

Recovering Surface Normal and Arbitrary Images: A Dual Regression Network for Photometric Stereo

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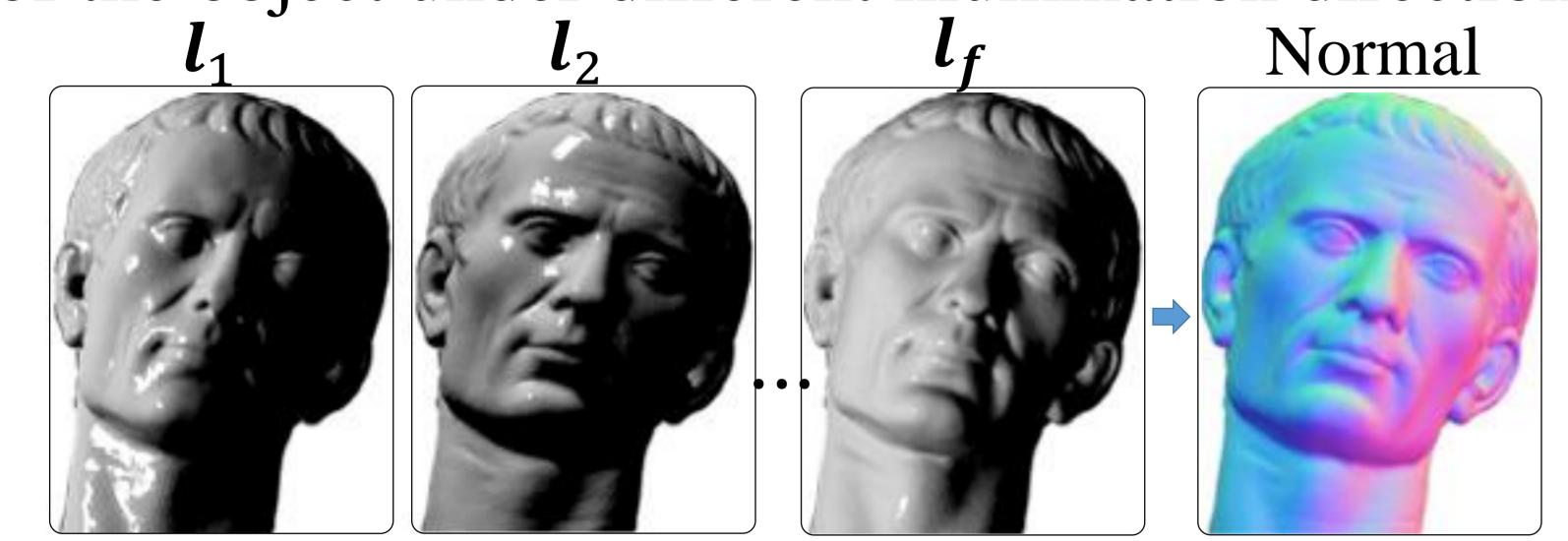
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## Background & Motivation

