Advanced Tools in Macroeconomics

Continuous time models (and methods)

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Let's go back to the HJB equation.

$$\rho v(k) = u(c) + v'(k)(k^{\alpha} - \delta k - c)$$
with $u'(c) = v'(k)$

► Thus

$$\rho v'(k) = v''(k)(k^{\alpha} - \delta k - c) + v'(k)(\alpha k^{\alpha - 1} - \delta)$$

► And

$$v''(k) = u''(c)c'(k)$$

Using

$$\rho v'(k) = v''(k)(k^{\alpha} - \delta k - c) + v'(k)(\alpha k^{\alpha - 1} - \delta)$$

Together with v'(k) = u'(c) and v''(k) = u''(c)c'(k) gives

$$\rho u'(c) = u''(c)c'(k)(k^{\alpha} - \delta k - c) + u'(c)(\alpha k^{\alpha - 1} - \delta)$$

or

$$-u''(c)c'(k)(k^{\alpha}-\delta k-c)=u'(c)(\alpha k^{\alpha-1}-\delta-\rho)$$

▶ Suppose CRRA utility, such that $\frac{u''(c)c}{u'(c)} = -\gamma$

► Then the last equation

$$-u''(c)c'(k)(k^{\alpha}-\delta k-c)=u'(c)(\alpha k^{\alpha-1}-\delta-\rho)$$

is equal to

$$\gamma \frac{c'(k)}{c} (k^{\alpha} - \delta k - c) = (\alpha k^{\alpha - 1} - \delta - \rho)$$

▶ This is the Euler equation in continuous time.

Before we attempt to solve the Euler equation, recall that we had

$$k_{t+\Delta} + \Delta c_t = \Delta k_t^{\alpha} + (1 - \Delta \delta)k_t$$

rearrange

$$k_{t+\Delta} - k_t = \Delta(k_t^{\alpha} - \delta k_t - c_t)$$

Divide with Δ and take limit $\Delta \rightarrow 0$ to get

$$\dot{k}_t = k_t^{\alpha} - \delta k_t - c_t$$

Or dropping time notation

$$\dot{\mathbf{k}} = \mathbf{k}^{\alpha} - \delta \mathbf{k} - \mathbf{c}$$

Our Euler equation is

$$\frac{c'(k)}{c}(k^{\alpha}-\delta k-c)=\frac{1}{\gamma}(\alpha k^{\alpha-1}-\delta-\rho)$$

or now

$$\gamma \frac{c'(k)}{c} \dot{k} = (\alpha k^{\alpha - 1} - \delta - \rho)$$

▶ What is c'(k)k? Recall chain rule

$$\dot{c} = \frac{\partial c_t}{\partial t} = \frac{\partial c_t}{\partial k} \frac{\partial k}{\partial t} = c'(k)\dot{k}$$

► Thus

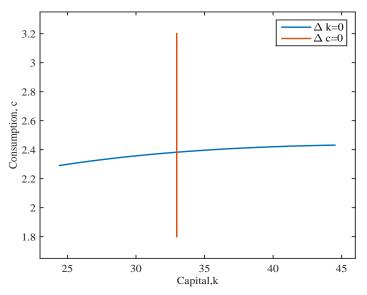
$$\frac{\dot{c}}{c} = \frac{1}{2} (\alpha k^{\alpha - 1} - \delta - \rho)$$

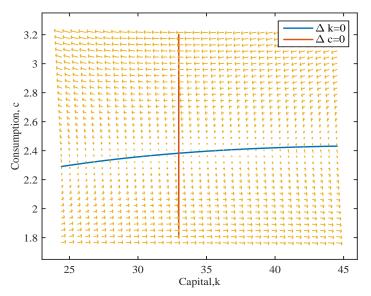
► Two equations

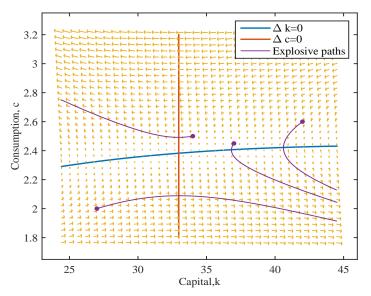
$$\dot{c} = \frac{c}{\gamma} (\alpha k^{\alpha - 1} - \delta - \rho)$$
$$\dot{k} = k^{\alpha} - \delta k - c$$

