

# **A Single Camera Virtual Keyboard**

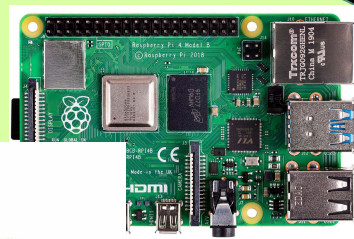
Peter West, Kevin Connell

# Introduction

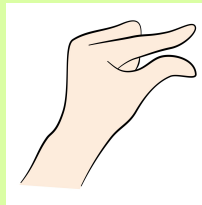
- Motivation
  - We aimed to create a virtual keyboard capable of creating a gesture controlled keyboard on any surface using one web camera. This could be expanded into any camera using AR to virtually have a keyboard anywhere.
- Goals
  - Create a virtual keyboard embedded on a microcontroller using hand gestures
  - Use one webcam or camera to capture the visuals
  - Create a readable character device or utilize a key-out system to render keyboard key presses
  - Calibration phase to map the keys the user's liking (could also choose what keys the user would like)
  - Typing phase showing resulting key presses after the calibration process where the user can type like a normal keyboard

# Overview:

- **Materials:**
  - BeagleBone Rev C or Raspberry Pi 4
  - Logitech C920 Webcam
  - Laptop/Monitor (Ethernet or HDMI)
  - Example keyboard layout (printed paper)
- **Software:**
  - OpenCV
  - MediaPipe
  - Pyautogui or kernel module
  - Other various config libraries
  - Python virtual environment -> embedded system (performance concern)
- **Set up:**
  - Webcam plugged into microcontroller positioned above reference keyboard layout (or no layout)
  - Calibration Phase: Follow key calibration steps to map keys using a pinch gesture
  - Typing Phase: Type by positioning index finger to a mapped key and using a pinch gesture

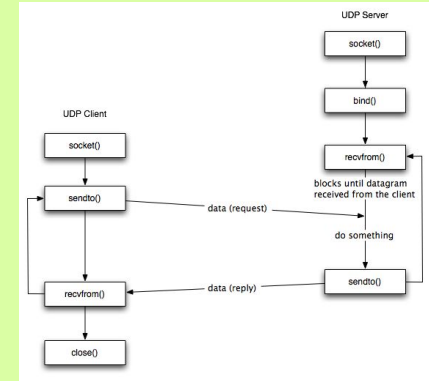
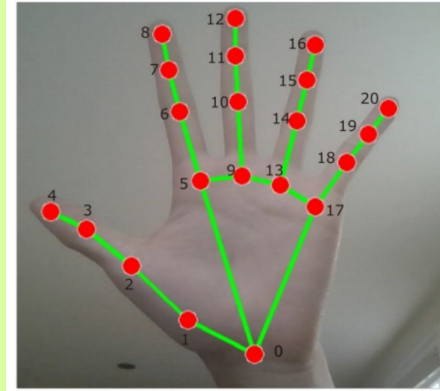


 **MediaPipe**



# Methods:

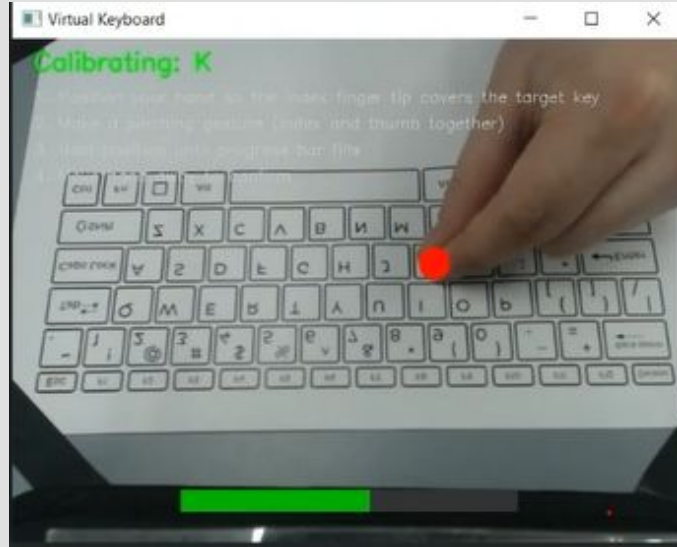
- Webcam streams live video feed through FFmpeg and v4l2
- Utilizes a UDP socket connection to send the video stream through WiFi and minimize latency (or HDMI)
- Video feed data is piped to python script through Pyautogui
- MediaPipe is used to detect and track hand movement and to detect keystrokes
- Opencv is then used to determine key positions and display the virtual keyboard to the user



