

Curved Yang-Mills gauge theories

Infinitesimal and integrated gauge theory

Simon-Raphael Fischer*

February 1, 2022

National Center for Theoretical Sciences, Mathematics Division, National Taiwan University
No. 1, Sec. 4, Roosevelt Rd., Taipei City 106, Taiwan Room 503, Cosmology Building, Taiwan

Abstract[†]

2020 MSC: Primary 53D17; Secondary 81T13, 17B99.

Keywords: **Mathematical Gauge Theory**, Differential Geometry, High Energy Physics - Theory, Mathematical Physics

*Email: sfischer@ncts.tw; ORCID iD: [0000-0002-5859-2825](https://orcid.org/0000-0002-5859-2825)

[†]Abbreviations used in this paper: **LGB** for Lie group bundle, **LAB** for Lie algebra bundle.

Contents

1. Introduction	1
1.1. Basic notations	1
1.2. Assumed background knowledge	1
2. Basic definitions	1
3. Curved Yang-Mills gauge theory	1
3.1. Integration	7
4. Curved Yang-Mills gauge theory based on using Lie group bundles	8
4.1. Lie group bundles	8
4.1.1. Definition and examples	8
4.1.2. LGB actions	14
4.1.3. Toy model	15
5. Conclusion	15
List of References	15
A. Axiomatic Yang-Mills gauge theories	15

1. Introduction

1.1. Basic notations

1.2. Assumed background knowledge

It is highly recommended to have basic knowledge about differential geometry and gauge theory as presented in [1, especially Chapter 1 to 5]; however, sometimes we will still give explicit references to help with more technical details. It can be useful to have knowledge about Lie algebra and Lie group bundles, and even Lie algebroids and Lie groupoids, but we will introduce their basic notions such that it is not necessarily needed to have knowledge about these upfront.

See also the previous subsection about notions we assume to be known.

2. Basic definitions

3. Curved Yang-Mills gauge theory

Notation as in [1]

- \tilde{G} Lie group with Lie algebra \mathfrak{g}

- M smooth manifold (usually also a spacetime). An open subset of M is usually denoted by U ; typically small enough that "everything works out" (especially without further mentioning intersections of given open sets and so on)
- $P \rightarrow M$ a principal bundle, a (local) gauge is usually denoted by s , an element of $\Gamma(P)$, sections of P
- V a vector space
- ρ a Lie group representation on V , ρ_* the induced Lie algebra representation on V
- $K := P \times_\rho V$ the associated vector bundle induced by P and ρ on V . An element Φ of K is denoted by $[p, \phi]$ for $p \in P$ and $\phi \in V$, where $[\cdot, \cdot]$ denotes the equivalence class with respect to the equivalence

$$(p, \phi) \sim (pg, \rho(g^{-1}) \cdot \phi)$$

for all $g \in \tilde{G}$; pg denotes the canonical group action (from the right) $P \times \tilde{G} \rightarrow P$ and \cdot the action of $\text{Aut}(V) \subset \text{End}(V)$ on V .

- Especially if fixing a local gauge $s : U \rightarrow P$ we can write for sections $\Phi \in \Gamma(K)$ locally

$$\Phi|_U = [s, \phi],$$

where $\phi : U \rightarrow V$, *i.e.* a local section of the trivial vector bundle $M \times V \rightarrow M$.

- We especially focus on $V = \mathfrak{g}$ and $\rho = \text{Ad}$ the adjoint representation of \tilde{G} on \mathfrak{g} .

The field of gauge bosons A is a connection on the principal bundle, *i.e.* an element of $\Omega^1(P; \mathfrak{g})$ with

$$r_g^! A = \text{Ad}_{g^{-1}}(A) := \text{Ad}_{g^{-1}} \circ A,$$

$$A(\tilde{X}) = X$$

for all $g \in \tilde{G}$ and $X \in \mathfrak{g}$, where $r_g^!$ is the pullback of forms via the right \tilde{G} -multiplication on P , and \tilde{X} the fundamental vector field of X on P .

Typically, a lot of the formalism of gauge theory comes from how to define the minimal coupling. So, let us look at this and reinvent it a bit. Usually the covariant derivative/minimal coupling ∇^A of A and $\Phi \in \Gamma(K)$ is locally (w.r.t. to a gauge s) defined by

$$\nabla^A \Phi := [s, \nabla^A \phi],$$

where

$$\nabla^A \phi := d\phi + \rho_*(A_s) \cdot \phi, \tag{1}$$

where $A_s := s^!A \in \Omega^1(U; \mathfrak{g})$ (local pullback as a form of A via s) and $d\phi := \nabla^0\phi$, ∇^0 the canonical flat connection on $M \times V$.

