

Adaptive Quadrature Methods

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Abstract

Adaptive quadrature refers to a family of techniques bringing the divide-and-conquer and Richardson extrapolation strategies to bear on the problem on numerical integration. Any integration scheme can hypothetically be given an adaptive version if there is a suitable error estimator available for that scheme. Here we focus on the adaptive version of Simpson's rule. The rule requires no precomputation in selecting subintervals to integrate over and demonstrably outperforms Simpson's rule in accuracy on bad integrals.

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1 Introduction

Adaptive quadrature is a general method for improving the accuracy of a quadrature rule (i.e., numerical integration scheme). A sketch of the idea is as follows: We select a quadrature rule with an a priori error estimator. We apply the quadrature to the function we want to integrate and estimate the error. If the error meets a certain condition (for example, exceeding a certain tolerance), we subdivide the interval and repeat the process on each subinterval. We hope to subdivide those regions more which make greater contributions to the total error, while settling for larger intervals when the local error is small.

An adaptive Simpson's method was proposed in 1962 and by now the idea has been applied to a wide range of quadrature rules. The subdivision criterion which appears in the adaptive Simpson's method is to subdivide when the discrepancy between a single approximation (on $[a,b]$) and the sum of two approximations (on $[a,c]$ and $[c,b]$) exceeds a certain tolerance. The discrepancy tolerance is derived by setting a tolerance for the

total error and then applying Simpson's rule's error estimate in the single-interval and composite-interval cases (see Section 3 for details).

In this report we will present the algorithm for adaptive Simpson's quadrature and compare it procedurally with composite Simpson quadrature in order to highlight the difference. The explanation and error analysis of the quadrature appear next, followed by empirical observations. These consist of tables of integration results obtained from composite Simpson quadrature and adaptive Simpson quadrature, tables comparing number of intervals and computations for each method for the same problems, and plots demonstrating this information against the graphs of the functions being integrated.

2 Adaptive Simpson Quadrature—Explanation and Analysis

(This analysis follows the explanation given in [3].) Let f be a given integrable function. Define

$$S(a, b) = \frac{b-a}{6} \left(f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right)$$

and

$$E(a, b) = -\frac{1}{90} \left(\frac{b-a}{2} \right)^5 f^{(4)}(a) + \dots$$

Then recall that Simpson's method evaluates the integral of f on $[a, b]$ as

$$I = \int_a^b f dx = S(a, b) + E(a, b).$$

Let $S_1 = S(a, b)$, let $E_1 = E(a, b)$, and let $h = b - a$. Then also let $c = (b + a)/2$. Applying Simpson's method to both of $[a, c]$ and $[c, b]$ we obtain

$$I = S(a, c) + S(c, b) + E(a, c) + E(c, b).$$

Write $S_2 = S(a, c) + S(c, b)$ and $E_2 = E(a, c) + E(c, b)$. Then under the simplifying assumption that $f^{(4)} = C$, a constant, on $[a, b]$, we have

$$E_2 = \frac{1}{16} \left(-\frac{1}{90} \left(\frac{h}{2} \right)^5 C \right) = \frac{1}{16} E_1.$$

Now subtracting one value obtained for I from the other, we arrive at the equation

$$S_2 - S_1 = E_1 - E_2 = 15E_2$$

which gives us

$$I = S_2 + \frac{1}{15}(S_2 - S_1).$$

Hence, if ϵ is our error tolerance for I , then we see that requiring

$$\frac{1}{15} |S_2 - S_1| < \epsilon$$

will guarantee that I is correct to within ϵ .

Therefore, we will take $S_2 + \frac{1}{15}(S_2 - S_1)$ as the value of the integral on $[a, b]$ if the above criterion is met, and otherwise we will split the interval $[a, b]$ into intervals $[a, c]$ and $[c, b]$, applying the same procedure to each subinterval. In order to keep our total error within ϵ , we clearly must require that the errors on $[a, c]$ and $[c, b]$ are within $\epsilon/2$. The procedure should remind the reader of Romberg integration, in the sense that $S_2 + \frac{1}{15}(S_2 - S_1)$ is the result obtained by applying the extrapolation process to Simpson's rule once.

In practice, we will handle this with a recursive function. The algorithm is presented in pseudocode in the next section.

