_E(P_1 - P_0) \cdot N = 0$$

$$t_E = -\frac{(P_0 - P_E) \cdot N}{(P_1 - P_0) \cdot N} \quad \text{--- (iii)}$$

•

Learn Derivation of t_E

Left

$$\frac{x_{\min} - x_0}{x_1 - x_0}$$

\rightarrow ~~area~~ ~~at~~ known, ~~at~~ unknown.

Right $\rightarrow N = (1, 0)$, Left $N = (-1, 0)$

Top $\rightarrow N = (0, 1)$ Bottom $N = (0, -1)$

For right,

$$N = (1, 0)$$

$x_e = x_{\max}$

$$t_e = \frac{(x_0 - x_e) \cdot N_x + (y_0 - y_e) \cdot N_y}{(x_1 - x_0) N_x + (y_1 - y_0) N_y}$$

$$= - \frac{(x - x_{\max}) \cdot 1}{(x_1 - x_0) \cdot 1} = \frac{x_{\max} - x_0}{x_1 - x_0}$$

like

\rightarrow for this we can proof for top,

$$\text{Left} \rightarrow \frac{x_{\min} - x_0}{x_1 - x_0}$$

$$\cdot \frac{y_{\max} - y_0}{y_1 - y_0}$$

$$\text{Bottom} \rightarrow \frac{y_{\min} - y_0}{y_1 - y_0}$$

Cytron-Beck LCA (last class ते असे कौनसी?)

$$\text{we saw, } t_E = \frac{(P_0 - P_E) \cdot N}{(P_1 - P_0) \cdot N}$$

A List of t , for all edges:



Boundary

→ TOP

Normal

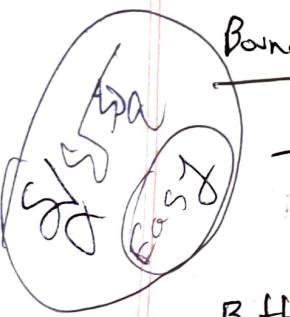
(0, 1)

$$(P_0 - P_E) \cdot N$$

top गो 3प्रेस N)

$$y_0 - y_{\max}$$

$$(x_0 - x, y_0 - y_{\max}).(0, 1)$$



Boundary

TOP

Bottom

~~RIGHT~~ LEFT

LEFT

Normal (W)

(0, 1)

(0, -1)

(-1, 0)

(-1, 0)

$$(P_0 - P_E) \cdot N$$

$$(y_0 - y_{\max})$$

$$-(y_0 - y_{\min})$$

$$(x_0 - x_{\max})$$

$$-(x_0 - x_{\min})$$

$$(P_1 - P_0) \cdot N$$

$$(y_1 - y_0)$$

$$(y_0 - y_1)$$

$$(x_1 - x_0)$$

$$(x_0 - x_1)$$

t

$$\frac{y_{\max} - y_0}{y_1 - y_0}$$

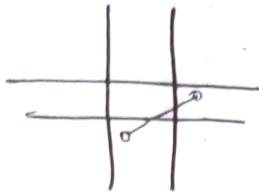
$$\frac{y_{\min} - y_0}{y_1 - y_0}$$

$$\frac{x_{\max} - x_0}{x_1 - x_0}$$

$$\frac{x_{\min} - x_0}{x_1 - x_0}$$



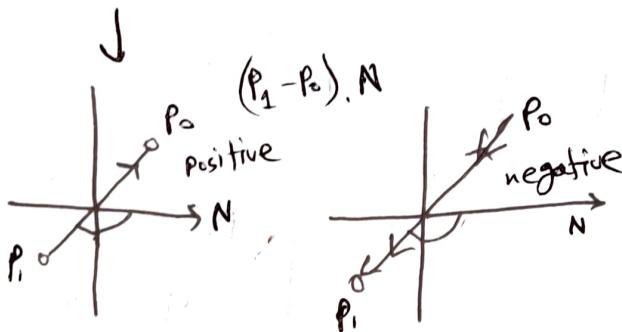
प्र० → make a list of t for all edges



$t_{\text{top}}, t_{\text{left}}$ of σ are
abnormal \rightarrow not less than 1.

