

Pyroelectric Infrared Radial Sensor

TYPE: BM612

SENBA SENSING TECHNOLOGY CO., LTD



Digital Smart Pyroelectric Detector BM612

BM612 is a newest smart digital motion detector with a small window size. It offers a complete motion detector solution, with all electronic circuitry built into the detector housing. Only a power supply and power-switching components need to be added to make the entire motion switch.

BL612 includes the setting for time, sensitivity and ALbient light level.

■ Features and Benefits

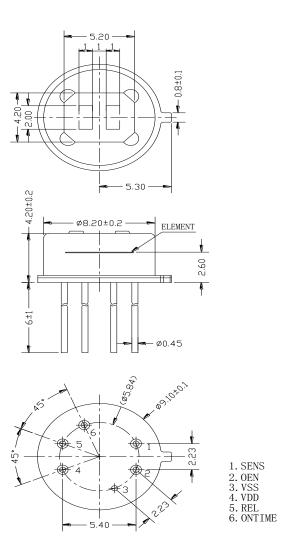
- Digital signal processing (DSP)
- Power adjustable, save more energy
- Two-way differential high impedance sensor input
- Built-in filter, screen the interference by other frequency
- Excellent power supply rejection, Insensitive to RF interference
- Schmidt REL output
- Low voltage, low power consumption, instantaneous settling after power up

Applications

- Toys
- Digital photo frame
- TV, Refrigerator, Air-conditioner
- USB Alarms
- PIR motion detection
- Intruder detection
- Occupancy detection
- Motion sensor lights
- Computer monitor
- Security system
- Automatic control
- Corridor
- Stairs Lights etc.



Dimension



PIR Dimension

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■ Technical Data

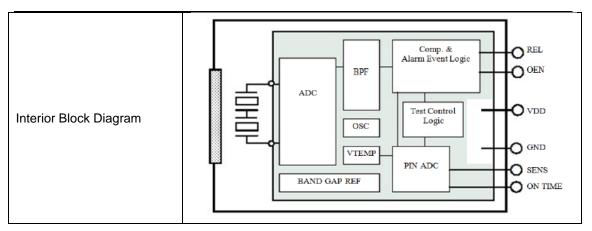
1. Maximum Ratings

| Characteristics | Symbol | Min. Value | Max. Value | Unit | Remarks |
|------------------------|--------|------------|------------|------|---------|
| Supply Voltage | VDD | -0.3 | 3.6 | V | |
| Working Temperature | Тѕт | -20 | 85 | °C | |
| Max.current for pin | Into | -100 | 100 | mA | |
| Storage Temperature | Тѕт | -40 | 125 | °C | |

2. Working Conditions (T=25°C, Vdd=3V, Except other requirements)

| 2.working Conditions | S (I = Z 3 | C, vac | a=3v, | ⊏xcept | otner | requirements) |
|------------------------------------|-------------------|-------------------------|-------|----------|-------|--|
| Characteristics | Symb ol | Min. | Туре | Max. | Unit | Remarks |
| Supply Voltage | V_{DD} | 2.2 | 3 | 3.7 | V | IR=0.5mA |
| Working Current | I_{DD} | 9 | 9.5 | 11 | μA | |
| Sensitivity | V _{SENS} | 90 | | 2000 | μV | |
| Output REL | | | I | -1 | I | • |
| Output Low Current | I _{OL} | 10 | | | mA | V _{OL} <1V |
| Output High Current | I _{OH} | | | -10 | mA | V _{OL} >(V _{DD-} 1V) |
| Lock time | T _{OL} | | 2 | | s | |
| On-time | T _{OH} | 2 | | 4793 | s | |
| SENS/ONTIME | | • | • | • | | |
| Input voltage | | 0 | | V_{DD} | V | 0V to VDD/2 |
| Input Bias Current | | -1 | | 1 | μΑ | |
| OEN | | • | • | • | | |
| Input Low Voltage | V _{IL} | 0.8V-1 .2VEn able | | 0.8 | Vdd | |
| Input High Voltage | V _{IH} | area 1.2 | | | Vdd | |
| Input Current | I _I | -1 | | 1 | μA | V _{SS} <v<sub>IN<v<sub>DD</v<sub></v<sub> |
| Oscillator & Filter | | | | · | | |
| Low pass filter cut-off frequency | | | | 7 | Hz | |
| High pass filter cut-off frequency | | | | 0.44 | Hz | |
| Oscillator frequency on Chip | F _{CLK} | | | 64 | kHz | |





