Mid-Term Assignment - Connect 4 - Laboratory Documentation





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15th March 2019

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15th March 2018 Lecturer/Instructor: Jonathan Dukes

Mid-Term Individual Assignment - Connect 4

Goal:

To create Connect 4 in Keil uVision5; a two-player puzzle game in which players take turns to drop discs into a vertically mounted board with seven columns and six rows. The program should check whether a player has won or not (i.e. 4 or more counters in a row). The program should also include an A.I. component that plays against the user.

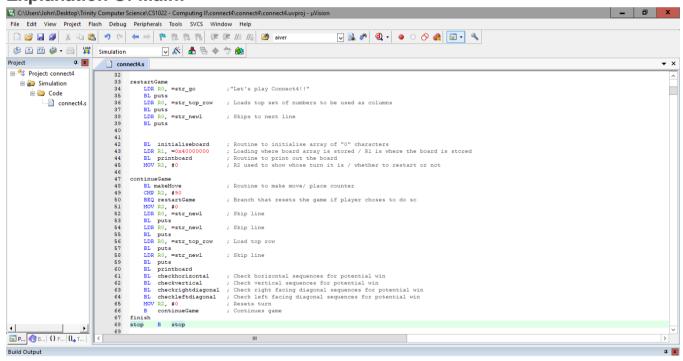
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```
// Main Pseudo Code
boolean finished = false;
boolean restartGame = false;
initialiseBoard (address, turn count)
// Miscellanious "puts"
printBoard (address, turn count)
if (restartGame == true)
        initialiseBoard (address, turn count)
        // Miscellanious "puts"
        printBoard (address, turn count)
        restartGame = false;
}
for (int i = 0; i < 42; i++)
        makeMove (address, turn count) / AIMove
        if (put == "q")
                 restartGame = true:
        // Miscellanious "puts"
        printBoard (address, turn count)
checkHorizontal (address, turn count)
        checkVertical (address, turn count)
        checkRightDiagonal (address, turn count)
        checkLeftDiagonal (address, turn count)
```

Explanation Of Main:



You can see from the pseudo-code that the main is simple enough. Essentially it can be boiled down to:

"A game is played 42 times, each time making one move, using the Branch Link instruction to perform various methods. The R1 and R2 registers are used to pass parameters. R1 = Array Address, R2 = Turn Count."

Little is need to be said about test with regards to this. We will see whether this is working based on the other subroutines.

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Explanation Of Initialise Board Routine:

```
C:\Users\John\Desktop\Trinity Computer Science\CS1022 - Computing II\connect4\connect4\con
 Simulation
         t x
 Project: connect4
     E Code
                            ; your subroutines go here
        connect4.s
                           ; Interface:
; initialiseboard Subroutine
; Initialises the board full of array of "0" ascii codes
; No parameters
; No return parameters
                           initialiseboard
                           whInit CMP R6, #42

BHS eWhInit

LDR R7, =0x30

STRB R7, [R4, R6]

ADD R6, R6, #1
                           B whInit
eWhInit
POP {R4, R5, R6, R7, pc}
 (3:27 (3)) ENG 15/03/2019
```

Like the main this routine is simple enough. The board array is stored at the address =0x40000000. Initialising the board fills it full of the ascii code for "0"; 0x30. As such we should see an array of the board beginning at the address full of "30" s 42 times. R6 = The count. We do this by loading the #0x30 into R7 and then storing the byte of R7 into an assigned address. The assigned address is just the original address which is immediately offset by the count. This is seen in line 91 with the instruction "LDRB R7, [R4, R6]". So after testing this routine we are left with:

```
      Memory 1

      Address:
      0x40000000

      0x40000000:
      30303030
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      30303030
```

As such the routine can clearly be seen working.

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```
// Print Board Pseudo Code
int columnNumber = 0; //R9
int rowShifter = 0; // R4
int columnShifter = 0; // R6
// R8 = Starting Address
for (int R4 = 0; R4 < 6; R4++)
        for (int R6 = 0; R6 < 6; R6++)
                // Load position = board [R4][R6];
                System.out.print(position + " ");
                // Miscellaneous puts for skip row etc.
        System.out.print(columnNumber + " ");
        columnNumber++;
```

