

**CARDIFF UNIVERSITY
EXAMINATION PAPER**

Academic Year: 2007/2008
Examination Period: Autumn
Examination Paper Number: CM0340SOLNS
Examination Paper Title: Multimedia
SOLUTIONS
Duration: 2 hours

Do not turn this page over until instructed to do so by the Senior Invigilator.

Structure of Examination Paper:

There are 13 pages.

There are 4 questions in total.

There are no appendices.

The maximum mark for the examination paper is 80 and the mark obtainable for a question or part of a question is shown in brackets alongside the question.

Students to be provided with:

The following items of stationery are to be provided:

ONE answer book.

Instructions to Students:

Answer 3 questions.

The use of translation dictionaries between English or Welsh and a foreign language bearing an appropriate departmental stamp is permitted in this examination.

Q1. (a) *Why is data compression desirable for multimedia activities?*

Data is high resolution in both temporal and/or spatial domains. [1]

Storage, bandwidth and processing limitations need compressed data. [1]

2 Marks total — BOOKWORK

(b) *What is the distinction between lossy and lossless data compression?*

Lossless Compression – Where data is compressed and can be reconstituted (uncompressed) without loss of detail or information. These are referred to as bit-preserving or reversible compression systems also. [1]

Lossy Compression – Where the aim is to obtain the best possible fidelity for a given bit-rate or minimizing the bit-rate to achieve a given fidelity measure. Video and audio compression techniques are most suited to this form of compression. [1]

2 Marks total — BOOKWORK

(c) *What are the main differences between the target media for JPEG and GIF compression?*

JPEG — 24 bit full/true colour imagery, typically photographic in nature. [1]

GIF — 8-bit colour imagery, suits graphics type images better. [1]

2 Marks total — BOOKWORK

(d) *What improvement did the LZW algorithm make on previous LZ versions?*

LZW introduced the idea that only the initial dictionary needs to be transmitted to enable **decoding**. [1]

The decoder is able to build the rest of the table from the encoded sequence. [1]

2 Marks total — BOOKWORK

- (e) *Describe the LZW algorithm for encoding an input sequence, giving suitable pseudocode.*

The LZW Compression Algorithm can summarised as follows:

```
w = NIL;
while ( read a character k )
{
    if wk exists in the dictionary
        w = wk;
    else
        { add wk to the dictionary;
          output the code for w;
          w = k;
        }
}
```

[6]

May have a prior dictionary

- Original LZW used dictionary with 4K entries, first 256 (0-255) are ASCII codes.
- GIF builds dictionary of “image blocks” no priors.

[1]

6 Marks for algorithm

1 Mark for dictionary build

7 Marks total — BOOKWORK

(f) Given an initial dictionary:

<i>Index</i>	<i>Entry</i>
1	a
2	b
3	h
4	i
5	s
6	t

and output of an LZW encoder:

6 3 4 5 1 3 1 6 2 9 11 16

decode the above sequence (which is not intended to represent meaningful English)

The LZW Decompression Algorithm is as follows:

```

read a character k;
output k;
w = k;
while ( read a character k )
/* k could be a character or a code. */
{
    entry = dictionary entry for k;
    output entry;
    add w + entry[0] to dictionary;
    w = entry;
}

```

Process as follows:

- Read 6 from input, lookup 6 so output *t*. Set $w = t$
- Read 3 from input, lookup 3 so output *h*. Add entry 7 to dictionary *th*. Set $w = h$
- Read 4 from input, lookup 4 so output *i*. Add entry 8 to dictionary *hi*. Set $w = i$
- Read 5 from input, lookup 5 so output *s*. Add entry 8 to dictionary *is*. Set $w = s$
- Read 1 from input, lookup 1 so output *a*. Add entry 9 to dictionary *sa*. Set $w = a$
- Read 3 from input, lookup 3 so output *h*. Add entry 10 to dictionary *ah*. Set $w = h$
- Read 1 from input, lookup 1 so output *a*. Add entry 11 to dictionary *ha*. Set $w = a$
- Read 6 from input, lookup 6 so output *t*. Add entry 12 to dictionary *at*. Set $w = t$
- Read 2 from input, lookup 2 so output *b*. Add entry 13 to dictionary *tb*. Set $w = b$
- Read 9 from input, lookup 9 so output *sa*. Add entry 14 to dictionary *bs*. Set $w = sa$

- Read 11 from input, lookup 11 so output *ha*. Add entry 15 to dictionary *sah*. Set $w = ha$
- Read 16 from input, lookup 16 so output *ha....* — We don't know full entry yet but we know it starts with current $w = ha....$ Add entry 16 to dictionary *hah*. **We now have entry 16** — this is the built in '*exception handler*' of LZW, so we can output 16 now. Set $w = hah$