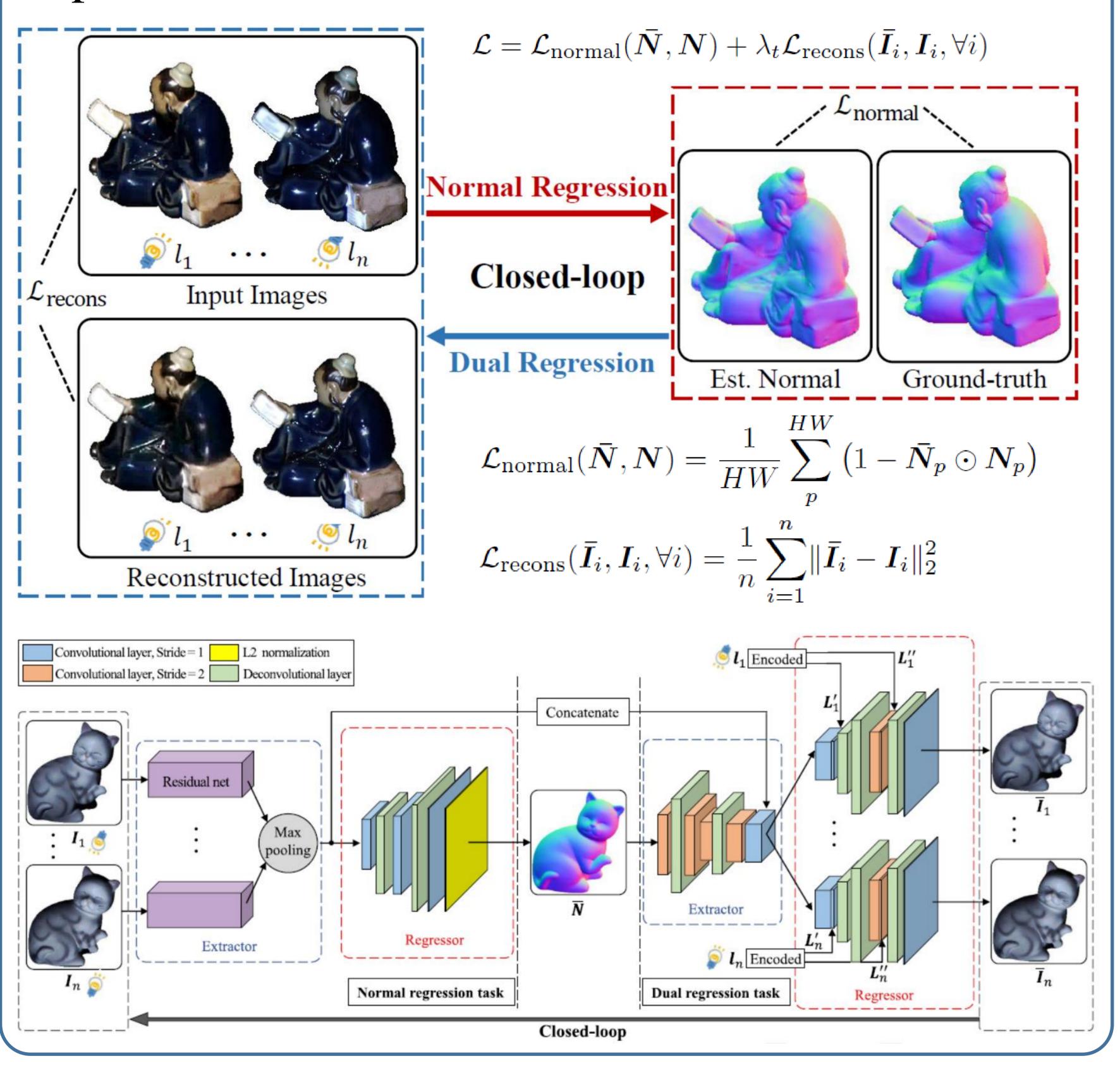
Photometric stereo recovers the dense surface normal of the object under different illumination directions.



The previous learning-based methods focus on the surface normal constraint without other supervision.

#### Method

DR-PSN, forming a closed-loop structure to provide additional constrain. The dual regression task learns the imaging model, which is the inverse task of and improves the surface normal estimation.



