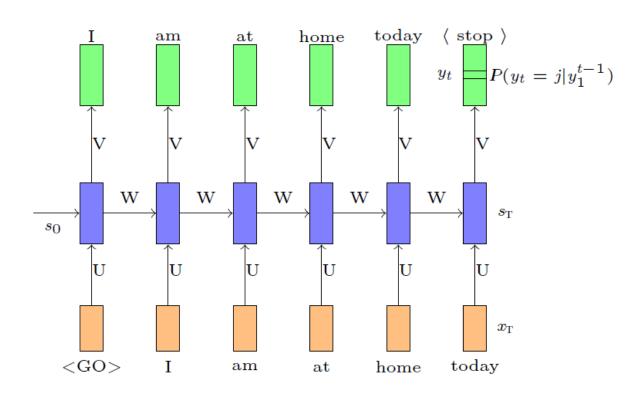
#### **DSE 3121 DEEP LEARNING**

# **Encoder-Decoder Models**

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Department of Data Science and Computer Applications
MIT Manipal

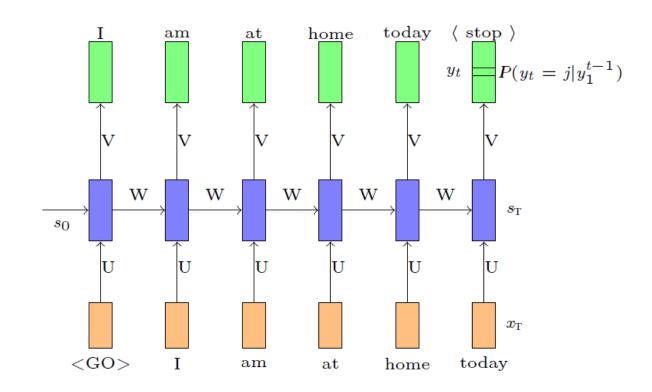
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Given the t-i words predict the tth word



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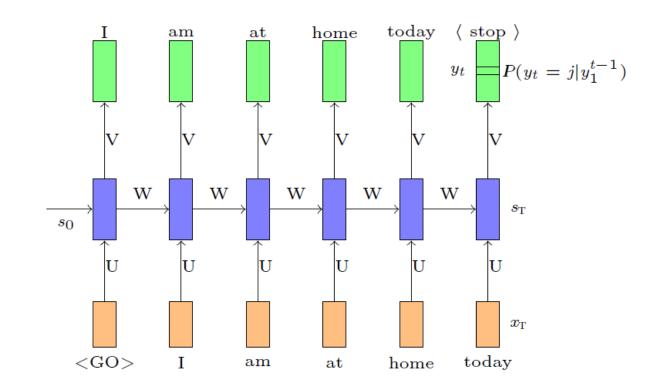


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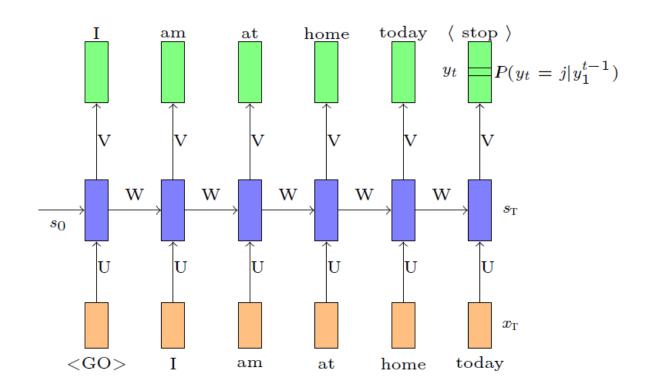
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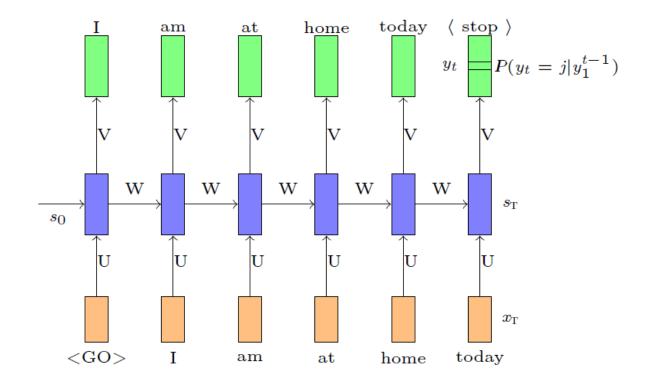
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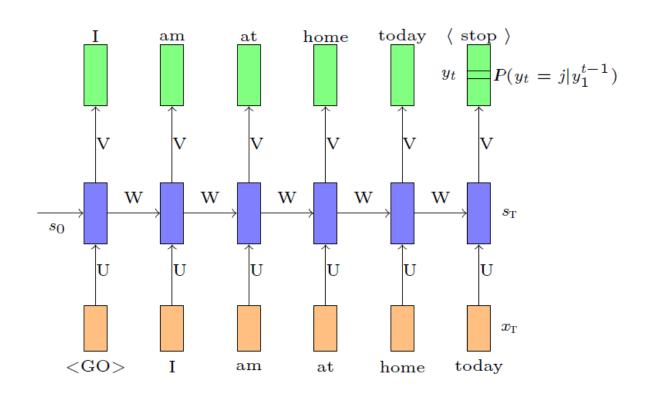
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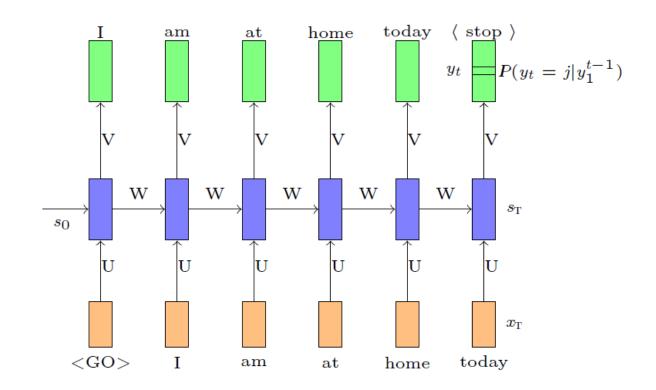
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j<sup>th</sup> word in the vocabulary

Using an RNN we will compute this as:



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 Given the t-i words predict the t<sup>th</sup> word

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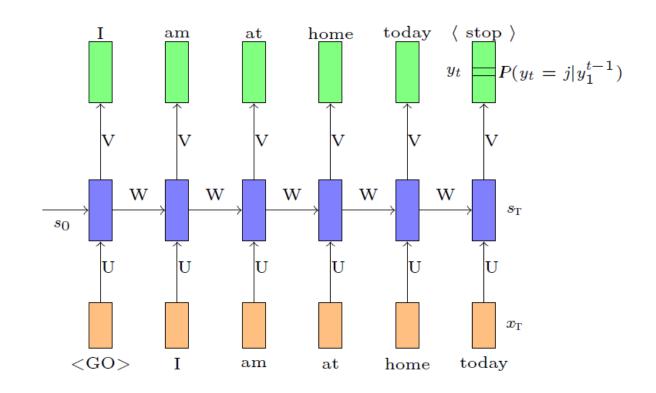
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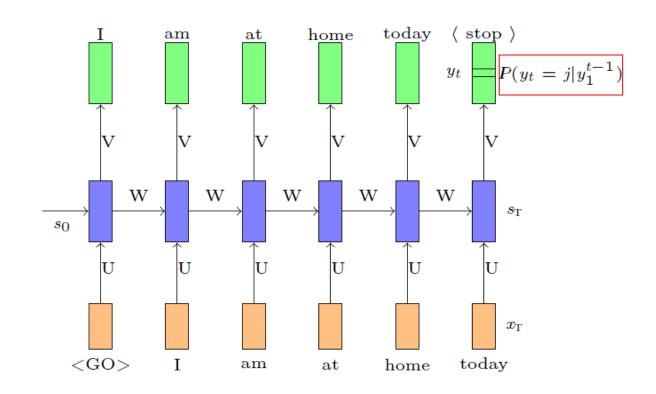
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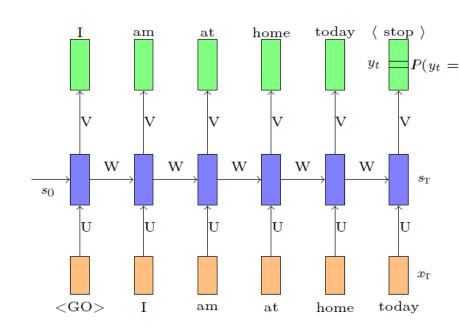
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Data:

India, officially the Republic of India, is a country in South Asia. It is the seventh-largest country by area, .....

