

# Importance of Imposing Equilibrium

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# Key message

Approximation error **CANNOT** be in equilibrium conditions

In KS-type algorithm this is important in simulation phase

## Some errors are NOT acceptable!!!

- Numerical approximation  $\implies$  some approximation error
- But equilibrium conditions must hold exactly. Why?
  - Consider an endowment economy with heterogeneous agents in which bonds are in zero net-supply
  - If aggregate bond demand  $\neq 0 \implies$  you create/destroy real resources
  - Such “disequilibrium” errors are unlikely to have an exact mean of zero  
 $\implies$  resources available in the economy change over time (especially problematic since we rely on long time series to accurately characterize economy properties)
- Algorithm imposes equilibrium *exactly* in the capital-only model (explanation given below)

# Economy with bonds

- Suppose we add one-period bonds
  - $\implies$  we also have to solve for
    - individual demand for bonds,  $b_{i,t+1} = b(s_{i,t})$
    - bond price,  $q(S_t)$
  - Simulated aggregate demand for bonds not necessarily  $= 0$
  - $\implies$  resources are either added or taken out of this economy

# Bonds and ensuring equilibrium #1

Possible solution #1

- Add the bond price as a state variable in individual problem
- For each period, solve for the bond price that sets aggregate bond demand equal to zero
- a bit unusual to make an endogenous variable a state variable
- risky in terms of getting convergence (in my experience)

# Reminder about function approximation

You usually have a lot of choices:

- Approximating the consumption function instead of the capital choice may at times be better/worse.
- Approximating log level may at times be better than the level.
- So instead of approximating  $b(s_{i,t})$  you could approximate
  - $d(s_{i,t}) = \log(b(s_{i,t}))$  and solve  $b_{i,t}$  from  $b_{i,t+1} = \exp(d(s_{i,t}))$
  - $d(s_{i,t}) = b(s_{i,t}) + 5$  and solve  $b_{i,t}$  from  $b_{i,t+1} = d(s_{i,t}) - 5$
  - $d(s_{i,t}) = b(s_{i,t}) + z_t$  and solve  $b_{i,t}$  from  $b_{i,t+1} = d(s_{i,t}) - z_t$

For an *accurate* solution, the implied  $b(s_{i,t})$  would be virtually the same for all three cases above

## Bonds and ensuring equilibrium #2

- ❶ Instead of approximating  $b_i(s_{i,t})$ , approximate  $d_i(s_{i,t})$  where

$$d(s_{i,t}) = b(s_{i,t}) + \zeta q(S_t)$$

- ❷ Imposing equilibrium gives

$$0 = \left( \sum_i b_{i,t+1} \right) / I \implies$$

$$0 = \left( \sum_i (d_{i,t+1} - \zeta q_t) \right) / I \implies$$

$$q_t = \left( \left( \sum_i d_i(s_{i,t}) \right) / I \right) / \zeta$$

- ❸ The numerical bond demand approximation now depends on  $q_t$  :

$$b_{i,t+1} = b(q_t, s_{i,t}) = d(s_{i,t}) - \zeta q_t$$

## Bonds and ensuring equilibrium #2

- Does any  $d(s_{i,t})$  work?
- For stability, the implied  $b_{i,t}$  needs to be *like* a demand equation, that is

$$\frac{\partial b_i(q_t, s_{i,t})}{\partial q_t} < 0,$$

which is equal to  $-\zeta$  here  $\implies$  we want  $\zeta > 0$ .

- We are not looking for some true complete derivative!
- $d(s_{i,t})$  implicitly also captures some of the relationship between  $b(s_{i,t})$  and  $q_t$  (obvious when  $\zeta = 0$ ).
- Approximating  $d(s_{i,t})$  just adds some flexibility to impose equilibrium exactly.
- For an accurate solution, the implied  $b(s_{i,t})$  would be the same, independent of the alternative  $d(s_{i,t})$  chosen.



## Bonds and ensuring equilibrium #2

Many ways to implement above idea:

- $d(s_{i,t}) = b(s_{i,t}) + \zeta q(S_t)$  is a bit ad hoc
- Alternative:
  - solve for  $c(s_{i,t})$
  - get  $b_{i,t}$  from budget constraint which contains  $q_t$
  - You get  $b_i(q_t, s_{i,t})$  with

$$\frac{\partial b_i(q_t, s_{i,t})}{\partial q_t} < 0$$

# Imposing equilibrium

- Capital market equilibrium is automatically imposed in simulation. Why?
  - Supply of capital comes from  $K_t = \sum_i k_{i,t}$
  - This value of  $K_t$  is used in firm FOC
  - $r_t$  adjusts so that firm demand for capital equals supply
- Where is the approximation error here?
  - FOC individual contains  $r_{t+1}$  and when solving for  $k_{i,t+1}$  we use  $\Gamma(\cdot; \eta)$  to determine  $K_{t+1}$  which in turn determines this  $r_{t+1}$  (together with  $z_{t+1}$ )
  - But simulated  $K_t = \sum_i k_{i,t}$  could be a bit different
- So agents' perception about future  $r$  may have an approximation error, but equilibrium is imposed