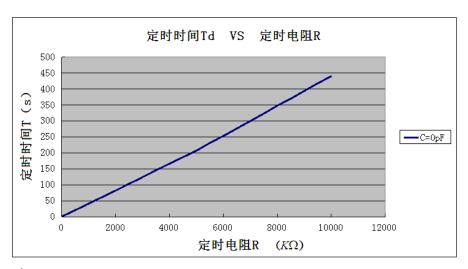
■ Ontime Setting

1. Analog setting style for on-time

Td: On-time time

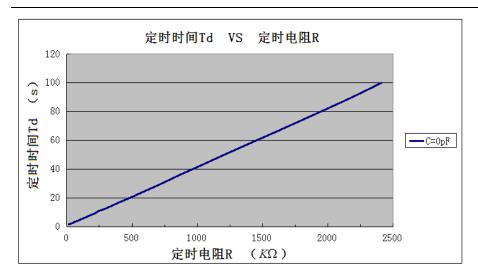
R: On-time Resistor

C: On-time Capacitor

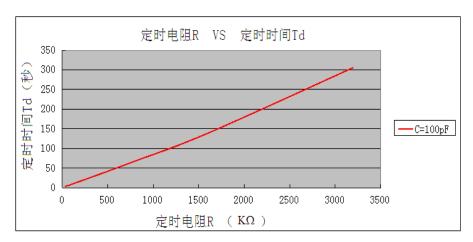


* C=0pF

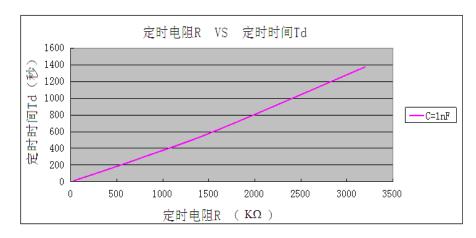




* C=0pF



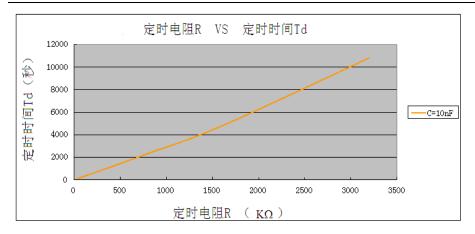
* C=100pF



* C=1npF

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* C=10npF

2. Digital setting style for on-time

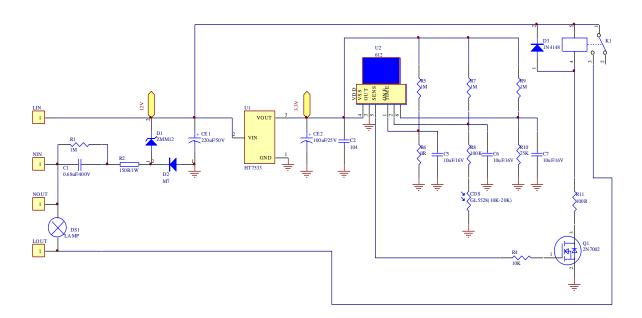
| No | Time (Td) | On-time Voltage | On-time center | Pull-down- Resistor (Ω) (Pull-up=1M) | | |
|----|------------|-------------------|----------------|--|---------|--|
| | (sec)(典型值) | (VDD) | Voltage (VDD) | 上拉电阻 RH | 下拉电阻 RL | |
| 1 | 2 | 0~1/32VDD | 1/64VDD | 不贴/1 M | 0R | |
| 2 | 5 | 1/32VDD~2/32VDD | 3/64VDD | 1M | 51K | |
| 3 | 10 | 2/32VDD~3/32VDD | 5/64VDD | 1M | 82K | |
| 4 | 15 | 3/32VDD~4/32VDD | 7/64VDD | 1M | 124K | |
| 5 | 20 | 4/32VDD~5/32VDD | 9/64VDD | 1M | 165K | |
| 6 | 30 | 5/32VDD~6/32VDD | 11/64VDD | 1M | 210K | |
| 7 | 45 | 6/32VDD~7/32VDD | 13/64VDD | 1M | 255K | |
| 8 | 60 | 7/32VDD~8/32VDD | 15/64VDD | 1M | 309K | |
| 9 | 90 | 8/32VDD~9/32VDD | 17/64VDD | 1M | 360K | |
| 10 | 120 | 9/32VDD~10/32VDD | 19/64VDD | 1M | 422K | |
| 11 | 180 | 10/32VDD~11/32VDD | 21/64VDD | 1M | 487K | |
| 12 | 300 | 11/32VDD~12/32VDD | 23/64VDD | 1M | 560K | |
| 13 | 600 | 12/32VDD~13/32VDD | 25/64VDD | 1M | 634K | |
| 14 | 900 | 13/32VDD~14/32VDD | 27/64VDD | 1M | 732K | |
| 15 | 1800 | 14/32VDD~16/32VDD | 29/64VDD | 1M | 825K | |
| 16 | 3600 | 15/32VDD~16/32VDD | 31/64VDD | 1M | 953K | |



