

BAYESIAN ESTIMATION

EXTENSIONS

Tools for Macroeconomists: The essentials

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Extensions

EXTENSIONS

- Bayesian inference and model comparison
- Dealing with trends
- More on priors

Extensions

BAYESIAN INFERENCE AND MODEL COMPARISON

BAYESIAN VS. FREQUENTIST INFERENCE

- Bayesian inference cannot use frequentist principles
 - t-test, F-test, LR-test etc.
 - they have a frequentist justification of repeated sampling
- instead, there are two common Bayesian principles:
 - Highest Posterior Density (HPD) interval
 - Bayes factors (posterior odds)

HIGHEST POSTERIOR DENSITY INTERVALS

A $100(1 - \alpha)\%$ posterior interval for Ψ is given by

$$P(\underline{b} < \Psi < \bar{b}) = \int_{\underline{b}}^{\bar{b}} P(\Psi | \mathcal{Y}^T) d\Psi = 1 - \alpha$$

- there exists many such intervals
- the HPD interval is the smallest one of them

HPD “TESTS”

- the HPD test amounts to checking whether $\Psi_i \in \text{HPD}_{1-\alpha}$
- this is an informal way of comparing nested models
 - i.e. different parameter values
- Bayesians can also compare non-nested models
- more on this below

BAYES FACTORS

$$B = \frac{P(\mathcal{Y}^T|\Psi_1)P(\Psi_1)}{P(\mathcal{Y}^T|\Psi_2)P(\Psi_2)}$$

- where Ψ_1 and Ψ_2 are two different sets of parameter values
- if $B > 1 \rightarrow \Psi_1$ is *a posteriori* more likely than Ψ_2
- important to use “proper” priors!

MODEL COMPARISON

- posterior densities can be used to evaluate
 - conditional probabilities of particular parameter values
 - conditional probabilities of different model specifications
- use Bayes factors (posterior odds ratio) to compare models
 - advantage is that all models are treated symmetrically
 - there is no “null” model compared to an alternative

MODEL COMPARISON

$$B_{A|B} = \frac{P_A(\mathcal{Y}^T|\Psi_A)P_A(\Psi_A)}{P_B(\mathcal{Y}^T|\Psi_B)P_B(\Psi_B)}$$

- it is also possible to assign priors on *models*
- the posterior odds ratio is then

$$PO_{A|B} = \frac{P(A|\mathcal{Y}^T)}{P(B|\mathcal{Y}^T)} = B_{A|B} \frac{P(A)}{P(B)}$$

HOW MUCH INFORMATION IN BAYES FACTOR?

Kass and Raftery (1995), if the value of $B_{A|B}$ is

- between 1 and 3 \rightarrow barely worth mentioning
- between 3 and 20 \rightarrow positive evidence
- between 20 and 150 \rightarrow strong evidence
- over 150 \rightarrow very strong evidence

Extensions

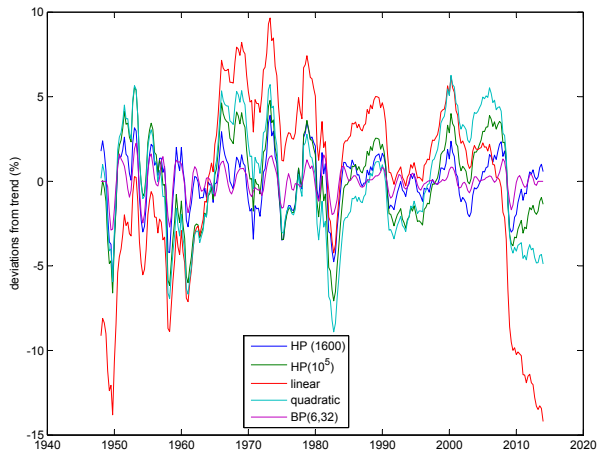
TRENDS

TRENDS

Problem:

- methodology works for stationary environments
- data has trends
- not clear which trend the model represents?

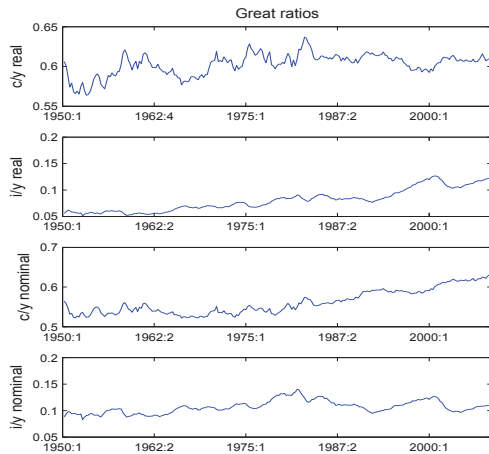
TRENDS



TRENDS

- we could build in a trend within the model
- e.g. productivity is trending
- “stationarize” non-stationary variables within the model
- i.e. inspect variables relative to productivity
- however, not clear that data satisfies balanced growth