- Data: All sentences from any large corpus (say wikipedia)
- Model:

$$s_t = \sigma(Ws_{t-1} + Ux_t + b)$$

$$P(y_t = j|y_1^{t-1}) = softmax(Vs_t + c)_j$$

- Parameters: U, V, W, b, c
- Loss:

$$\mathcal{L}(\theta) = \sum_{t=1}^{T} \mathcal{L}_t(\theta)$$
$$\mathcal{L}_t(\theta) = -\log P(y_t = \ell_t | y_1^{t-1})$$

where  $\ell_t$  is the true word at time step t

#### **Shorthand notations:**

$$s_t = \sigma(U x_t + W s_{t-1} + b)$$

$$s_{t} = \sigma(U x_{t} + W s_{t-1} + b) \qquad \tilde{s}_{t} = \sigma(W(o_{t} \odot s_{t-1}) + U x_{t} + b) \qquad \tilde{s}_{t} = \sigma(W h_{t-1} + U x_{t} + b)$$

$$s_{t} = i_{t} \odot s_{t-1} + (1 - i_{t}) \odot \tilde{s}_{t} \qquad s_{t} = f_{t} \odot s_{t-1} + i_{t} \odot \tilde{s}_{t}$$

$$\tilde{s}_{t} = \sigma(W h_{t-1} + Ux_{t} + b)$$

$$s_{t} = f_{t} \odot s_{t-1} + i_{t} \odot \tilde{s}_{t}$$

$$h_{t} = o_{t} \odot \sigma(s_{t})$$



 $s_t = \text{RNN}(s_{t-1}, x_t)$ 



$$s_t = \text{GRU}(s_{t-1}, x_t)$$

$$h_t, s_t = \text{LSTM}(\ h_{t-1}, s_{t-1}, x_t)$$



Task: generate a sentence given an image

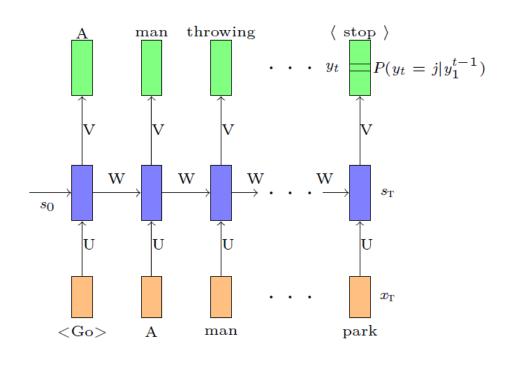


A man throwing a frisbee in a park

We are now interested in  $P(y_t|y_1^{t-1}, I)$  instead of  $P(y_t|y_1^{t-1})$  where I is an image

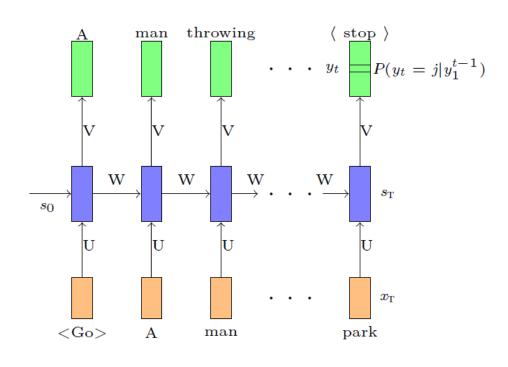
• Earlier we modeled  $P(y_t|y_1^{t-1})$  as

$$P(y_t|y_1^{t-1}) = P(y_t = j|s_t)$$



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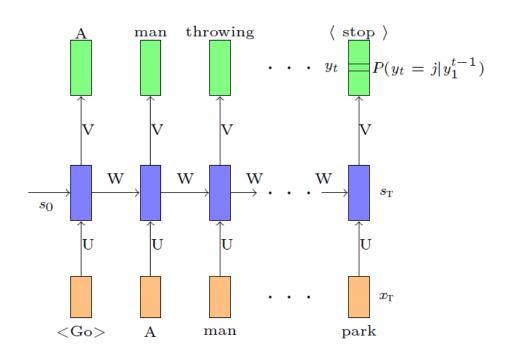
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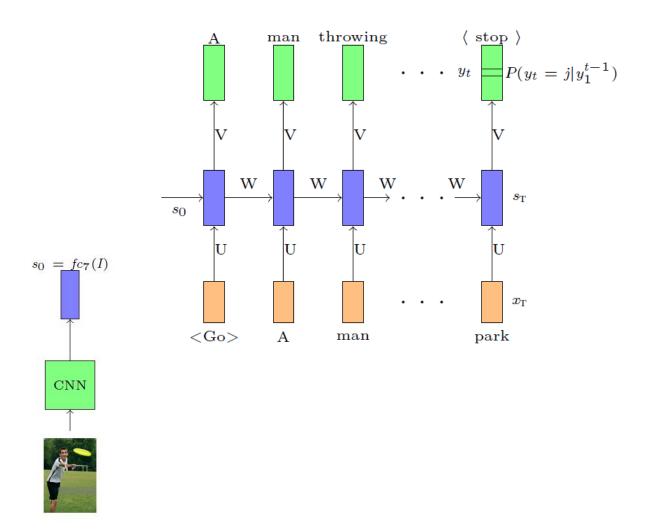
• Where  $s_t$  was a state capturing all the previous words



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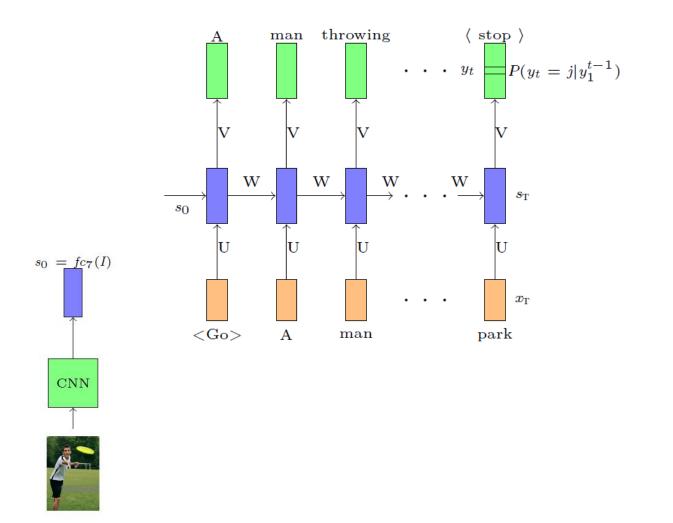
- Where  $s_t$  was a state capturing all the previous words
- We could now model  $P(y_t = j | y_1^{t-1}, I)$ as  $P(y_t = j | s_t, f_{c_7}(I))$



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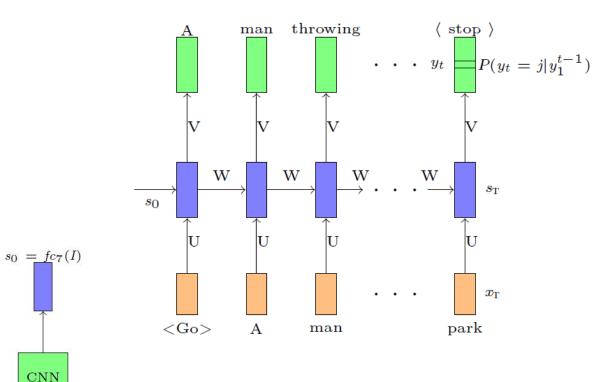
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- where  $fc_7(I)$  is the representation obtained from the  $fc_7$  layer of an image



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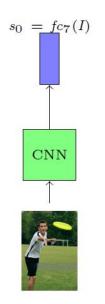
There are many ways of making  $P(y_t = j)$  conditional on  $f_{c_7}(I)$ 

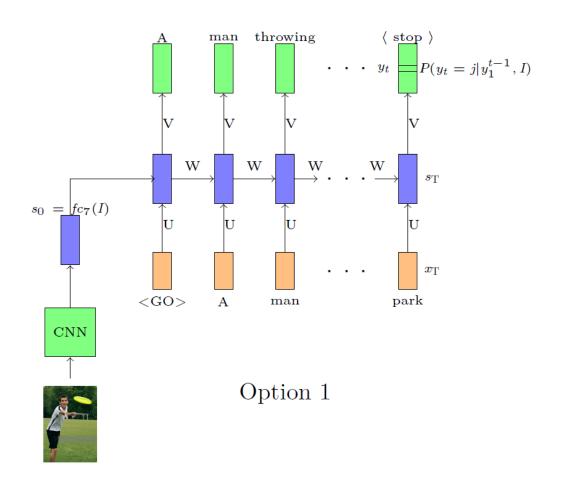
Source: CS7015 Deep Learning, Dept. of CSE, IIT Madras

CNN

**Option 1:** Set 
$$s_0 = f_{c_7}(I)$$

Now  $s_0$  and hence all subsequent  $s_t$ 's depend on  $f_{c_7}(I)$ 



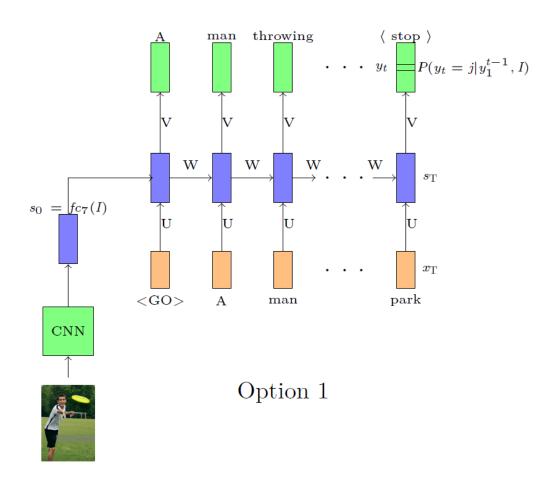


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In other words, we are computing  $P(y_t = j | s_t, f_{c_7}(I))$ 



