DLSS 4 - Super Resolution

A Transformer-based Model

14 - Jiahao Song

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- Developed by <u>NVIDIA</u>
- A suite of neural rendering technologies

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- Developed by <u>NVIDIA</u>
- A suite of neural **rendering** technologies
- Boosts frames rates (Frame Generation)
- Delivers crisp, high-quality images (CNN-based Super Resolution)



• Multi Frame Generation (2x, 3x, 4x)



- Multi Frame Generation (2x, 3x, 4x)
 - Boosts frames significantly, but introduces input latency



- Super Resolution Enhancement
 - Transformer-based



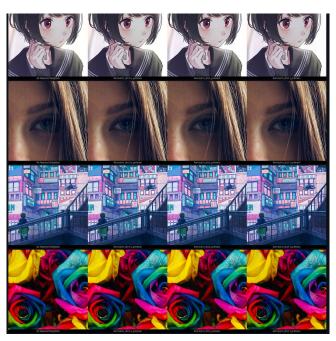
- Super Resolution Enhancement
 - Transformer-based
 - Higher detail in motion, less ghosting and artifacts



- Super Resolution Enhancement
 - Unfortunately, the DLSS 4 paper is not released yet, so I'll focus on a more general one called <u>DRCT</u>

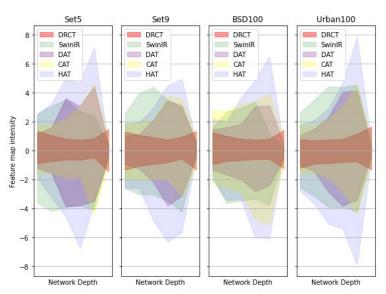


Dense-Residual-Connected Transformer (DRCT)



From left to right: Nearest Neighbor - DRCT-S - DRCT - DRCT-L

- Dense-Residual-Connected Transformer (DRCT)
- Solve the problem of information bottleneck in Swin-Transformer
 - Swin-Transformer: window-sliding vision transformer



* DRCT maintains **stable feature map intensity** as the network becomes deeper, while the intensity of other transformer-based vision networks approaches to zero (losing "long-term memory")

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- Less parameters to get similar performance as Swin-Transformer



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DRCT-L uses nearly half of parameters of HAT-L but gets better results

- Shallow Feature Extraction
- Deep Feature Extraction
- Image Reconstruction

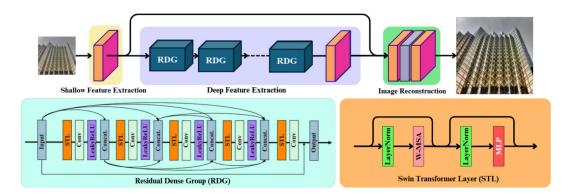


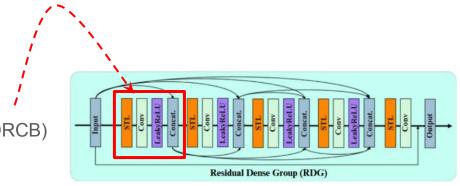
Figure 3. The overall architecture of the proposed Dense-residual-connected Transformer (DRCT) and the structure of Residual-Dense Group (RDG). Each RDG contains five consecutive Swin-Dense-Residual-Connected Blocks (SDRCBs). By integrating dense-connection [15] into SwinIR [34], the efficiency can be improved for *Saving Image Super-resolution away from Information Bottleneck*.

Shallow Feature Extraction

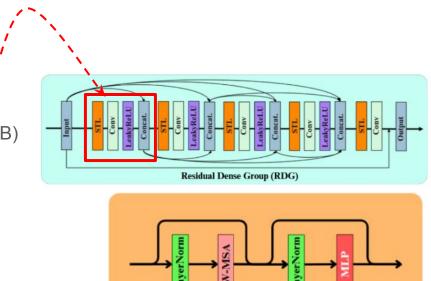
$$F_0 = Conv(I_{LQ})$$

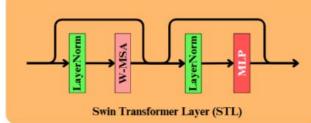
- The equation takes in a **low-quality image** into a 3x3 conv.
- Shallow features are the output of conv

- Shallow Feature Extraction
- Deep Feature Extraction
- Residual Dense Group (RDG)
 - Swin-Dense-Residual-Connected Block (SDRCB)
 - Captures long-range dependency



- Shallow Feature Extraction
- **Deep Feature Extraction**
- Residual Dense Group (RDG)
 - Swin-Dense-Residual-Connected Block (SDRCB)
 - Captures long-range dependency
- Swin Transformer Layer (STL)
 - Focuses on the **global** content of feature maps





- Shallow Feature Extraction
- Deep Feature Extraction
- Image Reconstruction

$$I_{SR} = H_{rec} (F_0 + F_{DF})$$

- Adds shallow and deep features
- Feeds it into the reconstruction layer
- Overall, low-quality images are upscaled to high-quality ones

Thank you!