The explicit definition of the field strength F of A is then usually motivated by looking at the curvature R_{∇^A} of ∇^A , that is

$$R_{\nabla^A}(\cdot, \cdot)\Phi|_U = [s, \rho_*(F_s) \cdot \phi],$$

where

$$F_s := dA_s + \frac{1}{2}[A_s \wedge A_s]_{\mathfrak{g}}$$

is the typical local definition of $F_s \in \Omega^2(U; \mathfrak{g})$ with

$$[A_s \wedge A_s]_{\mathfrak{g}}(X, Y) = 2 [A_s(X), A_s(Y)]_{\mathfrak{g}}$$

for all $X, Y \in \mathfrak{X}(U)$. (The notation F_s is of course due to the fact that $F_s = s^!F$, where F is the curvature of A . But I want to avoid that for now because of what we are about doing to do.) We shortly could denote this also as

$$R_{\nabla^A}\phi = \rho_*(F_s) \cdot \phi \tag{2}$$

Now: One could question why using $d\phi = \nabla^0\phi$ in Eq. (1). Thence, let us assume that we have a general vector bundle connection $\widehat{\nabla}$ on the trivial vector bundle $M \times V \rightarrow M$. We are going to redefine ∇^A and F locally w.r.t. a gauge s , then discuss how the gauge transformations have to look like to receive definitions independent of the chosen gauge s . This also means that the following discussion is now often local by fixing a gauge without further mentioning it.

Let us first locally redefine $\nabla^A\phi$:

$$\nabla^A\phi := \widehat{\nabla}\phi + \rho_*(A_s) \cdot \phi. \tag{3}$$

Motivated by Eq. (2), we want to identify the field strength with the curvature of ∇^A . One can check that we have

$$R_{\nabla^A} = R_{\widehat{\nabla}} + d\widehat{\nabla}(\rho_*(A_s)) + \rho_*(A_s) \wedge \rho_*(A_s), \tag{4}$$

where $d\widehat{\nabla}$ is the exterior covariant derivative of $\widehat{\nabla}$ canonically extended to $\text{End}(V)$, viewing $\rho_*(A_s)$ as an element of $\Omega^1(U; \text{End}(V))$, and where $\rho_*(A_s) \wedge \rho_*(A_s)$ is an element of $\Omega^2(U; \text{End}(V))$ given by

$$\begin{aligned} (\rho_*(A_s) \wedge \rho_*(A_s))(X, Y) &:= \rho_*(A_s(X)) \circ \rho_*(A_s(Y)) - \rho_*(A_s(Y)) \circ \rho_*(A_s(X)) \\ &= [\rho_*(A_s(X)), \rho_*(A_s(Y))]_{\text{End}(V)} \\ &= \rho_*([A_s(X), A_s(Y)]_{\mathfrak{g}}) \end{aligned}$$

$$= \rho_* \left(\frac{1}{2} [A_s \wedge A_s]_{\mathfrak{g}} \right) (X, Y)$$

for all $X, Y \in \mathfrak{X}(U)$.

In order to have a similar shape as in Eq. (2), we now assume that $\widehat{\nabla}$ satisfies the following **compatibility conditions**:

Remark 3.1: Comaptibility conditions

$$R_{\widehat{\nabla}} = \rho_*(\zeta), \quad (5)$$

$$\widehat{\nabla} \circ \rho_* = \rho_* \circ \nabla \quad (6)$$

for some $\zeta \in \Omega^2(M; \mathfrak{g})$ and ∇ a vector bundle connection on the trivial vector bundle $M \times \mathfrak{g} \rightarrow M$.

If we want that Eq. (4) has a shape like Eq. (2), it is obvious why we require (5); (6) is needed for the second summand in Eq. (4). Hence, let us study (6), that is

$$\widehat{\nabla}(\rho_*(\nu)) = \rho_*(\nabla \nu)$$

for all $\nu \in \Gamma(M \times \mathfrak{g})$,¹ especially $\widehat{\nabla}$ is again extended to $\text{End}(V)$ on the left hand side. With this we get

$$\begin{aligned} d^{\widehat{\nabla}}(\rho_*(A_s))(X, Y) &= \widehat{\nabla}_X(\rho_*(A_s(Y))) - \widehat{\nabla}_Y(\rho_*(A_s(X))) - \rho_*(A_s([X, Y])) \\ &= \rho_*(\nabla_X(A_s(Y))) - \rho_*(\nabla_Y(A_s(X))) - \rho_*(A_s([X, Y])) \\ &= \rho_*(\nabla_X(A_s(Y)) - \nabla_Y(A_s(X)) - A_s([X, Y])) \\ &= \rho_*(d^{\nabla} A_s)(X, Y) \end{aligned}$$

for all $X, Y \in \mathfrak{X}(U)$. Collecting everything, Eq. (4) has now the following form

$$R_{\nabla^A} = \rho_* \left(d^{\nabla} A_s + \frac{1}{2} [A_s \wedge A_s]_{\mathfrak{g}} + \zeta \right).$$