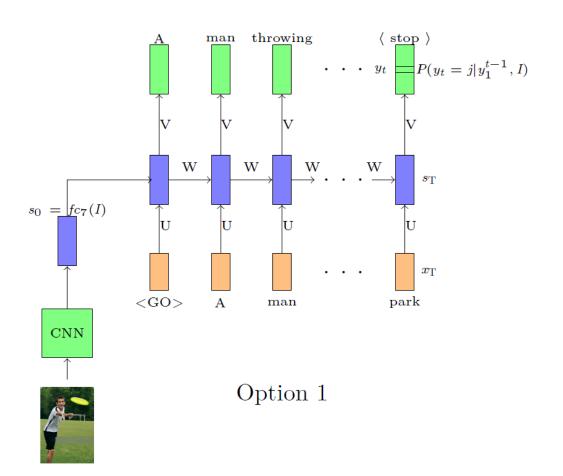
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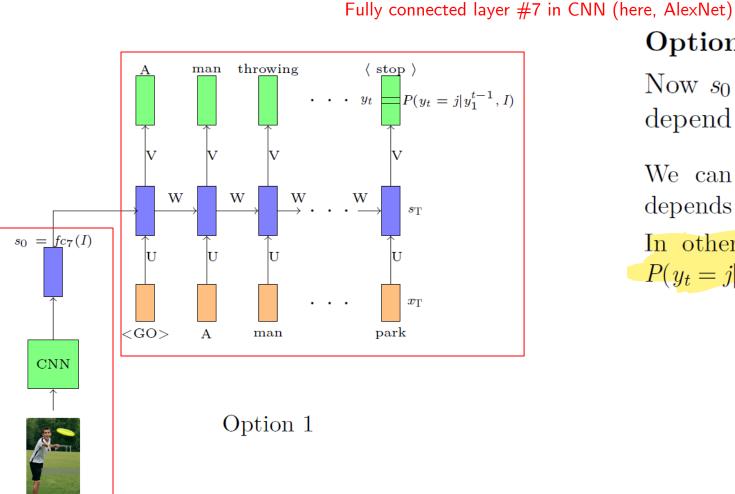


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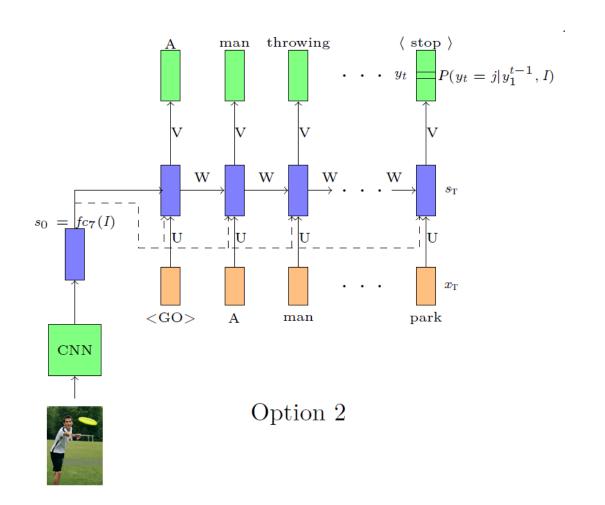


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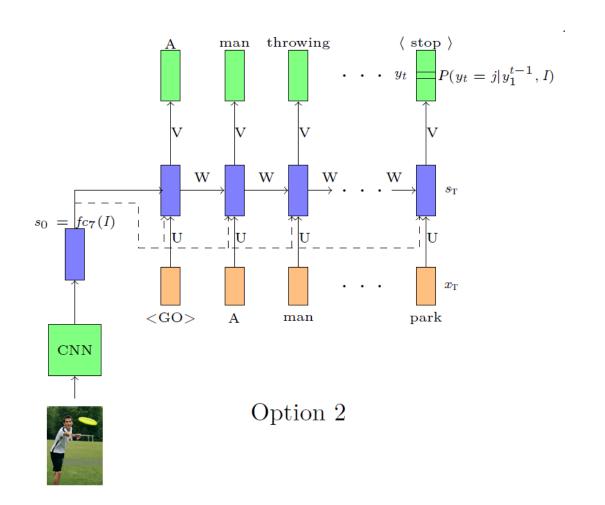
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Option 2: Another more explicit way of doing this is to compute

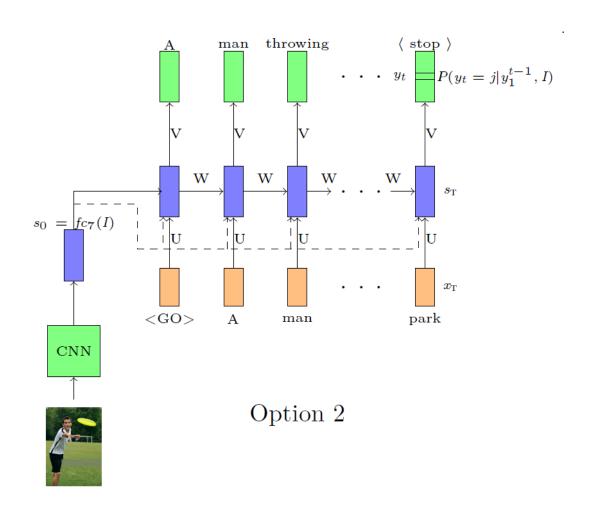
$$s_t = RNN(s_{t-1}, [x_t, f_{c_7}(I)])$$



Option 2: Another more explicit way of doing this is to compute

$$s_t = RNN(s_{t-1}, [x_t, f_{c_7}(I)])$$

In other words we are explicitly using  $f_{c_7}(I)$  to compute  $s_t$  and hence  $P(y_t = j)$ 

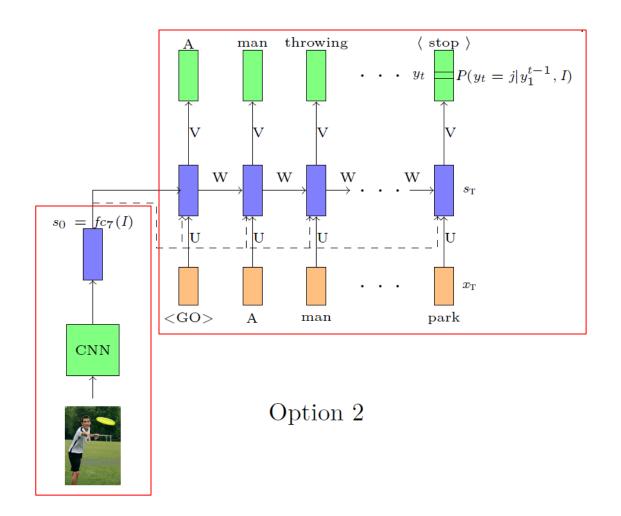


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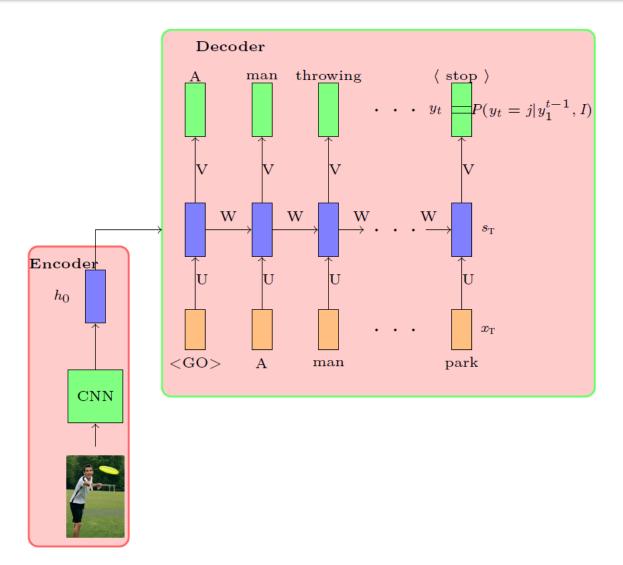


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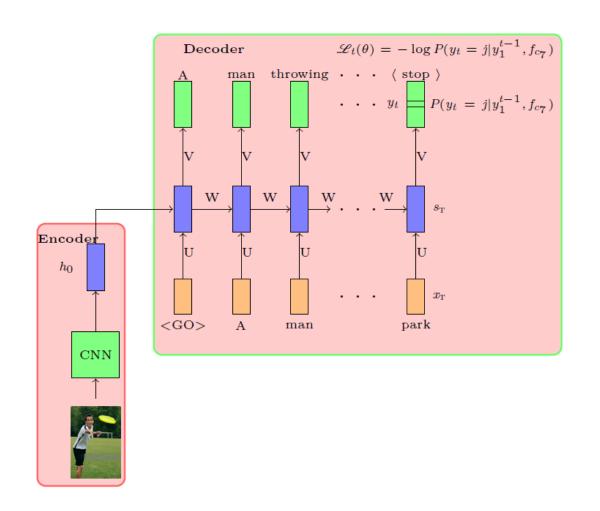
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This is typical encoder decoder architecture

## Applications of Encoder Decoder Models: Image Captioning



• Task: Image captioning

• Data:  $\{x_i = image_i, y_i = caption_i\}_{i=1}^N$ 

• Model:

• Encoder:

$$s_0 = CNN(x_i)$$
 embedding of the output obtained at

Represents the input embedding of the output obtained at time step t-1

• Decoder:

$$s_t = RNN(s_{t-1}, e(\hat{y}_{t-1}))$$

$$P(y_t|y_1^{t-1}, I) = softmax(Vs_t + b)$$

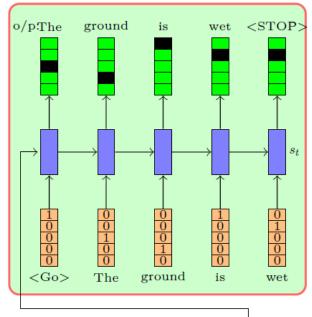
- Parameters:  $U_{dec}$ , V,  $W_{dec}$ ,  $W_{conv}$ , b
- Loss:

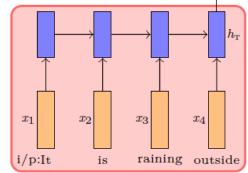
$$\mathscr{L}(\theta) = \sum_{i=1}^{T} \mathscr{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, I)$$