# **Experimental Results**

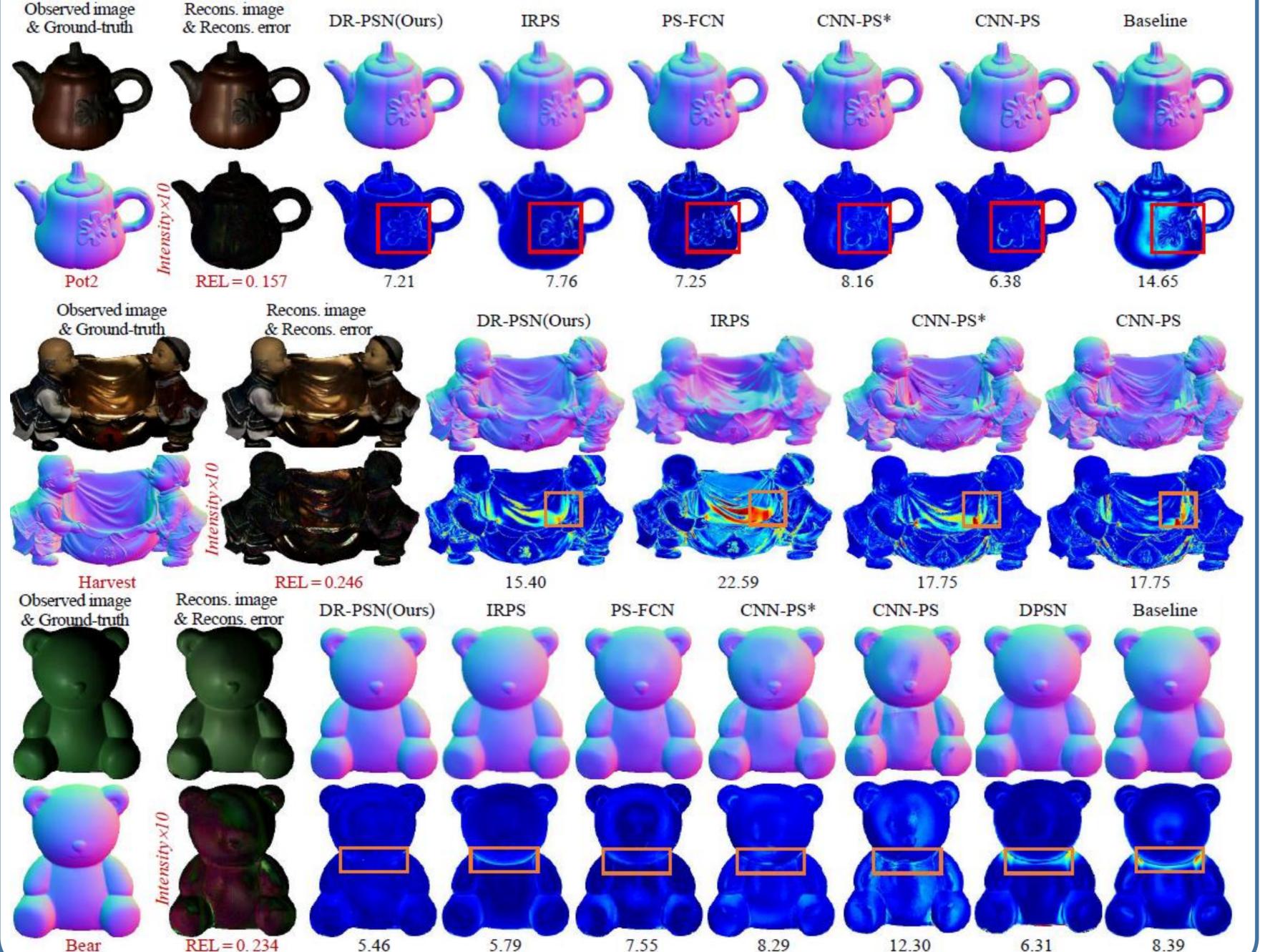
Ablations with varying $\lambda_t$									
Variants	Surface	normal	Reconstructed images						
variants	MAE (°) ↓	$< err_{15} \circ \uparrow$	SSIM ↑	$REL \downarrow$					
Dual, proposed linear $\lambda_t$ ( $\Delta = 0.02$ , PT= 0.8)	11.47	84.99%	0.947	0.171					
Single $\lambda = 0$	12.53	81.55%	-	-					
Dual, fixed $\lambda = 0.1$	11.64	84.61%	0.895	0.235					
Dual, fixed $\lambda = 0.5$	11.88	82.94%	0.939	0.182					
Dual, fixed $\lambda = 1$	12.50	81.79%	0.963	0.166					
Dual, linear $\lambda_t$ ( $\Delta = 0.02$ , PT= 0.6)	11.57	85.01%	0.926	0.197					
Dual, linear $\lambda_t$ ( $\Delta = 0.02$ , PT= 1)	11.80	83.33%	0.951	0.169					
Dual, linear $\lambda_t$ ( $\Delta = 0.01$ , PT= 0.8*)	11.58	84.52%	0.914	0.209					
Dual, linear $\lambda_t$ ( $\Delta = 0.04$ , PT= 0.8)	11.55	84.39%	0.929	0.175					
Dual, quadratic $\lambda_t$ ( $\Delta = 0.001$ , PT= 0.8)	11.49	84.95%	0.916	0.197					
Dual, quadratic $\lambda_t$ ( $\Delta = 0.0005$ , PT= 0.8)	11.58	84.78%	0.934	0.188					