t_E, t_L 1. group 40% तरं Intersection of σ -

positive \rightarrow leaving, negative \rightarrow entering



So, for top,
 $y_1 - y_0 = y_1 > y_0$
means leaving.
bottom \rightarrow entering

\Rightarrow According to Cyrus-beck, a line is from

$(t_E \text{ max} \text{ to } t_E \text{ min})$. $t_E \text{ max}$ एवं $t_E \text{ min}$

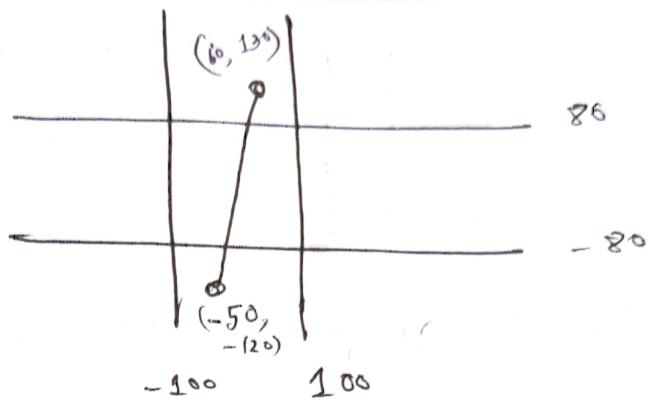
new (x_0, y_0) $t_E \text{ min}$ तरं new (x_1, y_1)
 $t_E \text{ max}$

\hookrightarrow $t_E \rightarrow 0$ (t_E max $\sigma(\sigma)$)

$t_E \rightarrow 1$ (t_E min $\sigma(\sigma)$)

so that $(P_1 - P_0).N = y_1 - y_0, (P_1 - P_0).N > 0$,
means $(y_1 - y_0) > 0 \Rightarrow y_1 > y_0$

example



- ① A line from $(-50, -120)$ to $(60, 130)$
 → value of t for all edges

Boundary	t
TOP	0.8
Bottom	0.16
Right	0.72 1.18 1.36
LEFT	0.46 -0.45

t_E

→

Boundary

TOP

t

0.8

Bottom

0.16

Right

~~0.72~~ ~~1.18~~ 1.36

Left

~~0.46~~ -0.45

goes out,

RIGHT \rightarrow leaving

as $x_1 > x_0$,

so, left \rightarrow

entering.

SO

$$\rightarrow t_{E \max} = \max(0.16, -0.45) = 0.16$$

Now,

goes

$f_1 > g_0$

So, top \rightarrow SCCR

line for

leaving!

Automatically

bottom \rightarrow SCCR

entering.

$$t_{\min} = \min(0.8, 1.36) = 0.8$$

(हाथी उत्तम)

→ Code out from given line

$\Rightarrow (x_0, y_0) \quad (x_1, y_1) \quad$ परिवर्तनी त को उत्तम
प्रयोग की t के लिए t_E, t_L को उत्तम

// for top

if ($y_1 > y_0$):

~~$t_L = t$~~

if ($t < t_L$): $t_L = t$

else if ~~$y_0 \geq y_1$~~ :

if ($t > t_{E\max}$): $t_E = t$

प्राप्त
accepted)