3 Adaptive Simpson Quadrature—Algorithm

For the description of the adaptive Simpson quadrature algorithm, we take for granted Simpson's rule for a single interval.

Data: a function F , an interval $[A, B]$ on which to integrate, a tolerance ϵ

Result: an approximation for the integral of f on $[a, b]$

Set W equal to $\text{Simpsons}(F, A, B)$;

Set C equal to $(A+B)/2$;

Set L equal to $\text{Simpsons}(F, A, C)$;

Set R equal to $\text{Simpsons}(F, C, B)$;

if $|L + R - W| \leq 15\epsilon$ **then**

 Return $L + R + (L + R - W)/15$;

else

 Return $\text{AdaptiveSimpsons}(F, A, C, \epsilon/2) + \text{AdaptiveSimpsons}(F, C, B, \epsilon/2)$;

end

Algorithm 1: Adaptive Simpson Quadrature

(See [2] for more details.)

4 Data—Figures

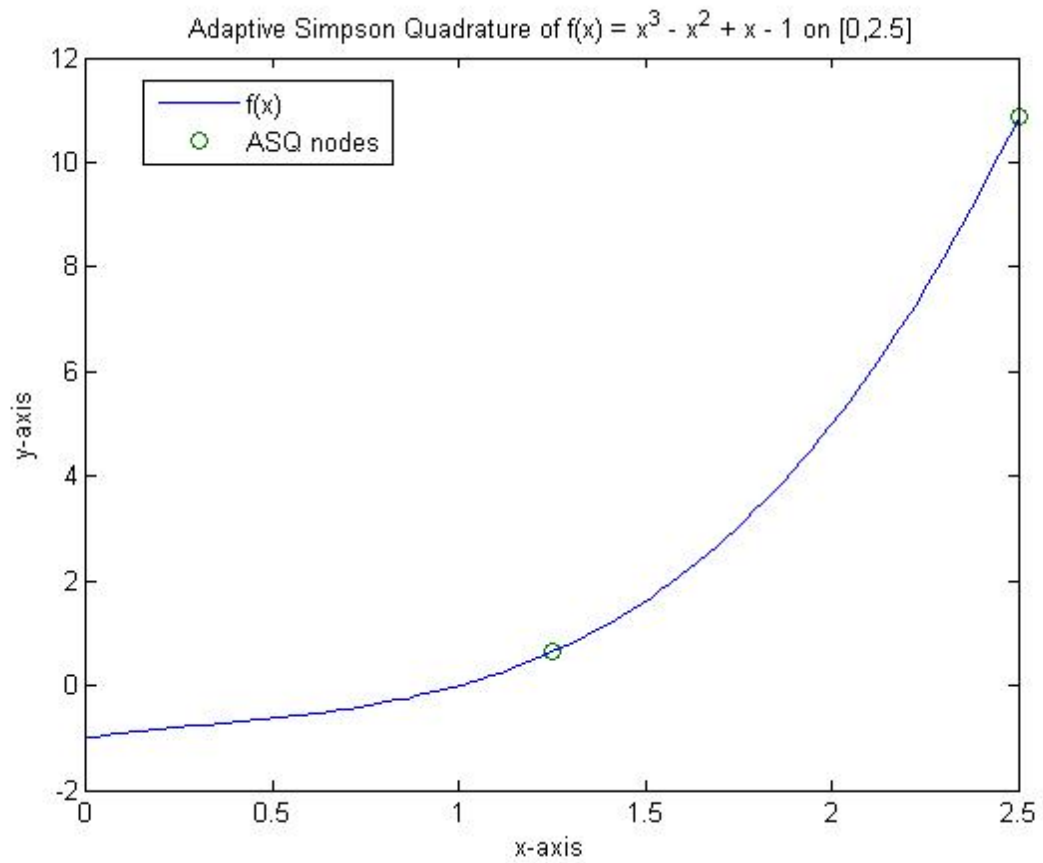


Figure 1: ASQ applied to a cubic function. Simpson's rule obtains an exact value for this integral, so the adaptive rule does not have to subdivide the interval at all.