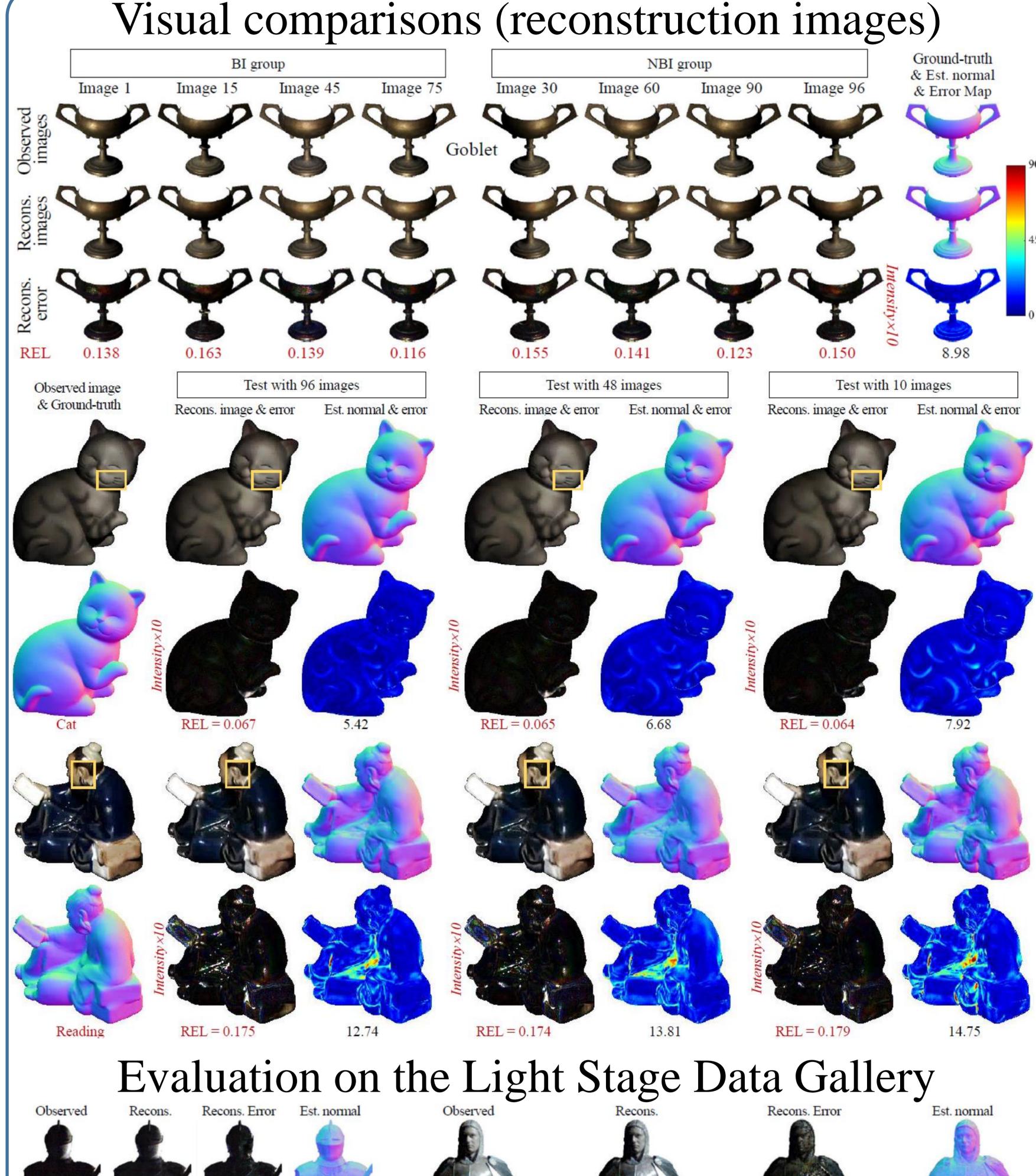
### DiLiGenT benchmark with inputs 96 & 10

Method	Ball	Bear	Buddha	Cat	Cow	Goblet	Harvest	Pot1	Pot2	Reading	Avg.
Baseline (Least squares) [1]	4.10	8.39	14.92	8.41	25.60	18.50	30.62	8.89	14.65	19.80	15.39
Matrix rank = $3$ [22]	2.54	7.32	11.11	7.21	25.70	16.25	29.26	7.74	14.09	16.17	13.74
Bivariate BRDF [26]	3.34	7.11	10.47	6.74	13.05	9.71	25.95	6.64	8.77	14.19	10.60
Bi-polynomial [28]	1.74	6.12	10.60	6.12	13.93	10.09	25.44	6.51	8.78	13.63	10.30
SDPS-Net [11]	2.77	6.89	8.97	8.06	8.48	11.91	17.43	8.14	7.50	14.90	9.51
DPSN [10]	2.02	6.31	12.68	6.54	8.01	11.28	16.86	7.05	7.86	15.51	9.41
IRPS [40]	1.47	5.79	10.36	5.44	6.32	11.47	22.59	6.09	7.76	11.03	8.83
CNN-PS* [12]	2.23	8.29	8.53	5.75	9.74	8.66	17.75	5.91	8.16	11.61	8.66
PS-FCN [13]	2.82	7.55	7.91	6.16	7.33	8.60	15.85	7.13	7.25	13.33	8.39
CNN-PS [12]	2.12	12.30	8.07	4.38	7.92	7.42	13.83	5.37	6.38	12.12	7.99
DR-PSN (Ours)	2.27	5.46	7.84	5.42	7.01	8.49	15.40	7.08	7.21	12.74	7.90
Method	Ball	Bear	Buddha	Cat	Cow	Goblet	Harvest	Pot1	Pot2	Reading	Avg.