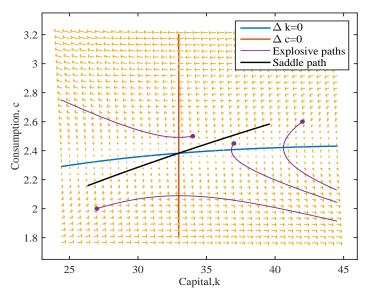
Nullclines

$$0 = \alpha k^{\alpha - 1} - \delta - \rho$$
$$0 = k^{\alpha} - \delta k - c$$









- ► How did I do that?
- ▶ I created a grid for k and c, and found \dot{c} and \dot{k} through

$$\dot{c} = \frac{c}{\gamma} (\alpha k^{\alpha - 1} - \delta - \rho)$$
$$\dot{k} = k^{\alpha} - \delta k - c$$

- ► Then I used Matlab's command quiver(k,c, \dot{k} , \dot{c})
 - ► This creates the swarm of arrows
- ▶ I then used Matlab's command streamline(k, c, \dot{k}, \dot{c}) at various starting values to get the explosive paths.
- ► Lastly I solved for the saddle path and plotted it.

The Ramsey growth model: Euler equation solution

Back to the "recursive" Euler

$$\frac{c'(k)}{c}(k^{\alpha}-\delta k-c)=\frac{1}{\gamma}(\alpha k^{\alpha-1}-\delta-\rho)$$

► Solve for *c*

$$c = \frac{c'(k)(k^{\alpha} - \delta k)}{\frac{1}{\gamma}(\alpha k^{\alpha - 1} - \delta - \rho) + c'(k)}$$

The Ramsey growth model: Euler equation solution

Algorithm

- 1. Construct a grid for k.
- 2. For each point on the grid, guess for a value of c_0 .
- 3. Calculate the derivative as $dc_0=D*c_0$.
- 4. Find c₁ from

$$c_1 = rac{dc_0(k^{lpha} - \delta k)}{rac{1}{\gamma}(lpha k^{lpha-1} - \delta -
ho) + dc_0}$$

5. Back to step 3 with c_1 replacing c_0 . Repeat until convergence.

The Ramsey growth model: Euler equation solution

Algorithm

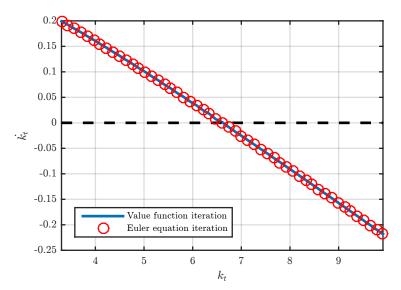
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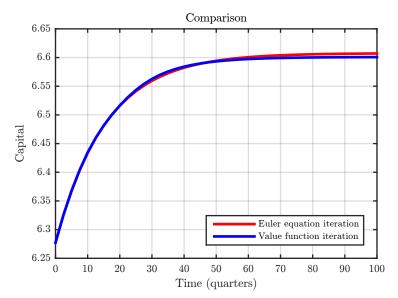
5. Back to step 3 with c_1 replacing c_0 . Repeat until convergence.

Beware: No guaranteed convergence. Update slowly. Fewer gridpoints appears to provide some stability.

The Ramsey growth model: Solution



The Ramsey growth model: Solution



- We derived the Euler equation in a slightly roundabout way
 - 1. Discrete time Bellman equation
 - 2. To continuous time HJB equation
 - To continuous time Euler equation using the envelope condition.
- ► This can be done more directly from the discrete time Euler equation.

