# Functional Analysis

Chapter 1. Seminorms

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• function (mapping, transformation, operator, functional)

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- function (mapping, transformation, operator, functional)
- $\bullet \ (\mathbb{R}, |\cdot|) \longrightarrow (X, \|\cdot\|)$



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- function (mapping, transformation, operator, functional)
- $\bullet$   $(\mathbb{R}, |\cdot|) \longrightarrow (X, ||\cdot||)$
- generalized function (applications in pdes, etc)



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set theory



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- set theory
- linear algebra

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- set theory
- linear algebra
- basic topology

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### Seminorms

#### Definition

A real-valued function  $p(\boldsymbol{x})$  defined on a linear space X is called a seminorm iff

- (1)  $p(x + y) \leq p(x) + p(y)$ ;
- (2)  $p(\alpha x) = |\alpha| p(x)$ .



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### Seminorms

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- (1)  $p(x + y) \leq p(x) + p(y)$ ;
- (2)  $p(\alpha x) = |\alpha| p(x)$ .
- (3) p(0) = 0;
- (4)  $p(x_1 x_2) \ge |p(x_1) p(x_2)|$ . In particular,  $p(x) \ge 0$ .



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About  $M = \{x \in X : p(x) \leqslant \varepsilon, \ \varepsilon > 0\}$ 

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## About $M = \{x \in X : p(x) \le \varepsilon, \ \varepsilon > 0\}$

#### Theorem

M is a convex, balanced and absorbing subset of X with  $0 \in M$ .



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The functional

$$p_M(x) = \inf_{\alpha > 0, \alpha^{-1} x \in M} \alpha$$

is called the Minkowski functional of M.



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#### Theorem

 $p_M(x)$  is a seminorm.



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Let's consider a family of seminorms

$$\{p_{\gamma}(x):\gamma\in\Gamma\}$$

satisfies

### Axiom of separation

$$\forall x_0 \neq 0 \exists \gamma_0 \in \Gamma(p_{\gamma_0}(x) \neq 0).$$

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### Axiom of separation

$$\forall x_0 \neq 0 \exists \gamma_0 \in \Gamma(p_{\gamma_0}(x) \neq 0).$$

#### Hausdorff's axiom

 $\forall x_1 \neq x_2 \exists$  disjoint open sets  $G_1, G_2(x_1 \in G_1, x_2 \in G_2)$ .

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1 Define the 0-neighborhoods

$$U_0 = \{x \in X : p_{\gamma_j}(x) \leqslant \varepsilon_j\}, \quad j = 1, 2, \dots, n$$

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and the  $x_0$ -neighborhoods

$$U_{x_0} = x_0 + U.$$

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② Consider  $G \subset X$ , which contains a neighborhood of each of its points, then totality  $\{G\}$  is a open set system.

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#### Theorem

 $\textit{linear space } X \xleftarrow{\textit{Minkowski functional}} \textit{locally convex, linear topological space } X$ 

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• The support of  $f: \Omega \to \mathbb{C}$ , denoted by  $\operatorname{supp}(f)$ , is the smallest closed set containing the set

$$\{x \in \Omega : f(x) \neq 0\},\$$

where  $\Omega \subset \mathbb{R}^n$ .



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•  $C^k(\Omega)$  and  $C_0^k(\Omega)$ .



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where  $\Omega \subset \mathbb{R}^n$ .

- ullet  $C^k(\Omega)$  and  $C^k_0(\Omega)$ .
- Differential operator

$$D^{s} = \frac{\partial^{s_1 + \dots + s_n}}{\partial^{s_1} x_1 \cdots \partial^{s_n} x_n}, \quad |s| = s_1 + \dots + s_n.$$

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## Application: a theorem of approximation

#### Theorem

Any  $f \in C_0^0(\mathbb{R}^n)$  can be approximated by functions of  $C_0^\infty(\mathbb{R}^n)$  uniformly on  $\mathbb{R}^n$ .

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For any compact  $K \subset \Omega$  and  $m \leqslant k$ , define seminorms

$$p_{K,m}(f) = \sup_{|s| \leqslant m, x \in K} |D^s f(x)|, \quad f \in C^k(\Omega).$$

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#### Theorem

 $\mathfrak{C}^k(\Omega)$  is a metric space.

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#### Theorem

 $\mathfrak{C}^k(\Omega)$  is a metric space.

$$\mathfrak{C}^{\infty} = \mathfrak{C}$$
.