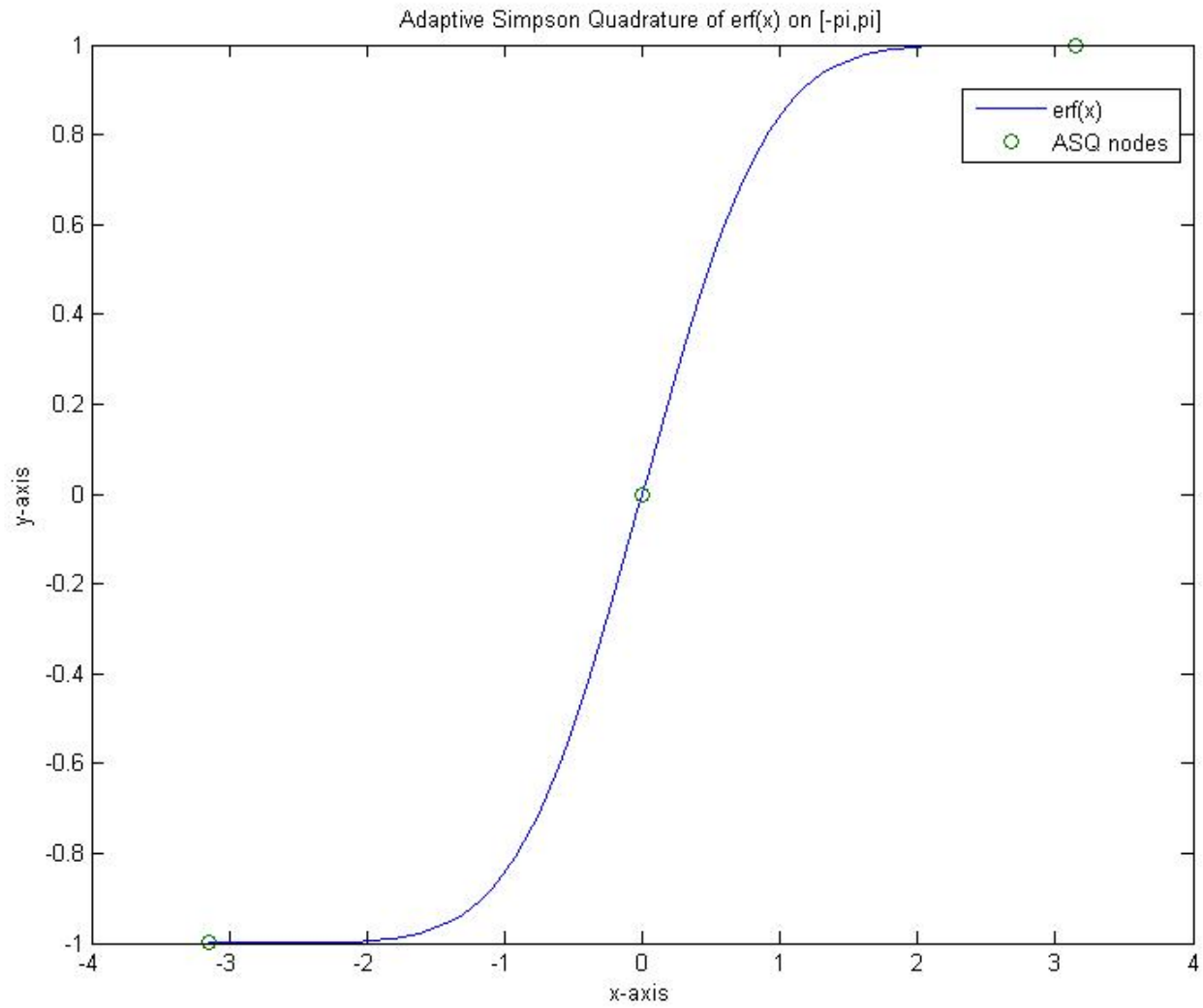


Figure 2: ASQ applied to the error function on a symmetric interval. As a consequence of the symmetry of this function about zero, the adaptive scheme finds the value of the integral—zero—without subdivision.