• Algorithm: Gradient descent with backpropagation

### Applications of Encoder Decoder Models: Textual Entailment







i/p : It is raining outside

Source: CS7015 Deep Learning, Dept. of CSE, IIT Madras

- Task: Textual entailment
- Data:  $\{x_i = premise_i, y_i = hypothesis_i\}_{i=1}^N$
- Model (Option 1):
  - Encoder:

$$h_t = RNN(h_{t-1}, x_{it})$$

• Decoder:

$$s_0 = h_T \quad (T \text{ is length of input})$$

$$s_t = RNN(s_{t-1}, e(\hat{y}_{t-1}))$$

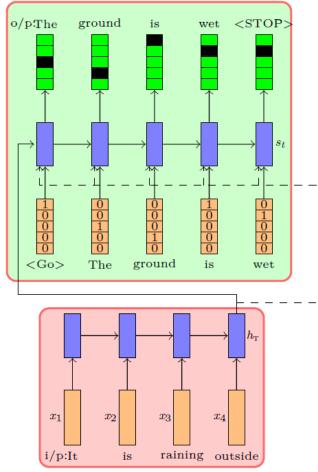
$$P(y_t|y_1^{t-1}, x) = softmax(Vs_t + b)$$

- Parameters:  $U_{dec}$ , V,  $W_{dec}$ ,  $U_{enc}$ ,  $W_{enc}$ , b
- Loss:

$$\mathcal{L}(\theta) = \sum_{i=1}^{T} \mathcal{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, x)$$

#### Applications of Encoder Decoder Models: Textual Entailment

o/p : The ground is wet



i/p: It is raining outside

- Task: Textual entailment
- Data:  $\{x_i = premise_i, y_i = hypothesis_i\}_{i=1}^N$
- Model (Option 2):
  - Encoder:

$$h_t = RNN(h_{t-1}, x_{it})$$

• Decoder:

$$s_0 = h_T \quad (T \text{ is length of input})$$

$$s_t = RNN(s_{t-1}, [h_T, e(\hat{y}_{t-1})])$$

$$P(y_t|y_1^{t-1}, x) = softmax(Vs_t + b)$$

- Parameters:  $U_{dec}$ , V,  $W_{dec}$ ,  $U_{enc}$ ,  $W_{enc}$ , b
- Loss:

$$\mathcal{L}(\theta) = \sum_{i=1}^{T} \mathcal{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, x)$$

• Algorithm: Gradient descent with backpropagation

# Applications of Encoder Decoder Models: Transliteration

 $\mathrm{o/p}$  : इंड या

i/p: INDIA

## Applications of Encoder Decoder Models: Image Question Answering

O/p: White

- Task: Image Question Answeing
- Data:  $\{x_i = \{I, q\}_i, y_i = Answer_i\}_{i=1}^N$
- Model:
  - Encoder:

$$\hat{h}_I = CNN(I), \ \tilde{h}_t = RNN(\tilde{h}_{t-1}, q_{it})$$

$$s = [\tilde{h}_T; \hat{h}_I]$$

• Decoder:

$$P(y|q, I) = softmax(Vs + b)$$

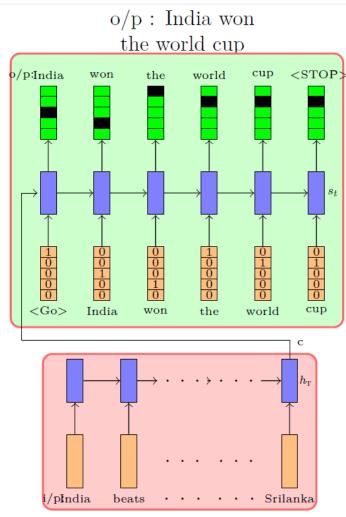
- Parameters:  $V, b, U_q, W_q, W_{conv}, b$
- Loss:

$$\mathcal{L}(\theta) = -\log P(y = \ell | I, q)$$

• Algorithm: Gradient descent with backpropagation

Question: What is the bird's color

### Applications of Encoder Decoder Models: Document Summarization



i/p : India beats Srilanka to win ICC WC 2011. Dhoni and Gambhir's half centuries help beat  ${\rm SL}$ 

• Task: Document Summarization

• Data:  $\{x_i = Document_i, y_i = Summary_i\}_{i=1}^{N}$ 

- Model:
  - Encoder:

$$h_t = RNN(h_{t-1}, x_{it})$$

• Decoder:

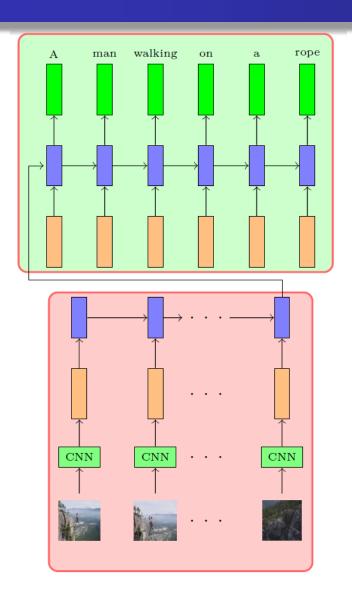
$$\begin{aligned} s_0 &= h_T \\ s_t &= RNN(s_{t-1}, e(\hat{y}_{t-1})) \\ P(y_t|y_1^{t-1}, x) &= softmax(Vs_t + b) \end{aligned}$$

- Parameters:  $U_{dec}$ , V,  $W_{dec}$ ,  $U_{enc}$ ,  $W_{enc}$ , b
- Loss:

$$\mathcal{L}(\theta) = \sum_{i=1}^{T} \mathcal{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, x)$$

• Algorithm: Gradient descent with backpropagation

### Applications of Encoder Decoder Models: Video Captioning



- Task: Video Captioning
- Data:  $\{x_i = video_i, y_i = desc_i\}_{i=1}^N$
- Model:
  - Encoder:

$$h_t = RNN(h_{t-1}, CNN(x_{it}))$$

• Decoder:

$$s_0 = h_T$$

$$s_t = RNN(s_{t-1}, e(\hat{y}_{t-1}))$$

$$P(y_t|y_1^{t-1}, x) = softmax(Vs_t + b)$$

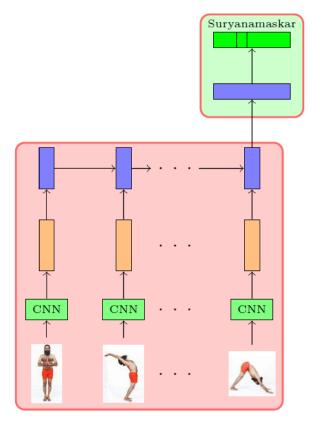
- Parameters:  $U_{dec}$ ,  $W_{dec}$ , V, b,  $W_{conv}$ ,  $U_{enc}$ ,  $W_{enc}$ , b
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• Algorithm: Gradient descent with backpropagation

### Applications of Encoder Decoder Models: Video Classification





- Task: Video Classification
- Data:  $\{x_i = Video_i, y_i = Activity_i\}_{i=1}^N$
- Model:
  - Encoder:

$$h_t = RNN(h_{t-1}, CNN(x_{it}))$$

• Decoder:

$$s = h_T$$

$$P(y|I) = softmax(Vs + b)$$

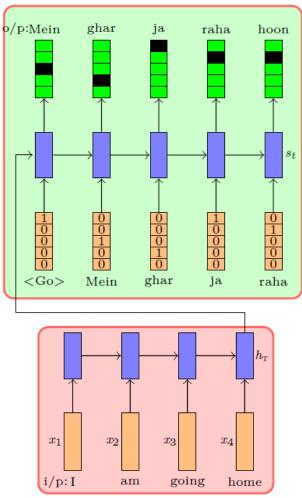
- Parameters:  $V, b, W_{conv}, U_{enc}, W_{enc}, b$
- Loss:

$$\mathcal{L}(\theta) = -\log P(y = \ell | Video)$$

• Algorithm: Gradient descent with backpropagation

### Applications of Encoder Decoder Models: Machine Translation

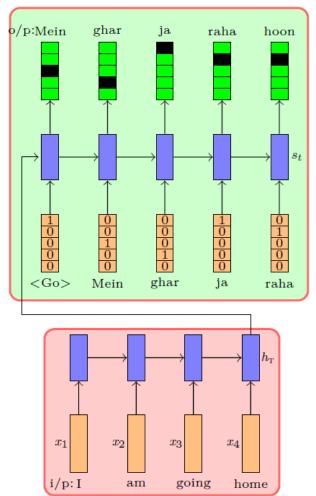
o/p : Mein ghar ja raha hoon



i/p : I am going home

### **Applications of Encoder Decoder Models: Machine Translation**

o/p: Mein ghar ja raha hoon



i/p : I am going home

- Task: Machine translation
- Data:  $\{x_i = source_i, y_i = target_i\}_{i=1}^N$
- Model (Option 1):
  - Encoder:

$$h_t = RNN(h_{t-1}, x_{it})$$

• Decoder:

$$s_0 = h_T \quad (T \text{ is length of input})$$

$$s_t = RNN(s_{t-1}, e(\hat{y}_{t-1}))$$

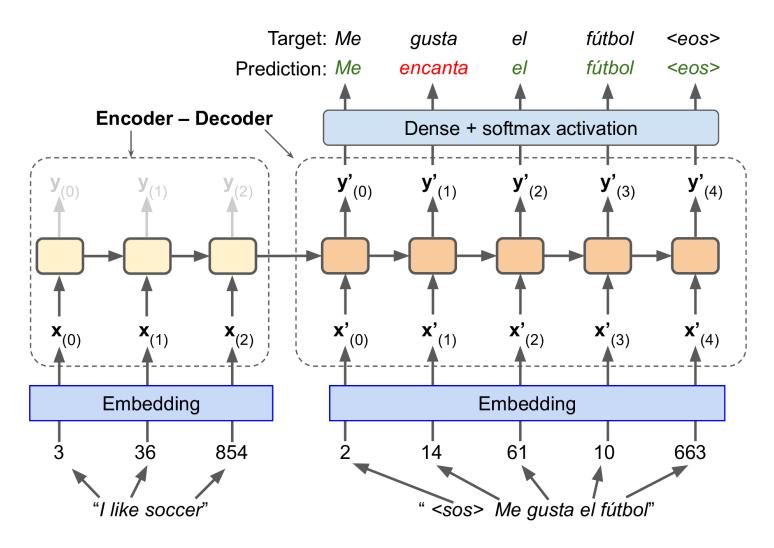
$$P(y_t|y_1^{t-1}, x) = softmax(Vs_t + b)$$