So, we have a new form of the field strength, assuming that ∇ and ζ satisfy the compatibility conditions in Remark 3.1. This is precisely the definition of the field strength as in the gauge theory of Thomas and Alexei, that is, we have a new field strength

$$G := d^{\nabla} A_s + \frac{1}{2} [A_s \wedge A_s]_{\mathfrak{g}} + \zeta.$$

Furthermore, if we are interested into Yang-Mills gauge theories, then we'd have $K = P \times_{\text{Ad}} \mathfrak{g}$ (the adjoint bundle), and so also $\rho_* = \text{ad}$. In this case we can put $\widehat{\nabla} = \nabla$ and then the

¹Elements of \mathfrak{g} are viewed as constant sections of $M \times \mathfrak{g}$.

compatibility conditions in Remark 3.1 read

$$R_{\nabla} = \text{ad}(\zeta),$$

$$\nabla \circ \text{ad} = \text{ad} \circ \nabla.$$

The second condition precisely gives after a short calculation

$$\nabla([\mu, \nu]_{\mathfrak{g}}) = [\nabla\mu, \nu]_{\mathfrak{g}} + [\mu, \nabla\nu]_{\mathfrak{g}}$$

for all $\mu, \nu \in \Gamma(M \times \mathfrak{g})$, so, ∇ has to be a Lie bracket derivation. So, in this case the compatibility conditions in Remark 3.1 precisely reduce to the compatibility conditions of Alexei's and Thomas's theory! (in the case of Lie algebra bundles; the general theory is more general, formulated on general Lie algebroids)

As a summary:

Remark 3.2: Summary

We have

$$R_{\nabla} = \text{ad}(\zeta), \tag{7}$$

$$\nabla \circ \text{ad} = \text{ad} \circ \nabla, \tag{8}$$

$$G = d^{\nabla} A_s + \frac{1}{2} [A_s \wedge A_s]_{\mathfrak{g}} + \zeta. \tag{9}$$

In fact, the compatibility conditions lead to a gauge invariant theory: Fix an ad-invariant scalar product κ on \mathfrak{g} ; then define the Lagrangian by

$$\mathfrak{L}_{\text{YM}} := -\frac{1}{2} \kappa(G \wedge *G) \tag{10}$$

where $*$ is the Hodge star operator w.r.t. some spacetime metric. (In short, the typical definition, but replace F with G) It is easier to look at the infinitesimal version of the gauge transformations, hence everything with respect to a gauge s now.

In order to derive a formula for these, let us again look at ∇^A . Fix an $\varepsilon \in \Gamma(M \times \mathfrak{g})$, then the infinitesimal gauge transformation $\delta_{\varepsilon}\phi$ of $\phi \in \Gamma(M \times \mathfrak{g})$ is usually defined by

$$\delta_{\varepsilon}\phi := \rho_*(\varepsilon) \cdot \phi.$$

We fix the infinitesimal gauge trafo $\delta_{\varepsilon}A$ of A by looking at the gauge trafo of $\nabla^A\phi$ via

$$\begin{aligned} \delta_{\varepsilon}\nabla^A\phi &= \left. \frac{d}{dt} \right|_{t=0} \left(\nabla^{A+t\delta_{\varepsilon}A}(\phi + t\delta_{\varepsilon}\phi) \right) \\ &= \underbrace{\widehat{\nabla}(\delta_{\varepsilon}\phi)}_{=(\widehat{\nabla}(\rho_*(\varepsilon))) \cdot \phi + \rho_*(\varepsilon) \cdot \widehat{\nabla}\phi} + \rho_*(\delta_{\varepsilon}A_s) \cdot \phi + \rho_*(A_s) \cdot \delta_{\varepsilon}\phi \end{aligned}$$

$$= (\rho_*(\nabla\varepsilon + \delta_\varepsilon A_s) + \rho_*(A_s) \cdot \rho_*(\varepsilon)) \cdot \phi + \rho_*(\varepsilon) \cdot \widehat{\nabla}\phi$$

using Remark 3.1. We want $\delta_\varepsilon \nabla^A \phi = \rho_*(\varepsilon) \cdot \nabla^A \phi$ which gives

$$\rho_*(\varepsilon) \cdot \nabla^A \phi = \rho_*(\varepsilon) \cdot \widehat{\nabla}\phi + \rho_*(\varepsilon) \cdot \rho_*(A_s) \cdot \phi.$$

Imposing $\delta_\varepsilon \nabla^A \phi = \rho_*(\varepsilon) \cdot \nabla^A \phi$ we get

$$\rho_*\left(\delta_\varepsilon A_s + \nabla\varepsilon + [A_s, \varepsilon]_{\mathfrak{g}}\right) = 0$$

using again that ρ_* is a Lie algebra representation. If we require that this shall work for all ρ_* , we may say

$$\delta_\varepsilon A_s := -\nabla\varepsilon + [\varepsilon, A_s]_{\mathfrak{g}}. \quad (11)$$

