

## KEIRAN CANTILINA

\*\*\* PERSONAL PROJECT PORTFOLIO: <https://keirancantilina.github.io> \*\*\*

<b>PERSONAL STATEMENT</b>	My interests focus on solving problems by drawing on interdisciplinary knowledge and resources. I have a demonstrated history of using this knowledge to very quickly pick up complex electromechanical systems and new programming languages on the fly. I love to use quantitative methods to gain insight especially in contexts where biology, engineering and programming intersect. I have 5 years of experience contributing to a wide variety of bioengineering research.	
<b>EDUCATION</b>	<b>MS in Bioproducts and Biosystems Engineering</b> , University of Minnesota, June 2018 <b>BS in Biological Sciences</b> , Cornell University, May 2015	
<b>RELEVANT EXPERIENCE</b>	<b>Senior Research Engineer – Cleveland Clinic Automated Surgical Robotics Lab</b> Aug 2019 – <ul style="list-style-type: none"><li>Developed algorithms for real-time motion and force control of multi-robot surgical platforms</li><li>Wrote code to handle kinematics of 7-DOF redundant robotic arms to enable execution of secondary tasks (collision, singularity, and joint limit avoidance)</li><li>Wrote LabVIEW, C++, Python, and Java drivers for control of hardware (sensors and robots)</li><li>Wrote high-speed multithreaded UDP and TCP server/clients in Python, LabVIEW, C++, and Java for a coordinated multi-robot multi-sensor system</li><li>Upgraded vision system of extant surgical robot by sourcing new cameras, designing a mechanical adaptor for optics, and writing Python drivers to stream video feed to a VR headset</li><li>Designed and fast-prototyped novel robotic end-effectors</li><li>Implemented real time object recognition, localization, and depth-mapping using neural networks with OpenCV in Python</li><li>Implemented camera calibration and distortion correction with OpenCV in Python</li><li>Designed and executed experiments to quantify susceptibility of competing magnetic motion tracking systems to interference/field distortion from metallic objects</li><li>Invented a method for identifying non-purposeful movements in a recording of teleoperated surgical robotic movements</li></ul> <b>Instrumentation Engineering Grad Research Asst. - U of MN</b> Aug 2016 – May 2018 <ul style="list-style-type: none"><li>Tested and characterized prototype water quality sensors and other devices using test equipment</li><li>Invented novel water conductivity sensors for Master's thesis</li><li>Wrote scripts to do statistical analysis of large datasets</li><li>Wrote data mining scripts to fetch data from geostationary climate satellite systems</li><li>Managed project timelines and personnel (Gantt charts, project management software, etc.)</li><li>Reverse-engineered communication protocol and built replacement for proprietary water sampler programming cable</li><li>Upgraded sampler power supply circuits to be more robust and resistant to user error</li><li>Programmed, inspected, and repaired ISCO autonomous water samplers</li><li>Wrote image processing pipeline to automatically determine microplastic concentration in effluent from degraded artificial floating treatment wetlands</li></ul> <b>Bioengineering Laboratory Service Tech - Cornell University</b> May 2015 – Jun 2016 <ul style="list-style-type: none"><li>Instrument software/hardware design and troubleshooting</li><li>Experimental design consulting</li><li>Creation of data processing scripts and programs</li><li>Used ImageJ to develop automated colony counting image processing script</li><li>Provided laboratory members with full-time multidisciplinary support</li><li>Managed projects in coordination with other departments and lab groups</li></ul> <b>Plant Genetics Research Assistant – Nat'l Chung Hsing University, Taiwan</b> May – Aug 2014 <ul style="list-style-type: none"><li>Planned and initiated a cloning project aimed to develop a viral cross-protection vector for Vietnam-strain Papaya ringspot virus (PRSV)</li><li>Became familiar with cross-cultural research contexts</li></ul>	

**Plant Bioinformatics Summer Intern – NYS Agricultural Research Station** May – Aug 2013

- Planned and contributed to cloning projects related to the improvement of Grapevine fanleaf virus (GFLV) as a virus induced gene silencing (VIGS) vector
- Gained proficiency in confocal laser microscopy
- Became familiar with UV photography

**Plant Pathology Research Assistant – NYS Agricultural Research Station** May – Aug 2012

- Learned sequence analysis, primer design, and phylogenetic analysis
- Ran mid-scale IC-RT-PCR and electrophoresis reactions, screening projects, and cloning projects
- Learned laboratory greenhouse skills such as planting, transplanting, inoculating, seed collecting, and sample collecting
- Created and presented poster to share research results with research station faculty

**PAPERS**

- BAEF Research Thesis: Use of additive manufacturing methods for carillon “autospeelwerk” mechanisms. *Koninklijke Beiaardschool 'Jef Denyn' Bibliotheek*, (2019)
- Absence of genetic selection in a pathogenic *Escherichia coli* strain exposed to the manure-amended soil environment. *PLOS ONE*, (2018).
- Master's Thesis: The Development of a Novel Capacitive Water Conductivity Sensor. *University of Minnesota Digital Conservancy*, (2018).
- Genetic variability, evolution, and biological effects of grapevine fanleaf virus satellite RNAs. *Phytopathology*, (2013).