- Parameters:  $U_{dec}$ , V,  $W_{dec}$ ,  $U_{enc}$ ,  $W_{enc}$ , b
- Loss:

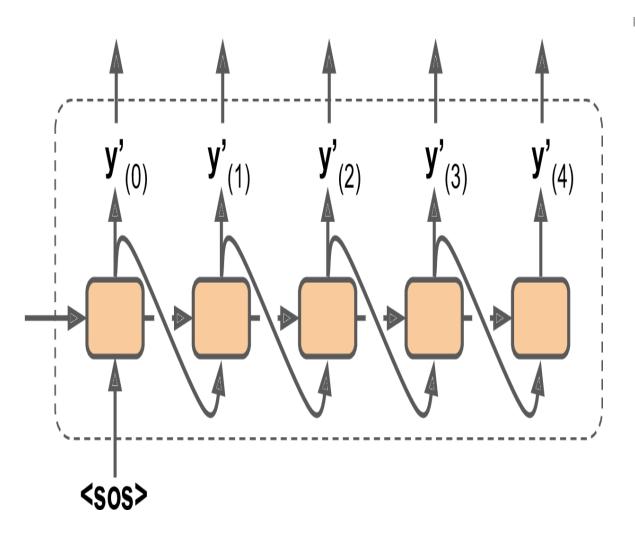
$$\mathcal{L}(\theta) = \sum_{i=1}^{T} \mathcal{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, x)$$

• Algorithm: Gradient descent with backpropagation

### Applications of Encoder Decoder Models: Machine Translation



#### **Encoder-Decoder Network for Machine Translation – in Inference Phase**



- Process of the Decoder in the test period-
  - The initial states of the decoder are set to the final states of the encoder.
  - process single word at every time step
  - The output produced at each time step is fed as input in the next time step
  - The internal states generated after every time step is fed as the initial states of the next time step.

## **Greedy Search**

$$Y_{argmax(y1,..yn)} = P(y1, y2, y3 ..., yn \mid x1,x2. ..., xm)$$
Output seq Input seq

- The greedy search algorithm involves selecting the most likely word at each step to generate a translation.
- **Problem:** Greedy search only considers the most likely word at each step, without considering the overall probability of the entire sentence.
- This can lead to getting stuck in local optima, where a suboptimal word choice at an early step
  prevents the algorithm from finding a better translation later on.
  - ☐ Jane visitr l'Afrique en Septembre (x:French)
  - ☐ Jane is visiting Africa in September (y: English)
  - ☐ Jane is going to be visiting Africa in September September (y: English)

#### Beam Search

#### READ BY COPY PASTING FROM THIS AND ALSO SCROLL DOWN TO GET WHAT IT MAINLY IS

#### "Comment vas-tu?" – How are you?

Yes, \*\*greedy search\*\* and \*\*beam search\*\* are decoding strategies that are typically used during the \*\*inference (testing) phase\*\* of sequence-to-sequence models, such as those used in machine translation, text generation, or any task where the model needs to make a teach tasks are to see the model selects the next token at each time step, balancing between generating coherent sequences and exploring multiple possibilities.

#### Beam Search

### Greedy Search and Beam Search in Detail:

- Keeps track of a short list of the k most promising sentences
  #### 1. \*\*Greedy Search\*\*:
- \*\*How it works\*\*: Greedy search is a simple decading strategy where, at each time step, the model chooses the token with the highest probability as the next token. It doesn't look ahead or consider other possibilities—it just picks the "best" option at each step based on the model's predictions.
- \*\*Process\*\*: At each decoder step it tries to extend them by 1 word
- 1. The model generates probabilities over the vocabulary for the first token (Probability of Council of Step big the highest probability of Closen as the Duput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the purput for the first token (Probability of Council of Step big the Step big the purput for the first token (Probability of Council of Step big the Step big big the Step big the Step big big the Step big the Step
- 3. This token is Step in 2: th3 reapies paformode limmade to find the next word
- 4. The process iStepe 3 in this statement will be looked forcen ext (INVOICE) safter "How" by computing conditional probabilities
- \*\*Example\*\*: Output could be "will (Prob:36%) "are", "do",
- Let's say you ar Steepen 4 No Go properties to het probability distribution over the vocabulary). If "on" has the highest probability, it's selected.

  - Time step 2A'd van tage this that ogood translation for fairly short sentences can be obtained
  - \*\*Pros\*\*: Disadvantage really bad at translating long sentences.
  - -Low campubited to Limited short term memory, lead to ATTENTION MECHANISM
  - \*\*Cons\*\*:
- Greedy search can miss globally optimal solutions because it only considers local (immediate) probabilities. This can lead to suboptimal sequences if a lower-probability token at an earlier step could lead to a better overall sequence.
  - Does not explore alternative sequences, potentially limiting fluency and accuracy in sequence generation.
- \*\*Use Cases\*\*: Greedy search is often used in simpler scenarios where a fast, approximate result is sufficient, but it's typically not ideal for tasks like machine translation or text generation where <u>more complex, coherent output is desired</u>

## Attention Mechanism (Bahdanau et al , 2014)

- Technique that allowed the decoder to focus on the appropriate words at each time steps
- Ensures that the path to from an input word to its translation is much shorter
- For instance, at the time step where the decoder needs to output the word 'lait' it focusses on the word "milk"
- Path from input word to translation is smaller, so not affected by the short term limitations of RNNS
- Visual Attention
  - For example : Generating image captions using visual attentions
  - CNN processes image and outputs some feature maps
  - Then decoder RNN with attention generates the caption, one word at a time
- Leads to Explainability (Ribeiro et al. 2016)
  - What led the model to produce its output
  - Which leads to fairness in results
    - Google apologizes after its Vision AI produced racist results



# Attention Mechanism (Bahdanau et al , 2014)

Attention is proposed as a method to both align and translate.

#### Alignment

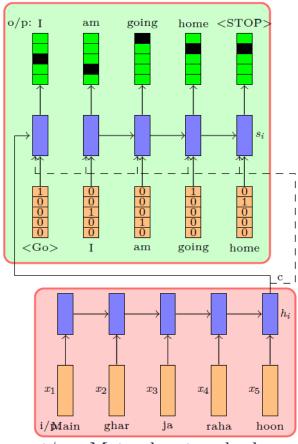
is the problem in machine translation that identifies which parts of the input sequence are relevant to each word in the output

#### translation

- is the process of using the relevant information to select the appropriate output
- "... we introduce an extension to the encoder—decoder model which learns to align and translate jointly. Each time the proposed model generates a word in a translation, it (soft-)searches for a set of positions in a source sentence where the most relevant information is concentrated. The model then predicts a target word based on the context vectors associated with these source positions and all the previous generated target words."
  - Neural Machine Translation by Jointly Learning to Align and Translate, 2015.

#### Task: Machine translation

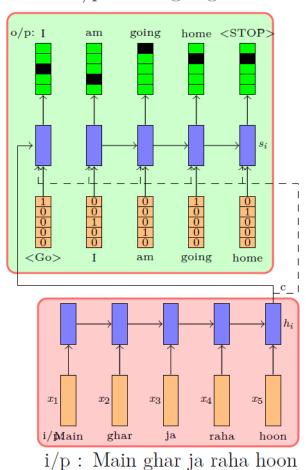
o/p : I am going home



i/p : Main ghar ja raha hoon

#### **Task:** Machine translation

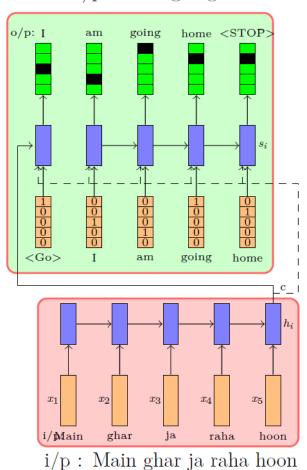
o/p: I am going home



• In a typical encoder decoder network, each time step of the decoder uses the information obtained from the last time step of the encoder.

#### **Task:** Machine translation

o/p: I am going home



- In a typical encoder decoder network, each time step of the decoder uses the information obtained from the last time step of the encoder.
- However, the translation would be effective if the network could focus/or pay attention to specific input word that would contribute to the prediction.

Consider the task of machine translation:

While predicting each word in the o/p we would like our model to mimic humans and focus on specific words in the i/p

$$o/p$$
: I am going home  $t_1$ : [ 1 0 0 0 0 ]

i/p: Main ghar ja raha hoon

While predicting each word in the o/p we would like our model to mimic humans and focus on specific words in the i/p

o/p : I am going home 
$$t_1$$
 : [ 1 0 0 0 0 ]  $t_2$  : [ 0 0 0 0 1 ]

i/p : Main ghar ja raha hoon

While predicting each word in the o/p we would like our model to mimic humans and focus on specific words in the i/p

```
o/p: I am going home t_1: [ 1 0 0 0 0 ] t_2: [ 0 0 0 0 1 ] t_3: [ 0 0 0.5 0.5 0 ]
```

i/p : Main ghar ja raha hoon

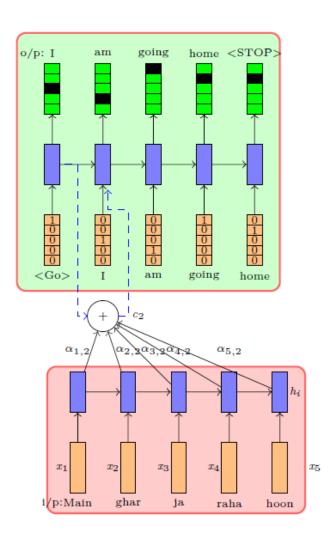
```
o/p: I am going home t_1: [ 1 0 0 0 0 ] t_2: [ 0 0 0 0 1 ] t_3: [ 0 0 0.5 0.5 0 ] t_4: [ 0 1 0 0 0 ]
```

i/p : Main ghar ja raha hoon

- Essentially, at each time step, a distribution on the input words must be introduced.
- This distribution tells the model how much attention to pay to each input words at each time step.

