### **Tut-Lab Week 6**

#### Aims:

- Consolidate knowledge of basic search algorithms
- Reinforce usage of design patterns

### **Preparation:**

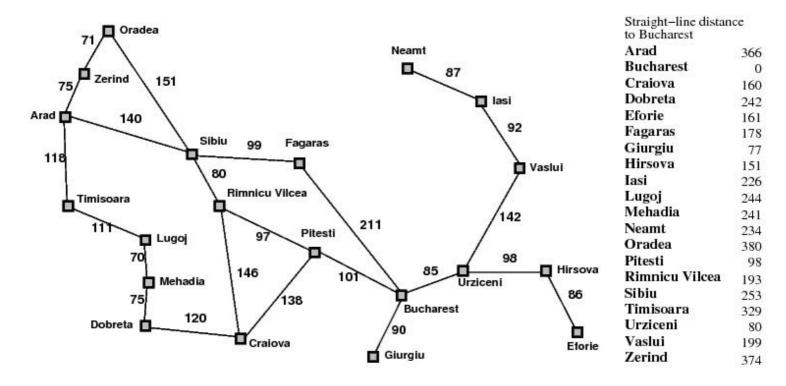
- Review graphs and basic search algorithms from COMP1927
- Review the Strategy pattern
- Review the use of the **Comparator** interface type for sorting collections

# **Graphs**

- A *directed graph* is a set of nodes and a binary relation over this set (that node a is related to node b can be represented by an arrow from a to b)
- Define a generic **Graph<E>** interface type that can handle nodes of a generic type **E** 
  - What are suitable accessors and mutators that would be needed with this interface type?
  - Apart from the basic operations, can you think of some more complex graph operations that could be part of the interface?
- As you will recall from COMP1927, the two standard ways of representing a graph are the *adjacency matrix* and the *adjacency list* 
  - o If a graph has n nodes, an adjacency matrix is an  $n \times n$  matrix with entry 1 (or some other data value) in the i, j element if node i is related to node j, while the adjacency list is a list whose elements are lists, where for element i of the main list, the associated list is of those nodes j such that node i is related to node j
- Choose one of the graph representations and provide a class that implements the **Graph<E>** interface type in this way
- Implement a test class that creates and performs some basic operations on graphs
  - Verify that the implementation really is generic by creating and manipulating two graphs whose nodes have different types
- Define some suitable class invariants for your implementation of the **Graph<E>** interface type and show that they are satisfied

## **Basic Search Algorithms**

• Consider the route-finding problem using the following Romania map as an example (ignore the straight-line distances for now)



- Define the route-finding problem (from Arad to Bucharest) as a state space search problem
- What order are nodes in the state space expanded for each of the following algorithms when searching for a path between Arad and Bucharest (when there is a choice of nodes, take the one earliest in the alphabetical ordering)?
  - Depth-first search (efficient use of space but may not terminate)
  - Breadth-first search (space inefficient, guaranteed to find a solution)
- Implement breadth-first search for route-finding in the Romania map
  - Use a class that implements the **Graph<E>** interface type to store the map
  - Use a class that implements the **Queue<E>** interface type to store the nodes generated in the search: what information, besides the state, needs to be stored at each node?
  - Store the successors of a node in an **ArrayList** and make sure they are sorted in alphabetical order of the city name before adding them to the **Queue**
  - How did you handle the problem of infinite looping in the search space?
- Refactor your design
  - Apply the Strategy pattern so that the successors of a node are sorted using an anonymous class that implements the **Comparator** interface type: in either the method that computes the successors of a node or the method that adds those successors to the **Queue** is either of these options better?
  - Draw a UML class diagram of your program, making sure your design and code conforms to the Strategy pattern