This is precisely the infinitesimal gauge trafo of A as in the theory of Thomas and Alexei! Hence, we achieve infinitesimal gauge invariance of \mathfrak{L}_{YM} . For completeness, let us check the gauge trafo of G using Def. (11) and Remark 3.2, it is very similar to the "classical" calculation due to Remark 3.2 which is why I skip some straightforward calculations to keep it short,

$$\begin{aligned} \delta_\varepsilon G &= \frac{d}{dt} \Big|_{t=0} \left(d^\nabla(A_s + t\delta_\varepsilon A_s) + \frac{1}{2} [A_s + t\delta_\varepsilon A_s \wedge A_s + t\delta_\varepsilon A_s]_{\mathfrak{g}} + \zeta \right) \\ &= d^\nabla(-\nabla\varepsilon + [\varepsilon, A_s]_{\mathfrak{g}}) + [A_s \wedge -\nabla\varepsilon + [\varepsilon, A_s]_{\mathfrak{g}}]_{\mathfrak{g}} \\ &= \underbrace{-(d^\nabla)^2 \varepsilon}_{=-R_\nabla \varepsilon = [\varepsilon, \zeta]_{\mathfrak{g}}} + [\nabla\varepsilon \wedge A_s]_{\mathfrak{g}} + [\varepsilon, d^\nabla A_s]_{\mathfrak{g}} + \underbrace{[A_s \wedge -\nabla\varepsilon]_{\mathfrak{g}}}_{=-[\nabla\varepsilon \wedge A_s]_{\mathfrak{g}}} + [A_s \wedge [\varepsilon, A_s]_{\mathfrak{g}}]_{\mathfrak{g}} \\ &= [\varepsilon, d^\nabla A_s + \zeta]_{\mathfrak{g}} + [A_s \wedge [\varepsilon, A_s]_{\mathfrak{g}}]_{\mathfrak{g}} \end{aligned}$$

and, using the Jacobi identity,

$$\begin{aligned} [A_s \wedge [\varepsilon, A_s]_{\mathfrak{g}}]_{\mathfrak{g}}(X, Y) &= [A_s(X), [\varepsilon, A_s(Y)]_{\mathfrak{g}}]_{\mathfrak{g}} - [A_s(Y), [\varepsilon, A_s(X)]_{\mathfrak{g}}]_{\mathfrak{g}} \\ &= [\varepsilon, [A_s(X), A_s(Y)]_{\mathfrak{g}}]_{\mathfrak{g}} \\ &= \left[\varepsilon, \frac{1}{2} [A_s \wedge A_s]_{\mathfrak{g}} \right]_{\mathfrak{g}}(X, Y) \end{aligned}$$

for all $X, Y \in \mathfrak{X}(U)$. Altogether

$$\delta_\varepsilon G = \left[\varepsilon, d^\nabla A_s + \frac{1}{2} [A_s \wedge A_s]_{\mathfrak{g}} + \zeta \right]_{\mathfrak{g}} = [\varepsilon, G]_{\mathfrak{g}}.$$

Hence, the field strength transforms with the adjoint of ε ; since κ is ad-invariant, we can derive that \mathfrak{L}_{YM} is invariant under the infinitesimal gauge trafo in Def. (11)!

Observe that by Remark 3.2 that ζ can be non-trivial even if we still use $\nabla = \nabla^0$, the canonical flat connection on $M \times \mathfrak{g}$, even though this whole discussion started with allowing more general connections.

If we minimise \mathfrak{L}_{YM} , then one obvious way would be to search solutions with $G \equiv 0$ for an absolute minimum/maximum (because of the sign), doing so would result into that the classical Yang-Mills energy would have a bound which is non-zero. May this be an explanation for the mass gap? As shown in my thesis, every classical theory has a ζ after a field redefinition. Even though field redefinitions are an equivalence for the classical theories, one may argue that it does not describe an equivalence for the quantised theory, leading to a possible explanation of the mass gap? But that is just high hope right now :)

3.1. Integration

For an integrated version of Def. (11) we need to discuss when the new "minimal coupling" of Def. (3) behaves nicely under a change of the gauge s . That is, we now want to extend the new definition of ∇^A to a well-defined connection on $K = P \times_\rho V$, especially on the adjoint bundle $K = P \times_{\text{Ad}} \mathfrak{g}$ in our case. (and later maybe generalise this to a \tilde{G} -quotient of a general Lie algebra bundle over P)

Let s' be another (local) gauge such that we have a unique smooth map $g : U \rightarrow G$ such that

$$s' = sg,$$

then we want for well-definedness

$$\nabla^A \Phi = [s, \nabla \phi + \text{ad}(A_s) \cdot \phi] \stackrel{!}{=} [s', \nabla \phi' + \text{ad}(A_{s'}) \cdot \phi'], \quad (12)$$

where we have $\Phi = [s, \phi] = [s', \phi']$, especially

$$\phi' = \text{Ad}(g^{-1}) \cdot \phi.$$

Since the new field strength G still transforms via the adjoint under δ_ε (see above), we make the following ansatz

$$A_{s'} = \text{Ad}(g^{-1}) \cdot A_s + \mu, \quad (13)$$

where $\mu \in \Omega^1(U; \mathfrak{g})$. Usually, $\mu = g^! \mu_{\tilde{G}}$, the pullback as a form of the Maurer-Cartan-Form $\mu_{\tilde{G}}$ on \tilde{G} . One can then check with some short calculation that Eq. (12) is equivalent to