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The space  $\mathfrak{D}_{\mathit{K}}(\Omega)$  and  $\mathfrak{D}(\Omega)$ 

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# The space $\mathfrak{D}_K(\Omega)$ and $\mathfrak{D}(\Omega)$

For any compact  $K \subset \Omega$ , let  $\mathfrak{D}_K(\Omega)$  be the class of all functions  $f \in C_0^{\infty}(\Omega)$  such that  $\operatorname{supp}(f) \subset K$ . Define seminorms by

$$p_{K,m}(f) = \sup_{|s| \leqslant m, x \in K} |D^s f(x)|.$$

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$$p_{K,m}(f) = \sup_{|s| \leqslant m, x \in K} |D^s f(x)|.$$

Let  $\mathfrak D$  denote the set of all  $f \in C_0^\infty(\Omega)$  with compact supports.



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# Topology on $\mathfrak{D}(\Omega)$

Let's define a topology on  $\mathfrak{D}$ , such that it works the same way with the family of topologies on  $\mathfrak{D}_K$ .

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# Topology on $\mathfrak{D}(\Omega)$

Let's define a topology on  $\mathfrak{D}$ , such that it works the same way with the family of topologies on  $\mathfrak{D}_K$ .

#### **Theorem**

D is a complete topological space.

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# Topology on $\mathfrak{D}(\Omega)$

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#### Theorem

 $\mathfrak D$  is a complete topological space.

#### Theorem

 $\mathfrak D$  is the "strict inductive limit" of  $\mathfrak D_K$ , i.e., each convex subset of  $\mathfrak D$  to be a 0-neighborhood iff its intersection with each  $\mathfrak D_K$  constructs a 0-neighborhood under the topology of  $\mathfrak D_K$ .

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## Normed linear space

#### Definition

A locally convex space is called a normed linear space iff its topology is defined by just one seminorm.

$$p(\cdot) = \|\cdot\|$$



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# Normed linear space

#### **Definition**

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$$p(\cdot) = \|\cdot\|$$

#### Theorem

- (1)  $(x_n \to x) \Rightarrow (||x_n|| \to ||x||);$
- (2)  $(x_n \to x, \alpha_n \to \alpha) \Rightarrow (\alpha_n x_n \to \alpha x);$
- (3)  $(x_n \to x, y_n \to y) \Rightarrow (x_n + y_n \to x + y)$ .



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### Example

$$C(S)$$
 with  $||x|| = \sup_{s \in S} |x(s)|$ .

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## Example

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 with  $||x|| = \sup_{s \in S} |x(s)|$ .

#### Example

$$L^p(S,\mathfrak{B},m)$$
 with  $||x|| = \left(\int_S |x(s)|^p m(ds)\right)^{1/p}$ .

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$$L^{\infty}(S)$$
 with  $||x|| = \operatorname{ess.sup}_{s \in S} |x(s)|$ .

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#### Example

$$L^{\infty}(S) \text{ with } \|x\| = \mathrm{ess.} \sup_{s \in S} |x(s)|.$$

#### Theorem

$$\lim_{p \to \infty} \left( \int_{S} |x(s)|^{p} m(ds) \right)^{1/p} = \operatorname{ess. sup}_{s \in S} |x(s)|, \quad x(s) \in L^{\infty}(S).$$

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#### Example

 $(c_0), (c) \text{ with } ||x|| = \sup_n |x_n|.$ 

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## Example

 $(c_0), (c) \text{ with } ||x|| = \sup_n |x_n|.$ 

#### Example

 $(l^p)$  with  $||x|| = (\sum_n |x_n|^p)^{1/p}$ .

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## Example

 $(c_0), (c) \text{ with } ||x|| = \sup_n |x_n|.$ 

#### Example

$$(l^p)$$
 with  $||x|| = (\sum_n |x_n|^p)^{1/p}$ .

#### Example

$$(l^{\infty}) = (m) \text{ with } ||x|| = \sup_n |x_n|.$$

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# Standard examples: space of measures

#### Example

$$A(S,\mathfrak{B})$$
 with  $\|\varphi\| = V(\varphi;S) = \sup_{\sup |x(s)| \le 1} |\int_S x(s)\varphi(ds)|$ .

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#### Quasinorms

#### Definition

A quasinorm is similar to a norm, just replace

$$\|\alpha x\| = |\alpha| \|x\|$$

by

$$||-x|| = ||x||, \quad \lim_{\alpha_n \to 0} ||\alpha_n x|| = 0, \quad \lim_{||x_n|| \to 0} ||\alpha x_n|| = 0.$$

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## Quasinorms

#### Theorem

In a quasinormed linear space X we also have

(1) 
$$(x_n \to x) \Rightarrow (||x_n|| \to ||x||);$$

(2) 
$$(x_n \to x, \alpha_n \to \alpha) \Rightarrow (\alpha_n x_n \to \alpha x);$$

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(3) 
$$(x_n \to x, y_n \to y) \Rightarrow (x_n + y_n \to x + y).$$

In other words,

$$\left(\lim_{n\to\infty} \|x_n\| = 0\right) \Rightarrow \left(\lim_{n\to\infty} \|\alpha x_n\| = 0\right)$$

uniformly in  $\alpha$  on any bounded set of  $\alpha$ .