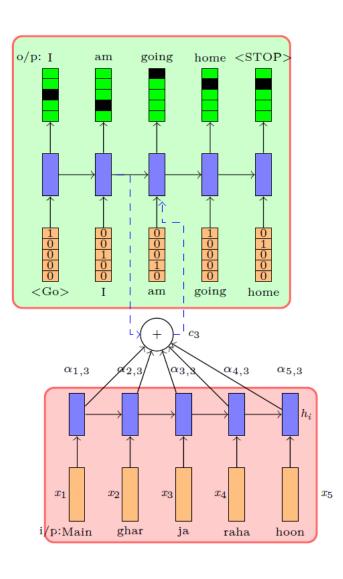
**Task:** Machine translation

 To do this, we could just take a weighted average of the corresponding word representations and feed it to the decoder



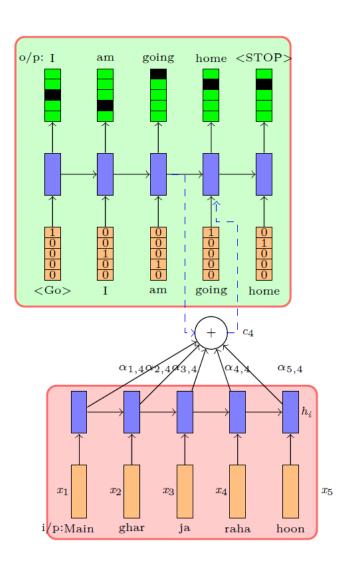
**Task:** Machine translation

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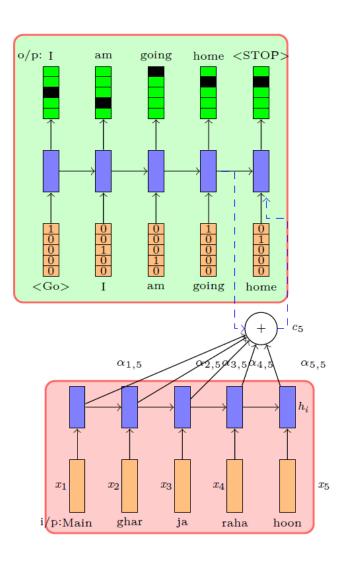
Task: Machine translation

 To do this, we could just take a weighted average of the corresponding word representations and feed it to the decoder

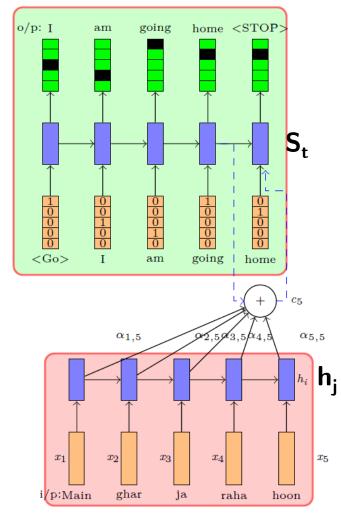


**Task:** Machine translation

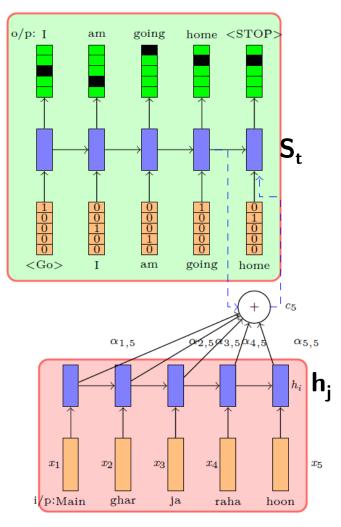
 To do this, we could just take a weighted average of the corresponding word representations and feed it to the decoder



**Task:** Machine translation

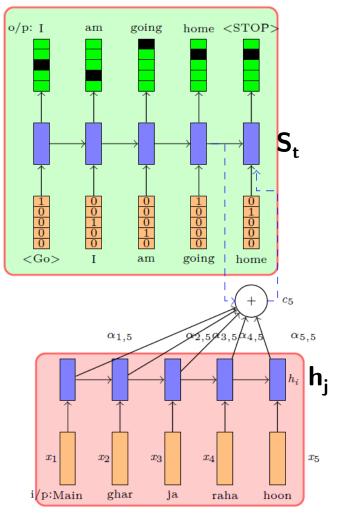


**Task:** Machine translation



To enable the network to focus on certain data we define the following function:

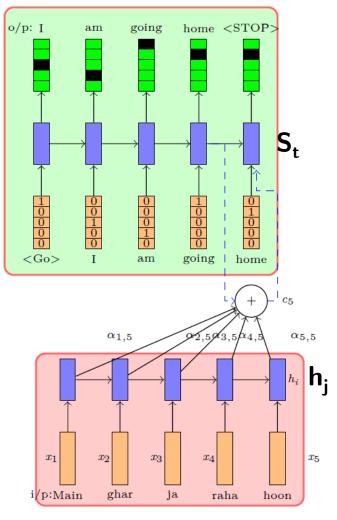
Task: Machine translation



 To enable the network to focus on certain data we define the following function:

$$e_{jt} = f_{ATT}(s_{t-1}, \mathbf{h_j})$$

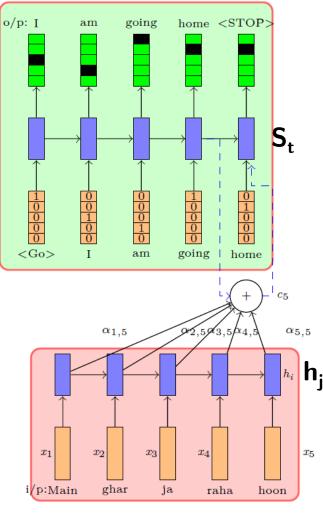
**Task:** Machine translation



 To enable the network to focus on certain data we define the following function:

$$e_{jt} = f_{ATT}(s_{t-1}, \mathbf{h_j})$$
 Can be considered as a separate feed forward network

**Task:** Machine translation

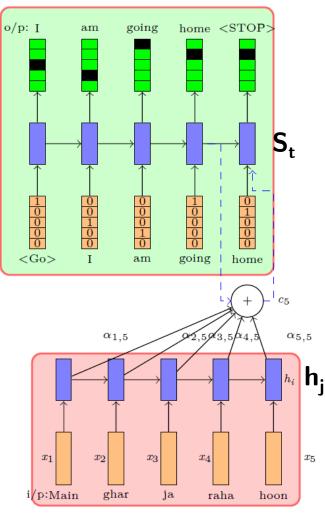


 To enable the network to focus on certain data we define the following function:

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 Can be considered as a separate feed forward network

 This quantity captures the importance of the j<sup>th</sup> input word for decoding the t<sup>th</sup> output word.

#### **Task:** Machine translation

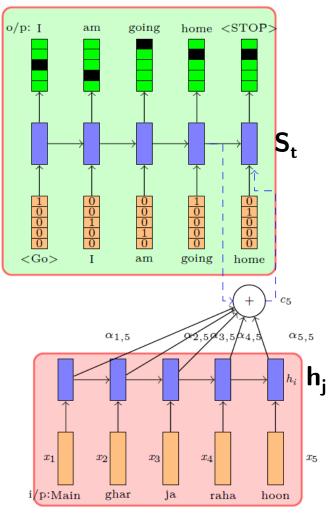


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- This quantity captures the importance of the j<sup>th</sup> input word for decoding the t<sup>th</sup> output word.
- We could compute  $\alpha_{jt}$  by normalizing these weights using the softmax function.

**Task:** Machine translation



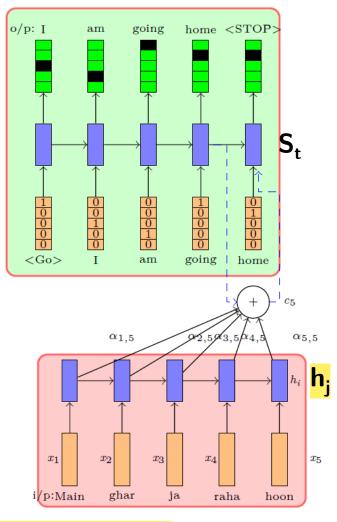
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$$\alpha_{jt} = \frac{exp(e_{jt})}{\sum_{j=1}^{M} exp(e_{jt})}$$

Task: Machine translation



To enable the network to focus on certain data we define the following function:

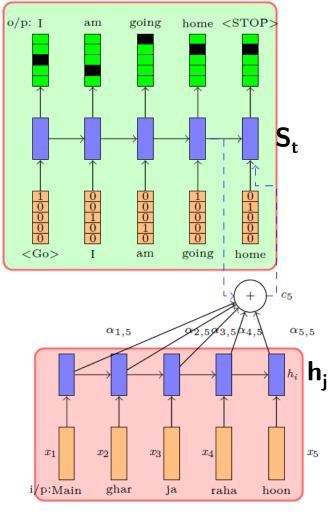
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- This quantity captures the importance of the j<sup>th</sup> input word for decoding the t<sup>th</sup> output word.
- We could compute  $\alpha_{jt}$  by normalizing these weights using the softmax function.

