Representing Agent reasoning with Meta-Knowledge on **ASP Modules Combination**

Tony Ribeiro National Institute of Informatics Tokyo, Japan ribeiro@nii.ac.jp

Katsumi Inoue National Institute of Informatics Tokyo, Japan ki@nii.ac.jp

Gauvain Bourgne Paris, France bourgne@nii.ac.jp

ABSTRACT

In this work, we focus on multi-agent systems in dynamic environment. Our interest is about individual agent reasoning in such environment. For reasoning in dynamic environment, an agent needs to be able to manage his knowledge in a non-monotonic way. To reach his goals in a changing environment, an agent needs to adapt his behaviours regarding the current state of the world. Our objective is to define a method which makes easier to design agent knowledge and reasoning in such environment. We use the expressivity of answer set programming to represent agent knowledge. To design agent reasoning, we propose a method based on ASP modules combination and meta-knowledge. We also propose a framework to implement and use this method in multi-agent systems.

Categories and Subject Descriptors

H.4 [Information Systems Applications]: Miscellaneous

General Terms

Design

Keywords

ASP modules

INTRODUCTION

STATE OF THE ART

DYNAMIC ENVIRONMENT

Our interest is about representing agent reasoning in dynamic environment. To make our work more understandable we will follow an intuitive example along our propositions: a survival game which represent a MAS in a dynamic environment. In this game there are three groups of agents: wolfs, rabbits and flowers. Each kind of agent have specific goals and behaviours. To be simple, wolfs eat rabbits and rabbits eat flowers.

Appears in: Proceedings of the 11th International Conference on Autonomous Agents and Multiagent Systems (AA-MAS 2012), Conitzer, Winikoff, Padgham, and van der Hoek (eds.), June, 4-8, 2012, Valencia, Spain.

Copyright © 2012, International Foundation for Autonomous Agents and Multiagent Systems (www.ifaamas.org). All rights reserved.

Wolfs have only one goal: feed themselves. To reach this goal they have to catch and eat rabbits. A wolf can be in two situations: a prey is in sight or not. If there is no rabbit in the sight range of a wolf, the predator have to explore his environment to find one. When a prey is spotted a wolf will try to perform a sneaky approach if he is not spotted himself, otherwise our predator will rush on his target. To resume, a wolf have three behaviours: exploration, approach and attack.

4. ASP MODULES

An ASP module is an ASP program which have a specific form and a specific use. The first advantage of these modules is their simplicity: a module is a little program which represent specific knowledge. We can have a module which contain observations about surroundings, an other one to define what is a prey and a module dedicated to compute path. To obtain all paths to surroundings preys an agent will combines this three modules. By combining modules an agent can produce knowledge, it the purpose of our ASP modules.

4.1 Background theory

Definition 1 (Rules module is a Multi-Agents System, Answer Set Programming, Meta-knowledge, set of rules which represent knowledge about a specific domain. The content of such module is static: it does not change regarding time. The purpose of these modules is to organise knowledge representation and produce new knowledge by combine it with others modules.

4.2 Observations

Definition 2 (Observations module). An observations module is a set of facts which represent related observations. The content of such module is dynamic: it change regarding time. An agent use it like a specific memory database. The purpose of these modules is to organise observations to facilitate their use and update.

4.3 Meta-knowledge

Definition 3 (Meta-knowledge module). A metaknowledge module is a set of rules which define the conditions to use an ASP module. The content of such module does not change regarding time. It contains knowledge on modules combination. The purpose of these modules is to quide reasoning and represent dynamic behaviours.

5. EXPERIMENTS

6. CONCLUSIONS

7. REFERENCES

- [1] C. Baral, S. Anwar, and J. Dzifcak. Macros, macro calls and use of ensembles in modular answer set programming. In AAAI Spring Symposium:

 Formalizing and Compiling Background Knowledge and Its Applications to Knowledge Representation and Question Answering, pages 1–9, 2006.
- [2] C. Baral and G. Gelfond. On representing actions in multi-agent domains. In Logic Programming, Knowledge Representation, and Nonmonotonic Reasoning, pages 213–232, 2011.
- [3] C. Baral, G. Gelfond, T. C. Son, and E. Pontelli. Using answer set programming to model multi-agent scenarios involving agents' knowledge about other's knowledge. In AAMAS, pages 259–266, 2010.
- [4] G. Bourgne. Hypotheses refinement and propagation with communication constraints. PhD thesis, University Paris IX Dauphine, 2008.
- [5] G. Bourgne, K. Inoue, and N. Maudet. Abduction of distributed theories through local interactions. In ECAI, pages 901–906, 2010.
- [6] G. Bourgne, K. Inoue, and N. Maudet. Towards efficient multi-agent abduction protocols. In *LADS*, pages 19–38, 2010.
- [7] S. Costantini. Integrating answer set modules into agent programs. In *LPNMR*, pages 613–615, 2009.
- [8] S. Costantini. Answer set modules for logical agents. In *Datalog*, pages 37–58, 2010.
- [9] W. Faber and S. Woltran. Manifold answer-set programs and their applications. In *Logic* Programming, Knowledge Representation, and Nonmonotonic Reasoning, pages 44–63, 2011.
- [10] M. Fisher, R. H. Bordini, B. Hirsch, and P. Torroni. Computational logics and agents: A road map of current technologies and future trends. *Computational Intelligence*, 23(1):61–91, 2007.
- [11] M. Gebser, B. Kaufmann, R. Kaminski, M. Ostrowski, T. Schaub, and M. T. Schneider. Potassco: The potsdam answer set solving collection. AI Commun., 24(2):107–124, 2011.
- [12] D. Hatano and K. Hirayama. Dynamic sat with decision change costs: Formalization and solutions. In *IJCAI*, pages 560–565, 2011.
- [13] R. A. Kowalski and F. Sadri. From logic programming towards multi-agent systems. Ann. Math. Artif. Intell., 25(3-4):391–419, 1999.
- [14] R. A. Kowalski and F. Sadri. Abductive logic programming agents with destructive databases. Ann. Math. Artif. Intell., 62(1-2):129–158, 2011.
- [15] M. Nakamura, C. Baral, and M. Bjäreland. Maintainability: A weaker stabilizability like notion for high level control. In AAAI/IAAI, pages 62–67, 2000.
- [16] P. Nicolas and B. Duval. Representation of incomplete knowledge by induction of default theories. In LPNMR, pages 160–172, 2001.

- [17] D. V. Nieuwenborgh, M. D. Vos, S. Heymans, and D. Vermeir. Hierarchical decision making in multi-agent systems using answer set programming. In CLIMA, pages 20–40, 2006.
- [18] C. Sakama, T. C. Son, and E. Pontelli. A logical formulation for negotiation among dishonest agents. In *IJCAI*, pages 1069–1074, 2011.
- [19] N. Tran and C. Baral. Hypothesizing about signaling networks. J. Applied Logic, 7(3):253–274, 2009.