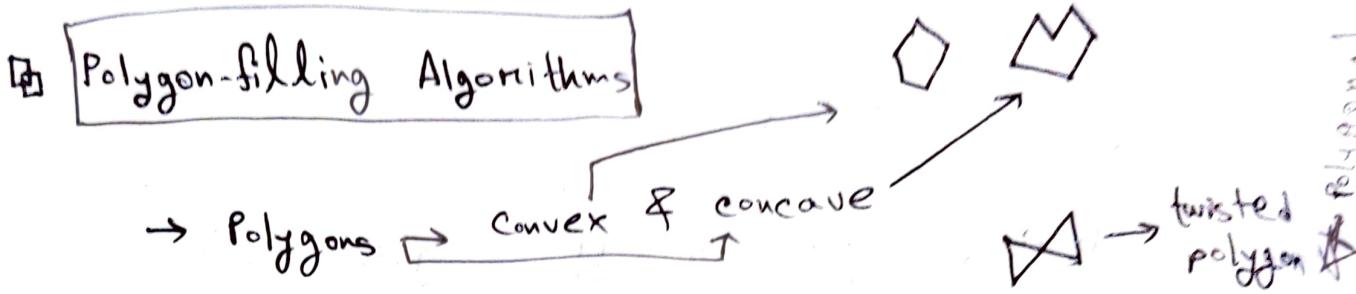
(x_0, y_0) नियुत
from function?

→ if ($t_{E\max} > t_{\min}$) then rejected

- $d > 0, d < 0$ alternate
for line but not circle

08.02.23

Leet-10, Wednesday



⇒ OpenGL uses convex polygon

filling first

⇒ easiest first for both convex
and concave since fog twisted polygon.

⇒ [ScanLine algorithm] of Polygon filling first

concept,

Polygons pixels are thought of
as set of lines. First a

boundary pixels set then

scanline w.r.t. Parity-based

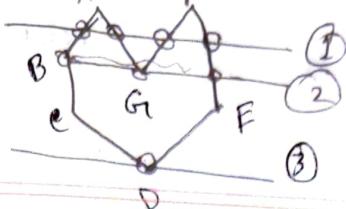
process. Parity change w.r.t.

filling w.r.t. w.r.t. w.r.t.

filling w.r.t.

Parity - for {

Polygon - mesh



Polygon as for different faces

- Solving colors in overlapping polygons.

↳ one side to pixel color (n)



→ solve color vertically

one pixel color (n),

→ AB line → A @ (n), B @ (n).

AB

$A = 0$ as AB A @ (n)

$B = 1$ as AB B @ (n), BC B @ (n)

$C = 1$, P = 2, F = 1, F = 0, G = 2

→ number of intersections



→ Problem as 3 types to line ↗

even.

⇒ Scanline to Bucket array

Bucket array: edgeTable → corner line to info next area

p-10



ABCDEF₆ (3) order entry

Edge-Table \rightarrow horizontal intersections info

Active-Edge Table \rightarrow Edge Table $\xrightarrow{\text{to}}$ Graph
 \downarrow
 (all the boundary pixels $\xrightarrow{\text{as vert}}$ $x = 1$ $y = 1$ arc cut $x = \frac{1}{2}$)
 (area scan-line $\xrightarrow{\text{arc}}$,
~~arc~~ !) \hookrightarrow with info

with info

Edge-Table (nD)

<img alt="A hand-drawn graph diagram illustrating an Edge-Table representation. The graph has six vertices labeled A through F. Vertex A is at (0,4), vertex B is at (8,0), vertex C is at (16,0), vertex D is at (16,8), vertex E is at (10,8), and vertex F is at (5,13). Edges connect A to B, A to E, B to E, E to F, and F to D. Each edge is labeled with its endpoints and a value in parentheses, such as (0,4) to (8,0) with value 2. To the right, a vertical array is shown with indices 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92, 93, 94, 95, 96, 97, 98, 99, 100, 101, 102, 103, 104, 105, 106, 107, 108, 109, 110, 111, 112, 113, 114, 115, 116, 117, 118, 119, 120, 121, 122, 123, 124, 125, 126, 127, 128, 129, 130, 131, 132, 133, 134, 135, 136, 137, 138, 139, 140, 141, 142, 143, 144, 145, 146, 147, 148, 149, 150, 151, 152, 153, 154, 155, 156, 157, 158, 159, 160, 161, 162, 163, 164, 165, 166, 167, 168, 169, 170, 171, 172, 173, 174, 175, 176, 177, 178, 179, 180, 181, 182, 183, 184, 185, 186, 187, 188, 189, 190, 191, 192, 193, 194, 195, 196, 197, 198, 199, 200, 201, 202, 203, 204, 205, 206, 207, 208, 209, 210, 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* start values \rightarrow null ~~start~~ ~~at~~ ~~at~~ intersection $\xrightarrow{\text{diff}}$
 \hookrightarrow ~~diff~~ \rightarrow λ ~~at~~