$$\alpha_{jt} = \frac{exp(e_{jt})}{\sum_{j=1}^{M} exp(e_{jt})}$$

Where,  $\alpha_{jt}$  denotes the probability of focusing on the j<sup>th</sup> word to produce the t<sup>th</sup> output word

Task: Machine translation



Introducing the parametric form of  $\alpha$ :

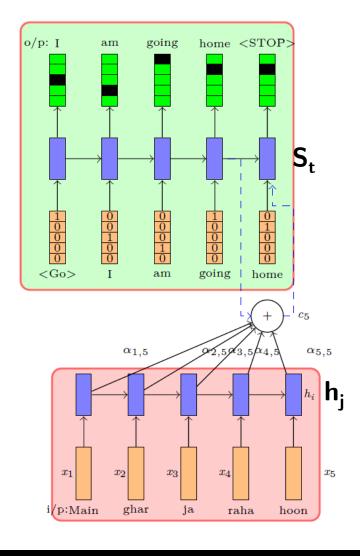
$$e_{jt} = V_{attn}^{T} tanh(U_{attn}h_{j} + W_{attn}s_{t})$$

$$\alpha_{jt} = \frac{exp(e_{jt})}{\sum_{j=1}^{M} exp(e_{jt})}$$

$$c_t = \sum_{j=1}^{T} \alpha_{jt} h_j$$

Where, c<sub>t</sub> (context) gives a weighted sum over the inputs.

#### **Task:** Machine translation



- Data:  $\{x_i = source_i, y_i = target_i\}_{i=1}^N$
- Encoder:

$$h_t = RNN(h_{t-1}, x_t)$$
$$s_0 = h_T$$

• Decoder:

$$e_{jt} = V_{attn}^{T} tanh(U_{attn}h_{j} + W_{attn}s_{t})$$

$$\alpha_{jt} = softmax(e_{jt})$$

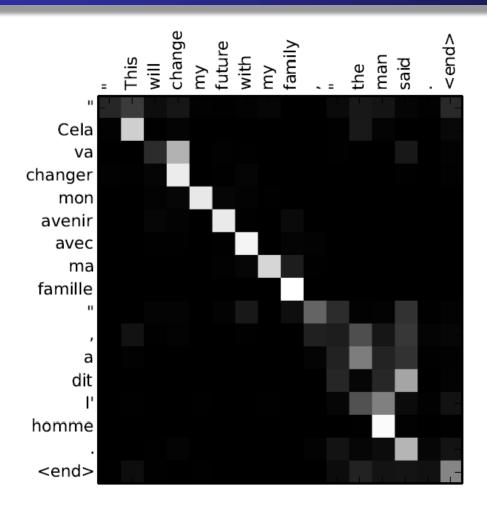
$$c_{t} = \sum_{j=1}^{T} \alpha_{jt}h_{j}$$

$$s_{t} = RNN(s_{t-1}, [e(\hat{y}_{t-1}), c_{t}])$$

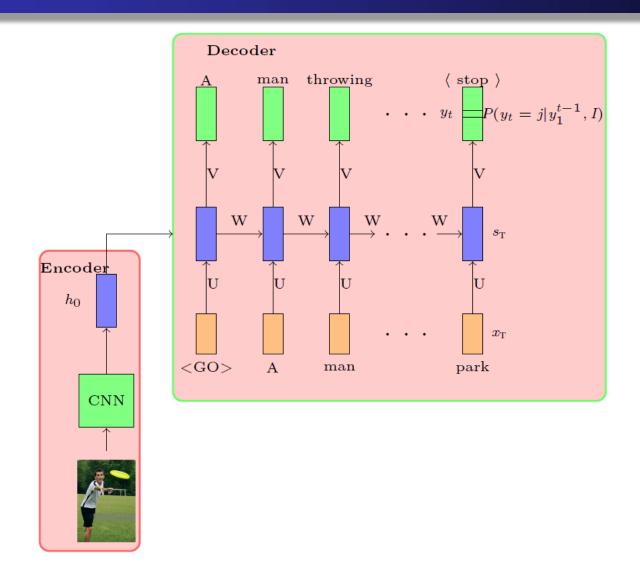
$$\ell_{t} = softmax(Vs_{t} + b)$$

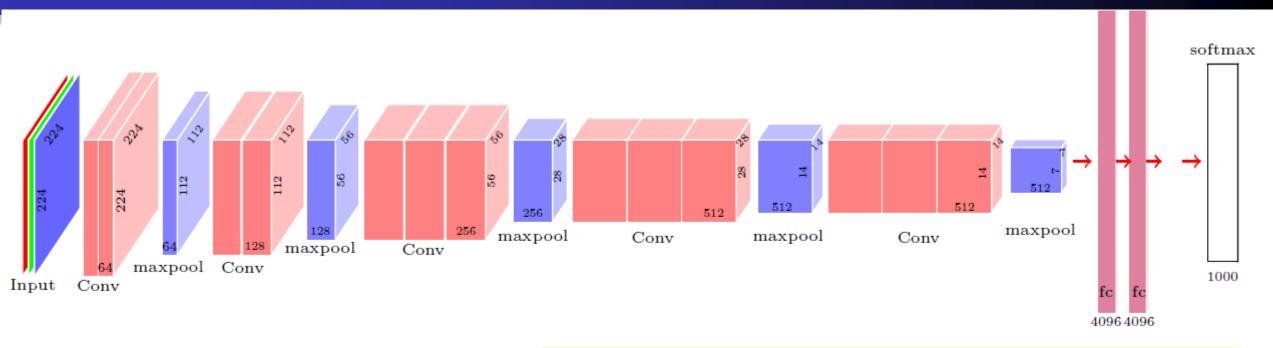
- Parameters:  $U_{dec}$ , V,  $W_{dec}$ ,  $U_{enc}$ ,  $W_{enc}$ , b,  $U_{attn}$ ,  $V_{attn}$
- Loss and Algorithm remains same

## **Encoder Decoder with Attention Mechanism: Visualization**

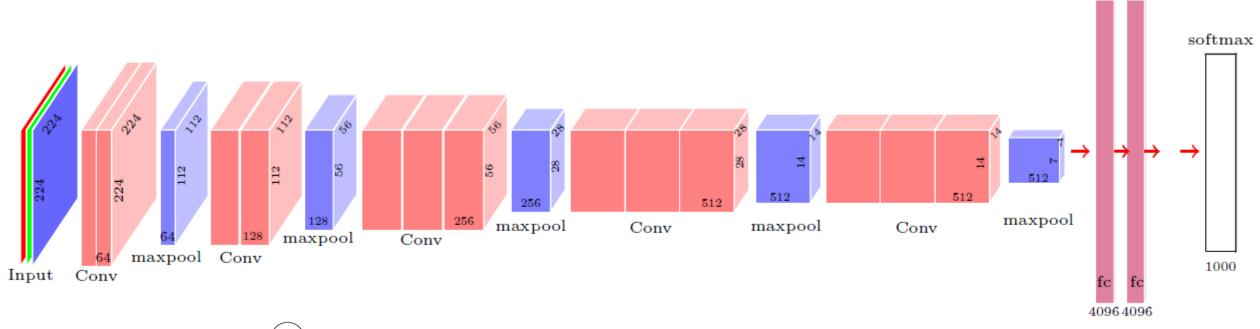


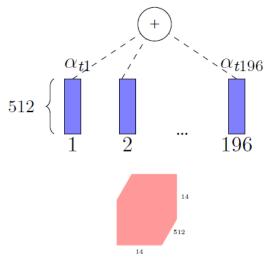
Example output of attention-based neural machine translation model Bahdanau et al. 2015



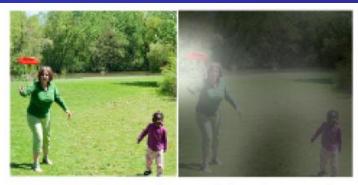


- For a CNN (eg: VGG-16) we would consider the convolution layer to be an input to the decoder, instead of the fully connected layers.
- This is because, the information about the image is contained in the feature maps in the convolution layer.
- Therefore, we could add attention weights to each pixel of the feature map volume to make the model focus on a particular pixel or region in the image.





- For a CNN (eg: VGG-16) we would consider the convolution layer to be an input to the decoder, instead of the fully connected layers.
- This is because, the information about the image is contained in the feature maps in the convolution layer.
- Therefore, we could add attention weights to each pixel of the feature map volume to make the model focus on a particular pixel or region in the image.



A woman is throwing a frisbee in a park.



A <u>dog</u> is standing on a hardwood floor.



A stop sign is on a road with a mountain in the background.



A little girl sitting on a bed with a teddy bear.



A group of <u>people</u> sitting on a boat in the water.



A giraffe standing in a forest with trees in the background.

Figure: Examples of the attention-based model attending to the correct object (white indicates the attended regions, underlines indicates the corresponding word) [Kyunghyun Cho et al. 2015.]

Task: Chat Bot

#### Context

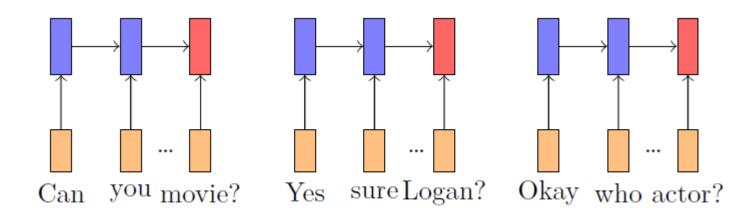
U: Can you suggest a good movie?

B: Yes, sure. How about Logan?

U: Okay, who is the lead actor?

