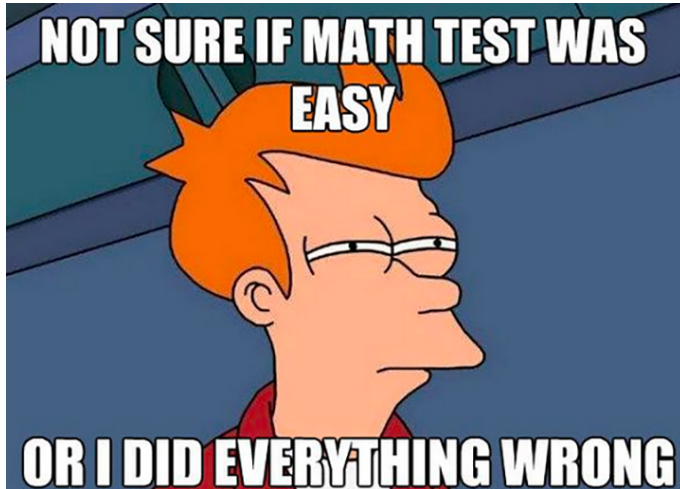


Analytical Geometry and Linear Algebra. Lecture 6.

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Lecture 6. Outline

- Part 1. Straight line in plane
- Part 2. Equations of a line

Locus

Definition

“When a point moves so as to satisfy some geometrical condition or conditions, the path traced out by the point is called the **locus** of the point.”

From: P. R. Vittal. “Analytical Geometry: 2D and 3D”.

Locus: Example

Suppose a point $P(x, y)$ moves such that its distances from two fixed points $A(2, 3)$ and $B(5, -3)$ are equal. Then the geometrical law is $PA = PB \Rightarrow PA^2 = PB^2$

$$(x - 2)^2 + (y - 3)^2 = (x - 5)^2 + (y + 3)^2 \Rightarrow$$

$$2x - 4y - 7 = 0$$

(locus is a straight line)

Locus: other examples

$$x^2 + y^2 = r^2$$

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The parabola is defined as the locus of a point which moves so that it is always the same distance from a fixed point (called the focus) and a given line (called the directrix)

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

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Part 1. Straight line in plane

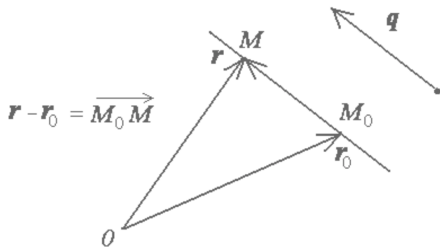
Definition

Given a point M_0 and a vector \mathbf{a} , set of all points M for which:

$$\overrightarrow{M_0M} = t\mathbf{a}$$

$$t \in \mathbb{R}$$

Parametric Vector Equation



Equation:

$$\mathbf{r} - \mathbf{r}_0 = t\mathbf{q}$$

where t is a parameter ($t \in \mathbb{R}$).

Parametric Equation in 3D

In rectangular Cartesian coordinate system

$$\text{Equation of a line: } \begin{cases} x = x_0 + q_x t \\ y = y_0 + q_y t \\ z = z_0 + q_z t \end{cases}$$

$$\mathbf{r} - \mathbf{r}_0 = [x - x_0, y - y_0, z - z_0]^\top$$

$$\mathbf{q} = [q_x, q_y, q_z]^\top$$

Canonical equation of a line

Eliminating t from the system:

$$\begin{cases} x = x_0 + q_x t \\ y = y_0 + q_y t \\ z = z_0 + q_z t \end{cases}$$

we get the **Canonical equation**

$$\frac{x - x_0}{q_x} = \frac{y - y_0}{q_y} = \frac{z - z_0}{q_z}$$

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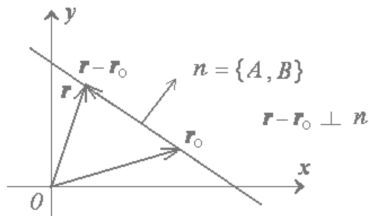
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Give two points: M_0 and M_1 :

$$\frac{x - x_0}{x_1 - x_0} = \frac{y - y_0}{y_1 - y_0} = \frac{z - z_0}{z_1 - z_0}$$

2D case



$$Ax + By + C = 0$$

for point M_0 on a line:

$$Ax_0 + By_0 + C = 0$$

$$(\mathbf{r} - \mathbf{r}_0) = [x - x_0, y - y_0]^T; \mathbf{n} = [A, B]^T$$

$$\mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_0) = 0$$

Angle Between Two Lines

1. The angle between two lines is the angle between direction vectors of the lines.

$$\cos \theta = \frac{\mathbf{p} \cdot \mathbf{q}}{\|\mathbf{p}\| \|\mathbf{q}\|}$$

Where \mathbf{p} and \mathbf{q} are direction vectors of lines.

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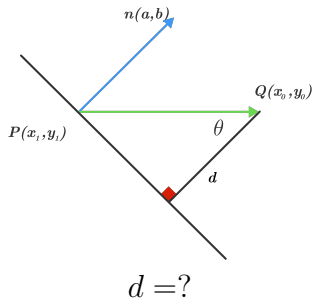
2. The angle between two lines is the angle between normal vectors of the lines.

$$\cos \theta = \frac{\mathbf{n}_1 \cdot \mathbf{n}_2}{\|\mathbf{n}_1\| \|\mathbf{n}_2\|}$$

Where \mathbf{n}_1 and \mathbf{n}_2 are normal vectors of lines.

Calculation of distances

Distance From a Point to a Line



$$d = \frac{|\mathbf{n} \cdot \overrightarrow{PQ}|}{\|\mathbf{n}\|} = \dots$$

What if the point Q is on one side of a line, but the normal vector (\mathbf{n}) points to the opposite side?

Distance between point and line

Find the perpendicular distance from the point $(5, 6)$ to the line $-2x + 3y + 4 = 0$,

Useful links

- <https://www.geogebra.org>
- https://youtu.be/fNk_zzaMoSs
- <http://immersivemath.com/ila>