$$\nabla(\text{Ad}(g^{-1}) \cdot \phi) + \text{ad}(\mu) \cdot \text{Ad}(g^{-1}) \cdot \phi \stackrel{!}{=} \text{Ad}(g^{-1}) \cdot \nabla \phi$$

using the definition of $P \times_{\text{Ad}} \mathfrak{g}$. Equivalently,

$$\text{ad}(\mu) = \text{Ad}(g) \circ ()$$

4. Curved Yang-Mills gauge theory based on using Lie group bundles

4.1. Lie group bundles

4.1.1. Definition and examples

Definition 4.1: Lie group bundle, [2, §1.1, Def. 1.1.19; p. 11]

Let G, \mathcal{G}, M be smooth manifolds. A fibre bundle

$$\begin{array}{ccc} G & \longrightarrow & \mathcal{G} \\ & & \downarrow \pi \\ & & M \end{array}$$

is called a **Lie group bundle** if:

1. G and each fibre $\mathcal{G}_x := \pi^{-1}(\{x\})$, $x \in M$, are Lie groups;
2. there exists a bundle atlas $\{(U_i, \phi_i)\}_{i \in I}$ such that the induced maps

$$\phi_{ix} := \text{pr}_2 \circ \phi_i|_{\mathcal{G}_x} : \mathcal{G}_x \rightarrow G$$

are Lie group isomorphisms, where I is an (index) set, U_i are open sets covering M , $\phi_i : \mathcal{G}|_{U_i} \rightarrow U_i \times G$ subordinate trivializations, and pr_2 the projection onto the second factor. This atlas will be called **Lie group bundle atlas** or **LGB atlas**.

We also often say that \mathcal{G} is an **LGB (over M)**, whose structural Lie group is either clear by context or not explicitly needed; and we may also denote LGBs by $G \rightarrow \mathcal{G} \xrightarrow{\pi} M$.

Remark 4.2: Principal and Lie group bundles

Beware, a Lie group bundle is **not** the same as a principal bundle $P \rightarrow M$ with the same fibre type G . First of all, the fibres of P are just diffeomorphic to a Lie group, a priori they carry no Lie group structure, while the fibres of \mathcal{G} carry a Lie group structure.

Second, on P we have a multiplication given as an action of G on P

$$P \times G \rightarrow P,$$

preserving the fibres P_x ($x \in M$) and simply transitive on them. Restricted on P_x we have

$$P_x \times G \rightarrow P_x.$$

For \mathcal{G} we have canonically a multiplication over x given by

$$\mathcal{G}_x \times \mathcal{G}_x \rightarrow \mathcal{G}_x,$$

also clearly simply transitive. Observe, the second factor is not "constant", *i.e.* we do not have $\mathcal{G}_x \times G \rightarrow \mathcal{G}_x$ in general. Hence, there is in general no well-defined product $\mathcal{G} \times \mathcal{G} \rightarrow \mathcal{G}$.

All of that is also resembled in the existence of sections. The existence of a section of P has a 1:1 correspondence to trivializations of P , which is why P in general only admits sections locally; see *e.g.* [1, §4.2, Thm. 4.2.19; page 219f.]. \mathcal{G} clearly admits always a global section, even if \mathcal{G} is non-trivial; just take the section which assigns each base point the neutral element of its fibre.

As usual, we have trivial examples given by the trivial LGB $M \times G \rightarrow M$ with canonical multiplication $(x, g) \cdot (x, q) := (x, gq)$, and we recover the notion of a Lie group in the case of $M = \{*\}$. For another important example recall that there is the notion of associated fibre bundles; following and stating the results of [2, §1, Construction 1.3.8, page 20] and [1, §4.7, page 237ff.; see also Rem. 4.7.8, page 242f.]: Let $P \xrightarrow{\pi_P} M$ be a principal bundle with structural Lie group G , a smooth manifold F and a smooth left G -action Ψ given by

$$\begin{aligned} G \times F &\rightarrow F, \\ (g, v) &\mapsto \Psi(g, v) := g \cdot v. \end{aligned}$$

Then we have a right G -action on $P \times F$ given by

$$\begin{aligned} (P \times F) \times G &\rightarrow P \times F, \\ (p, v, g) &\mapsto (p \cdot g, g^{-1} \cdot v), \end{aligned}$$

and one can show that the quotient under this action, $P \times_{\Psi} F := (P \times F) / G$, yields the structure of a fibre bundle

$$\begin{array}{ccc} F & \longrightarrow & P \times_{\Psi} F \\ & & \downarrow \pi_{P \times_{\Psi} F} \\ & & M \end{array}$$

such that the projection $P \times F \rightarrow P \times_{\Psi} F$ is a smooth surjective submersion, where the projection $\pi_{P \times_{\Psi} F} : P \times_{\Psi} F \rightarrow M$ is given by

$$\pi_{P \times_{\Psi} F}([p, v]) := \pi_P(p)$$

for all $[p, v] \in P \times_{\Psi} F$, denoting equivalence classes of (p, v) by square brackets. For $x \in M$, the fibre $(P \times_{\Psi} F)_x$ is given by $(P_x \times F) / G = P_x \times_{\Psi} F$, and the fibre is diffeomorphic to F by $F \ni v \mapsto [p, v] \in (P \times_{\Psi} F)_x$ for a fixed $p \in P_x$.