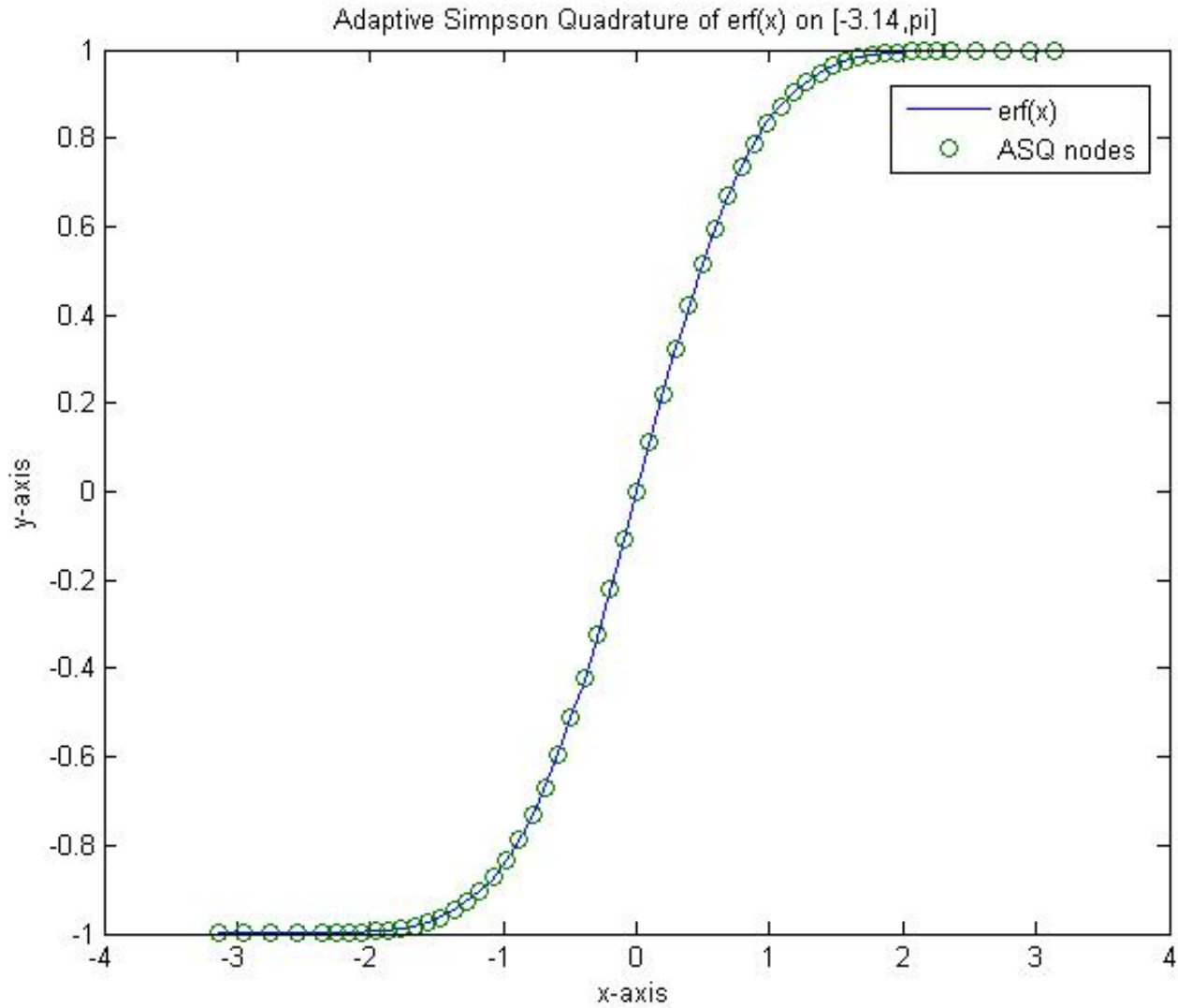


Figure 3: ASQ applied to the error function on an asymmetric interval. By shifting the values of the endpoints slightly we break the symmetry, and now ASQ needs many subdivisions to find a satisfactory approximation. Perhaps surprisingly, slightly more intervals are needed where the values of the function change the least. See the next section for the results of CSQ on this function.