$\Rightarrow y=0$ intersection worst case link ~~(3)~~

worst case link \rightarrow after f_1 value

2nd C

$y=0 \Rightarrow$ AB — line is from 0 to 3

4	8	-2	
y_{\max}	x-value	$\frac{1}{m}$	link

CD

8	16	0	λ
y_{\max}	x-value	$\frac{1}{m}$	link

≈ 4.2

$y = 1$ to $3 \Rightarrow \lambda$

BC

case

one point

point

$y_{\min} = 0$

and $y_{\max} = 0$

$y_{\min} = y_{\max}$

AG

8	0	0	λ
λ			

$y = 5$ to $7 \Rightarrow \lambda$

FG

EF

13	0	1	λ
13	18	-1	λ

So, five intersections.

Polygon ~~bit~~ F, D survive ~~cost~~

cost list of (x_{\min}, y_{\max}) ~~bit~~

now,

zero Active-Edge $\rightarrow y_{\min}$ ~~cost~~

$$\begin{aligned} & (y_{\max} - 1) \quad \text{cost} \quad \text{cost} \quad 1 \\ & y+1 \quad \text{cost} \quad x + \frac{1}{m} \quad \text{cost} \\ & \underbrace{\qquad\qquad\qquad}_{\text{table}} \rightarrow \text{sort cost} \end{aligned}$$

Active

PF

Active-Edge Table

-1	13	4	1	→	13	6	-1	1
12	13	3	1	→	13	7	-1	1
11	13	2	1	→	13	8	-1	λ
10	13	1	1	→	13	9	9	λ
9	13	0	1	→	13	10	-1	λ
8	8	0	0	FG	8	4	6	0
7	8	0	0	→	8	4	6	0
6	8	0	0	→	8	16	0	λ
5	8	0	0	→	8	16	0	λ
4	8	0	0	GA	8	16	0	λ
3	4	2	-2	AB	8	16	0	λ
2	4	4	-2	AB	8	16	0	λ
1	4	6	-2	AB	8	16	0	λ
0	4	8	-2	AB	8	16	0	λ

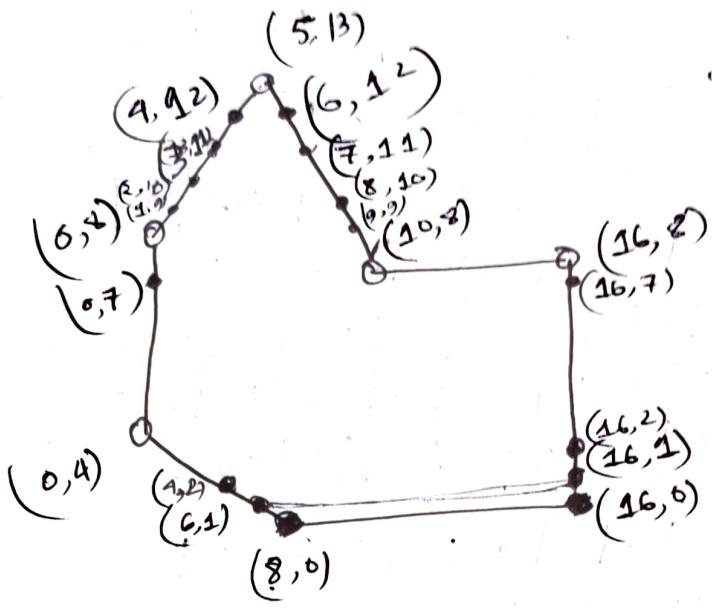
2. Next
 FG sorted
 steps
 কানুন
 পর্যবেক্ষণ
 পরিচয়
 পরিচয়
 case →