A very important example are of course associated vector bundles, related to F being a vector space. We need a similar concept for Lie groups.

Definition 4.3: Lie group representation on Lie groups

Let G, H be Lie groups. Then a **Lie group representation of G on H** is a smooth left action ψ of G on H

$$\begin{aligned} G \times H &\rightarrow H, \\ (g, h) &\mapsto \psi_g(h) := \psi(g, h) \end{aligned}$$

such that

$$\psi_g(hq) = \psi_g(h) \psi_g(q) \tag{14}$$

for all $g \in G$ and $h, q \in H$.

Remark 4.4: Note about labeling

Observe that we have by the definition of group actions

$$\psi_{gg'} = \psi_g \circ \psi_{g'}$$

for all $g, g' \in G$, viewing ψ_g as a map $H \rightarrow H$. Therefore we can view the action ψ as a homomorphism

$$G \rightarrow \text{Aut}(H),$$

where $\text{Aut}(H)$ is the set of Lie group automorphisms. The similarity to Lie group representations on vector spaces is obvious, thence the name.

This definition is of course also motivated by various references pointing out that Lie group representations define Lie group actions with extra properties; see for example [1, §3, Ex. 3.4.2, page 143f.].

With this we can discuss and define associated Lie group bundles.

Theorem 4.5: Associated Lie group bundle as quotient,

[1, motivated by vector spaces as in §4, Thm. 4.7.2, page 239f.]

Let G, H be Lie groups, $P \xrightarrow{\pi_P} M$ a principal G -bundle over a smooth manifold M , and ψ a G -representation on H . Then $\mathcal{H} := P \times_{\psi} H$ is an LGB

$$\begin{array}{ccc} H & \longrightarrow & \mathcal{H} \\ & & \downarrow \pi \\ & & M \end{array}$$

with projection π given by

$$\mathcal{H} \rightarrow M,$$

$$[p, h] \mapsto \pi_P(p), \quad (15)$$

and fibres

$$\mathcal{H}_x = P_x \times_{\psi} H \quad (16)$$

for all $x \in M$, which are isomorphic to H as Lie groups. The Lie group structure on each fibre \mathcal{H}_x is defined by

$$[p, h] \cdot [p, q] := [p, hq] \quad (17)$$

for all $h, q \in H$ and $p_x \in P_x$, where $\pi_P(p) = x$.

Proof.

• That π is the well-defined projection and that the fibres are precisely $P_x \times_{\psi} H$ for all $x \in M$ is well-known, see our discussion before Def. 4.3 and the references therein; it is also very straightforward to check. We also discussed that \mathcal{H} is a fibre bundle with structural fibre H . Hence, if one knows that the proposed group structure in Def. (17) is well-defined, then the smoothness of the group structure is implied by the smoothness structures of H and \mathcal{H} . Thence, let us check whether Def. (17) is well-defined. Let $x \in M$, $p \in P_x$ and $p' := p \cdot g'$ be another element of P_x , where $g' \in G$. Also let $[p_1, h_1], [p_2, h_2] \in P_x \times_{\psi} H$; then we have unique elements q_i, q'_i of G such that ($i \in \{1, 2\}$)

$$p_i = p \cdot q_i, \quad p_i = p' \cdot q'_i,$$

especially, it follows $q_i = g' q'_i$. On the one hand, if we use p as fixed element of P_x to calculate the multiplication, we get

$$[p_1, h_1] \cdot [p_2, h_2] = [p, \psi_{q_1}(h_1)] \cdot [p, \psi_{q_2}(h_2)] = [p, \psi_{q_1}(h_1) \psi_{q_2}(h_2)], \quad (18)$$

on the other hand, using Def. 4.3 and $p' = p \cdot g'$ instead of p ,

$$\begin{aligned} [p_1, h_1] \cdot [p_2, h_2] &= [p \cdot g', \psi_{q'_1}(h_1) \psi_{q'_2}(h_2)] \\ &= \left[p, \underbrace{\psi_{g'}(\psi_{q'_1}(h_1) \psi_{q'_2}(h_2))}_{=\psi_{g'}(\psi_{q'_1}(h_1)) \psi_{g'}(\psi_{q'_2}(h_2))} \right] \\ &= [p, \psi_{g'q'_1}(h_1) \psi_{g'q'_2}(h_2)] \\ &= [p, \psi_{q_1}(h_1) \psi_{q_2}(h_2)], \end{aligned}$$

which implies that Def. (17) is well-defined, and thus defines a Lie group structure on each fibre of \mathcal{H} .