Explanation Of Print Board Routine:

```
Simulation V AN A A A A A
Simulation
                                                                                                                                                                   mulation

connects.

100 ; Interface:
101 ; printboard Subroutine
102 ; Frints the values stored in the board
103 ; R1 - Address - Uses LSR and a count to reach the values of the board in m
104
105 printboard
106 printboard
107 LDR 84, =0 ; Row Shifter
107 LDR 84, =0 ; Row Shifter
108 LDR 88, =0 ; Row Shifter
109 LDR 88, =0 ; Row Shifter
110 LDR 80, =0 ; Storage for Row and Column Shifter
111 LDR 810, =7 ; Storage for Row value should be outputted
112 forc CMP 84, #6
113 EEO endforc
114
115 ror CMP 84, #6
116 CMP 85, #1
117 NHE col2
118 col2 CMP 84, #2
119 col2 CMP 85, #2
120 col3 CMP 85, #3
121 COL3 CMP 85, #3
122 col3 CMP 85, #3
123 COL3 CMP 85, #3
124 LDR 80, =str_12
125 col4 CMP 85, #4
126 col6 CMP 89, #8
127 LDR 80, =str_5
128 ENE col5
127 LDR 80, =str_5
129 ENE col6 CMP 89, #8
120 LDR 80, =str_5
121 CMP 80, =str_5
122 LDR 80, =str_5
123 ENE col6 CMP 89, #8
124 LDR 80, =str_5
125 LDR 80, =str_5
126 LDR 80, =str_5
127 LDR 80, =str_5
128 LDR 80, =str_5
129 ENE col6
120 LDR 80, =str_5
121 LDR 80, =str_5
122 ENE col6
123 ENE col6
124 LDR 80, =str_5
125 ENE col6
126 LDR 80, =str_5
127 LDR 80, =str_5
128 LDR 80, =str_5
129 ENE col6
120 LDR 80, =str_5
121 LDR 80, =str_5
122 ENE col6
123 LDR 80, =str_5
124 LDR 80, =str_5
125 ENE col6
126 LDR 80, =str_5
127 LDR 80, =str_5
128 LDR 80, =str_5
129 ENE col6
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121 LDR 80, =str_5
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125 LDR 80, =str_5
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127 LDR 80, =str_5
128 LDR 80, =str_5
129 LDR 80, =str_5
120 LDR
      E Project: connect4
                                         in Code
                                                                    connect4.s
€ P... ③ B... ! F... ! 0, T... !
                                                                                                                                                                                     annulation 
Connects

128

Simulation

S
                                                                                                                                                                                                  Project 📮 🔀

☐ 

Project: connect4
                   ■ Simulation
                                         Code connect4.s
                                                                                                                                                                                                                                                                                                                                                                                                                            ; Restart Column Shifter
                                                                                                                                                                                                                                                                                                                                                                                                                                                           ; If finished row (i.e Column shifter at max, restart)
                                                                                                                                                                                                                                                                                                                                                                                                                                                           ; R4 = Row decider
; R5 = Column decider
; Finds place on board / Stores above found place in R0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                ; Puts place in UART #1
; Put space
                                                                                                                                                                                                                                                                        BL put
LDR RO, = str_space
BL puts
ADD R5, R5, #1
B forr
                                                                                                                                                                                                                                                                                                                                                                                                                                                                ; Move to next column
                                                                                                                                                                                                                                            endforc POP {R4, R5, R6, R7, R8, R9, R10, pc}
```

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From the first screenshot we see a block of code whose entire purpose is simply just to distance the row numbers to the left hand side using a count and puts operations.

The main aspect of this subroutine can be seen in the second block of code. Something which can be seen clearly in the pseudo code above is that the this routine consists of two for loops; the first representing the row number (or the forr/endforr label), the second the column number (or the forc/endforc label). To explain via assembly, both pieces of code use their indexes, or in this case R4/ R5 respectively to reach the next position of the array and load the byte stored at that position and then "put" it. They reach their positions by using a simple formula:

```
"position = rowNumber * sizeOfRow"

"position = position + columnNumber"

"load the byte of the (beginning of the array shifted by the position"
```

Or as I have it written in the program:

```
MUL R6, R4, "Register with size of row"
ADD R6, R6, R5
LDRB R0, [beginning address, R6]
```

It is important to remember the above code as it is used plenty of times in the program and for convenience I have called it an array place finder.