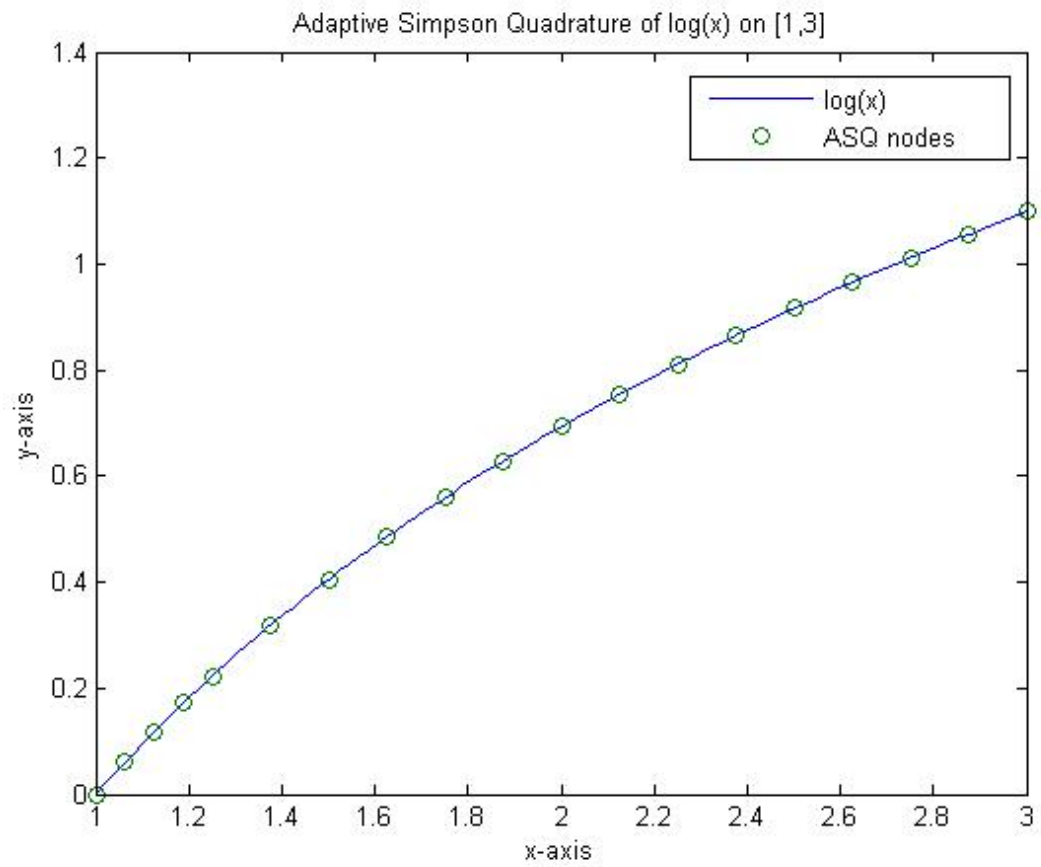


Figure 4: ASQ applied to the natural logarithm. For particularly well-behaved integrals, the intervals found by ASQ end up being evenly-spaced or close to it.

