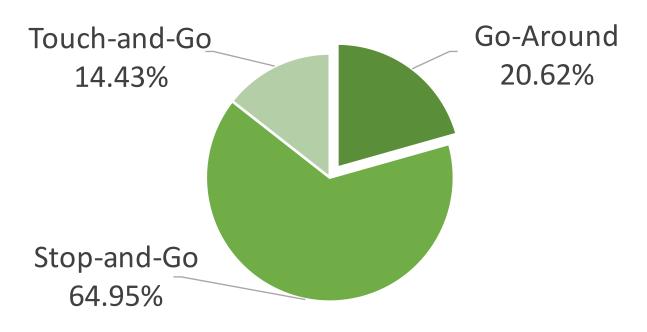
## Unstable Approach Results



- Go-Around
- Stop-and-Go
- Touch-and-Go