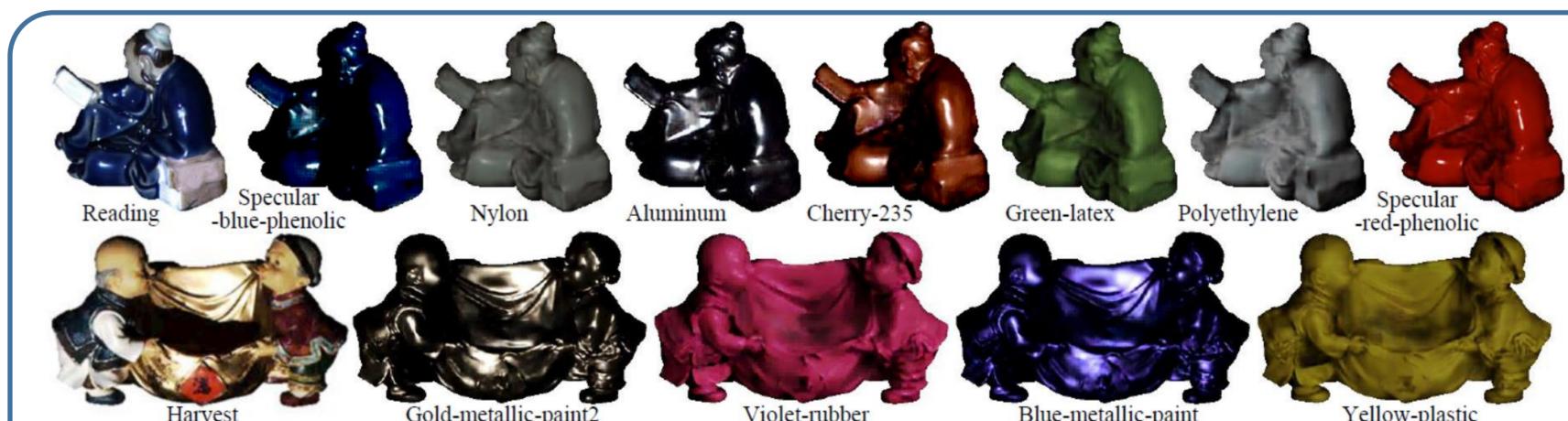
Method	Ball	Bear	Buddha	Cat	Cow	Goblet	Harvest	Pot1	Pot2	Reading	Av
Bivariate BRDF [26]	12.94	16.40	20.63	15.53	18.08	18.73	32.50	6.28	14.31	24.99	19.
Baseline (Least squares) [1]	5.09	11.59	16.25	9.66	27.90	19.97	33.41	11.32	18.03	19.86	17.
Bi-polynomial [28]	5.24	9.39	15.79	9.34	26.08	19.71	30.85	9.76	15.57	20.08	16.
Matrix rank $=3$ [22]	3.33	7.62	13.36	8.13	25.01	18.01	29.37	8.73	14.60	16.63	14.
CNN-PS [12]	9.11	14.08	14.58	11.71	14.04	15.48	19.56	13.23	14.65	16.99	14.
CNN-PS* [12]	6.39	14.51	15.08	10.96	15.26	14.40	19.73	11.35	13.58	16.67	13.
PS-FCN [13]	4.02	7.18	9.79	8.80	10.51	11.58	18.70	10.14	9.85	15.03	10.
SPLINE-Net [38]	4.96	5.99	10.07	7.52	8.80	10.43	19.05	8.77	11.79	16.13	10.
LMPS [37]	3.97	8.73	11.36	6.69	10.19	10.46	17.33	7.30	9.74	14.37	10.
DR-PSN (Ours)	3.83	7.52	9.55	7.92	9.83	10.38	17.12	9.36	9.16	14.75	9.9

#### Visual comparisons (surface normals)





#### Extended Work



Our extended work (submitting) can render both arbitrary light and reflectance of the image, which will expand the limited dataset of photometric stereo.

Feel free to contact me via juyakun@stu.ouc.edu.cn, whether meets any questions about any photometric stereo papers of mine, or for cooperation.