Using immediate offset the value is then placed in the R0 register and then using the "put" routine is placed into the UART#1 window. We can see that this successfully works from the screenshot:

```
Let's play Connect4!!

0 1 2 3 4 5 6
0 0 0 0 0 0 0 0 0
1 0 0 0 0 0 0 0
2 0 0 0 0 0 0 0
3 0 0 0 0 0 0 0
4 0 0 0 0 0 0 0
5 0 0 0 0 0 0
RED: choose a column for your next move (0-6, q to restart):
```

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```
// Make Move Pseudo Code
int columnShifter = 0; // R6
// R10 = Starting Address
int rowSize = 7 // R11
boolean redTurn = true; // R2
String "R" = 0x52 // String "Y" = 0x59 // R4
boolean finished = false;
if (!finished)
        if (redTurn = true)
               String "R" = 0x52
               String "Y" = 0x59
        // BL get input
        if(input = "q")
        finished = true;
        int index = BL get;
        // load byte of [address, board [index]]
        // Drop Down Pseudo Code
                for(int i = 0; i < 6; i++)
                if (board [index/ ("columnNumber")][i] == 0x30)
                        board [index/ ("columnNumber")][i] = "R"/"Y"
                        for(int i2 = i; i2>-1; i2--)
                                board [index/ ("columnNumber")][i2] = 0x30
```

Explanation of makeMove/ dropDown Routines:

This routine consists of two separate methods; a makeAMove function and a dropDown function. The purpose of the first is to determine the player and then take the input. The drop

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down then places the input in the correct column and continues down the rows until it reaches a non "0" and places above.

In assembly, the code uses R2, based on either #0 or #1 whose turn it is. If R2 is #1 R is swapped for Y as the byte to be stored in the array.

Then using BL get and BL put I grab the input. If the user inputs "q" / #0x71 the routine ends and R2 is stored with a value that will cancel the main and restart the program using a BEQ. Otherwise if a number is entered I then subtract #0x30 from the input to convert it to decimal. Then using the array position finder from above I find that position in the first row of the array and check if its empty. If it is it continues to check below until it either reaches the end or it reaches a value other than #0x30. This is performed by the dropDown section of my code. Which performs a for loop to continues to stay in the original column but increments by one row each time, ADD R7, R7, #1 at the end of each check.

Once the red operation is complete, a MOV R2, #1 is performed and then using a BEQ I perform the Al's movement. However I'll get to that later in the document. Once the Al's routines are complete it's red's turn again.

To test my routine I preformed the following tests:

Inputs Visual Examples 1, 1 UART#1 Let's play Connect4!! This input demonstrates not only that the input works correctly. i.e. places in the correct column 0 0 0 0 0 0 0 but also that the drop down RED: choose a column for your next move (0-6, q to restart): 1 works correctly. The two "R"'s can be seen placed on top of each other. RED: choose a column for your next move (0-6, q to restart): 1 RED: choose a column for your next move (0-6, q to restart):

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1,4

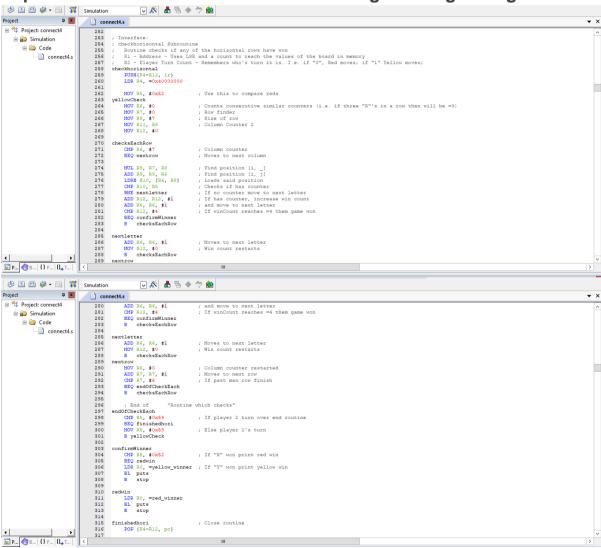
Like the input above, these inputs show that the input places the "R"/"Y" in the correct column. After entering 1 the R is placed in the the first column and continues to move down till it reaches the bottom. It does the same for the input of 4.

1, "q"

The board is initialised at the beginning and then an R and Y is placed. Then after entering "q" the board is cleared by reinitialising it.

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Explanations of Horizontal/Vertical/Left Diagonal/ Right Diagonal



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The first part of this routine is determines whether to check the "R" or "Y" first. It does this by using the R2 to determine whose turn it is and then stores the "R" / "Y" in R5.

Then using two for loops, one inside another, the program checks one byte at a time moving to the right checking for repeating R5's. If the program finds a consecutive loop it increases a winCount. If the winCount reaches up to 4 (therefore 4 consecutive R5's) it uses the R5 to determine who has won.

In assembly, what this is doing is using an ADD R/, R/, #1 to increase a counter and check each column of a row by keeping the row Register (in this case R7) the same until the column Register (in this case R6) which is affected by the counter reaches the end of it's row (then B nextletter). Once it has reached the end of the row:

(CMP R6, #6), it restarts the counter and increases the row until it reaches the end of the board (then B nextrow).

If the loaded byte loads a value the same as the hex code of our R5 register it increases the winCount by (in this case R12) 1. Once that R12 has reached #4, (4 in a row) it considers a winner and uses B stop to stop the program.

This routine is virtually the same for the checkVertical, checkRightDiagonal and checkLeftDiagonal operations. The only difference being that for the checkVertical it goes down each row one column at a time. Then for the diagonals it adjusts either forward one row and one column or back one row and back one column.

To demonstrate the success of this of these routines I have tested the following inputs:

Inputs	Visual Representation	
2, 3, 4, 5 As you can see from the ascii art, once four consecutive "R" have been placed horizontally Red Wins !!!	UART*1	# X

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A.I. Implementation

