D* Lite Pseudocode (final version)

```
procedure CalculateKey(s)
{01'} return [min(g(s), rhs(s)) + h(s_start, s) + k_m ; min(g(s), rhs(s))];
procedure Initialize()
{02'} U = ∅;
{03'} k_m = 0;
{04'} for all s ∈ S rhs(s) = g(s) = ∞;
{05'} rhs(s_goal) = 0;
{06'} U.Insert(s_goal, CalculateKey(s_goal));
procedure UpdateVertex(u)
{07'} if (u ≠ s_goal) rhs(u) = min_{s'∈Succ(u)}(c(u, s') + g(s'));
{08'} if (u ∈ U) U.Remove(u);
{09'} if (g(u) ≠ rhs(u)) U.Insert(u, CalculateKey(u));
procedure ComputeShortestPath()
{10'} while (U.TopKey() < CalculateKey(s_start) OR rhs(s_start) ≠ g(s_start))
{11'}   k_old = U.TopKey();
{12'}   u = U.Pop();
{13'}   if (k_old < CalculateKey(u))
{14'}     U.Insert(u, CalculateKey(u));
{15'}   else if (g(u) > rhs(u))
{16'}     g(u) = rhs(u);
{17'}     for all s ∈ Pred(u) UpdateVertex(s);
{18'}   else
{19'}     g(u) = ∞;
{20'}     for all s ∈ Pred(u) ∪ {u} UpdateVertex(s);
procedure Main()
{21'} s_last = s_start;
{22'} Initialize();
{23'} ComputeShortestPath();
{24'} while (s_start ≠ s_goal)
{25'}   /* if (g(s_start) = ∞) then there is no known path */
{26'}   s_start = arg min_{s'∈Succ(s_start)}(c(s_start, s') + g(s'));
{27'}   Move to s_start;
{28'}   Scan graph for changed edge costs;
{29'}   if any edge costs changed
{30'}     k_m = k_m + h(s_last, s_start);
{31'}     s_last = s_start;
{32'}     for all directed edges (u, v) with changed edge costs
{33'}       Update the edge cost c(u, v);
{34'}       UpdateVertex(u);
{35'}     ComputeShortestPath();
```

If some edge costs have changed:

- Update km
- Update S_{Last}
- update the rhs-values and keys of the vertices potentially affected, as well as their memberships in the priority queue, if they have become locally consistent or inconsistent.
- Recalculate shortest path (line 35)