* গোড়ার্থী Edge-table to Active-Edge-Table

Conversion এন্ডেজ টেবিল



एवं एप्पे रूपः



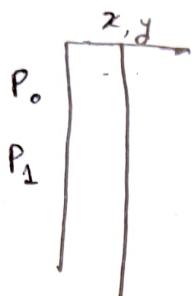
Active-edge
table से सब
रोड जाना
सीज़ियल

Active-edge table features → even number of
intersections
guaranteed.

* एप्पे एज़े टेबल, Active-Edge
एवं

LAR → Edge table एवं फॉर्मूला फॉर रुलेस
follow एप्पे,
A, B, C, D, E, F, G के एज़े Edge
table एवं
→ एप्पे steps एप्पे
(internet) एप्पे (प्रॉकैट)

⇒ Per line \rightarrow का इसी value से कैसे चर्चा होती है।



for this Edge table का क्या होता है?

क्या यहाँ पर्सेज आता है?

① अन्तर vertex का edge array

$$E \rightarrow (P_0 P_1, P_1 P_2, \dots, P_n P_0)$$

vertex 5 की दल 5 की edge

बिल्कुल नहीं

② y_{\min} की sort कौनसे हैं एवं edge C.

③ $|y_{\min} - y_{\max}|$ का — का कौनसे है, क्योंकि size

of array कितना है, किंतु अच्छी या नहीं है

intersection, ताकि $(y_{\min} - y_{\max}) \times 2^0$

④ y_{\min} की value का GT \Rightarrow Poly[X][Y] का Array

first location \rightarrow कौनसा

from Edge table का कौनसा

किसी शब्द का 'Blank' कौनसा

2^0

4^0

8^0

16^0

32^0

64^0

128^0

256^0

512^0

1024^0

⑤ मिलाने की y_{\min} की, अच्छी X को sort out करना।

↪ y_{\min} की X को sort out करना lower X

array, higher X पर।

first location \neq null थाएँ \rightarrow intersection part.

⑥ For value \neq null तो इसे to make edge table.

⑦ नहीं था Blank स्थान fill करके बनाओ
Active edge table मात्र तक ($y_{max} - 1$)

प्रक्रिया,

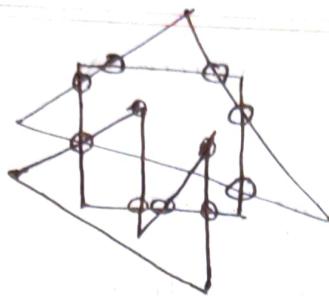
\Rightarrow Poly.txt नामक data file करके बनाओ
Point छापो,

22 दो अल्गोरिदम्स Algo or प्रक्रिया \rightarrow लिखो

उदाहरण।

H.W

Polygon-Clipping:



- We'll see Sutherland - Hodgeman

Algorithm for Polygon Clipping

→ Point inside-outside status etc (like even-odd)

→ Edge boundary vector etc (with direction)

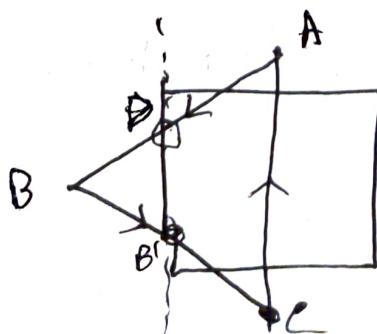
↳ Edge property of Edge while
intersecting → entering, leaving,
(~~no~~ ~~one~~ intersection) \Rightarrow inside, outside

→ If left boundary etc, Left no more
start "outside", it's start \Rightarrow Inside

→ Edge part, no group to \Rightarrow leaving, entering,
totally outside,
totally inside.