```
228
230
     aiturn
          ; Block of code which runs through AI's movements
231
233
          BL airightdiagonal
                                    ; Checks if AI can win by right diagonal, if not moves on
                                   ; Checks if AI can win by left diagonal, if not moves on ; Checks if AI can win by vertical, if not moves on
234
          BL aileftdiagonal
235
          BL aivertical
236
          BL aihorizontal
                                     ; Checks if AI can win by horizontal, if not places random/ or besid
237
                                                                     ;... inputted (depends on how many previ
```

Here we can see the A.I. block I talked about earlier in the makeAMove routine. This block of code; the A.I. turn block uses branch links to run routines to check if the yellow could win by placing a counter in a certain position it places it there. Otherwise it places it in a random spot or/ next to the player.

```
// AI Moveset Pseudo Code

AI Turn

checkVerAI
checkRightDiaAI
checkLeftDiaAI
checkHorAI
// Otherwise places random position

E.g.:
checkHorAI
// same routine as the check for win, if winCount =3
// use the makeAMove subroutine to place a counter next to the previous
// counter
// If no win choice, random position chosen
```

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```
nextletterAI
ADD R6, R6, $1
NOV R12, $0
R6, $1
NOV R12, $0
ADD R7, R7, $1
CMP R7, 87
BEQ endOfCheckEachRowAI
B checksEachRowAI
                                                                                                                                                                                    □ 1 Project: connect4
                                                                                                                                                                                                 ☐ ☐ Simulation
☐ ☐ Code
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             ; Moves to next letter
; Win count restarts
                                                                                                                                                                                                                                  connect4 s
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            ; Column counter restarted
; Moves to next row
; If past max row finish
                                                                                                                                                                                                                                                                                                                                                                endOfCheckEachAI

LDR R10, =0x40000000

MOV R6, #36

LDRB R9, [R10, R6]

CMP R9, #0x36

BNE nextmoveright

MOV R9, #1

MOV R9, #3

B confirmWinnerAI
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            ; Choses AI's first move
; If empty place
; Choses AI's second move
; If empty place
                                                                                                                                                                                                                                                                                                                                                            mextmoveright
MOV RS, $2
MOV RS, $2
MOV RC, RS
LDR RIO, =0040000000
MOV RC, $30
LDRB RS, [RIO, RC]
CMP RS, $0030
BNE mextmoveright2
MOV RC, $2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            ; If not empty move on
                                                                                                                                                                                                                                                                                                                                                                nextmoveright2
ADD R6, R6, #1
LDR R10, =0x40000000
MOV R6, #31
LDRB R9, [R10, R6]
                                                                                                                                                                                 ◆ AR () F () T
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  III
                                                                  Ť 🗶
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         ▼ ×
    Project: connect4
                                                                                                                                                                              nextmoweright2

ADD R6, R6, f1

LDR 810, =0x4000000

LDR 88, (811

LDR 88, (810, R6)

LDR 88, 10x30

ME R8, 10x30

ME R9, 10x30

MOV R8, 22

HOV R6, R9

B confirm@innerAl
                             Code connect4.s
                                                                                                                                                                            nextmoveright3
ADD R6. R6. #1
                                                                                                                                                                                                 B confirmWinnerAI
                                                                                                                                                                                confirmWinnerAI
                                                                                                                                                                                        LDR R11, =7
LDR R4, =0x59
MOV R7, #0
                                                                                                                                                                                              MUL R8, R7, R11
ADD R8, R8, R6
LDRB R9, [R10, R8]
                                                                                                                                                 663 ; if empty space overwrite register with address
664 LDR 210, =0x40000000
665 children of code to check if empty space below in board
666 children of code to check if empty space below in board
667 children of code to check if empty space below in board
668 ESD CO finishedplacementAI if Temporary number of places to drop
670 ADD 87, R7, #1 if Move to check next row
671 MUL 80, R7, R11 if Getting next row
672 LOBB 89, R8 R6 if Getting next row
673 LOBB 89, R100, R8] if Getting next row
674 LOBB 89, R100, R8] if Getting next row
675 LOBB 89, R100, R8] if Getting next row
676 LOBB 89, R100, R8] if Getting next row
677 LOBB 89, R100, R8] if Getting next row
678 LOBB 89, R100, R8] if Getting next row
679 LOBB 89, R100, R8] if Getting next row
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679 LOBB 89, R100, R8] if Getting next row
679 LOBB 89, R100, R8] if Getting next row
679 LOBB 89, R100, R8] if Getting next row
679 LOBB 89, R100, R8] if Getting next row
679 LOBB 89, R100, R8] if R10
Project: connect4
                                                                                                                                                                              confirmWinnerAI

LDR R11, =7

LDR R4, =0x59

MOV R7, #0
                                                                                                                                                                                                                                                                                                          ; Size of row
; Prepare to place
; Place Count = 0
                           Code connect4.s
                                                                                                                                                                                                MUL R8, R7, R11
ADD R8, R8, R6
LDRB R9, [R10, R8]
                                                                                                                                                                                              ; Loop through the whole column
; if empty space overwrite register with address
                                                                                                                                                                         ; if empty space overwrite register with address

LDR R10, -0x40000000
;block of code to check if empty space below in board
continuefindingAI

CMD R7, f86 ; Temporary number of places to drop
;If finished checking all places, finished loop
ADD R7, R7, f1 ; Move to check next row
ADD R8, R8, R8 ; Getring next row
LDRB R8, R810, R81 ; Loading row
CMP R8, $0x30

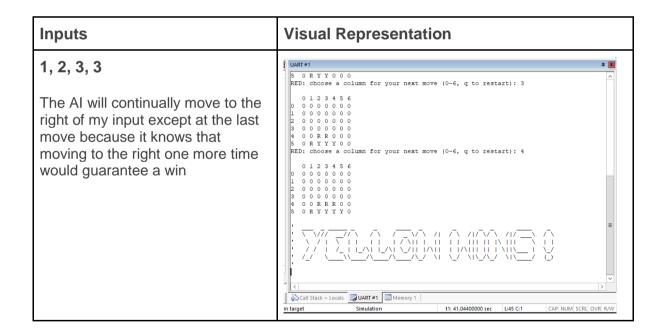
ENR finishedplacementAI ; If not empty finished placing
B continuefindingAI ; If not empty finished;
SUB R7, R1 ; Remove last add
MUL R8, R7, R1 ; Remove last add
MUL R8, R7, R1 ; Find position (i, j]
ADD R8, R8, R8 ; Find position (i, j]
STRB R4, (R10, R8) ; Place counter in position
                                                                                                                                                                                cannotmakemoveAI
finishedhoriAI
POF {R4-R12, pc}
```