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# Example

 $\mathfrak{C}^k(\Omega)$ .

#### Example

 $\mathfrak{C}^k(\Omega)$ .

#### Example

 $M(S, \mathfrak{B}, m)$  with  $||x|| = \int_{S} |x(s)|(1 + |x(s)|)^{-1} m(ds)$ .

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#### Example

 $\mathfrak{C}^k(\Omega)$ .

#### Example

 $M(S, \mathfrak{B}, m)$  with  $||x|| = \int_{S} |x(s)|(1 + |x(s)|)^{-1} m(ds)$ .

#### Example

 $\mathfrak{D}_K(\Omega)$ .

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#### Definition

A linear space X is called a pre-Hilbert space iff its norm satisfies

$$||x + y||^2 + ||x - y||^2 = 2(||x||^2 + ||y||^2).$$

We define, for X over  $\mathbb{R}$ , the inner product

$$(x, y) = 4^{-1}(\|x + y\|^2 - \|x - y\|^2)$$

and

$$(x, y)_{\mathbb{C}} = (x, y) + i(x, iy)$$

for X over  $\mathbb{C}$ .

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# Simple examples

### Example

 $L^2(S,\mathfrak{B},m)$ .

#### Example

 $(l^2).$ 

Spaces  $\hat{H}^k(\Omega)$  and  $\hat{H}^k_0(\Omega)$ 

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# Spaces $\hat{H}^k(\Omega)$ and $\hat{H}^k_0(\Omega)$

Let  $\Omega \subset \mathbb{R}^n$  is open and  $k \in \mathbb{N}$ . Then  $f \in C^k(\Omega)$  for which

$$||f||_k = \left(\sum_{|j| \le k} \int_{\Omega} |D^j f(x)|^2 dx\right)^{1/2} < \infty$$

constitutes a pre-Hilbert space  $\hat{H}^k(\Omega)$ .

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# Spaces $\hat{H}^k(\Omega)$ and $\hat{H}^k_0(\Omega)$

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constitutes a pre-Hilbert space  $\hat{H}^k(\Omega)$ . Replace  $C^k$  by  $C_0^k$  we get space  $\hat{H}_0^k(\Omega)$ .

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# Space $A^2(G)$

Let G be a bounded open domain of the complex z-plane. Let  $A^2(G)$  be the set of all holomorphic functions f(z) defined on G such that

$$||f|| = \left( \int_G |f(z)|^2 dx dy \right)^{1/2} < \infty, \quad z = x + iy.$$

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# Hardy-Lebesgue class H- $L^2$

That is the set of all f(z) which are holomorphic in the unit disk  $\{z:|z|\leqslant 1\}$  of the complex z-plane and such that

$$\sup_{r \in (0,1)} \left( \int_0^{2\pi} |f(re^{i\theta})|^2 d\theta \right) < \infty.$$

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# Hardy-Lebesgue class H- $L^2$

That is the set of all f(z) which are holomorphic in the unit disk  $\{z:|z|\leqslant 1\}$  of the complex z-plane and such that

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#### Theorem

The Hardy-Lebesgue class is in 1-1 correspondence with the pre-Hilbert space  $(\mathit{l}^{2})$  as

$$f(z) = \sum_{n=0}^{\infty} c_n z^n.$$

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# B-spaces and F-spaces

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## B-spaces and F-spaces

#### **Definition**

A quasinormed (or normed) linear space X is called an F-space (or B-space) if it is complete, i.e., if every Cauchy sequence  $\{x_n\} \subset X$  converges strongly to a point  $x_\infty \in X$ :

$$\lim_{n\to\infty} \|x_n - x_\infty\| = 0.$$

A complete pre-Hilbert space is called a Hilbert space.

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## Example

 $\mathfrak{C}(\Omega)$  is an F-space.

## Example

 $\mathfrak{C}(\Omega)$  is an F-space.

### Example

 $L^p(S)$  is a B-space.

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## Example

 $\mathfrak{C}(\Omega)$  is an F-space.

#### Example

 $L^p(S)$  is a B-space.

## Example

 $A^2(G)$  is a *B*-space.

### Example

 $\mathfrak{C}(\Omega)$  is an F-space.

#### Example

 $L^p(S)$  is a B-space.

#### Example

 $A^2(G)$  is a B-space.

#### Example

 $M(S, \mathfrak{B}, m)$  with  $m(B) < \infty$  is an F-space.

### Next TODO:

#### Next TODO:

ullet Sobolev spaces  $\mathit{W}^{k,p}$  ( $\mathit{B} ext{-space}$ )



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#### Next TODO:

- Sobolev spaces  $W^{k,p}$  (B-space)
- Generalized functions



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