The discrete time Euler equation is given by

$$u'(c_t) = (1 - \rho)(1 + \alpha k_{t+1}^{\alpha - 1} - \delta)u'(c_{t+1})$$

 \triangleright In \triangle units of time

$$u'(c_t) = (1 - \Delta \rho)(1 + \Delta(\alpha k_{t+\Delta}^{\alpha-1} - \delta))u'(c_{t+\Delta})$$

• Use the approximation $u'(c_{t+\Delta}) \approx u'(c_t) + u''(c_t) \dot{c}_t \Delta$ to get

$$u'(c_t) = (1 - \Delta \rho)(1 + \Delta(\alpha k_{t+\Delta}^{\alpha-1} - \delta))(u'(c_t) + u''(c_t)\dot{c}_t\Delta)$$



$$u'(c_t) = (1 - \Delta \rho)(1 + \Delta(\alpha k_{t+\Delta}^{\alpha-1} - \delta))(u'(c_t) + u''(c_t)\dot{c}_t\Delta)$$

Move the $u'(c_t + \dot{c}_t \Delta)$ term to the left-hand side and expand

$$-u''(c_t)\dot{c}_t\Delta$$

$$=\Delta[\alpha k_{t+\Delta}^{\alpha-1}-\delta-\rho-\rho\Delta(\alpha k_{t+\Delta}^{\alpha-1}-\delta)](u'(c_t)+u''(c_t)\dot{c}_t\Delta)$$

▶ Divide by Δ and take limits $\Delta \rightarrow 0$

$$-u''(c_t)\dot{c}_t = [\alpha k_t^{\alpha-1} - \delta - \rho]u'(c_t)$$



$$-u''(c_t)\dot{c}_t = [\alpha k_t^{\alpha-1} - \delta - \rho]u'(c_t)$$

► Lastly, use the CRRA property to get

$$\frac{\dot{c}_t}{c_t} = \frac{1}{\gamma} [\alpha k_t^{\alpha - 1} - \delta - \rho]$$

Now consider a stochastic model with a "good", g, and a "bad", b, state

$$u'(c_t^g) = (1 - \rho)[(1 - p)(1 + z_{t+1}^g \alpha (k_{t+1}^g)^{\alpha - 1} - \delta)u'(c_{t+1}^g) + p(1 + z_{t+1}^b \alpha (k_{t+1}^b)^{\alpha - 1} - \delta)u'(c_{t+1}^b)]$$

and

$$u'(c_t^b) = (1 - \rho)[(1 - q)(1 + z_{t+1}^g \alpha (k_{t+1}^g)^{\alpha - 1} - \delta)u'(c_{t+1}^g) + q(1 + z_{t+1}^b \alpha (k_{t+1}^b)^{\alpha - 1} - \delta)u'(c_{t+1}^b)]$$

► We will focus on the good state (the treatment of the bad state is symmetric)

▶ Good state Euler equation in ∆ units of time

$$u'(c_t^g) = (1 - \Delta \rho)[(1 - \Delta p)(1 + \Delta(z_{t+\Delta}^g \alpha(k_{t+\Delta}^g)^{\alpha - 1} - \delta)) \times u'(c_{t+\Delta}^g) + \Delta p(1 + \Delta(z_{t+\Delta}^b \alpha(k_{t+\Delta}^b)^{\alpha - 1} - \delta))u'(c_{t+\Delta}^b)]$$

• Use $u'(c_{t+\Delta}^g) \approx u'(c_t^g) + u''(c_t^g)\dot{c}_t^g\Delta$ again, move to the left-hand side, divide by Δ and take limits

$$-u''(c_t^g)\dot{c}_t^g = (z_t^g\alpha(k_t^g)^{\alpha-1} - \delta - \rho))u'(c_t^g) + p(u'(c_t^b) - u'(c_t^g))$$