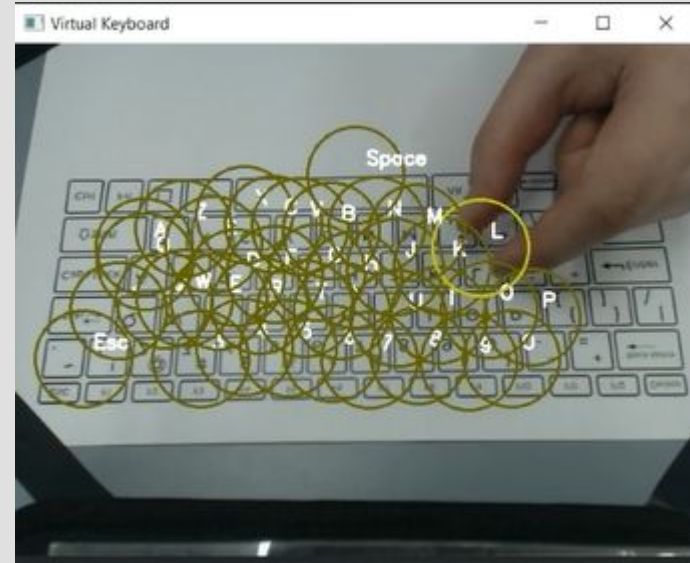
# Challenges

- Getting the BeagleBone running with eduroam
- Libraries were difficult to install/not optimized for microcontroller
- Calibration system went through several different iterations
- Camera feed latency and image quality issues
- TCP vs UDP
- Establishing piping for camera feed directly to keyboard process
- Translating Python to C++ for BeagleBone implementation

# Results



**Calibration Phase**



**Typing Phase**

# Future Steps:

Switching over to a more power microcontroller such as a Raspberry Pi 4

Full Implementation on microcontroller and limit need for an additional external device (Full vs Hybrid)

Kernel modules to enable direct control over a laptop through the virtual keyboard

**Thank you!**



PythonProject Version control

Project

- activate
- activate.bat
- activate.fish
- activate.nu
- activate.ps1
- activate\_this.py
- calibration.npy
- deactivate.bat
- f2py.exe
- fonttools.exe
- keyboard.py
- keyboarvirt.py
- pip.exe
- pip3.10.exe
- pip3.exe
- pydoc.bat
- pyftmerge.exe

Terminal Local

```
W0000 00:00:1746071389.346151 56996 inference_feedback_manager.cc:114] Feedback or feedback tensors.  
Starting new calibration  
  
Calibration Guide:  
1. Position your hand so the index finger tip covers the target key  
2. Make a pinching gesture (index and thumb together)  
3. Hold position until progress bar fills  
4. Move hand away to confirm  
  
W0000 00:00:1746071413.784045 34992 landmark_projection_calculator.cc:186] Using de IMAGE_DIMENSIONS or use PROJECTION_MATRIX.
```

PythonProject > .venv > Scripts

recordscreen.io

Choose what to share with recordscreen.io

The site will be able to see the contents of your screen.

Chrome Tab Window Entire Screen

Getting permissions for mic and screen...

Stop sharing Hide

Windows Gamebar Record Desktop and not a window

Type here to search

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