**RELEVANT SKILLS**

**Electronics/Mechanical**

- 2D and 3D CAD (AutoCAD, Onshape/Solidworks, Inventor)
- Parametric CAD techniques
- Finite Element Analysis
- Electronics design, reverse engineering, troubleshooting
- PCB design and assembly (soldering, choosing components, etc.)
- HF and VHF RF circuit and antenna design
- Mechanical design for fast prototyping (3D printing, laser cutting, or waterjet)
- Mechanical design for traditional machining
- Use of test equipment
- Use of power tools and standard shop equipment
- Basic woodworking and welding

**Programming/Data Analysis**

- Languages: R, C++, Python, Java, LabVIEW, MATLAB, bash, ROS
- Proficient in multithreading
- TCP/UDP clients & servers
- Design and implementation of software-hardware interfaces
- Optimization of code for embedded hardware
- Optimization of code for fast execution
- Robotic control and motion planning
- OpenCV machine vision and neural networks
- Image processing and camera distortion calibration
- Design of Experiments (DOE)
- Data mining/web scraping
- Statistical analysis of large datasets
- Test method development
- Data visualization

**Bio/Wet Lab**

- Conventional genetic engineering/cloning
- Plant, bacterial, viral and soil DNA and RNA extraction
- PCR, electrophoresis, ligation, primer & expression cassette design
- Plant and bacterial transformation
- Analysis of sequencing data
- Brightfield, darkfield, dissecting, confocal, and laser scanning microscopy
- Standard microbio skills (cell culture, pipetting, etc.)
- Biosafety Level 2 training
- Sterile technique, etc.
- Greenhouse plant care

**HONORS & AWARDS**

**Belgian American Education Foundation Fellowship**

July 2018 – June 2019

Thesis: “Use of additive manufacturing methods for carillon “autospeelwerk” mechanisms.” Yearlong fellowship to study Belgium’s UNESCO-protected carillon culture at the Belgian Royal Carillon School.

**Fulbright U.S. Student Researcher Grant**

May 2018

Award declined in order to accept the BAEF Research Fellowship

**Diversity of Views and Experiences Fellowship**

Aug 2016 – July 2017

Two-semester fellowship including tuition and stipend

**2015 Plant Biology Student Excellence Award**

May 2015

Awarded by faculty of Cornell University Department of Plant Sciences

## LICENSES

### **Guild of Carilloneurs in North America**

Professional Carillonneur License (valid in North America)

June 2019

### **Mechelen Beiaardschool Eindedioma**

Professional Carillonneur License (valid in Europe)

May 2019

### **US FCC Amateur Radio License**

General Class Privileges, callsign KD2KQE

March 2016

## REFERENCES

Dr. Robb Colbrunn

Director, BioRobotics Core, Biomedical Engineering Department

Cleveland Clinic, Lerner Research Institute

ND-20, 2111 E 96th St, Cleveland, OH 44106

(216) 385-5914

[colbrur@ccf.org](mailto:colbrur@ccf.org)

Dane Kouttron

Staff Research Engineer, Plasma Science and Fusion Center

Massachusetts Institute of Technology

167 Albany St, Cambridge, MA 02139

(631) 978-1650

[kouttron@mit.edu](mailto:kouttron@mit.edu)

Dr. M. Todd Walter

Professor of Ecohydrology, Department of Biological and Environmental Engineering

Cornell University

Riley-Robb Hall, Cornell University, Ithaca, NY 14850

(607) 255-2488

[mtw5@cornell.edu](mailto:mtw5@cornell.edu)

Dr. Peter Marchetto

Assistant Professor, Department of Bioproducts and Biosystems Engineering

University of Minnesota- Twin Cities

218 BioAgEng Building, 1390 Eckles Ave, St. Paul, MN 55208

(201) 403-5470

[pmarchet@umn.edu](mailto:pmarchet@umn.edu)

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