▶ Or

$$\frac{\dot{c}_t^g}{c_t^g} = \frac{1}{\gamma} (z_t^g \alpha (k_t^g)^{\alpha - 1} - \delta - \rho)) + p \frac{(u'(c_t^b) - u'(c_t^g))}{u'(c_t^g)}$$

For the bad state

$$\frac{\dot{c}_t^b}{c_t^b} = \frac{1}{\gamma} (z_t^b \alpha (k_t^b)^{\alpha - 1} - \delta - \rho)) + q \frac{(u'(c_t^b) - u'(c_t^g))}{u'(c_t^b)}$$

▶ These can be solved using the previous methods. The only difference is that we now iterate on two equations instead of one. But the procedure is the same.

- ▶ As a last step, I just want to give you a hint on how these ideas can be applied in different settings.
- For instance, the Euler equation for a standard deterministic monetary model is given by

$$u'(c_t) = (1 - \rho)(1 + i_{t+1})\frac{p_t}{p_{t+1}}u'(c_{t+1})$$

ightharpoonup In Δ units of time

$$u'(c_t) = (1 - \Delta \rho)(1 + \Delta i_{t+1}) \frac{p_t}{p_{t+\Delta}} u'(c_{t+\Delta})$$

• Use the approximations $u'(c_{t+\Delta}) \approx u'(c_t) + u''(c_t)\dot{c}_t\Delta$, and $p_t \approx p_{t+\Delta} - \dot{p}_t\Delta$ and rewrite

$$u'(c_t) = (1-\Delta
ho)(1+\Delta i_{t+\Delta})rac{
ho_{t+\Delta}-\dot{
ho_t}\Delta}{
ho_{t+\Delta}}(u'(c_t)+u''(c_t)\dot{c_t}\Delta)$$

Expand

$$u'(c_t) = (1 - \Delta \rho + \Delta i_{t+\Delta} - \Delta^2 i_{t+\Delta} \rho) (1 - \frac{\dot{p_t}\Delta}{p_{t+\Delta}}) (u'(c_t) + u''(c_t)\dot{c_t}\Delta)$$

► Thus

$$-u''(c_t)\dot{c}_t\Delta = (-\Delta\rho + \Delta i_{t+\Delta} - \Delta^2 i_{t+\Delta}\rho)$$

$$\times (1 - \frac{\dot{p}_t\Delta}{p_{t+\Delta}})(u'(c_t) + u''(c_t)\dot{c}_t\Delta) - \frac{\dot{p}_t\Delta}{p_{t+\Delta}}(u'(c_t) + u''(c_t)\dot{c}_t\Delta)$$

Previous equation

$$egin{aligned} &-u''(c_t)\dot{c}_t\Delta = \left(-\Delta
ho + \Delta\dot{i}_{t+\Delta} - \Delta^2\dot{i}_{t+\Delta}
ho
ight) \ & imes (1-rac{\dot{p}_t\Delta}{p_{t+\Delta}})(u'(c_t)+u''(c_t)\dot{c}_t\Delta) - rac{\dot{p}_t\Delta}{p_{t+\Delta}}(u'(c_t)+u''(c_t)\dot{c}_t\Delta) \end{aligned}$$

Divide by Δ

$$egin{aligned} &-u''(c_t)\dot{c}_t = \left(-
ho + i_{t+\Delta} - \Delta i_{t+\Delta}
ho
ight) \ imes & (1-rac{\dot{p}_t\Delta}{p_{t+\Delta}})(u'(c_t) + u''(c_t)\dot{c}_t\Delta) - rac{\dot{p}_t}{p_{t+\Delta}}(u'(c_t) + u''(c_t)\dot{c}_t\Delta) \end{aligned}$$

ightharpoonup And take limit $\Delta \rightarrow 0$

$$\frac{\dot{c}_t}{c_t} = \frac{1}{\gamma} (i_t - \frac{\dot{p}_t}{p_t} - \rho)$$