TRENDS



TRENDS

Solutions:

- use differenced data
 - highlights high-frequency movements (measurement error)
- detrend prior to estimation

ESTIMATION ON DETRENDED DATA

- use e.g. quadratic trend:

$$y_t = a_0 + a_1t + a_2t^2 + u_t$$

- each variable can have its own trend
- using HP or Band Pass filter:

$$y_t^{obs-filtered} = B(L)y_t^{obs}$$

- $B(L)$ is a 2-sided filter!
- → creates artificial serial correlation in the filtered data
- → apply filter also to model data

ESTIMATION ON DETRENDED DATA

- the above implies that the model is fitted to low(er) frequencies only
- Canova (2010) points out that the above can lead to:
 - underestimated volatility of shocks
 - persistence of shocks is overestimated
 - less perceived noise \rightarrow policy rules imply higher predictability
 - substitution and income effects may be distorted due to above
- proposes to estimate flexible trend specifications within model

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MORE ON PRIORS

MORE ON SELECTING PRIORS

- so far selecting (independent) priors about deep parameters
- however, this may not be the best way to go
 - often we have priors about *observables*
 - good independent priors may still cause weird model properties
- solutions proposed in the literature:
 - Del Negro, Schorfheide (2008)
 - Andrlle, Benes (2013)
 - Jarocinsky, Marcet (2013)

DEL NEGRO, SCHORFHEIDE (2008)

- more guidance for eliciting priors
- issues with (independent) priors on deep parameters:
 - may lead to probability mass on unrealistic model properties
 - most exogenous shock processes are latent → what priors?
 - priors are often transferred to different models

DEL NEGRO, SCHORFHEIDE (2008)

- they group parameters into three categories:
 - those determining the steady state
 - those determining exogenous shocks
 - those determining the endogenous propagation mechanism

DEL NEGRO, SCHORFHEIDE (2008)

Parameters related to steady state relationships

- discount rate, depreciation, returns to scale etc.
- let $S_D(\Psi_{ss})$ be a vector of steady state relationships
 - Ψ_{ss} : set of parameters
- then $\hat{S} = S_D(\Psi_{ss}) + \eta$ are their measurements
 - η : measurement error
- \hat{S} has a probabilistic interpretation and therefore
- using Bayes' rule, one can write $P(\Psi_{ss}|\hat{S}) \propto \mathbb{L}(\hat{S}|\Psi_{ss})P(\Psi_{ss})$
- allows for overidentification

Exogenous processes

- volatility and persistence parameters
- use implied moments of endog. variables to “back out” priors
- the above is given values for Ψ_{ss} and Ψ_{endo}
- \rightarrow valid for a particular model
- i.e. should not be directly transfered across models

DEL NEGRO, SCHORFHEIDE (2008)

Endogenous propagation mechanisms

- price rigidity, labor supply elasticity etc.
- one could use similar principle as above
- authors suggest independent priors
 - researchers often have a relatively good idea
- joint prior induces non-linear relationships between parameters
- joint prior becomes

$$P(\Psi|\hat{S}) \propto \mathbb{L}(\hat{S}|\Psi_{ss})P(\Psi_{ss})P(\Psi_{endo})$$

- requires an additional step in MCMC algorithm

- do not distinguish between groups of parameters
- their “system priors” are priors about concepts such as
 - impulse response functions
 - conditional correlations etc.

- good independent priors may still cause weird model properties
- estimation can assign substantial mass on such regions
- call for careful prior-predictive analysis:
 - IRFs, second moments ...
 - compare with posterior results
 - is it the data or the model driving the results?

Candidates for system priors:

- steady states
 - sensible values in levels or growth rates
- (un-)conditional moments
 - cross-correlations (conditional on shocks)
- impulse response properties
 - peak impacts, duration, horizon of MP effectiveness etc.

Implementation:

- use Bayes' rule again
- specify model properties you care about $Z = h(\Psi)$
- these can be characterized by a probabilistic model $Z \sim D(Z^s)$
 - $D(Z^s)$ is a distribution function
 - Z^s are parameters of that function (hyper-parameters)
- its likelihood function (the system prior): $P(Z^s|\Psi, h)$
- composite joint prior: $P(\Psi|Z^s, h) \propto P(Z^s|\Psi, h)P(\Psi)$

The posterior becomes

$$P(\Psi | \mathbb{Y}^T, Z^S) \propto \mathbb{L}(\mathbb{Y}^T | \Psi) P(Z^S | \Psi, h) P(\Psi)$$

- evaluation is in principle the same as before
- use of MCMC methods
- additional step in evaluating the system prior
- slows things down - have to run MCMC on prior

- similar ideas as above, but in the context of Bayesian VARs
 - their point is that widely used priors about parameters
 - can lead to behavior of observables that is counterfactual
 - → always a good to do prior-predictive analysis of you model!