■ Sensitivity Setting

| | V _{SENS} | | | V _{SENS} | |
|----|-------------------------------------|--------------------------------------|----|-------------------|-----------------------------------|
| | Voltage Range (V _{DD}) | Center Voltage (V _{DD}) | | Voltage Range | Center Voltage (V _{DD}) |
| 0 | 0~1/64 | 1/128 | 16 | 16/64~17/64 | 33/128 |
| 1 | 1/64~2/64 | 3/128 | 17 | 17/64~18/64 | 35/128 |
| 2 | 2/64~3/64 | 5/128 | 18 | 18/64~19/64 | 37/128 |
| 3 | 3/64~4/64 | 7/128 | 19 | 19/64~20/64 | 39/128 |
| 4 | 4/64~5/64 | 9/128 | 20 | 20/64~21/64 | 41/128 |
| 5 | 5/64~6/64 | 11/128 | 21 | 21/64~22/64 | 43/128 |
| 6 | 6/64~7/64 | 13/128 | 22 | 22/64~23/64 | 45/128 |
| 7 | 7/64~8/64 | 15/128 | 23 | 23/64~24/64 | 47/128 |
| 8 | 8/64~9/64 | 17/128 | 24 | 24/64~25/64 | 49/128 |
| 9 | 9/64~10/64 | 19/128 | 25 | 25/64~26/64 | 51/128 |
| 10 | 10/64~11/64 | 21/128 | 26 | 26/64~27/64 | 53/128 |
| 11 | 11/64~12/64 | 23/128 | 27 | 27/64~28/64 | 55/128 |
| 12 | 12/64~13/64 | 25/128 | 28 | 28/64~29/64 | 57/128 |
| 13 | 13/64~14/64 | 27/128 | 29 | 29/64~30/64 | 59/128 |
| 14 | 14/64~15/64 | 29/128 | 30 | 30/64~31/64 | 61/128 |
| 15 | 15/64~16/64 | 31/128 | 31 | 31/64~32/64 | 63/128 |

■ Typical Application

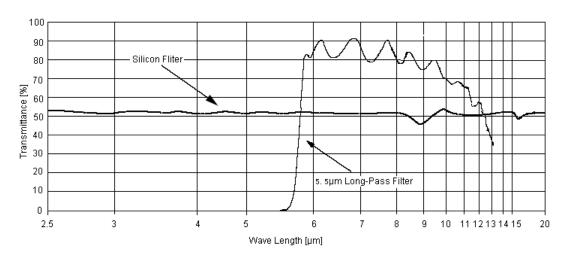


Notes: The circuit design for PIR Sensor BM612.

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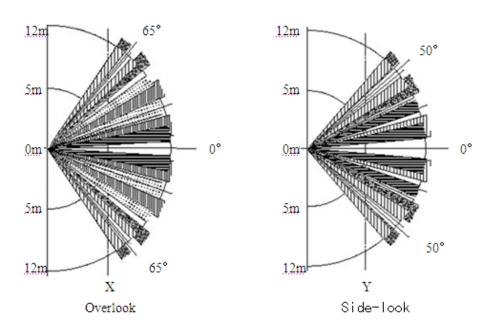


■ Spectral Response of Window Materials



Notes: The average transitivity curve for silicon filter with 5.5 µm pass IR filter

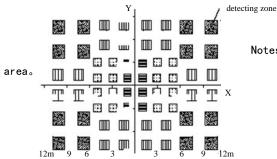
■ Detection View



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X-Y sectional view



Notes: 1.X-Y sectional view represent the detecting

2. Objects with temperature difference can be Detected in the vertical level.



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