- That the fibres \mathcal{H}_x are isomorphic to H as Lie groups for all $x \in M$ also quickly follows. Recall by our discussion before Def. 4.3 that the fibres are diffeomorphic to H by $H \ni h \mapsto [p, h] \in \mathcal{H}_x$ for a fixed $p \in P_x$. By Def. (17) it is clear that this map is a Lie group homomorphism and hence a Lie group isomorphism.

- Let us now construct an LGB atlas for \mathcal{H} by using a principal bundle atlas for P . That is, for some $U \subset M$ open and a trivialization $\varphi_U : P|_U \rightarrow U \times G$ we write

$$\varphi_U(p) = (\pi_P(p), \beta_U(p))$$

for all $p \in P$, where $\beta_U : P|_U \rightarrow G$ is an equivariant map, *i.e.* $\beta_U(p \cdot g) = \beta_U(p) \cdot g$ for all $g \in G$. Then define ϕ_U as a map by

$$\mathcal{H}|_U \rightarrow U \times H,$$

$$[p, h] \mapsto (\pi_P(p), \psi_{\beta_U(p)}(h)).$$

ϕ_U is well-defined: Let $[p', h'] \in \mathcal{H}|_U$ with $[p', h'] = [p, h]$. Then there is a $g \in G$ such that

$$(p', h') = (p \cdot g, \psi_{g^{-1}}(h)),$$

hence, using the equivariance of β_U and Def. 4.3,

$$\phi_U([p', h']) = \left(\underbrace{\pi_P(p \cdot g)}_{=\pi_P(p)}, \underbrace{(\psi_{\beta_U(p \cdot g)} \circ \psi_{g^{-1}})(h)}_{=\psi_{\beta_U(p)} \circ \psi_{g^{-1}}}(h) \right) = (\pi_P(p), \psi_{\beta_U(p)}(h)) = \phi_U([p, h]),$$

which proves that ϕ_U is well-defined. Denote the projection onto equivalence classes $P \times H \rightarrow \mathcal{H}$ by ϖ , then observe

$$\phi_U \circ \varpi = L,$$

where $L_U : P|_U \times H \rightarrow U \times H$ is given by $L_U(p, h) := (\pi_P(p), \psi_{\beta_U(p)}(h))$ for all $(p, h) \in P|_U \times H$. L_U is clearly smooth and recall that ϖ is a smooth surjective submersion, therefore ϕ_U is smooth; this is a well-known fact for right-compositions with surjective submersions, see *e.g.* [1, §3.7.2, Lemma 3.7.5]. We define a candidate of the inverse $\phi_U^{-1} : U \times H \rightarrow \mathcal{H}|_U$ by

$$\phi_U^{-1}(x, h) = [\varphi_U^{-1}(x, e), h]$$

for all $(x, h) \in U \times H$, where e is the neutral element of G . By the definition of φ_U we immediately get

$$(\varphi_U \circ \phi_U^{-1})(x, e) = (\pi_P(\varphi_U^{-1}(x, e)), \beta_U(\varphi_U^{-1}(x, e))) = (x, e),$$

for all $x \in U$, and, also using again the equivariance of β_U ,

$$\varphi_U^{-1}(\pi_P(p), e) = \varphi_U^{-1}(\pi_P(p \cdot \beta_U^{-1}(p)), \beta_U(p) \cdot \beta_U^{-1}(p))$$

$$\begin{aligned}
 &= \varphi_U^{-1} \left(\pi_P(p \cdot \beta_U^{-1}(p)), \beta_U(p \cdot \beta_U^{-1}(p)) \right) \\
 &= (\varphi_U^{-1} \circ \varphi_U)(p \cdot \beta_U^{-1}(p)) \\
 &= p \cdot \beta_U^{-1}(p)
 \end{aligned}$$

for all $p \in P|_U$. Then

$$(\phi_U \circ \phi_U^{-1})(x, h) = \left(\pi_P(\varphi_U^{-1}(x, e)), \psi_{\beta_U(\varphi_U^{-1}(x, e))}(h) \right) = (x, \psi_e(h)) = (x, h),$$

for all $(x, h) \in U \times H$, and

$$\begin{aligned}
 (\phi_U^{-1} \circ \phi_U)([p, h]) &= \underbrace{[\varphi_U^{-1}(\pi_P(p), e), \psi_{\beta_U(p)}(h)]}_{=p \cdot \beta_U^{-1}(p)} \\
 &= [p, h]
 \end{aligned}$$

for all $[p, h] \in \mathcal{H}|_U$. Thus, ϕ_U is bijective; additionally observe

$$\phi_U^{-1}(x, h) = \varpi(\varphi_U^{-1}(x, e), h)$$

such that ϕ_U^{-1} is clearly smooth as the composition of smooth maps, and we therefore conclude that ϕ_U is a diffeomorphism. Finally, derive with Def. 4.3 and Eq. (18) that