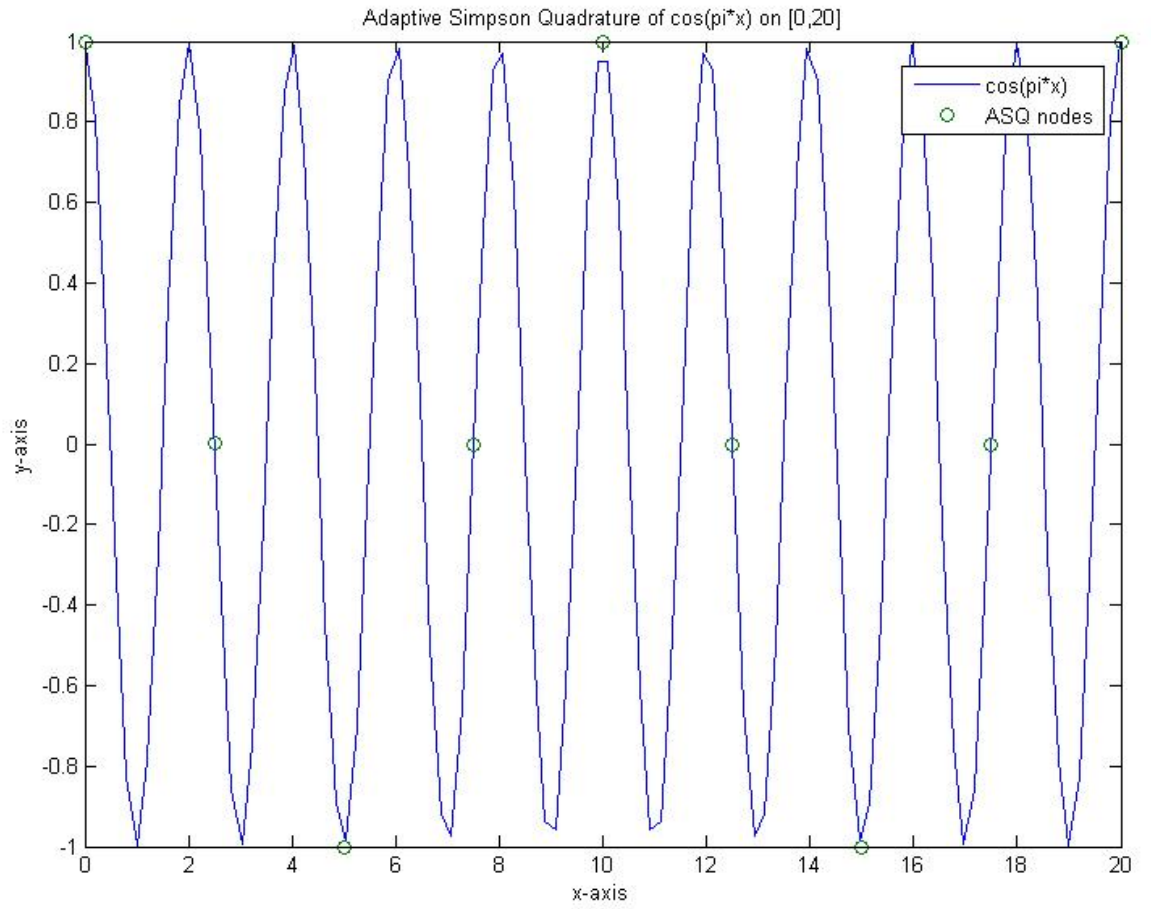


Figure 5: ASQ applied to $\cos(\pi x)$. Ultimately, ASQ finds evenly-spaced intervals. However, one easily sees why evenly-spaced intervals chosen *a priori* could become a problem when numerically integrating a periodic function. Compare this figure to the next.