Final Decode Table:

Index	Entry
1	<i>a</i>
2	<i>b</i>
3	<i>h</i>
4	<i>i</i>
5	<i>s</i>
6	<i>t</i>
7	<i>th</i>
8	<i>hi</i>
9	<i>sa</i>
10	<i>ah</i>
11	<i>ha</i>
12	<i>at</i>
13	<i>tb</i>
14	<i>bs</i>
15	<i>sah</i>
16	<i>hah</i>

Output decode sequence:

thisahatbsahahah

6 Marks for correct algorithm and applying it.

4 marks for showing table constructions and the correct decoded sequence

2 Marks for solving the LZW '*exception handler*' look ahead last step.

12 Marks total — UNSEEN

27 Marks Total Question 1

- Q2. (a) *In a digital signal processing system, what is meant by block and sample-by-sample processing.*
Give one example of an application of each type.

Block processing : data is transferred into a **memory buffer** and then processed each time the buffer is filled with new data. [1]

E.g. fast Fourier transforms (FFT), Discrete Cosine Transform (DCT), convolution, convolution reverb — **more soon** [1]

Sample-by-sample processing : input is processed on individual sample data. [1]

E.g. volume control, envelope shaping, modulation (ring/amplitude), IIR/-FIR filtering.... [1]

4 Marks Total — Bookwork

- (b) *In a digital signal processing system, what is meant by a linear and a non-linear time invariant system.*
Give one example of an application of each type.

Linear time invariant system (LTI) : Systems that **do not change** behaviour over time and satisfy the superposition theory. The output signal is signal changed in amplitude and phase. [1]

E.g. Convolution, Filters [1]

Non-linear time invariant system : Systems whose output is strongly shaped by non-linear processing that introduces harmonic distortion — *i.e.* harmonics that are not present in the original signal will be contained in the output. [1]

E.g. Limiters, Compressors, Exciters, Distortion, Enhancers. [1]

4 Marks Total — Bookwork

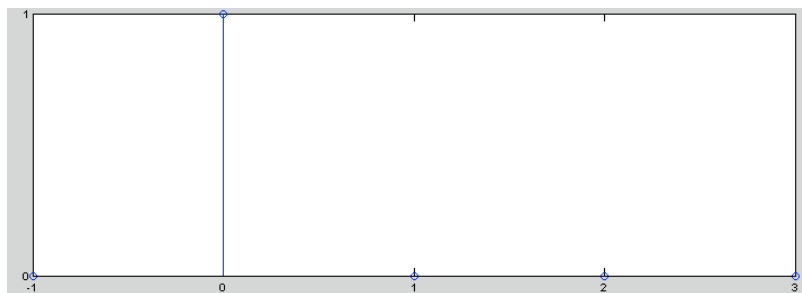
(c) Give the definition of an impulse response.

Give **two** practical uses of an impulse response in digital signal processing.

E.g. Unit Impulse:

- Defined as:

$$\delta(n) = \begin{cases} 1 & \text{if } n = 0 \\ 0 & \text{otherwise } (n \neq 0) \end{cases}$$



[2]

Two Uses:

- A test signal for digital systems, characterise system by their response functions. [1]
- Convolution Reverb — sample a rooms impulse response, convolve with input to get a reverberated output. [1]

4 Marks Total — Bookwork

(d) List the three basic components used in constructing a signal flow graph.

3 Components:

- Delay [1]
- Multiplication [1]
- Summation [1]

3 Marks Total — Bookwork

Why is it desirable to describe systems using these components.

- Componentisation of nearly all basic DSP filters, delays into standard processes. [1]
- Basic building blocks of nearly all basic DSP filters, delays description of algorithms simple. [1]
- These component make easy cost-effective construction of hardware implementations from standard components. [1]

3 Marks Total — Unseen/Assimilation of bookwork/discussed in tutorial

6 Marks Total For Question (d) Subpart

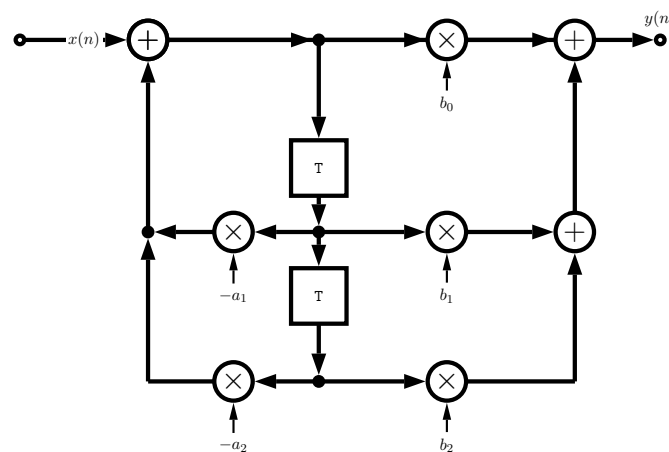
- (e) What is the **main** distinction between an infinite impulse response (IIR) and a finite impulse response (FIR) filter.