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This was undoubtedly the longest routine of the program mainly because it incorporates two routines; a check method and then a move method, and then multiplies that by four for each individual type of check.

In assembly, it starts with the checkVerticalAI routine and using the array position finder method explain earlier checks each individual byte by using an ADD R/, R/, #1 to increase the shift by #1 each check. If the check CMP more than 3 cases of consecutive hex codes of the same value it chooses to place another counter on those hex codes in the same column to win. It places this counter by using the make a move method where it check each byte of a column below and determines if it can move down or not. Once it reaches the end or reaches a BNE R/, #0x59, the program places the counter in the current position.

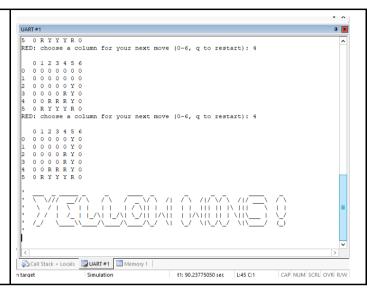
This is virtually the same for the other Branch Links/Routines in the A.I. turn block of code, the only difference being the check routines are swapped with their respective routines.



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1, 2, 3, 5, 4, 4, 4

The AI moves three to the left by then I block it from getting a fourth. Knowing this, instead it moves up using the vertical branch and continues until it wins. Showing that it corrects itself if the win is no longer available.



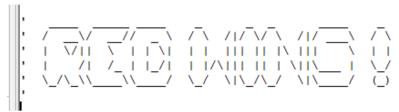
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15th March 2018 Lecturer/Instructor: Jonathan Dukes

Ascii Art Usage

For the output of the win condition I decided to use ascii art to add something extra to the program. In this case I used the following images:

For red:



For yellow:



In both cases I used a string of the appropriate list of hex codes to form this output. Then loading said strings to the R0 register I then used puts to display then once a win condition had been meet.