#### Response

- Consider a dialog between a user (u) and a bot (B)
- The dialog contains a sequence of utterances between the user and the bot
- Each utterance in turn is a sequence of words
- Thus, what we have here is a "sequence of sequences" as input.



#### Task: Chat Bot

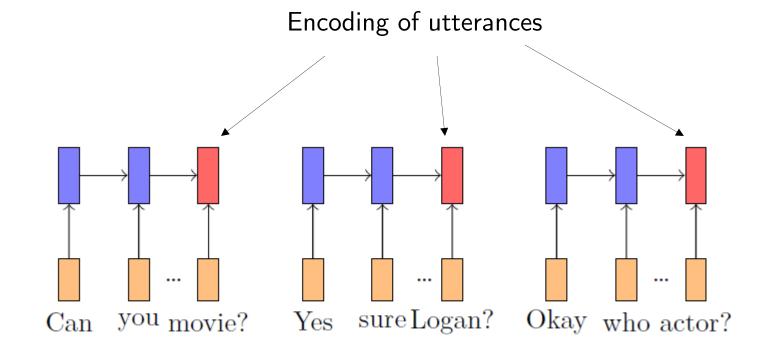
#### Context

U: Can you suggest a good movie?

B: Yes, sure. How about Logan?

U: Okay, who is the lead actor?

#### Response



#### Task: Chat Bot

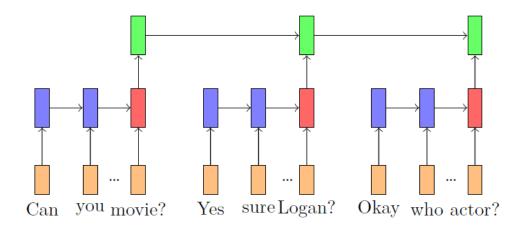
#### Context

U: Can you suggest a good movie?

B: Yes, sure. How about Logan?

U: Okay, who is the lead actor?

#### Response



#### Task: Chat Bot

#### Context

U: Can you suggest a good movie?

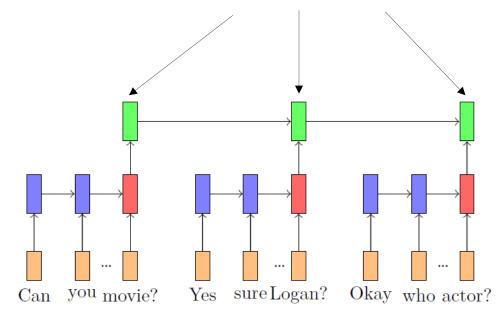
B: Yes, sure. How about Logan?

U: Okay, who is the lead actor?

#### Response

B: Hugh Jackman, of course

#### Encoding of sequence of utterances



#### Task: Chat Bot

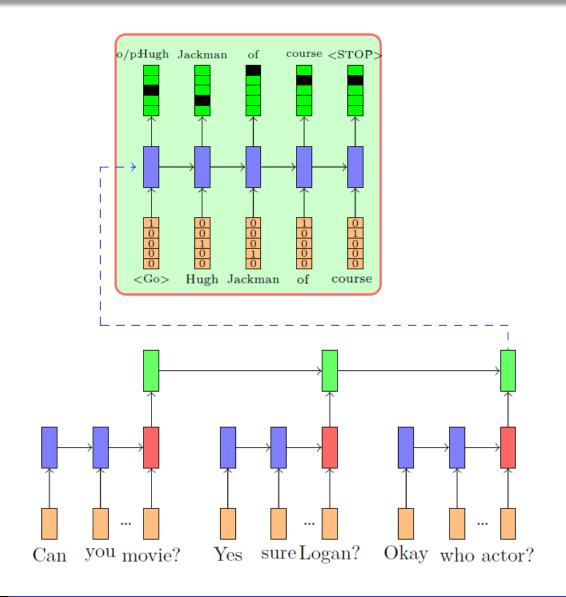
#### Context

U: Can you suggest a good movie?

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U: Okay, who is the lead actor?

#### Response

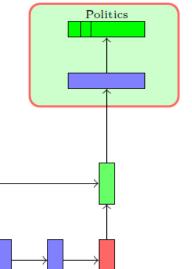


#### Task: Document Summarization

Politics is the process of making decisions applying to all members of each group.

More narrowly, it refers to achieving and ...

- A document is a sequence of sequences
- It's a sequence of sentences which in turn
   I s sequence of words



• Data: 
$$\{Document_i, class_i\}_{i=1}^N$$

• Word level (1) encoder:

$$h_{ij}^1 = RNN(h_{ij-1}^1, w_{ij})$$
  
 $s_i = h_{iT_i}^1 \quad [T \text{ is length of sentence } i]$ 

• Sentence level (2) encoder:

$$h_i^2 = RNN(h_{i-1}^2, s_i)$$
  
 $s = h_K^2$  [K is number of sentences]

• Decoder:

$$P(y|document) = softmax(Vs + b)$$

- Params:  $W_{enc}^1$ ,  $U_{enc}^1$ ,  $W_{enc}^2$ ,  $U_{enc}^2$ , V, b
- Loss: Cross Entropy
- Algorithm: Gradient Descent with backpropagation

Source: CS7015 Deep Learning, Dept. of CSE, IIT Madras

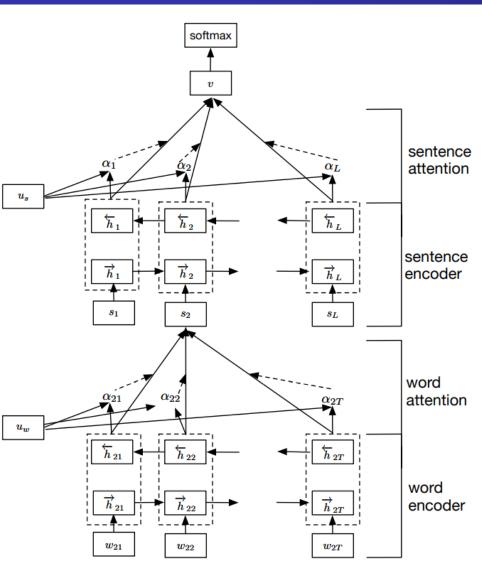
Politics is decisions applying to group

Morenarrowlyand

## **Document Classification using Hierarchical Attention Networks**

- To understand the main message of a document
  - Not every word in a sentence and every sentence in a document are equally important
- Meaning of word depends on context
  - For example "The bouquet of flowers is pretty" vs. "The food is pretty bad".
- HAN
  - considers the hierarchical structure of documents (document sentences words)
  - Includes an attention mechanism that is able to find the most important words and sentences in a document while taking the context into consideration

#### **Hierarchical Attention Networks**



- Data:  $\{Document_i, class_i\}_{i=1}^N$
- Word level (1) encoder:

$$h_{ij} = RNN(h_{ij-1}, w_{ij})$$

$$u_{ij} = tanh(W_w h_{ij} + b_w)$$

$$\alpha_{ij} = \frac{exp(u_{ij}^T u_w)}{\sum_t exp(u_{it}^T u_w)}$$

$$s_i = \sum_t \alpha_{ij} h_{ij}$$

• Sentence level (2) encoder:

$$h_{i} = RNN(h_{i-1}, s_{i})$$

$$u_{i} = tanh(W_{s}h_{i} + b_{s})$$

$$\alpha_{i} = \frac{exp(u_{i}^{T}u_{s})}{\sum_{i} exp(u_{i}^{T}u_{s})}$$

$$s = \sum_{i} \alpha_{i}h_{i}$$

• Decoder:

$$P(y|document) = softmax(Vs + b)$$

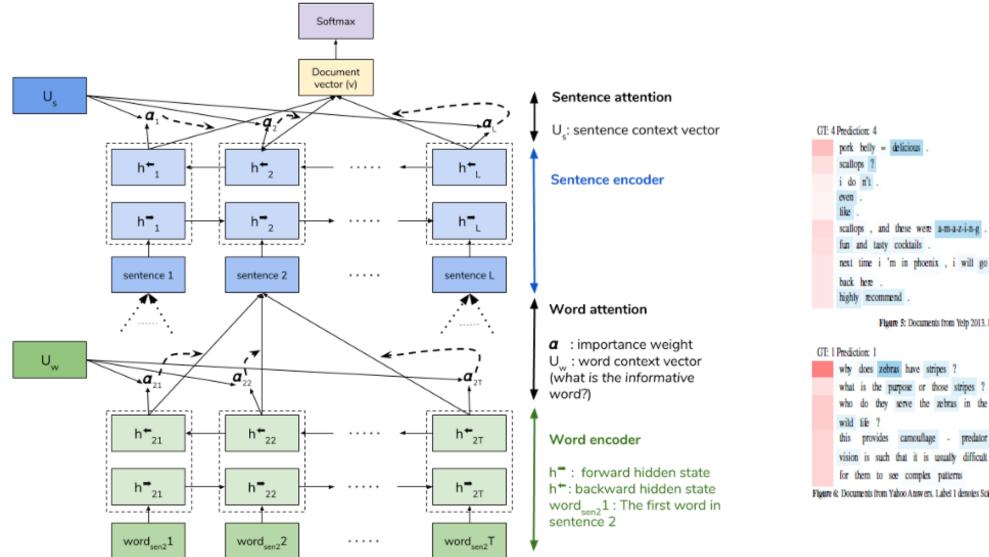
• Parameters:

$$W_w$$
,  $W_s$ ,  $V$ ,  $b_w$ ,  $b_s$ ,  $b$ ,  $u_w$ ,  $u_s$ 

- Loss: cross entropy
- Algorithm: Gradient Descent and backpropagation

Yang et al. Hierarchical Attention Networks for Document Classification, Proceedings of NAACL-HLT 2016

## Hierarchical Attention Networks (Yang et al. 2016)



then click " delete history " and "

clean up temporary internet files . "