\Rightarrow Example \rightarrow no group to no

Rule are -



Rule #1 (Entering): \geq vertex

- Output
① Border
② End

Entering Edge goes after \Rightarrow output vertex into.

From left (in image): entering $\rightarrow \overrightarrow{BC}$
output from edge $\rightarrow B', C$
 \downarrow send border

Rule #2 (Inside): output \rightarrow 1 vertex (End only)

completely inside $\overrightarrow{CA} \rightarrow$ output
edge $\rightarrow A$ (end)

Rule #3 (Leaving): output \rightarrow 1 vertex (Border only)

leaving $\overrightarrow{AB} \rightarrow$ output
edge $\rightarrow D$

Rule #4 (Outside): outside \Rightarrow discard \rightarrow vertex

no vertex will be considered

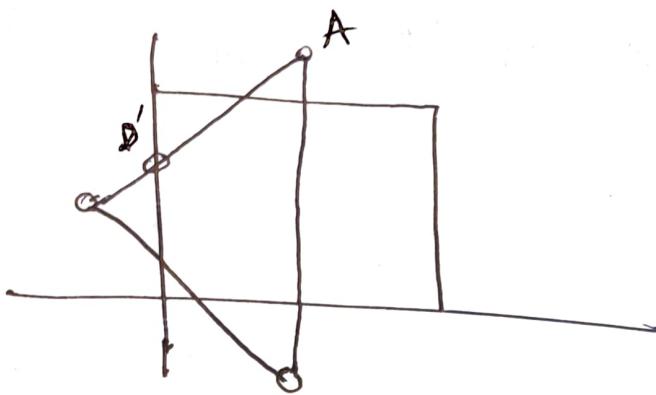
Now, for lower border,

$(P - P_f) \cdot N > 0 \rightarrow$ leaving
 $\leftarrow 0 \rightarrow$ entering

B'C is leaving \rightarrow borders only $\rightarrow B''$

C'A is entering \rightarrow ~~end only~~ borders $\rightarrow C'$, A
 end

A'D is inside \rightarrow end only $\rightarrow D$



\Rightarrow Cyrus-beak ~~to score~~ leaving-entering
 to do. However, $0 \leq t \leq 1$ at last
 intersect point,
 first: Cyrus-beak \rightarrow AD was entering
 but never inside.

Inside
 Outside

$(P - P_f) \cdot N >$ +ve, inside
 -ve, outside

80° 80° ?

Lect 14, Wednesday

Q1

Line-Drawing Algorithm

(x_0, y_0) equation or intersection (पूँजी)

- ① zone too को
- ② derive को d , del
- ③ Algorithm
- ④ Simulation

Q2

Circle तो तर्ज $(0, r)$ ग्राम (पूँजी)

center शुद्धि,

@ R-1 पूँजी वर्णन R-3

इसी stuff पूँजी उत्पत्ति

• Z-3 कोड में zone त

आवश्यक रूप फैसला,

• zone-determination algo फैसला,

• 8-way symmetry apply को



slope-independent link

- Ellipse R₁ to R₂ → derivation
of R₂ to R₁ derivations
- Cohen-Sutherland go makeCode for 2D or 3D.
 → Basic principle of cohen-sutherland
3 for accepted
- Algo for 2D / 3D
-
- Cyrus-Beck
 - ① Derivation of t and list of t
 - ② Determining inside or outside points and entering/leaving edges

~~"f to & co"~~

③ Line to int t_E, t_L (co)
new point co opt

- Polygon to Corners (w3st 2nd last)
Edge-Table of A E T (co)

- Polygon Clipping \rightarrow "4 for Basic Rule write"
"At 4 for rule important"

\rightarrow clip area ³ of Triangle exist \Rightarrow 3 points
with Boundary clip point \Rightarrow 4 points

for ex,