ML hw8 report

VAE is the artificial neural network architecture introduced by Diederik P. Kingma and Max Welling, belonging to the families of probabilistic graphical models and variational Bayesian methods.
 Variational autoencoders allows us to re-write statistical inference problems as statistical optimization problems. They are meant to map the input variable to a multivariate latent distribution.
 Advantage: capable of learning smooth latent state representations of the input data.
 Problem: VAE models tend to produce unrealistic, blurry samples.

2.

Model 1:

model architecture

```
class fon autoencoder(nn. Module):
       def __init__(self):
              super(fcn_autoencoder, self).__init__()
               self.encoder = nn.Sequential(
                      nn.Linear(64 * 64 * 3, 2048),
                      nn. ReLU(),
                      nn.Linear(2048, 1024),
                      nn.ReLU(),
                      nn.Linear(1024, 512),
                      nn. ReLU().
                      nn. Linear (512, 256),
                      nn. ReLU(),
                      nn.Linear(256, 128),
                         nn. ReLU().
                         nn.Linear(12, 3)
               self.decoder = nn.Sequential(
                       nn.Linear(3, 12),
                         nn. ReLU(),
                      nn.Linear(128, 256),
                      nn.ReLU(),
                      nn. Linear (256, 512),
                      nn. ReLU(),
                      nn.Linear(512, 1024),
                      nn.ReLU(),
                      nn.Linear(1024, 2048),
                      nn. ReLU(),
                      nn.Linear(2048, 64 * 64 * 3),
```

```
class conv_autoencoder(nn.Module):
       def __init__(self):
              super(conv_autoencoder, self).__init__()
              self.encoder = nn.Sequential(
                       nn.Conv2d(3, 64, 4, stride=2, padding=1),
                      nn.ReLU(),
                     nn.Conv2d(64, 128, 4, stride=2, padding=1),
                      nn.Conv2d(128, 256, 4, stride=2, padding=1),
                        nn.Conv2d(256, 512, 4, stride=2, padding=1),
                        nn.ReLU(),
               self.decoder = nn.Sequential(
                     nn.Conv2d(512, 256, 4, stride=2, padding=1),
                      nn.ReLU(),
                      nn.ConvTranspose2d(256, 128, 4, stride=2, padding=1),
                      nn. ReLH().
                      nn.ConvTranspose2d(128, 64, 4, stride=2, padding=1),
                        nn. ReLU(),
                        nn.ConvTranspose2d(64, 3, 4, stride=2, padding=1),
                      nn. Tanh(),
```

original image



reconstructed images



Model 2:

model architecture

```
class fcn_autoencoder(nn.Module):
       def __init__(self):
              super(fcn_autoencoder, self).__init__()
self.encoder = nn.Sequential(
                      nn.Linear(64 * 64 * 3, 1024),
                      nn.ReLU(),
                      nn.Linear(1024, 128),
                      nn.ReLU(),
                      nn.Linear(128, 64),
                      nn.ReLU(),
                      nn.Linear(64, 32),
                      # nn. ReLU(),
                      # nn.Linear(256, 128),
                        nn.ReLU(),
                        nn.Linear(12, 3)
              self.decoder = nn.Sequential(
                        nn.Linear(3, 12),
                        nn.ReLU(),
                      # nn.Linear(128, 256),
                      # nn.ReLU(),
                      nn.Linear(32, 64),
                      nn.ReLU(),
                      nn. Linear (64, 128),
                      nn.ReLU(),
                      nn.Linear(128, 1024),
                      nn.ReLU(),
                      nn.Linear(1024, 64 * 64 * 3),
                      nn. Tanh()
```

```
class conv_autoencoder(nn.Module):
       def __init__(self):
              super(conv_autoencoder, self).__init__()
              self.encoder = nn.Sequential(
                       nn.Conv2d(3, 64, 4, stride=2, padding=1),
                      nn. ReLU(),
                      nn.Conv2d(64, 128, 4, stride=2, padding=1),
                      nn.ReLU(),
                      nn.Conv2d(128, 256, 4, stride=2, padding=1),
                      nn.ReLU(),
                      nn.Conv2d(256, 512, 4, stride=2, padding=1),
                      nn.ReLU(),
               self.decoder = nn.Sequential(
                     nn.Conv2d(512, 256, 4, stride=2, padding=1),
                      nn.ReLU(),
                      nn.ConvTranspose2d(256, 128, 4, stride=2, padding=1),
                      nn.ReLU(),
                      nn.ConvTranspose2d(128, 64, 4, stride=2, padding=1),
                      nn.ReLU(),
                      nn.ConvTranspose2d(64, 3, 4, stride=2, padding=1),
                      nn. Tanh(),
              )
```

reconstructed images



Model 3:

model architecture

```
class fcn_autoencoder(nn.Module):
      def __init__(self):
              super(fcn_autoencoder, self).__init__()
              self.encoder = nn.Sequential(
                     nn.Linear(64 * 64 * 3, 512),
                     nn.ReLU(),
                     nn.Linear(512, 128),
                     nn.ReLU(),
                     nn.Linear(128, 64),
                     nn.ReLU(),
                     nn.Linear(64, 32),
                      # nn.ReLU(),
                     # nn.Linear(256, 128),
                       nn.ReLU(),
                        nn.Linear(12, 3)
              self.decoder = nn.Sequential(
                        nn.Linear(3, 12),
                        nn.ReLU(),
                      # nn.Linear(128, 256),
                      # nn.ReLU(),
                     nn.Linear(32, 64),
                     nn.ReLU(),
                     nn.Linear(64, 128),
                     nn.ReLU(),
                     nn.Linear(128, 512),
                     nn.ReLU(),
                     nn.Linear(512, 64 * 64 * 3),
                     nn. Tanh()
```

```
class conv_autoencoder(nn.Module):
        def __init__(self):
                 super(conv_autoencoder, self).__init__()
                 self.encoder = nn.Sequential(
                           nn.Conv2d(3, 64, 4, stride=2, padding=1),
                          nn.ReLU(),
                         nn.\,\texttt{Conv2d}(64, \quad 128, \quad 4, \quad \texttt{stride=2}, \quad \texttt{padding=1}),\\
                          nn.ReLU(),
                         nn.Conv2d(128, 256, 4, stride=2, padding=1),
                          nn.ReLU(),
                          nn.Conv2d(256, 512, 4, stride=2, padding=1),
                         nn.ReLU(),
                 self.decoder = nn.Sequential(
                         nn.Conv2d(512, 256, 4, stride=2, padding=1),
                          nn.ReLU(),
                         nn.ConvTranspose2d(256, 128, 4, stride=2, padding=1),
                          nn.ReLU(),
                          nn.\,ConvTranspose2d(128,\quad 64,\quad 4,\quad stride=2,\quad padding=1),\\
                         nn.ReLU(),
                          nn.\ ConvTranspose2d(64, \quad 3, \quad 4, \quad stride=2, \quad padding=1),\\
                          nn. Tanh(),
```

reconstructed images



The reconstruct images are more clear as the size of the model become larger.