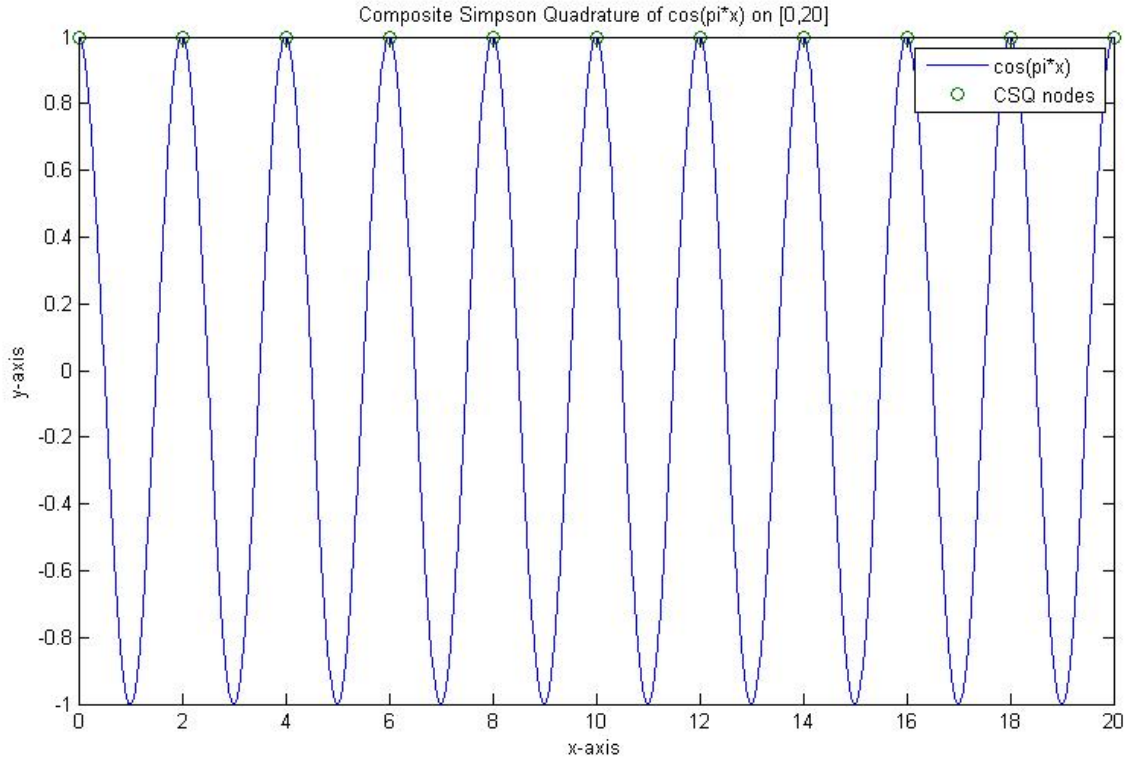


Figure 6: CSQ applied to $\cos(\pi x)$. By carelessly selecting evenly-spaced intervals for composite Simpson quadrature, we accidentally chose the crest of every wave as the sampling point! Refer to Tables 1 and 2 for numerical data on this integral.

5 Data—Tables

| f | I | Simpson | Adaptive Simpson |
|---------------|---------------|----------------|-------------------------|
| cubic | [0:2.5] | 2.6855662247 | 5.1822916667 |
| erf | $[-\pi:\pi]$ | -0.6961222732 | 0.0000000000 |
| erf | $[-3.14:\pi]$ | -0.6943581282 | 0.0015926394 |
| log | [1:3] | 1.0601181852 | 1.2958368650 |
| $\cos(\pi*x)$ | [1:3] | -2.0489218097 | 0 |

Table 1: Integrals computed by composite Simpson’s rule (20 intervals) are compared with those computed by adaptive Simpson’s rule.

| N | CSQ(N) |
|----|----------------|
| 2 | 0.00000000000 |
| 3 | 20.00000000000 |
| 4 | -3.33333333333 |
| 5 | -6.66666666667 |
| 6 | 16.00000000000 |
| 7 | -0.00000000000 |
| 8 | -1.04669631628 |
| 9 | -0.00000000000 |
| 10 | -2.04892180972 |
| 11 | 20.00000000000 |
| 12 | -1.72197183808 |
| 13 | -0.00000000000 |
| 14 | -1.08745470782 |
| 15 | -0.00000000000 |
| 16 | -0.66666666667 |
| 17 | 0.00000000000 |
| 18 | -0.45089524089 |
| 19 | -0.00000000000 |
| 20 | -0.35566270056 |
| 21 | -6.66666666667 |
| 22 | -0.32100608691 |
| 23 | 0.00000000000 |
| 24 | -0.31385179667 |
| 25 | -0.00000000000 |

Table 2: Results from composite Simpson quadrature applied to $\cos(\pi x)$ on $[0, 20]$. The number of intervals, N , ranges from 2 to 25, demonstrating the high errors that can result from applying CSQ to a periodic function.

6 Explanation of Data and Conclusions

The cubic function demonstrates clearly that the adaptive method agrees with the composite method for a polynomial of sufficiently small degree—of course, the value found by Simpson’s rule is actually the exact value of the integral. The error function reveals some of the behavior of the adaptive versus the naïve scheme. On the symmetric interval, the integral is 0 and adaptive Simpson’s finds the same exact value as composite Simpson’s without extra subdivisions. On the asymmetric interval, adaptive Simpson’s needs extra subdivisions to compute the integral correctly, and the value found is not exactly zero but in fact closer to the minimum floating point allowed by the running architecture.

Figures 5 and 6 and Table 2 further demonstrate the usefulness of adaptive quadrature. Given a periodic function, such as $f(x) = \cos(\pi x)$, manually choosing subdivision nodes

for composite Simpson's rule requires careful attention to the location of the waveform's crests and troughs so as not to wildly over- or underestimate the integral, and attempting to find the integral as the limit of composite Simpson's rule as the number of intervals goes up can be a very slowly-converging process. For a function represented as a Fourier or generalized Fourier sequence, this can mean that a very large number of intervals are required to make composite Simpson's rule acceptable.

7 References

1. Calvetti, D.; Golub, G. H.; Gragg, W. B. and Reichel, L. "Computation of Gauss-Kronrod Quadrature Rules." Math. Comput. 69, 1035-1052, 2000.
2. <http://www.mathworks.com/moler/quad.pdf>
3. Cheney, W.; Kincaid, D. Numerical Mathematics and Computing, 7th Edition.