IIR filters have a **feedback loop** in their construction

1 Mark Bookwork

- (f) Given the following difference equation construct its *signal flow diagram*:

$$y(n) = b_0x(n) + b_1x(n-1) + b_2x(n-2) - a_1y(n-1) - a_2y(n-2)$$



[8]

8 Marks — Unseen.

Possible other less efficient solutions with more than two delay units (not shared for $y(n-1)/x(n-1) \dots$ tapping award less marks if so

27 Marks Total Question 2

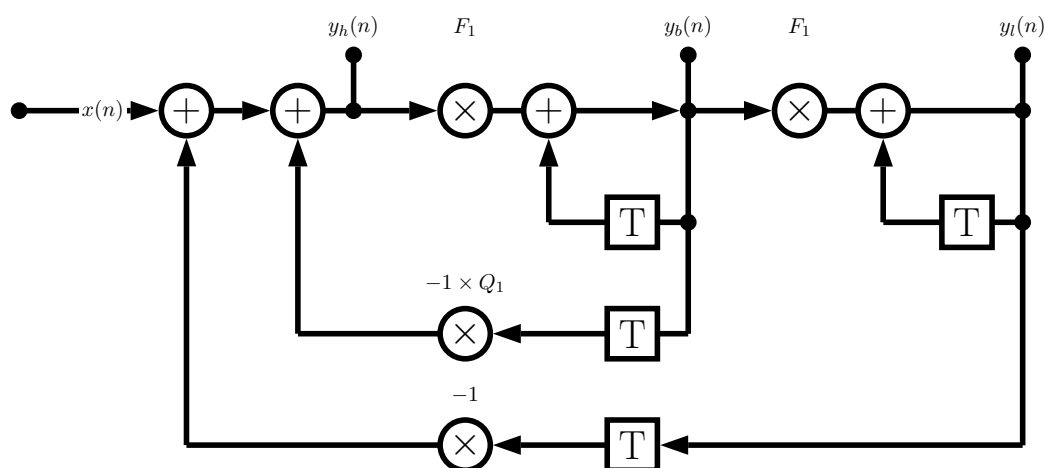
- Q3. (a) List **six** broad classes of digital audio effect. Give an example effect of **each** type of effect.

6 broad classes:

Basic Filtering — Lowpass, Highpass filter etc., Equaliser	[1]
Time Varying Filters — Wah-wah, Phaser	[1]
Delays — Vibrato, Flanger, Chorus, Echo	[1]
Modulators — Ring modulation, Tremolo, Vibrato	[1]
Non-linear Processing — Compression, Limiters, Distortion, Exciters/Enhancers	[1]
Spacial Effects — Panning, Reverb, Surround Sound	[1]

6 Marks — Bookwork

- (b) Give a description, including a signal flow diagram and algorithm, of the state variable filter.



where:

$$\begin{aligned}
 x(n) &= \text{input signal} \\
 y_l(n) &= \text{lowpass signal} \\
 y_b(n) &= \text{bandpass signal} \\
 y_h(n) &= \text{highpass signal}
 \end{aligned}$$

[4]

The state variable filter algorithm/difference equations are given by:

$$\begin{aligned}
 y_l(n) &= F_1 y_b(n) + y_l(n-1) \\
 y_b(n) &= F_1 y_h(n) + y_b(n-1) \\
 y_h(n) &= x(n) - y_l(n-1) - Q_1 y_b(n-1)
 \end{aligned}$$

[2]

with tuning coefficients F_1 and Q_1 related to the cut-off frequency, f_c , and damping, d :

$$F_1 = 2 \sin(\pi f_c / f_s), \quad \text{and} \quad Q_1 = 2d$$

[2]

8 Marks — Bookwork

(c) Give **two** advantages of the state variable filter.