$$\begin{aligned}
 (\text{pr}_2 \circ \phi_U)([p_1, h_1] \cdot [p_2, h_2]) &= (\text{pr}_2 \circ \phi_U)([p, \psi_{q_1}(h_1) \cdot \psi_{q_2}(h_2)]) \\
 &= \psi_{\beta_U(p)}(\psi_{q_1}(h_1) \cdot \psi_{q_2}(h_2)) \\
 &= \underbrace{\psi_{\beta_U(p)}(\psi_{q_1}(h_1))}_{=\psi_{\beta_U(p) \cdot q_1}(h)} \cdot \psi_{\beta_U(p)}(\psi_{q_2}(h_2)) \\
 &= \psi_{\beta_U(p_1)}(h) \cdot \psi_{\beta_U(p_2)}(h) \\
 &= (\text{pr}_2 \circ \phi_U)([p_1, h_1]) \cdot (\text{pr}_2 \circ \phi_U)([p_2, h_2])
 \end{aligned}$$

for all $[p_1, h_1], [p_2, h_2] \in \mathcal{H}_x$, where we used again the equivariance of β_U and the same notation as introduced for Eq. (18), and pr_2 denotes the projection onto the second factor. Thence, $\text{pr}_2 \circ \phi_U$ induces Lie group isomorphisms $\mathcal{H}_x \rightarrow H$ for all $x \in U$; by Def. 4.1 we can finally conclude that \mathcal{H} is an LGB. ■

The special situation of $H = G$ is already an important example:

Example 4.6: Inner group bundle,

[2, §1, paragraph after Def. 1.1.19, page 11; comment after Construction 1.3.8, page 20]

The **inner group bundle** or **inner LGB** of a principal bundle $P \rightarrow M$, denoted by $c_G(P)$, is defined by

$$c_G(P) := P \times_{c_G} G, \quad (19)$$

where $c_G : G \times G \rightarrow G$ is the left action of G on itself given by the very well-known **conjugation**

$$c_G(g, h) := c_g(h) = (L_g \circ R_{g^{-1}})(h) = ghg^{-1} \quad (20)$$

for all $g, h \in G$, where we also denote left- and right-multiplications (with g) by L_g and R_g , respectively; see *e.g.* [1, beginning of §1.5.2, page 40f.] for its common properties. It is well-known that c_G satisfies the properties of a Lie group representation of G on itself in the sense of Def. 4.3.

$c_G(P)$ is an LGB by Thm. 4.5.

4.1.2. LGB actions

As for Lie groups, we are interested into their actions. The idea is the following, similar to [2, §1.6, discussion around Def. 1.6.1, page 34]: We have an LGB $\mathcal{G} \rightarrow M$ over a smooth manifold M , and we want to construct an action of \mathcal{G} on another smooth manifold N . Each fibre of \mathcal{G} is a Lie group, and we have a notion of Lie groups actions on manifold N . Therefore one could define an LGB action as a collection of Lie group actions, that is, sections of \mathcal{G} act on N ; however, this would lead to that the general outcome of a product of $\Gamma(\mathcal{G})$ on N would be smooth maps from M to N .

Recall that there is a notion of pullbacks of fibre bundles, see *e.g.* [1, §4.1.4, page 203ff.; especially Thm. 4.1.17, page 204f.]. That is, if we additionally have a smooth manifold N and a smooth map $f : M \rightarrow N$, then we have the pullback $f^*\mathcal{G}$ of \mathcal{G} as a fibre bundle defined as usual by

$$f^*\mathcal{G} := \{(g, x) \in \mathcal{G} \times N \mid f(x) = \pi(g)\}. \quad (21)$$

That is, the following diagram commutes

$$\begin{array}{ccc} f^*\mathcal{G} & \xrightarrow{\pi_1} & \mathcal{G} \\ \downarrow & & \downarrow \pi \\ N & \xrightarrow{f} & M \end{array}$$

where $\pi_1 : \mathcal{G} \times N \rightarrow \mathcal{G}$ is the projection onto the first factor.

Definition 4.7: Lie group actions, [2, §1.6, special case of Def. 1.6.1, page 34]

Let M, N be smooth manifolds, $\mathcal{G} \xrightarrow{\pi} M$ an LGB over M and $f : N \rightarrow M$ a smooth map.

4.1.3. Toy model

We want to use LGBs in the context in the context of gauge theory, somewhat as a replacement of the structural Lie group.

5. Conclusion

Acknowledgements: I want to thank Mark John David Hamilton and Alessandra Frabetti for their great help and support in making this paper.

Funding: The paper was finalised as part of my post-doc fellowship at the National Center for Theoretical Sciences (NCTS), which is why I also want to thank the NCTS.

List of References

- [1] Mark JD Hamilton. *Mathematical Gauge Theory*. Springer, 2017. <https://doi.org/10.1007/978-3-319-68439-0>.
- [2] K. Mackenzie. General Theory of Lie Groupoids and Algebroids. *London Mathematical Society Lecture Note Series*, 213, 2005. <https://doi.org/10.1017/CBO9781107325883>.

A. Axiomatic Yang-Mills gauge theories

Let us discuss where the compatibility conditions may arise from a certain axiomatic point of view.