The 2 advantages are:

- i. Independent control over the cut-off frequency and damping factor of a filter. [1]
- ii. Simultaneous lowpass, bandpass and highpass filter output. [1]

2 Marks — Bookwork

(d) A band-reject filter is a filter which passes all frequencies except those in a stop band centered on a center frequency. How can such a filter be implemented using **two** state variable filters?

- Create a low pass filter with cut-off frequency, f_{low} [1]
- Create a high pass filter with cut-off frequency, f_{high} [1]
- Add the outputs of the low and high pass filter. [1]
- Band reject is the range f_{low} — f_{high} , where $f_{low} < f_{high}$ [1]

4 Marks — UNSEEN.

Band-reject/bandstop filter defined in lecture but not implemented

(e) How may a phaser effect be implemented using **two** state variable filters?

- A **phaser** is implemented with a (set of) *time-varying* frequency *notch* filters. [2]
- *Notch* filter a very narrow *band-reject/bandstop* filter. [1]
- To get narrow band,:
 - set high Q factor — sharp slope on filter cut-off [1]
 - $f_{low} < f_{high}$, but f_{low} close in value to f_{high} (around some centre frequency) [1]
- Perform band-reject with above parameters, as in part (d) above **BUT** modulate the frequency range with a sine or triangular wave over a short range. [1]

- A *cascade* of such filters implements an multiple notch phases where each notch filter has a different centre frequency. [1]

7 Marks — UNSEEN.

Phaser defined in lecture but no implementation given — similar to wah-wah (notch filter instead of bandpass) implementation which was given in lecture. Notch filter defined in lecture as very narrow band-reject/bandstop filter

27 Marks Total Question 3

Q4. (a) Give a definition of a one-dimensional Fourier transform.

The Fourier transform of that function is denoted $F(u)$, where u represents spatial frequency is defined by

$$F(u) = \int_{-\infty}^{\infty} f(x)e^{-2\pi i x u} dx.$$

[2]

2 Marks - BOOKWORK

(b) Explain in detail how data is represented after the Fourier transform has been applied to a signal.

Essentially the Fourier transform decomposes an input signal into a series of sine waveforms with varying amplitude, frequency and phase. [2]

2 Marks - BOOKWORK

(c) Outline the basic approach to performing data *filtering* with the Fourier transform.

- Compute Fourier transform of signal. [1]
- Compute Fourier transform of Filter (if convolution) or create filter in frequency space (e.g. ideal low pass/butterworth filter). [1]
- Multiply (or divide if forward filter form used above) the two Fourier transforms above. [1]
- Inverse Fourier transform to get filtered data. [1]

4 Marks - BOOKWORK

(d) Describe **one** application of Fourier transform filtering methods in multimedia data compression.

Most obvious is MPEG AUDIO, (however one alternative answer might be in JPEG/MPEG video if Fourier Transform is replaced by a Discrete Cosine Transform which is a related method?)

MPEG audio compression basically works by:

- Dividing the audio signal up into a set of 32 frequency subbands — apply FOURIER FILTERING [2]
- Subbands approximate **critical bands of human hearing**. [1]
- Each band quantised according to the ‘*audibility*’ of *quantisation noise*. [1]

- Exploit Frequency Masking — near frequencies not heard in same time frame [2]
- Exploit Temporal Masking — near frequencies not heard close to some short time frame between frequencies [2]

8 Marks - (Distillation of) BOOKWORK

- (e) An exciter is a digital audio signal process that emphasises or de-emphasises certain frequencies in a signal in order to change its timbre. Describe how you could use the Fourier transform to implement such a process, giving a practical example and explaining how it works.

Approach similar to basic filtering except no frequency content removed. [2]
 In some cases similar to an equaliser (discussed in lectures) — but non-linear exaggeration of frequencies. [1]

Basic Approach:

- Compute Fourier transform of signal. [1]
- Apply some function that will enhance/diminish certain frequencies in frequency/Fourier space. [6]

Example to enhance high frequencies: This could be similar to distortion type amplification (discussed in lectures) which operates on amplitude not frequencies.

E.g:

Some *soft clipping*

$$f(x) = \begin{cases} x & \text{for } 0 \leq x < 1/3 \text{freqrange} \\ \frac{3-(2-3x)^2}{3} & \text{for } 1/3 \leq x < 2/3 \text{freqrange} \\ 1 & \text{for } 2/3 \leq x \leq 1 \text{freqrange} \end{cases}$$

or some non-linear function:

$$f(x) = \frac{x}{|x|} (1 - e^{\alpha x^2/|x|})$$

- Inverse Fourier transform to get excited data. [1]

11 Marks - UNSEEN. *exciter* mentioned briefly in lecture but no implementation details discussed

27 Marks Total Question 4